## 10-725 Recitation 1 Topics

Vector space over scalar field (for us, the real numbers) is a set X with vector addition and scalar multiplication.

Various combinations of vector elements: linear, affine, convex, conic.

Abstract specification of linear function t on X: t(x + y) = t(x) + t(y) and T(c x) = c t(x)

(Real) inner product  $\langle \cdot, \cdot \rangle : X \times X \to \mathbb{R}$  is symmetric, linear in first argument, nonnegative, 0 only when 0 is an argument.

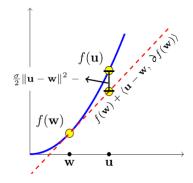
Example: standard inner product on vectors (and matrices)  $\langle x, y \rangle = \sum_{i} x_i y_i$ .

Inner product useful because it provides a concrete implementation of linear functions:  $t(x) = \langle m, x \rangle$ .

Affine functions are translated linear functions, i.e.  $u(x) = \langle m, x \rangle + b$ .a

Favorite affine functions? Those tangent to some (convex) function f at a point x: slope is  $\nabla f(x)$ , intercept is f(x). First-order definition of convexity. Proof that  $f(x) = x^2$  is convex.

Speaking of convexity, here is a strongly convex function:



Speaking of gradients: on the homework, you'll need to take a derivative with respect to a matrix.

Affine functions in n dimensions are linear functions in n + 1 dimensions. (This is an example of "lifts".) Will be loose about affine/linear.

Various hulls: linear, affine, convex, conic.

"Subspace" or "span" = linear hull. Example: hyperplanes.

Linearly independent vectors: no vector contained in span of others

Basis of vector space: linearly independent and they span the vector space.

Dimension of vector space: size of basis.

Linear vector inequality (aka halfspace):  $\{x : a_0 + \sum_i \langle a_i, x \rangle \ge 0\}$ 

(I also mentioned linear matrix inequalities, which each specify infinitely many linear vector inequalities. We will perhaps revisit these.)

Polyhedron: intersection of a finite number of halfspaces

Polytope: convex hull of a finite set of points

Minkowski-Weyl: every bounded polyhedron is a polytope. every polytope is a polyhedron.

For a convex set K, a point in K is

- exposed if it is  $K \cap H$  for some halfspace H
- extreme if it is not a convex combination of any two other points in K

Example of extreme but not exposed? The "hockey rink".

Example of exposed but not extreme? Use a higher-dimensional H.

Farkas' lemma: http://demonstrations.wolfram.com/FarkassLemmaInTwoDimensions/