

Readings listed in class website

# Gaussians Linear Regression Bias-Variance Tradeoff

Machine Learning – 10701/15781

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## Maximum Likelihood Estimation

- **Data:** Observed set  $D$  of  $\alpha_H$  Heads and  $\alpha_T$  Tails
- **Hypothesis:** Binomial distribution
- Learning  $\theta$  is an optimization problem
  - What's the objective function?
- MLE: Choose  $\theta$  that maximizes the probability of observed data:

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} P(\mathcal{D} | \theta) \\ &= \arg \max_{\theta} \ln P(\mathcal{D} | \theta)\end{aligned}$$

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# Bayesian Learning for Thumbtack

$$P(\theta \mid \mathcal{D}) \propto P(\mathcal{D} \mid \theta)P(\theta)$$

- Likelihood function is simply Binomial:

$$P(\mathcal{D} \mid \theta) = \theta^{\alpha_H} (1 - \theta)^{\alpha_T}$$

- What about prior?

- ☐ Represent expert knowledge
- ☐ Simple posterior form

- Conjugate priors:

- ☐ Closed-form representation of posterior
- ☐ **For Binomial, conjugate prior is Beta distribution**

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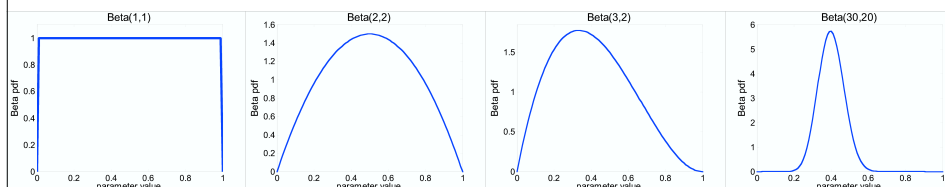
## Posterior distribution

- Prior:  $Beta(\beta_H, \beta_T)$

- Data:  $\alpha_H$  heads and  $\alpha_T$  tails

- Posterior distribution:

$$P(\theta \mid \mathcal{D}) \sim Beta(\beta_H + \alpha_H, \beta_T + \alpha_T)$$



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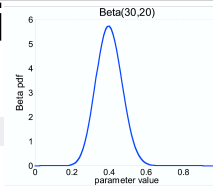
## MAP: Maximum a posteriori approximation

$$P(\theta | \mathcal{D}) \sim \text{Beta}(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

$$E[f(\theta)] = \int_0^1 f(\theta) P(\theta | \mathcal{D}) d\theta$$

- As more data is observed, Beta is more certain
- MAP: use most likely parameter:

$$\hat{\theta} = \arg \max_{\theta} P(\theta | \mathcal{D}) \quad E[f(\theta)] \approx f(\hat{\theta})$$



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## What about continuous variables?

- Billionaire says: If I am measuring a continuous variable, what can you do for me?
- **You say: Let me tell you about Gaussians...**

$$P(x | \mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

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## Some properties of Gaussians

- affine transformation (multiplying by scalar and adding a constant)
  - $X \sim N(\mu, \sigma^2)$
  - $Y = aX + b \rightarrow Y \sim N(a\mu + b, a^2\sigma^2)$
- Sum of Gaussians
  - $X \sim N(\mu_X, \sigma_X^2)$
  - $Y \sim N(\mu_Y, \sigma_Y^2)$
  - $Z = X + Y \rightarrow Z \sim N(\mu_X + \mu_Y, \sigma_X^2 + \sigma_Y^2)$

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## Learning a Gaussian

- Collect a bunch of data
  - Hopefully, i.i.d. samples
  - e.g., exam scores
- Learn parameters
  - Mean
  - Variance

$$P(x \mid \mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

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## MLE for Gaussian

- Prob. of i.i.d. samples  $D=\{x_1, \dots, x_N\}$ :

$$P(\mathcal{D} \mid \mu, \sigma) = \left( \frac{1}{\sigma\sqrt{2\pi}} \right)^N \prod_{i=1}^N e^{\frac{-(x_i - \mu)^2}{2\sigma^2}}$$

- Log-likelihood of data:

$$\begin{aligned} \ln P(\mathcal{D} \mid \mu, \sigma) &= \ln \left[ \left( \frac{1}{\sigma\sqrt{2\pi}} \right)^N \prod_{i=1}^N e^{\frac{-(x_i - \mu)^2}{2\sigma^2}} \right] \\ &= -N \ln \sigma\sqrt{2\pi} - \sum_{i=1}^N \frac{(x_i - \mu)^2}{2\sigma^2} \end{aligned}$$

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## Your second learning algorithm: MLE for mean of a Gaussian

- What's MLE for mean?

$$\frac{d}{d\mu} \ln P(\mathcal{D} \mid \mu, \sigma) = \frac{d}{d\mu} \left[ -N \ln \sigma\sqrt{2\pi} - \sum_{i=1}^N \frac{(x_i - \mu)^2}{2\sigma^2} \right]$$

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## MLE for variance

- Again, set derivative to zero:

$$\begin{aligned}\frac{d}{d\sigma} \ln P(\mathcal{D} \mid \mu, \sigma) &= \frac{d}{d\sigma} \left[ -N \ln \sigma \sqrt{2\pi} - \sum_{i=1}^N \frac{(x_i - \mu)^2}{2\sigma^2} \right] \\ &= \frac{d}{d\sigma} \left[ -N \ln \sigma \sqrt{2\pi} \right] - \sum_{i=1}^N \frac{d}{d\sigma} \left[ \frac{(x_i - \mu)^2}{2\sigma^2} \right]\end{aligned}$$

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## Learning Gaussian parameters

- MLE:

$$\hat{\mu}_{MLE} = \frac{1}{N} \sum_{i=1}^N x_i$$

$$\hat{\sigma}_{MLE}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})^2$$

- BTW. MLE for the variance of a Gaussian is **biased**

- ☐ Expected result of estimation is **not** true parameter!
- ☐ Unbiased variance estimator:

$$\hat{\sigma}_{unbiased}^2 = \frac{1}{N-1} \sum_{i=1}^N (x_i - \hat{\mu})^2$$

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## Bayesian learning of Gaussian parameters

- Conjugate priors
  - Mean: Gaussian prior
  - Variance: Wishart Distribution

- Prior for mean:

$$P(\mu \mid \eta, \lambda) = \frac{1}{\lambda\sqrt{2\pi}} e^{-\frac{(\mu-\eta)^2}{2\lambda^2}}$$

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## MAP for mean of Gaussian

$$P(\mu \mid \eta, \lambda) = \frac{1}{\lambda\sqrt{2\pi}} e^{-\frac{(\mu-\eta)^2}{2\lambda^2}} \quad P(\mathcal{D} \mid \mu, \sigma) = \left( \frac{1}{\sigma\sqrt{2\pi}} \right)^N \prod_{i=1}^N e^{-\frac{(x_i-\mu)^2}{2\sigma^2}}$$
$$\frac{d}{d\mu} [\ln P(\mathcal{D} \mid \mu) P(\mu)] = \frac{d}{d\mu} [\ln P(\mathcal{D} \mid \mu) + \ln P(\mu)]$$

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# Prediction of continuous variables

- Billionaire says: Wait, that's not what I meant!
- You says: Chill out, dude.
- He says: I want to predict a continuous variable for continuous inputs: I want to predict salaries from GPA.
- You say: **I can regress that...**

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# The regression problem

- **Instances:**  $\langle \mathbf{x}_j, t_j \rangle$
- **Learn:** Mapping from  $\mathbf{x}$  to  $t(\mathbf{x})$
- **Hypothesis space:**
  - Given, basis functions  $H = \{h_1, \dots, h_K\}$
  - Find coeffs  $\mathbf{w} = \{w_1, \dots, w_K\}$   $t(\mathbf{x}) \approx \hat{f}(\mathbf{x}) = \sum_i w_i h_i(\mathbf{x})$
  - Why is this called linear regression?
    - model is linear in the parameters
- Precisely, minimize the **residual squared error**:

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \sum_j \left( t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$

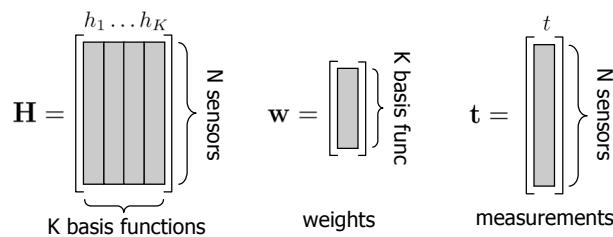
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## The regression problem in matrix notation

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \sum_j \left( t(\mathbf{x}_j) - \sum_i w_i h_i(\mathbf{x}_j) \right)^2$$

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \underbrace{(\mathbf{H}\mathbf{w} - \mathbf{t})^T (\mathbf{H}\mathbf{w} - \mathbf{t})}_{\text{residual error}}$$

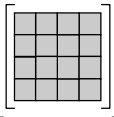
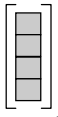


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## Regression solution = simple matrix operations

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \underbrace{(\mathbf{H}\mathbf{w} - \mathbf{t})^T (\mathbf{H}\mathbf{w} - \mathbf{t})}_{\text{residual error}}$$

$$\text{solution: } \mathbf{w}^* = \underbrace{(\mathbf{H}^T \mathbf{H})^{-1}}_{\mathbf{A}^{-1}} \underbrace{\mathbf{H}^T \mathbf{t}}_{\mathbf{b}} = \mathbf{A}^{-1} \mathbf{b}$$

where  $\mathbf{A} = \mathbf{H}^T \mathbf{H} =$    $\mathbf{b} = \mathbf{H}^T \mathbf{t} =$  

$\mathbf{A}$  is a  $k \times k$  matrix for  $k$  basis functions.  $\mathbf{b}$  is a  $k \times 1$  vector.

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## But, why?

- Billionaire (again) says: Why sum squared error???
- You say: Gaussians, Dr. Gateson, Gaussians...
- Model: prediction is linear function plus Gaussian noise
  - $t = \sum_i w_i h_i(\mathbf{x}) + \varepsilon$

- Learn  $\mathbf{w}$  using MLE

$$P(t \mid \mathbf{x}, \mathbf{w}, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{[t - \sum_i w_i h_i(\mathbf{x})]^2}{2\sigma^2}}$$

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## Maximizing log-likelihood

**Maximize:**

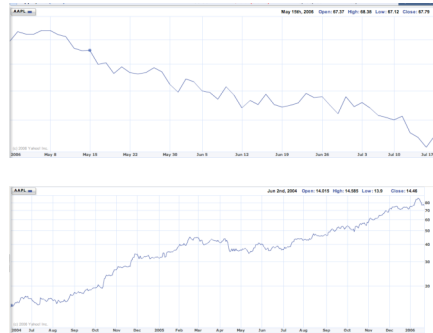
$$\ln P(\mathcal{D} \mid \mathbf{w}, \sigma) = \ln \left( \frac{1}{\sigma\sqrt{2\pi}} \right)^N \prod_{j=1}^N e^{-\frac{[t_j - \sum_i w_i h_i(\mathbf{x}_j)]^2}{2\sigma^2}}$$

**Least-squares Linear Regression is MLE for Gaussians!!!**

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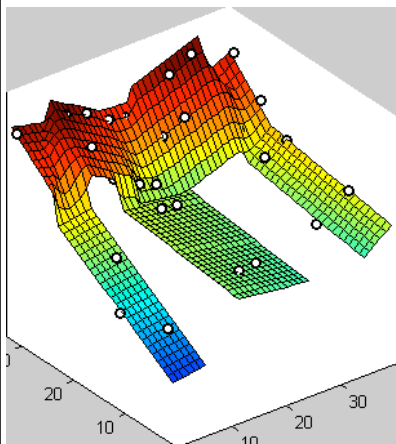
## Applications Corner 1

- Predict stock value over time from
  - past values
  - other relevant vars
    - e.g., weather, demands, etc.

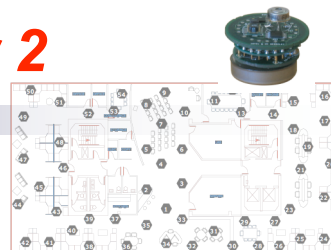


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## Applications Corner 2



[Guestrin et al. '04]



- Measure temperatures at some locations
- Predict temperatures throughout the environment

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## *Applications Corner 3*

- Predict when a sensor will fail
  - based several variables
    - age, chemical exposure, number of hours used,...

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## Announcements

- Readings associated with each class
  - See course website for specific sections, extra links, and further details
  - Visit the website frequently
- Recitations
  - Thursdays, 5:30-6:50 in Wean Hall 5409
- Special recitation on Matlab
  - Jan. 24 Wed. 5:30-6:50pm NSH 1305

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## Bias-Variance tradeoff – Intuition

- Model too “simple” → does not fit the data well
  - A biased solution
- Model too complex → small changes to the data, solution changes a lot
  - A high-variance solution

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## (Squared) Bias of learner

- Given dataset  $D$  with  $m$  samples, learn function  $h(x)$
- If you sample a different datasets, you will learn different  $h(x)$
- **Expected hypothesis:**  $E_D[h(x)]$
- **Bias:** difference between what you expect to learn and truth
  - Measures how well you expect to represent true solution
  - Decreases with more complex model  $\phi$

$$bias^2 = \int_x (E_D[h(x)] - t(x))^2 p(x) dx$$

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$$bias^2 = \int_x \{E_D[h(x)] - t(x)\}^2 p(x) dx$$

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## Variance of learner

- Given a dataset  $D$  with  $m$  samples, you learn function  $h(x)$
- If you sample a different datasets, you will learn different  $h(x)$
- **Variance:** difference between what you expect to learn and what you learn from a from a particular dataset
  - Measures how sensitive learner is to specific dataset
  - Decreases with simpler model

$$\begin{aligned}\bar{h}(x) &= E_D[h(x)] \\ variance &= \int E_D[(h(x) - \bar{h}(x))^2] p(x) dx\end{aligned}$$

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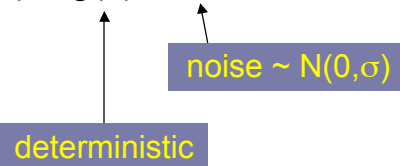
# Bias-Variance Tradeoff

- Choice of hypothesis class introduces learning bias
  - More complex class  $\rightarrow$  less bias
  - More complex class  $\rightarrow$  more variance

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# Bias–Variance decomposition of error

- Consider simple regression problem  $f: X \rightarrow T$   
 $t = f(x) = g(x) + \varepsilon$



Collect some data, and learn a function  $h(x)$   
What are sources of prediction error?

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## Sources of error 1 – noise

- What if we have perfect learner, infinite data?

- If our learning solution  $h(x)$  satisfies  $h(x)=g(x)$
- Still have remaining, unavoidable error of  $\sigma^2$  due to noise  $\varepsilon$

$$error(h) = \int_x \int_t (h(x) - t)^2 p(f(x) = t|x) p(x) dt dx$$

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## Sources of error 2 – Finite data

- What if we have imperfect learner, or only  $m$  training examples?

- What is our expected squared error per example?

- Expectation taken over random training sets  $D$  of size  $m$ , drawn from distribution  $P(X,T)$

$$E_D \left[ \int_x \int_t \{h(x) - t\}^2 p(f(x) = t|x) p(x) dt dx \right]$$

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## Bias-Variance Decomposition of Error

Bishop Chapter 3

Assume target function:  $t = f(x) = g(x) + \varepsilon$

Then expected sq error over fixed size training sets  $D$  drawn from  $P(X,T)$  can be expressed as sum of three components:

$$E_D \left[ \int_x \int_t (h(x) - t)^2 p(t|x) p(x) dt dx \right] \\ = \text{unavoidableError} + \text{bias}^2 + \text{variance}$$

Where:

$$\begin{aligned} \text{unavoidableError} &= \sigma^2 \\ \text{bias}^2 &= \int (E_D[h(x)] - g(x))^2 p(x) dx \\ \bar{h}(x) &= E_D[h(x)] \\ \text{variance} &= \int E_D[(h(x) - \bar{h}(x))^2] p(x) dx \end{aligned}$$

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## What you need to know

- Gaussian estimation
  - MLE
  - Bayesian learning
  - MAP
- Regression
  - Basis function = features
  - Optimizing sum squared error
  - Relationship between regression and Gaussians
- Bias-Variance trade-off
- Play with Applet

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