Lecture 16
Images in ITK

Methods in Medical Image Analysis - Spring 2019
16-725 (CMU RI) : BioE 2630 (Pitt)
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Based in part on Damion Shelton's slides from 2006

Data storage in ITK

- ITK separates storage of data from the actions you can perform on data
- The `DataObject` class is the base class for the major “containers” into which you can place data
Data containers in ITK

- Images: N-d rectilinear grids of regularly sampled data
- Meshes: N-d collections of points linked together into cells (e.g. triangles)
  - Meshes are outside the scope of this course
  - (Meshes are covered in section 4.3 of the ITK Software Guide, Book 1.)
- ITK Spatial Objects
  - May discuss in a future lecture
- ITK Path Objects
  - Final Lecture

What is an image?

- For our purposes, an image is an N-d rectilinear grid of data
- Images can contain any type of data, although scalars (e.g. grayscale) or vectors (e.g. RGB color) are most common
- We will deal mostly with scalars, but keep in mind that unusual images (e.g. linked-lists as pixels) are perfectly legal in ITK
Images are templated

\[
\text{\texttt{\textit{itk::Image\textless TPixel, VImageDimension\textgreater}}} \\
\]

\[
\begin{array}{cc}
\text{Pixel type} & \text{Dimensionality (value)} \\
\end{array}
\]

Examples:

\[
\text{\texttt{\textit{itk::Image\textless double, 4\textgreater}}} \\
\text{\texttt{\textit{itk::Image\textless unsigned char, 2\textgreater}}} \\
\]

An aside: smart pointers

- In C++ you typically allocate memory with \texttt{new} and deallocate it with \texttt{delete}.
- Traditional C++ for a keyboard class \texttt{KB}:
  \[
  \text{\texttt{KB* pKB = new KB;}} \\
  \text{\texttt{pKB -> WaitForKeyPress();}} \\
  \text{\texttt{delete pKB;}} \\
  \]
Danger!

- Suppose you allocate memory in a function and forget to call delete prior to returning... the memory is still allocated, but you can’t get to it
- This is a memory leak
- Leaking doubles or chars can slowly consume memory, leaking 200 MB images will bring your computer to its knees

Smart pointers to the rescue

- Smart pointers get around this problem by allocating and deallocating memory for you
- You do not explicitly delete objects in ITK, this occurs automatically when they go out of scope
- Since you can’t forget to delete objects, you can’t leak memory

(ahem, well, you have to try harder at least)
Smart pointers, cont.

- This is often referred to as *garbage collection* - languages like Java have had it for a while, but it’s fairly new to C++
- Keep in mind that this only applies to ITK objects - you can still leak arrays of floats/chars/widgets until your heart’s content...or your program crashes.

Why are smart pointers smart?

- Smart pointers maintain a “reference count” of how many copies of the pointer exist
- If $N_{\text{ref}}$ drops to 0, nobody is interested in the memory location and it’s safe to delete
- If $N_{\text{ref}} > 0$ the memory is not deleted, because someone still needs it
Scope

- Refers to whether or not a variable exists within a certain segment of the code.
  - When does a variable cease to exist?
- Local vs. global
- Example: variables created within member functions typically have local scope, and “go away” when the function returns

Scope, cont.

- Observation: smart pointers are only deleted when they go out of scope (makes sense, right?)
- Problem: what if we want to “delete” a SP that has not gone out of scope; there are good reasons to do this, e.g. loops
Scope, cont.

- You can create local scope by using `{ }`
- Instances of variables created within the `{ }` will go out of scope when execution moves out of the `{ }
- Therefore… “temporary” smart pointers created within the `{ }` will be deleted
- Keep this trick in mind, you may need it

A final caveat about scope

- Don’t obsess about it
- 99% of the time, smart pointers are smarter than you!
- 1% of the time you may need to haul out the previous trick
Images and regions

- ITK was designed to allow analysis of very large images, even images that far exceed the available RAM of a computer.
- For this reason, ITK distinguishes between an entire image and the part which is actually resident in memory or requested by an algorithm.

Image regions

- Algorithms only process a region of an image that sits inside the current buffer.
- **BufferedRegion** is the portion of image in physical memory.
- **RequestedRegion** is the portion of image to be processed.
- **LargestPossibleRegion** describes the entire dataset.
Image regions, cont.

- It may be helpful for you to think of $LargestPossibleRegion$ as the “size” of the image
- When creating an image from scratch, you must specify sizes for all three regions - they do not have to be the same size
- Don’t get too concerned with regions just yet, we’ll look at them again with filters

Data space vs. “physical” space

- Data space is what you probably think of as “image coordinates”
- Data space is an N-d array with integer indices, each indexed from 0 to $(L_i - 1)$
  - e.g. pixel (3,0,5) in 3D space
- Physical space relates to data space by defining the origin and spacing of the image
Creating an image: step-by-step

- **Note:** this example follows 4.1.1 from the ITK Software Guide's Book 1, but differs in content - please be sure to read the guide as well.

- This example is provided more as a demonstration than as a practical example - in the real world images are often/usually provided to you from an external source rather than being explicitly created.
Declaring an image type

Recall the `typedef` keyword... we first define an image type to save typing later on:

```
typedef itk::Image< unsigned short, 3 > ImageType;
```

We can now use `ImageType` in place of the full class name, a nice convenience.

A syntax note

It may surprise you to see something like the following:

```
ImageType::SizeType
```

(well, not if you were paying attention during the ITK background lecture)

Classes can have typedefs as members. In this case, `SizeType` is a public member of `itk::Image`.

Remember that `ImageType` is itself a typedef, so we could express the above more verbosely as

```
 itk::Image< unsigned short, 3 >::SizeType
```
Syntax note, cont.

- This illustrates one criticism of templates and typedefs—it’s easy to invent something that looks like a new programming language!
- Remember that names ending in “Type” are types, not variables or class names
- Doxygen is your friend - you can find developer-defined types under “Public Types”

Creating an image pointer

An image is created by invoking the New() operator from the corresponding image type and assigning the result to aSmartPointer.

```cpp
ImageType::Pointer image = ImageType::New();
```

Pointer is typedef’d in itk::Image Note the use of “big New”
A note about “big New”

- Many/most classes within ITK (all that derive from itk::Object) are created with the ::New() operator, rather than new
  ```cpp
  MyType::Pointer p = MyType::New();
  ```
- Remember that you should not try to call delete on objects created this way

When not to use ::New()

- “Small” classes, particularly ones that are intended to be accessed many (e.g. millions of) times will suffer a performance hit from smart pointers
- These objects can be created directly (on the stack) or using new (on the free store)
Setting up data space

The ITK Size class holds information about the size of image regions

SizeType is another typedef

```cpp
ImageType::SizeType size;
size[0] = 200; // size along X
size[1] = 200; // size along Y
size[2] = 200; // size along Z
```

Setting up data space, cont.

Our image has to start somewhere - how about starting at the (0,0,0) index?

Don't confuse (0,0,0) with the physical origin!

```cpp
ImageType::IndexType start;
start[0] = 0; // first index on X
start[1] = 0; // first index on Y
start[2] = 0; // first index on Z
```

Note that the index object `start` was not created with ::New()
Setting up data space, cont.

Now that we have defined a size and a starting location, we can build a region.

```cpp
ImageType::RegionType region;
region.SetSize( size );
region.SetIndex( start );
```

*region was also not created with ::New()*

Allocating the image

Finally, we’re ready to actually create the image. The SetRegions function sets all 3 regions to the same region and Allocate sets aside memory for the image.

```cpp
image->SetRegions( region );
image->Allocate();
```
Dealing with physical space

- At this point we have an image of “pure” data; there is no relation to the real world
- Nearly all useful medical images are associated with physical coordinates of some form or another
- As mentioned before, ITK uses the concepts of origin and spacing to translate between physical and data space

Image spacing

We can specify spacing by calling the SetSpacing function in Image.

```c++
ImageType::SpacingType spacing;
spacing[0] = 0.33; // spacing in mm along X
spacing[1] = 0.33; // spacing in mm along Y
spacing[2] = 1.20; // spacing in mm along Z
image->SetSpacing( spacing );
```
Image origin

Similarly, we can set the image origin

```cpp
ImageType::PointType origin;
origin[0] = 0.0; // coordinates of the
origin[1] = 0.0; // first pixel in N-D
origin[2] = 0.0;
image->SetOrigin(origin);
```

Origin/spacing units

- There are no inherent units in the physical coordinate system of an image—i.e. referring to them as mm’s is arbitrary (but very common)
- Unless a specific algorithm states otherwise, ITK does not understand the difference between mm/inches/miles/etc.
Direct pixel access in ITK

- There are many ways to access pixels in ITK
- The simplest is to directly address a pixel by knowing either its:
  - Index in data space
  - Physical position, in physical space

Why not to directly access pixels

- Direct pixels access is simple conceptually, but involves a lot of extra computation (converting pixel indices into a memory pointer)
- There are much faster ways of performing sequential pixel access, through iterators
Accessing pixels in data space

The Index object is used to access pixels in an image, in data space.

```cpp
ImageType::IndexType pixelIndex;
pixelIndex[0] = 27; // x position
pixelIndex[1] = 29; // y position
pixelIndex[2] = 37; // z position
```

Pixel access in data space

To set a pixel:

```cpp
ImageType::PixelType pixelValue = 149;
image->SetPixel(pixelIndex, pixelValue);
```

(the type of pixel stored in the image)

And to get a pixel:

```cpp
ImageType::PixelType value =
image->GetPixel(pixelIndex);
```
Why the runaround with PixelType?

- It might not be obvious why we refer to `ImageType::PixelType` rather than (in this example) just say `unsigned short`.
- In other words, what’s wrong with...

```cpp
unsigned short value = image->GetPixel( pixelIndex );
```

PixelType, cont.

- Well... nothing is wrong in this example
- *But*, when writing general-purpose code we don’t always know or control the type of pixel stored in an image
- Referring to `ImageType` will allow the code to compile for any type that defines the `=` operator (float, int, char, etc.)
PixelType, cont.

That is, if you have a 3D image of doubles,

```cpp
ImageType::PixelType value = image->GetPixel( pixelIndex );
```

works fine, while

```cpp
unsigned short value = image->GetPixel( pixelIndex );
```

will produce a compiler warning, and probably result in a runtime error.

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Accessing pixels in physical space

- ITK uses the Point class to store the position of a point in N-d space

- Example for a 2D point:
  ```cpp
  itk::Point< double, 2 >
  ```

- Using `double` here has *nothing* to do with the pixel type
- `double` specifies the precision of the point’s positioning
- Points are usually of type float or double.
Defining a point

Hopefully this syntax is starting to look somewhat familiar...

```cpp
ImageType::PointType point;
point[0] = 1.45; // x coordinate
point[1] = 7.21; // y coordinate
point[2] = 9.28; // z coordinate
```

Why do we need a Point?

- The image class contains a number of convenience methods to convert between pixel indices and physical positions (as stored in the Point class)
- These methods take into account the origin and spacing of the image, and do bounds-checking as well (i.e., is the point even inside the image?)
TransformPhysicalPointToIndex

- This function takes as parameters a **Point** (that you want) and an **Index** (to store the result in) and returns **true** if the point is inside the image and **false** otherwise.
- Assuming the conversion is successful, the **Index** contains the result of mapping the **Point** into data space.

The transform in action

First, create the index:

```cpp
ImageType::IndexType pixelIndex;
```

Next, run the transformation:

```cpp
image->TransformPhysicalPointToIndex(
    point, pixelIndex);
```

Now we can access the pixel:

```cpp
ImageType::PixelType pixelValue =
    image->GetPixel( pixelIndex );
```
Point and index transforms

2 methods deal with integer indices:
- TransformPhysicalPointToIndex
- TransformIndexToPhysicalPoint

And 2 deal with floating point indices (used to interpolate pixel values):
- TransformPhysicalPointToContinuousIndex
- TransformContinuousIndexToPhysicalPoint

Ways of accessing pixels

- So far we have seen two “direct” methods of pixel access
  - Using an Index object in data space
  - Using a Point object in physical space
- Both of these methods look like typical C++ array access:
  myDataArray[x][y][z] = 2;
Walking through an image

If you’ve done image processing before, the following pseudo code should look familiar:

```
loop over rows
  loop over columns
    build index (row, column)
    GetPixel(index)
  end column loop
end row loop
```

Image traversal, cont.

- The loop technique is easy to understand but:
  - Is slow
  - Does not scale to N-d
  - Is unnecessarily messy from a syntax point of view
- Iterators are a way around this
Why direct access is bad

1... It’s slow:
   a) Build the index
   b) Pass the index to the image
   c) Build a memory address from the index
   d) Access the pixel

Direct access = bad, cont.

2... It’s hard to make it N-d:
Let’s say I want to do something really simple,
like access all of the pixels in an image (any
data type, any dimensionality)
How would you do this using indices?
N-d access troubles

- You could probably come up with a fairly complicated way of building an index
- \textit{But}, nested for-loops will \textit{not} work, because you don’t know ahead of time how many loops to nest

N-d access troubles, cont.

I.e. the following works on 2D images only

\begin{verbatim}
loop over rows
  loop over columns
    build index (row, column)
    GetPixel(index)
  end column loop
end row loop
\end{verbatim}
Iterators to the rescue

- There’s a concept in generic programming called the *iterator*
- It arises from the need to sequentially & efficiently access members of complex data objects
- Iterators are not unique to ITK; the Standard Template Library (STL) uses them extensively

Iterators in ITK

- ITK has many types of iterators. There are iterators to traverse:
  - image regions
  - neighborhoods
  - arbitrary functions (“inside” the function)
  - random pixels in an image
  - and more...
- We’ll be covering several of these in class
See the software guide

- All this and more can be found in Chapter 6 of the ITK Software Guide, Book 1

Good news about iterators

Iterators are:
- Simple to learn and use, and make your code easier to read (!)
- Wrap extremely powerful data access methods in a uniform interface
- N-d
- Fast
An aside: “Concepts” in ITK

- One of the ways the Doxygen documentation is organized is by concepts
- This helps sort classes by similar functionality (concepts) even if they don’t share base classes
- Iterators are one of the concepts you can look up

Image region iterators

- The simplest type of iterator lets you traverse an image region
- The class is ` itk::ImageRegionIterator` — it requires an image pointer, and a region of the image to traverse
Creating the iterator

First, we assume we have or can get an image

```cpp
ImageType::Pointer im = GetAnImageSomeHow();
```

Next, create the iterator

```cpp
typedef itk::ImageRegionIterator<ImageType> ItType;
ItType it( im, im->GetRequestedRegion() );
```

note that each iterator is attached to a specific image

Finally, move the iterator to the start of the image

```cpp
it.GoToBegin();
```

Using the iterator

Loop until we reach the end of the image, and set all of the pixels to 10

```cpp
while( !it.IsAtEnd() )
{
    it.Set( 10 );
    ++it;
}
```
More compact notation

We can skip the explicit “move to beginning” stage and write the following:

```cpp
for (it = it.Begin(); !it.IsAtEnd(); ++it)
{
    it.Set( 10 );
}
```

Image regions

We initialized the iterator with:

```cpp
ItType it( im, im->GetRequestedRegion() );
```

Note that the region can be anything - pick your favorite image region (using the requested region is common in filters).
Other iterator tricks

- Access the pixel with Get()
- Figure out the Index of the pixel with GetIndex()
- Get a reference to a pixel with Value()
  - Value() is somewhat faster than Get()

Iterator tricks, cont.

- Moving forwards and backwards
  - Increment with ++
  - Decrement with --
- Beginning/ending navigation:
  - GoToBegin()
  - GoToEnd()
  - IsAtBegin()
  - IsAtEnd()
**Const vs. non-const iterators**

- You will notice that most iterators have both `const` and non-`const` versions.
- `Const` iterators do not allow you to set pixel values (much like `const` functions don’t allow you to change class member values).
- In general, the non-`const` versions of each iterator derive from the `const`.

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**Const vs. non-const, cont.**

- Good programming technique is to enforce `const` access when you don’t intend to change data.
- Moreover, input images in ITK filters are `const`, so you can’t traverse them using non-`const` iterators.
- Why? It’s very important to not accidentally modify the input to a filter!
Problems with iterating regions

- It’s not easy to know “who” your neighbors are, which is often important
- You don’t have much control over how the iteration proceeds (why?)
- Fortunately, there are solutions to both of these problems... stay tuned