Readings listed in class website

Gaussians
Linear Regression
Bias-Variance Tradeoff

Machine Learning – 10701/15781

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What about continuous variables?

- Billionaire says: If I am measuring a continuous variable, what can you do for me?
- **You say: Let me tell you about Gaussians…**

$$P(x \mid \mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

Some properties of Gaussians

- affine transformation (multiplying by scalar and adding a constant)
  - X ~ $N(\mu,\sigma^2)$
  - Y = aX + b → Y ~ $N(a\mu+b,a^2\sigma^2)$
- Sum of Gaussians
  - X ~ $N(\mu_X,\sigma^2_X)$
  - Y ~ $N(\mu_Y,\sigma^2_Y)$
  - Z = X+Y → Z ~ $N(\mu_X+\mu_Y, \sigma^2_X+\sigma^2_Y)$

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Learning a Gaussian

- Collect a bunch of data
  - Hopefully, i.i.d. samples
  - e.g., exam scores
- Learn parameters
  - Mean
  - Variance

$$P(x \mid \mu,\sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

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MLE for Gaussian

- Prob. of i.i.d. samples $D=\{x_1,\ldots,x_N\}$:

$$P(\mathcal{D} \mid \mu, \sigma) = \left(\frac{1}{\sigma\sqrt{2\pi}}\right)^N \prod_{i=1}^N e^{\frac{-(x_i-\mu)^2}{2\sigma^2}}$$

- Log-likelihood of data:

$$\begin{aligned}\ln P(\mathcal{D} \mid \mu, \sigma) &= \ln\left[\left(\frac{1}{\sigma\sqrt{2\pi}}\right)^N \prod_{i=1}^N e^{\frac{-(x_i-\mu)^2}{2\sigma^2}}\right] \\ &= -N \ln \sigma\sqrt{2\pi} - \sum_{i=1}^N \frac{(x_i-\mu)^2}{2\sigma^2}\end{aligned}$$

Your second learning algorithm: MLE for mean of a Gaussian

- What's MLE for mean?

$$\frac{d}{d\mu} \ln P(\mathcal{D} \mid \mu, \sigma) = \frac{d}{d\mu}\left[-N \ln \sigma\sqrt{2\pi} - \sum_{i=1}^N \frac{(x_i-\mu)^2}{2\sigma^2}\right]$$

MLE for variance

- Again, set derivative to zero:

$$\frac{d}{d\sigma} \ln P(\mathcal{D} \mid \mu, \sigma) = \frac{d}{d\sigma}\left[-N \ln \sigma\sqrt{2\pi} - \sum_{i=1}^{N} \frac{(x_i - \mu)^2}{2\sigma^2}\right]$$

$$= \frac{d}{d\sigma}\left[-N \ln \sigma\sqrt{2\pi}\right] - \sum_{i=1}^{N} \frac{d}{d\sigma}\left[\frac{(x_i - \mu)^2}{2\sigma^2}\right]$$

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Learning Gaussian parameters

- MLE:

$$\widehat{\mu}_{MLE} = \frac{1}{N}\sum_{i=1}^{N} x_i$$

$$\widehat{\sigma}^2_{MLE} = \frac{1}{N}\sum_{i=1}^{N} (x_i - \widehat{\mu})^2$$

- BTW. MLE for the variance of a Gaussian is **biased**
  - Expected result of estimation is **not** true parameter!
  - Unbiased variance estimator:

$$\widehat{\sigma}^2_{unbiased} = \frac{1}{N-1}\sum_{i=1}^{N} (x_i - \widehat{\mu})^2$$

Bayesian learning of Gaussian parameters

- Conjugate priors
  - Mean: Gaussian prior
  - Variance: Wishart Distribution

- Prior for mean:

$$P(\mu \mid \eta, \lambda) = \frac{1}{\lambda\sqrt{2\pi}} e^{\frac{-(\mu-\eta)^2}{2\lambda^2}}$$

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MAP for mean of Gaussian

$$P(\mu \mid \eta, \lambda) = \frac{1}{\lambda\sqrt{2\pi}} e^{\frac{-(\mu-\eta)^2}{2\lambda^2}} \qquad P(\mathcal{D} \mid \mu, \sigma) = \left(\frac{1}{\sigma\sqrt{2\pi}}\right)^N \prod_{i=1}^{N} e^{\frac{-(x_i-\mu)^2}{2\sigma^2}}$$

$$\frac{d}{d\mu}[\ln P(\mathcal{D} \mid \mu)P(\mu)] = \frac{d}{d\mu}[\ln P(\mathcal{D} \mid \mu) + \ln P(\mu)]$$

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Prediction of continuous variables

- Billionaire says: Wait, that's not what I meant!
- You says: Chill out, dude.
- He says: I want to predict a continuous variable for continuous inputs: I want to predict salaries from GPA.
- You say: **I can regress that…**

The regression problem

- **Instances:** <$\mathbf{x}_j$, t_j>
- **Learn:** Mapping from x to t(**x**)
- **Hypothesis space:**
  - Given, basis functions
  - Find coeffs **w**={w_1,…,w_k}
  - Why is this called linear regression???
    - model is linear in the parameters

$$H = \{h_1, \ldots, h_K\}$$

$$\underbrace{t(\mathbf{x})}_{\text{data}} \approx \widehat{f}(\mathbf{x}) = \sum_i w_i h_i(\mathbf{x})$$

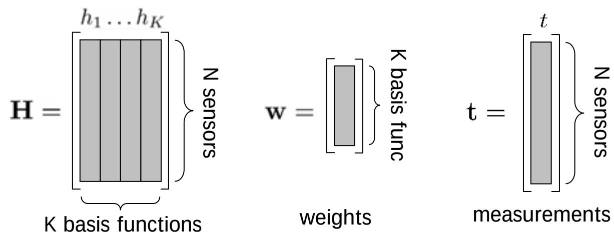
- Precisely, minimize the residual squared error:

$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \sum_j \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$

The regression problem in matrix notation

$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \sum_j \left(t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$

$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \underbrace{(\mathbf{H}\mathbf{w} - \mathbf{t})^T (\mathbf{H}\mathbf{w} - \mathbf{t})}_{\text{residual error}}$$

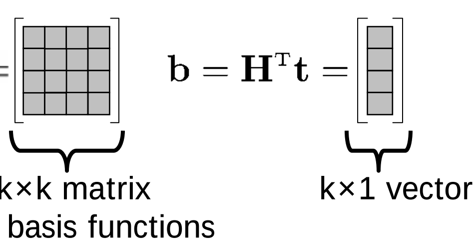


Regression solution = simple matrix operations

$$\mathbf{w}^* = \arg\min_{\mathbf{w}} \underbrace{(\mathbf{H}\mathbf{w} - \mathbf{t})^T (\mathbf{H}\mathbf{w} - \mathbf{t})}_{\text{residual error}}$$

$$\text{solution: } \mathbf{w}^* = \underbrace{(\mathbf{H}^{\mathrm{T}}\mathbf{H})^{-1}}_{\mathbf{A}^{-1}} \underbrace{\mathbf{H}^{\mathrm{T}}\mathbf{t}}_{\mathbf{b}} = \mathbf{A}^{-1}\mathbf{b}$$

where $\mathbf{A} = \mathbf{H}^{\mathrm{T}}\mathbf{H} =$ [matrix] $\quad \mathbf{b} = \mathbf{H}^{\mathrm{T}}\mathbf{t} =$ [vector]



But, why?

- Billionaire (again) says: Why sum squared error???
- You say: Gaussians, Dr. Gateson, Gaussians…

- Model: prediction is linear function plus Gaussian noise
  - $t = \sum_i w_i h_i(\mathbf{x}) + \varepsilon$

- Learn **w** using MLE

$$P(t \mid \mathbf{x}, \mathbf{w}, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{\frac{-[t - \sum_i w_i h_i(\mathbf{x})]^2}{2\sigma^2}}$$

Maximizing log-likelihood

Maximize:

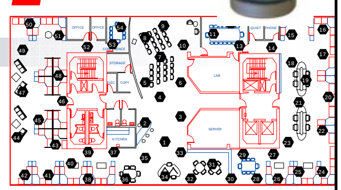
$$\ln P(\mathcal{D} \mid \mathbf{w}, \sigma) = \ln \left(\frac{1}{\sigma\sqrt{2\pi}}\right)^N \prod_{j=1}^{N} e^{\frac{-[t_j - \sum_i w_i h_i(\mathbf{x}_j)]^2}{2\sigma^2}}$$

Least-squares Linear Regression is MLE for Gaussians!!!

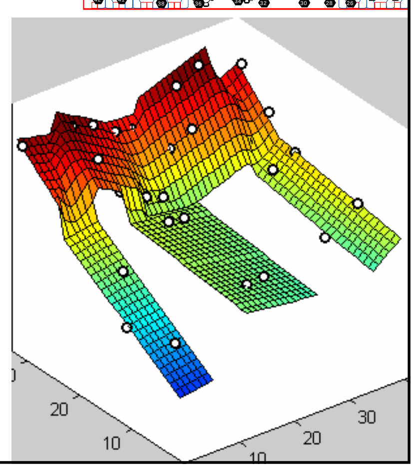
Applications Corner 1

- Predict stock value over time from
  - past values
  - other relevant vars
    - e.g., weather, demands, etc.

Applications Corner 2



- Measure temperatures at some locations
- Predict temperatures throughout the environment



[Guestrin et al. '04]

Applications Corner 3

- Predict when a sensor will fail
  - based several variables
    - age, chemical exposure, number of hours used,…

Announcements 1

- Readings associated with each class
  - See course website for specific sections, extra links, and further details
  - Visit the website frequently
- Recitations
  - Thursdays, 5:00-6:20 in Wean Hall 5409
- Special recitation on Matlab
  - Sept. 18 Tue. 4:30-5:50pm NSH 3002
- Carlos away on Monday Sept. 17th
  - Prof. Eric Xing will teach the lecture

Announcement 2

- First homework out later today!
  - Download from course website!
  - Start early!!! :)
  - Due Oct 3rd
- To expedite grading:
  - there are 4 questions
  - please hand in 4 stapled separate parts, one for each question

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Bias-Variance tradeoff – Intuition

- Model too “simple” $\rightarrow$ does not fit the data well
  - A biased solution
- Model too complex $\rightarrow$ small changes to the data, solution changes a lot
  - A high-variance solution

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(Squared) Bias of learner

- Given dataset *D* with *m* samples, learn function h(x)
- If you sample a different datasets, you will learn different h(x)
- **Expected hypothesis**: $E_D[h(x)]$
- **Bias:** difference between what you expect to learn and truth
  - Measures how well you expect to represent true solution
  - Decreases with more complex model

$$bias^2 = \int_x \{E_D[h(x)] - t(x)\}^2 p(x) dx$$

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Variance of learner

- Given a dataset *D* with *m* samples, you learn function h(x)
- If you sample a different datasets, you will learn different h(x)
- **Variance:** difference between what you expect to learn and what you learn from a from a particular dataset
  - Measures how sensitive learner is to specific dataset
  - Decreases with simpler model

$$\begin{aligned} \bar{h}(x) &= E_D[h(x)] \\ variance &= \int E_D[(h(x) - \bar{h}(x))^2] p(x) dx \end{aligned}$$

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Bias-Variance Tradeoff

- Choice of hypothesis class introduces learning bias
  - More complex class → less bias
  - More complex class → more variance

Bias–Variance decomposition of error

- Consider simple regression problem f:X→T

  $t = f(x) = g(x) + \varepsilon$

  noise ~ N(0,σ)

  deterministic

  Collect some data, and learn a function h(x)

  What are sources of prediction error?

Sources of error 1 – noise

- What if we have perfect learner, infinite data?
  - If our learning solution h(x) satisfies h(x)=g(x)
  - Still have remaining, *unavoidable error* of σ^2 due to noise ε

$$error(h) = \int_x \int_t (h(x) - t)^2 p(f(x) = t|x) p(x) dt dx$$

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Sources of error 2 – Finite data

- What if we have imperfect learner, or only m training examples?
- What is our expected squared error per example?
  - Expectation taken over random training sets *D* of size m, drawn from distribution P(X,T)

$$E_D\left[\int_x \int_t \{h(x) - t\}^2 p(f(x) = t|x) p(x) dt dx\right]$$

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Bias-Variance Decomposition of Error

Bishop Chapter 3

Assume target function: t = f(x) = g(x) + ε

Then expected sq error over fixed size training sets *D* drawn from P(X,T) can be expressed as sum of three components:

$$E_D\left[\int_x \int_t (h(x) - t)^2 p(t|x)p(x)dtdx\right]$$

$$= unavoidableError + bias^2 + variance$$

Where:

$$unavoidableError = \sigma^2$$

$$bias^2 = \int (E_D[h(x)] - g(x))^2 p(x)dx$$

$$\bar{h}(x) = E_D[h(x)]$$

$$variance = \int E_D[(h(x) - \bar{h}(x))^2]p(x)dx$$

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What you need to know

- Gaussian estimation
  - MLE
  - Bayesian learning
  - MAP
- Regression
  - Basis function = features
  - Optimizing sum squared error
  - Relationship between regression and Gaussians
- Bias-Variance trade-off
- Play with Applet

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