



## Setting

Goal: Draw samples  $\{\vec{x}^{(t)}\}_{t=1}^T$  from  $p(\vec{x})$

Assume:  $p(\vec{x}) = \frac{\tilde{p}(\vec{x})}{Z}$  — can compute

## Metropolis Alg.

- Choose a proposal  $q(\vec{x}|\vec{x}')$   
s.t.  $q(x, x') = q(x', x)$  (symmetric)
  - Choose initial state  $x^{(1)}$
  - For  $t = 1 \dots T$ :
    - Propose a new state  $x \sim q(x|x^{(t)})$
    - Accept  $x$  w/prob.  

$$q = A(x \leftarrow x^{(t)}) = \min\left(1, \frac{\tilde{p}(x)}{\tilde{p}(x^{(t)})}\right)$$
    - IF  $x$  is accepted:  $x^{(t+1)} = x$
    - Otherwise:  $x^{(t+1)} = x^{(t)}$
- $q > u \sim \text{Uniform}(0,1)$

## Metropolis - Hastings Alg.

- The proposal  $q$  need not be symmetric
- Identical to Metropolis alg., but accept w/prob.

$$A(x \leftarrow x^{(t)}) = \min\left(1, \frac{\tilde{p}(x) q(x^{(t)}|x)}{\tilde{p}(x^{(t)}) q(x|x^{(t)})}\right)$$

- M is a special of M-H w/  $q$  symmetric.

## Gibbs Sampling

- Instead, draw samples of one-dimension from "full conditionals"  
 $p(x_i | \{x_j\}_{j \neq i})$  and always accept.
- Let  $x^{(1)}$  be the initial state.

$$\boxed{|\vec{X}| = N}$$

$t = 1$

- while true:

for  $i = 1 \dots N$ :

$$\begin{aligned} \text{sample } x_i^{(t+1)} &\sim p(x_i | \{x_j^{(t)}\}_{j \neq i}) \\ \text{set } \vec{x}_{-i}^{(t+1)} &= \vec{x}_{-i}^{(t)} \\ \text{set } t &= t+1 \end{aligned}$$

## Gibbs as M-H

- Gibbs Sampling is just a special case of M-H

$$\begin{aligned} A(x \leftarrow x^{(t)}) &= \min \left( 1, \frac{\tilde{p}(x) q(x^{(t)} | x)}{p(x^{(t)}) q(x | x^{(t)})} \right) \\ &= \min \left( 1, \frac{p(x) p(x_i^{(t)} | \vec{x}_{-i})}{p(x^{(t)}) p(x_i | \vec{x}_{-i}^{(t)})} \right) \\ &= \min \left( 1, \frac{p(x_i | \vec{x}_{-i}) p(\vec{x}_{-i})}{p(x_i^{(t)} | \vec{x}_{-i}^{(t)}) p(\vec{x}_{-i}^{(t)})} \cdot \frac{p(x_i^{(t)} | \vec{x}_{-i})}{p(x_i | \vec{x}_{-i}^{(t)})} \right) \\ &\quad \boxed{X_{-i}^{(t)} = \vec{x}_{-i}^{(t)}} \\ &= \min(1, 1) \end{aligned}$$

## Markov Chains

Markov chain is a random process

↳ gives series of r.v.s  $\vec{x}^{(1)}, \dots, \vec{x}^{(T)}$

$$\begin{aligned} \bullet \text{ first-order MC: } & p(\vec{x}^{(t+1)} | \vec{x}^{(t)} \dots x^{(1)}) = p(\vec{x}^{(t+1)} | \vec{x}^{(t)}) \\ \bullet \text{ second-order MC: } & p(\dots) = p(\vec{x}^{(t+1)} | \vec{x}^{(t)}, \vec{x}^{(t-1)}) \end{aligned}$$

## Transition Probabilities

$$\text{Trans Probs: } p(x^{(t+1)} | x^{(t)}) = R_t(x_{t+1} \leftarrow x_t)$$

Homogeneous MC:  $R_t \triangleq R \Rightarrow$  the trans probs are the same for all  $t$

## Invariant Dist (Required Property #1)

Consider the marginal of  $x^{(t+1)}$

$$p(x^{(t+1)}) = \sum_{x^{(t)}} p(x^{(t+1)} | x^{(t)}) p(x^{(t)})$$

true by induction

We say  $p^*(x)$  is invariant (aka. stationary) w.r.t. the transition matrix (aka. our Markov chain)  $R$  if:

$$p^*(x) = \sum_{x'} R(x \leftarrow x') p^*(x')$$

OR

$$p^*(x) = \sum_x R(x \leftarrow x') p^*(x')$$

## Equilibrium Dist (Required Property #2)

Given an arbitrary initial dist  $p^{(0)}(x)$

Suppose  $p^*(x)$  is invariant w.r.t  $R$

$p^*(x)$  is the equilibrium distribution if

$$\lim_{t \rightarrow \infty} p^{(t)}(x) = p^*(x)$$

if it exists, there can only be one

(aka. the MC is ergodic)

## Sufficient Conditions

$R$  satisfies detailed balance if:

$$R(x' \leftarrow x) p^*(x) = R(x \leftarrow x') p^*(x')$$

and  $\Rightarrow p^*(x)$  is invariant w.r.t  $R$ .

IF  $p^*(x)$  is invariant w.r.t  $R$ , and

$$v = \min_{x, x'} \frac{R(x' \leftarrow x)}{p^*(x)} > 0$$

s.t.  $p^*(x') > 0$

then  $p^*$  is the equilibrium distribution for  $R$ .

## Transition Matrix for M-H

$$R(x \leftarrow x^{(t)}) = \underbrace{q(x|x^{(t)})} \cdot \min \left( 1, \underbrace{\frac{p(x)}{p(x^{(t)})} \frac{q(x^{(t)}|x)}{q(x|x^{(t)})}} \right)$$

Ex: Prove that M-H satisfies detailed balance.