# **A**PPENDIX

#### A.1 MMH: Max-margin Harmonium

For the special max-margin Harmonium (MMH), the learning problem is the same as defined in Section 4.1.1, and only several changes are needed to estimate parameters based on the general learning procedure. In this section, we present the necessary changes for learning MMH. For any other special cases of multi-view Markov networks, the learning can be similarly done.

With the definitions of local conditionals in Section 3.1, we can directly write the joint model distribution  $p(\mathbf{x}, \mathbf{z}, \mathbf{h})$  based on the constructive definition and the marginal data likelihood  $p(\mathbf{x}, \mathbf{z})$ 

$$p(\mathbf{x}, \mathbf{z}) \propto \exp\left\{ \alpha^{\top} \mathbf{x} + \beta^{\top} \mathbf{z} - \frac{1}{2} \sum_{j} \frac{z_{j}^{2}}{\sigma_{j}^{2}} + \frac{1}{2} \sum_{k} (\mathbf{x}^{\top} \mathbf{W}_{\cdot k} + \mathbf{z}^{\top} \mathbf{U}_{\cdot k})^{2} \right\}.$$

Then, we use the contrastive divergence method and introduce two variational distribution  $q_0$  and  $q_1$ . In this case, we can make a superficially simpler mean field assumption that  $q(\mathbf{x}, \mathbf{z}, \mathbf{h}) = \prod_i q(x_i) \prod_j q(z_j) \prod_k q(h_k)$ . Indeed, the general structured mean field assumption as made in Section 4.1.2 will lead to the same results, that is, a fully factorized form of  $q(\mathbf{x})$ ,  $q(\mathbf{z})$  and  $q(\mathbf{h})$ . Specifically, we have the following fully factorized update rules for posterior inference of q

$$q(\mathbf{x}) = \prod_{i} q(x_{i}) = \prod_{i} p(x_{i} | \mathbb{E}_{q(\mathbf{h})}[\mathbf{h}])$$

$$q(\mathbf{z}) = \prod_{j} q(z_{j}) = \prod_{j} p(z_{j} | \mathbb{E}_{q(\mathbf{h})}[\mathbf{h}])$$

$$q(\mathbf{h}) = \prod_{k} q(h_{k}) = \prod_{k} p(h_{k} | \mathbb{E}_{q(\mathbf{x})}[\mathbf{x}], \mathbb{E}_{q(\mathbf{z})}[\mathbf{z}])$$

Similarly,  $(x_i, z_j)$  are clamped at their observed values for  $q_0$ , and only  $q(h_k)$  is updated. The distribution  $q_1$ is achieved by performing the above updates starting from  $q_0$ . Several iterations can yield a good  $q_1$ . After we have inferred  $q_0$  and  $q_1$ , parameter estimation can be done by an alternating procedure as in Section 4.1.2, where the step of estimating **V** with  $\Theta$  fixed is to learn a multi-class SVM

$$\min_{\mathbf{V}} \quad \frac{1}{2}C_1 \|\mathbf{V}\|_2^2 + C_2 \sum_d \max_y [\Delta \ell_d(y) - \mathbf{V}^\top \mathbb{E}_{p(\mathbf{h}|\mathbf{x}_d, \mathbf{z}_d)} [\Delta \mathbf{f}_d(y)]].$$

Note that in this case, the latent representation (i.e., expectation of **H**) is simply written as  $\mathbb{E}_{p(\mathbf{h}|\mathbf{x},\mathbf{z})}[\mathbf{h}] = \Upsilon$ , where  $\Upsilon_k = \mathbf{x}^\top \mathbf{W}_{\cdot k} + \mathbf{z}^\top \mathbf{U}_{\cdot k}, \forall 1 \leq k \leq K$ , when input data **x** and **z** are fully observed. If missing values exist in **x** or **z**, the corresponding components are replaced with their expected values. Therefore, the prediction tasks (e.g., classification and retrieval) can be easily done in testing, as detailed in Section 4.4.

For the step of estimating  $\Theta$ , the sub-gradient is computed as

$$\begin{aligned} \partial \alpha_{i} &= -\mathbb{E}_{q_{0}}[x_{i}] + \mathbb{E}_{q_{1}}[x_{i}], \\ \partial \beta_{j} &= -\mathbb{E}_{q_{0}}[z_{j}] + \mathbb{E}_{q_{1}}[z_{j}], \\ \partial(\sigma_{j}^{-1}) &= -\mathbb{E}_{q_{0}}[z_{j}^{2}\sigma_{j}^{-1}] + \mathbb{E}_{q_{1}}[z_{j}^{2}\sigma_{j}^{-1}], \\ \partial \mathbf{W}_{ik} &= -\mathbb{E}_{q_{0}}[x_{i}h_{k}'] + \mathbb{E}_{q_{1}}[x_{i}h_{k}'] - C_{2}\sum_{d} (\mathbf{V}_{y_{d}k} - \mathbf{V}_{\bar{y}_{d}k})\mathbb{E}_{q_{0}}[x_{i}] \\ \partial \mathbf{U}_{jk} &= -\mathbb{E}_{q_{0}}[z_{j}h_{k}'] + \mathbb{E}_{q_{1}}[z_{j}h_{k}'] - C_{2}\sum_{d} (\mathbf{V}_{y_{d}k} - \mathbf{V}_{\bar{y}_{d}k})\mathbb{E}_{q_{0}}[z_{j}], \end{aligned}$$

where  $h'_k = \mathbf{x}^\top \mathbf{W}_{\cdot k} + \mathbf{z}^\top \mathbf{U}_{\cdot k}$  and  $\bar{y}_d = \arg \max_y [\Delta \ell_d(y) + \mathbf{V}^\top \mathbb{E}_{q_0}[\mathbf{f}(y, \mathbf{h}_d)]$  is the *loss-augmented prediction*. Based on the definition of  $q_0$ , the expectations  $\mathbb{E}_{q_0}[x_i]$  and  $\mathbb{E}_{q_0}[z_j]$  are actually the count frequency of  $x_i$  and  $z_j$ , respectively.

## A.2 Multi-view Latent Subspace MN for Modeling Paragraph Ordering Information

In this section, we formally define the structured multiview latent subspace Markov network used in Section 5.4. Let x be an  $P \times N$  observation matrix, where P is the number of paragraphs in a document and N is the vocabulary size. Each row  $\mathbf{x}_p$  is a vector, of which the element  $x_{pi} = 1$  if word *i* appears in paragraph p; otherwise  $x_{pi} = 0$ . Each column  $\mathbf{x}_{i}$  represents the appearance pattern of word i in all paragraphs. To consider the paragraph ordering information, we define a first-order Markov chain on each  $\mathbf{x}_{i}$  while assuming that different  $\mathbf{x}_{.i}$ 's are conditional independent. More formally, we define the factorial conditional distribution  $p(\mathbf{x}|\mathbf{h}) = \prod_{i=1}^{N} p(\mathbf{x}_{i}|\mathbf{h})$ , where each  $p(\mathbf{x}_{i}|\mathbf{h})$  is a linear chain CRF [27]. This model is actually an N-view latent subspace MN, where the ith view has P variables  ${X_{pi}}_{p=1}^{P}$  that are connected via a linear chain.

By the constructive definition as discussed in Section 3 (please see Eq. (1) and Eq. (2)), we need to specify the edge set for each view and define the feature functions. Specifically, let *E* denote the set of generalized edges (including both singleton vertices and pairwise edges) of a linear chain on each view<sup>13</sup>, then  $E = \{(1), \dots, (P), (1, 2), \dots, (P - 1, P)\}$ , where (*p*) is a degenerate edge (i.e., the node *p*). Accordingly, the feature functions  $\phi$  consists of a *singleton* feature function *g* that is defined on a single variable and 4 *pairwise* feature functions  $\phi_0, \phi_1, \phi_2$  and  $\phi_3$  that defined on a pair of variables. Mathematically, we define the singleton feature function as

$$g(x_{pi}) = x_{pi},$$

and we define the 4 pairwise feature functions as

$$\forall j = 0, \cdots, 3: \ \phi_j(x_{pi}, x_{p+1,i}) = \begin{cases} 1, \ \text{if } 2x_{pi} + x_{p+1,i} = j \\ 0, \ \text{otherwise} \end{cases}$$

We denote the corresponding weights by  $\alpha$  and  $\beta_j$ ,  $j = 0, \dots 3$ . To make the model reasonably rich, we assume

<sup>13.</sup> By definition, all views have the same set of edges

different views have different feature weights, while within each view, the weights of these feature functions are shared by all edges. For notation simplicity, we define  $g(\mathbf{x}_{.i}) \triangleq \sum_{p=1}^{P} g(x_{pi})$ , which is the accumulated function value of g evaluated on the sequence  $\mathbf{x}_{.i}$ , and  $\phi_j(\mathbf{x}_{.i}) \triangleq \sum_{p=1}^{P-1} \phi_j(x_{pi}, x_{p+1,i})$ , which is again an accumulated function value of  $\phi_j$ . Now, we define the interaction terms between  $\mathbf{X}$  and latent variables  $\mathbf{H}$  as

$$\sum_{i=1}^{N} (g(\mathbf{x}_{.i})\mathbf{U}^{i}\mathbf{h} + \sum_{j} \phi_{j}(\mathbf{x}_{.i})\mathbf{W}_{j}^{i}\mathbf{h}),$$

where  $\mathbf{W}_{j}^{i}$  and  $\mathbf{U}^{i}$  are *K*-dimensional real vectors. Finally, we include a quadratic energy term of the real variables **H** in the exponent of the joint distribution.

Putting the above definitions together, we define the joint distribution

$$\begin{split} p(\mathbf{x}, \mathbf{h}) \propto \exp \Big\{ \sum_{i} g(\mathbf{x}_{.i}) (\alpha^{i} + \mathbf{U}^{i} \mathbf{h}) \\ + \sum_{ij} \phi_{j}(\mathbf{x}_{.i}) (\beta_{j}^{i} + \mathbf{W}_{j}^{i} \mathbf{h}) - \frac{1}{2} \mathbf{h}^{\top} \mathbf{h} \Big\} \end{split}$$

and we have the conditional distributions as

$$p(\mathbf{x}_{.i}|\mathbf{h}) \propto \exp\left\{g(\mathbf{x}_{.i})(\alpha^{i} + \mathbf{U}^{i}\mathbf{h}) + \sum_{j} \phi_{j}(\mathbf{x}_{.i})(\beta_{j}^{i} + \mathbf{W}_{j}^{i}\mathbf{h})\right\}$$
$$p(h_{k}|\mathbf{X}) = \mathcal{N}(h_{k}|\sum_{i=1}^{N} (g(\mathbf{x}_{.i})\mathbf{U}_{k}^{i} + \sum_{j} \phi_{j}(\mathbf{x}_{.i})\mathbf{W}_{jk}^{i}), 1).$$

Now, we can follow the procedure in Section 4 to perform parameter estimation and inference. Sine each view is a linear-chain Markov network, we can perform inference with a forward-backward message passing scheme, which can be done in the same way as in [27]. We omit the details for brevity.

The message passing for each document is of a complexity  $O(N \times P \times S^2)$ , where *S* is the number of possible values for each variable  $X_{pi}$ . Since  $X_{pi}$  is binary, we have  $S^2 = 4$  (a very small constant). Moreover, the number of paragraphs *P* is on average very small, e.g., the average *P* is 9 in the hotel review dataset. Therefore, the time complexity is linear in terms of the feature dimension *N* (i.e., the number of terms in the given vocabulary).

### A.3 Additional Experimental Results

In this section, we present additional experimental results.

Fig. 11 shows the 5-bottom ranked (i.e., with small expectation values of  $H_k$ ) images for each of the 5 topics, as presented in Fig. 3. For convenience, we also include the average probability of each category distributed on the particular topic, which is the same as that in Fig. 3.

Fig. 12 shows the average value of  $\mathbb{E}[\mathbf{H}]$  discovered by a 60-topic MMH, together with the variance across the images from the 13 classes of animals. The variance of each  $\mathbb{E}[H_k]$  indicates the discriminative power of topic k over all the 13-class images.

Table 2 shows the complete table which contains the average distributions over topics for all the three methods, i.e., MMH, TWH, and DWH.

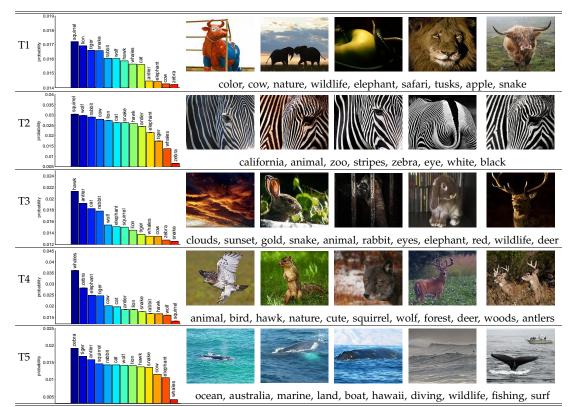


Fig. 11. Example topics discovered by the 60-topic MMH as in Fig. 3 on the Flickr animal dataset. For each topic, we show 5 bottom-ranked images as well as the average probabilities of that topic on representing images from the 13 categories.

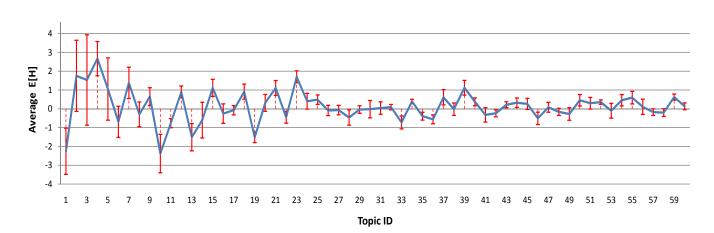


Fig. 12. Average value and variance of E[H] discovered by a 60-topic MMH across 13class-animal Flickr images.

#### Max Margin Harmonium (Avg-KL: 3.568) Average $\mathbb{E}_{p(\mathbf{h}|\mathbf{x},\mathbf{z})}[\mathbf{h}]$ in 5-level Rating Score examples T3 T4 T5 T1 T2 R 1 R 2 R 3 R 4 R 5 room great small worst worst 0.8 0.8 0.8 0.8 0.8 hotel loved worst small dirty 0.7 0.7 0.7 0.7 0.7 n't arrived dirty dirty small time enjoyed shower shower shower 0.6 0.6 0.6 0.6 0.6 broken stay fantastic broken broken smell day bit smell smell 0.5 0.5 0.5 0.5 0.5 wonderful Avg E[H] [H]3 0.4 Avg E[H] Avg E[H] Avg E[H] night paying paying paying 0.4 0.4 0.4 good lovely bathroom bathroom poor toilet staff pool poor poor 0.3 0.3 0.3 0.3 0.3 pool trip toilet toilet refund 0.2 0.2 0.2 0.2 0.2 staying refund back beach manager rooms fun refund staying bathroom 0.1 0.1 0.1 0.1 0.1 happy breakfast walls walls food area pools hotel hotel carpet n ۰L Λ ٦Ι 12345 12345 Topics 12345 12345 12345 walls carpet paid nice perfect Topics Topics Topics Topics Tri-Wing Harmonium (Avg-KL: 0.045) Average $\mathbb{E}_{p(\mathbf{h}|\mathbf{x},\mathbf{z})}[\mathbf{h}]$ in 5-level Rating Score examples T3 T4 T2 T5 T1 beach bathroom resort experience R 1 R 2 R 3 R 4 room parking beach breakfast hotel food 0. 0.9 0. n't pool tv ocean stay 0.8 0.8 0.8 0.8 0.8 great area service time trip 0.7 0.7 0.7 0.7 0.7 stay bar coffee vacation beautiful dav resort kitchen desk dinner 0.6 0.6 0. 0.6 0.6 night restaurants bed check guests [H] 0.5 H 0.5 H 0.5 표 0.5 표 0.5 drinks street time made 9000 ₿ <sub>0.4</sub> BA 0.4 - Bvg 0. 6 A 0.4 604 0.4 staff restaurant floor front wonderful view large great feel pool 0.3 0.3 0.3 0. 0.3 called back lunch small trip 0.2 0.2 0.2 0.2 0.2 good rooms tub call house 0.1 0. 0. 0.1 0.1 comfortable food sea property visit area beautiful location beautiful special 12345 12345 12345 2345 comfortable internet Topics Topics Topics Topics Topics nice walk people Dual-Wing Harmonium (Avg-KL: 0.038) Average $\mathbb{E}_{p(\mathbf{h}|\mathbf{x},\mathbf{z})}[\mathbf{h}]$ in 5-level Rating Score examples T2 T3 T4 T5 T1 beach food breakfast belize R R 3 R 4 P F room hotel told reception 0.9 0.9 food brett 0.9 0.9 0 asked bathroom n't pool cam 0.8 0.8 0.8 0.8 0.8 time holiday bed canapes resort 0.7 0.7 0.7 0. 0.7 great reception shower canoeing stay dav restaurants day holiday caracol 0.6 0.6 0.6 0.6 0.6 night bar bar coffee hosts H] 0.5 0.4 H] 0.5 [H]3 0.5 0.4 H]3 0.5 Avg E[H] 0.5 evening drinks staff nadege 900d 0.4 0.4 0.4 0.4 0.4 underway staff restaurant back small lunch manager clean wineries pool 0.3 0.3 0.3 0.3 0.3 back sea people bar adopted 0.2 0.2 0.2 0.2 0.2 evening rooms beautiful hotel amanda 0.1 0.1 0 ' 0. 0.1 food entertainment entertainment good aurora arrived main begun area pools Ω 0 12345 Topics 12345 Topics 12345 Topics 12345 Topics 1 2 3 4 5 Topics hotel nice view tea boasted

# TABLE 2

Average distributions over the topics for documents with different rating scores by a 5-topic MMH, 5-topic TWH and 5-topic DWH.