

Reading:
Chapters 5&6 of Koller&Friedman

Variable elimination

Graphical Models – 10708

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Announcements



- Waiting List

- Anyone still wants to be registered?

Inference in BNs hopeless?



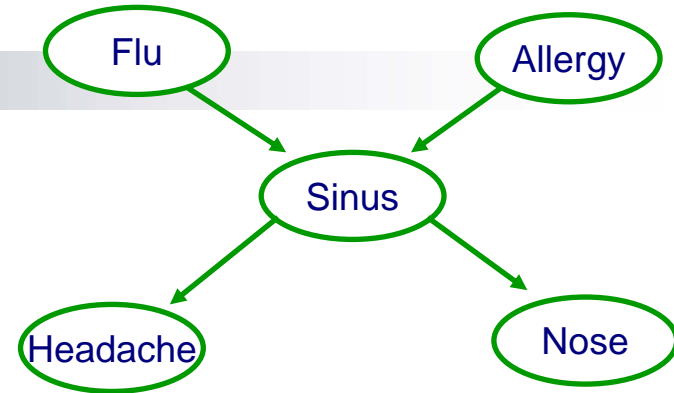
- In general, yes!
 - Even approximate!

- In practice
 - Exploit structure
 - Many effective approximation algorithms (some with guarantees)

- For now, we'll talk about exact inference
 - Approximate inference later this semester

General probabilistic inference

- Query: $P(X | e)$



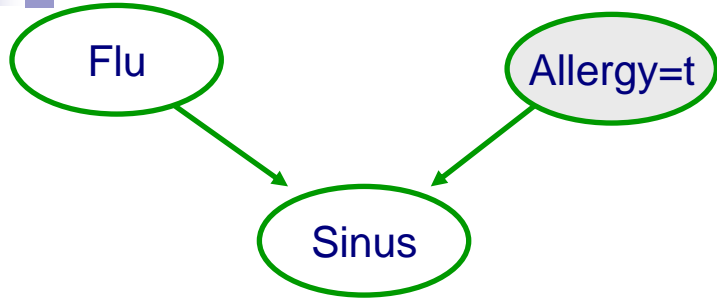
- Using def. of cond. prob.:

$$P(X | e) = \frac{P(X, e)}{P(e)}$$

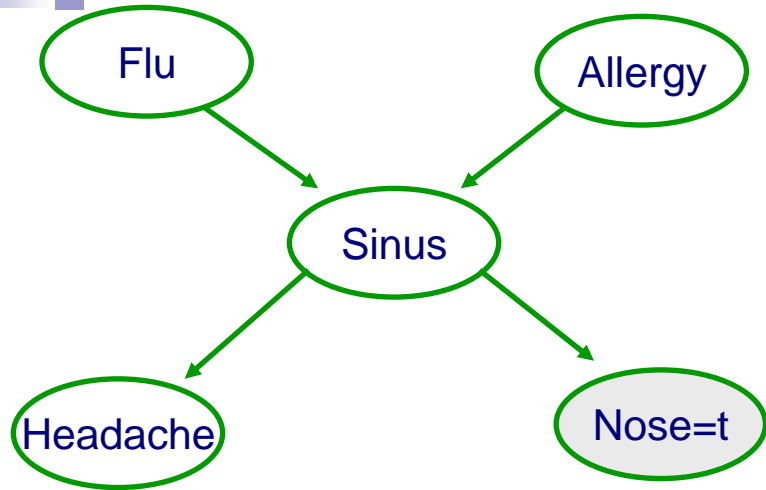
- Normalization:

$$P(X | e) \propto P(X, e)$$

Marginalization

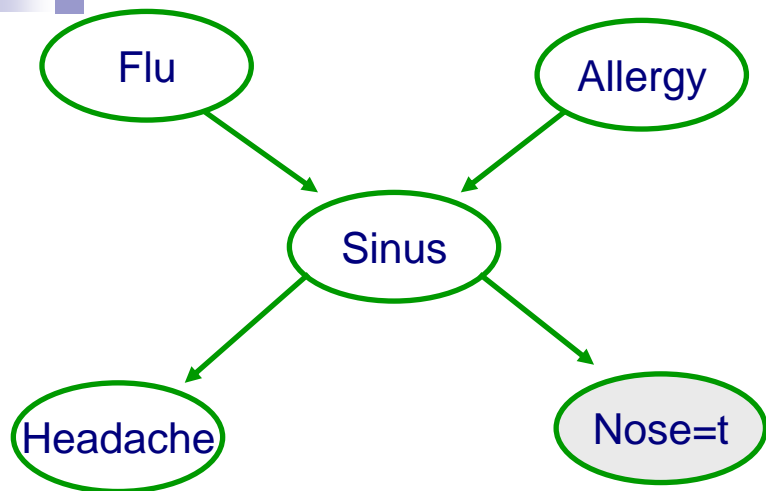


Probabilistic inference example



Inference seems exponential in number of variables!

Fast probabilistic inference example – Variable elimination

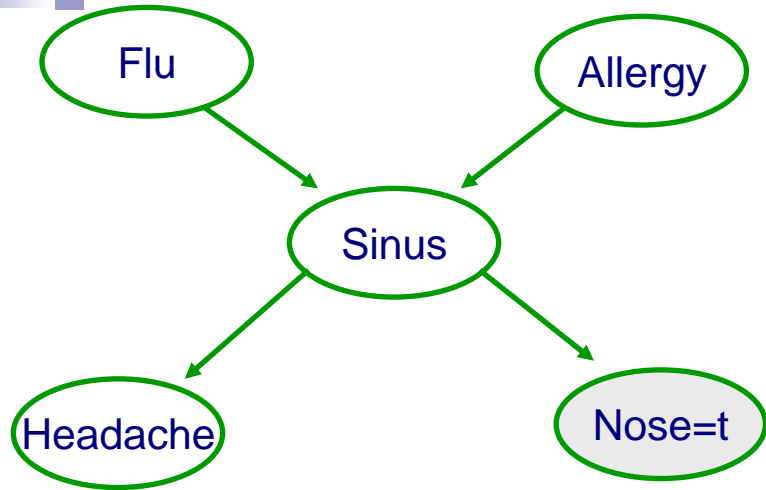


(Potential for) Exponential reduction in computation!

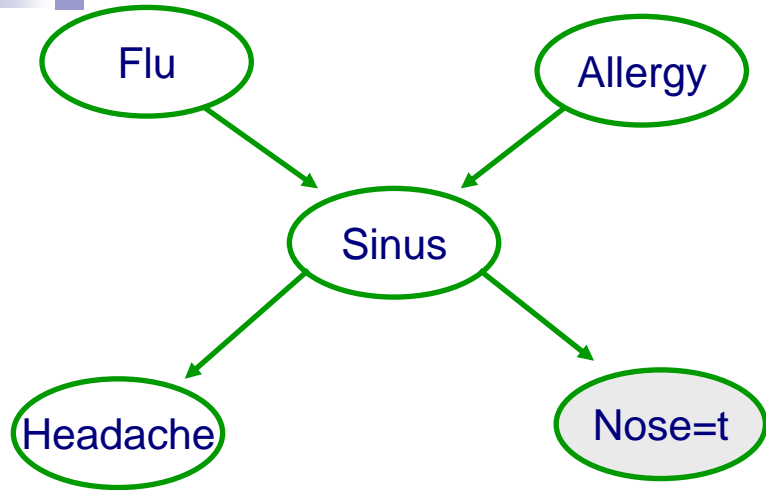
Understanding variable elimination – Exploiting distributivity



Understanding variable elimination – Order can make a HUGE difference

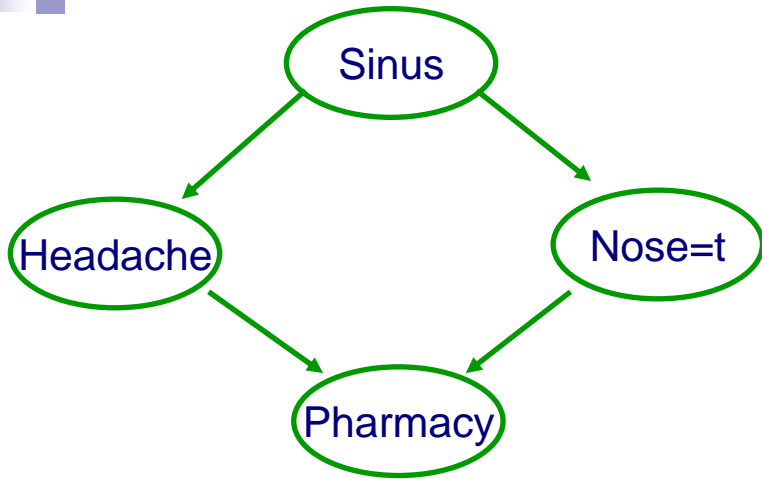


Understanding variable elimination – Intermediate results

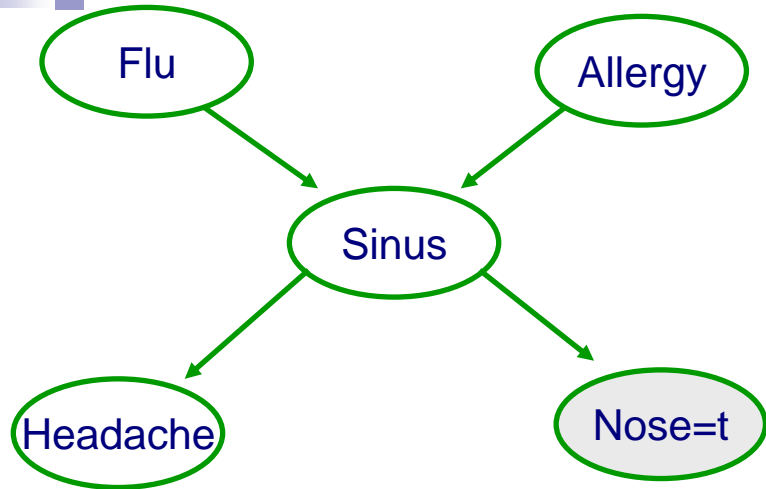


Intermediate results are probability distributions

Understanding variable elimination – Another example



Pruning irrelevant variables



Prune all non-ancestors of query variables
More generally: Prune all nodes not on active trail between evidence and query vars

Variable elimination algorithm

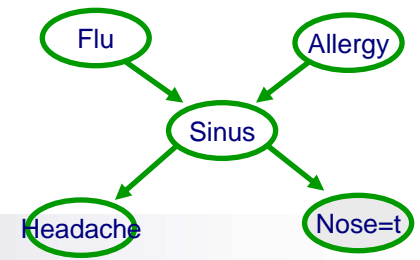
- Given a BN and a query $P(X|\mathbf{e}) \propto P(X,\mathbf{e})$
- Instantiate evidence \mathbf{e}
- Prune non-active vars for $\{X,\mathbf{e}\}$
- Choose an ordering on variables, e.g., X_1, \dots, X_n
- Initial *factors* $\{f_1, \dots, f_n\}$: $f_i = P(X_i | \mathbf{Pa}_{X_i})$ (CPT for X_i)
- For $i = 1$ to n , If $X_i \notin \{X, \mathbf{E}\}$
 - Collect factors f_1, \dots, f_k that include X_i
 - Generate a new factor by eliminating X_i from these factors

IMPORTANT!!!

$$g = \sum_{X_i} \prod_{j=1}^k f_j$$

- Variable X_i has been eliminated!
- Normalize $P(X,\mathbf{e})$ to obtain $P(X|\mathbf{e})$

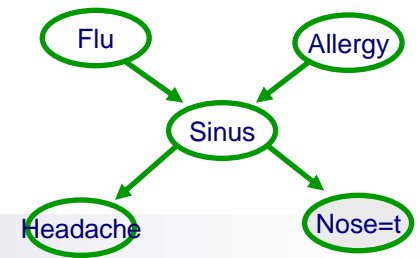
Operations on factors



$$g = \sum_{X_i} \prod_{j=1}^k f_j$$

Multiplication:

Operations on factors



$$g = \sum_{X_i} \prod_{j=1}^k f_j$$

Marginalization:

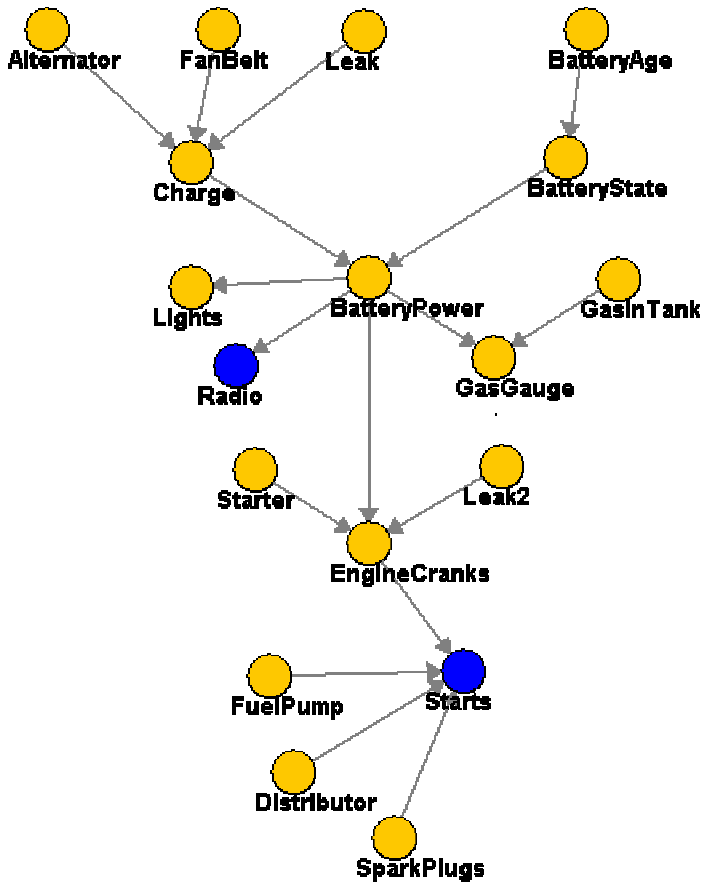
Complexity of VE – First analysis



- Number of multiplications:

- Number of additions:

Complexity of variable elimination – (Poly)-tree graphs



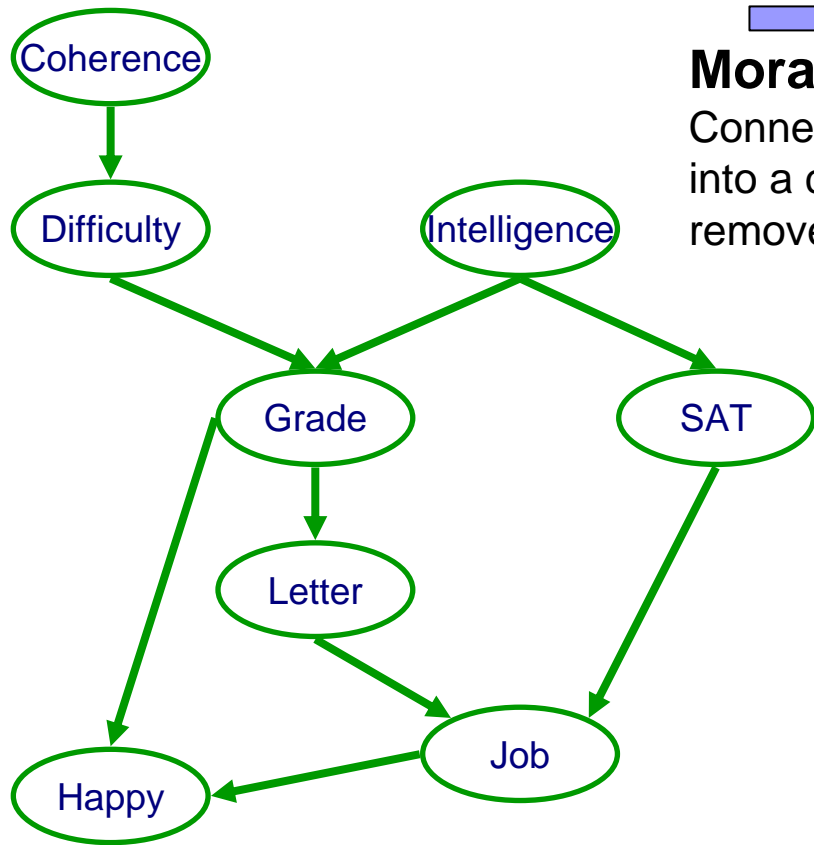
Variable elimination order:

Start from “leaves” inwards:

- Start from skeleton!
- Choose a “root”, any node
- Find topological order for root
- Eliminate variables in reverse order

Linear in CPT sizes!!! (versus exponential)

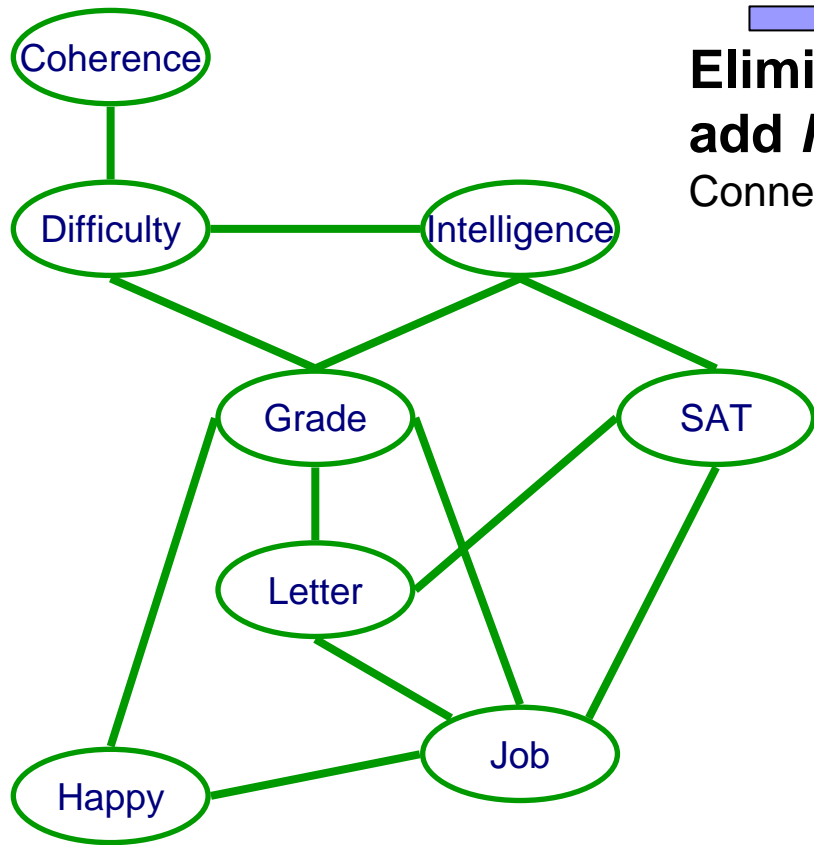
Complexity of variable elimination – Graphs with loops



➔
Moralize graph:
Connect parents
into a clique and
remove edge directions

Connect nodes that appear together in an initial factor

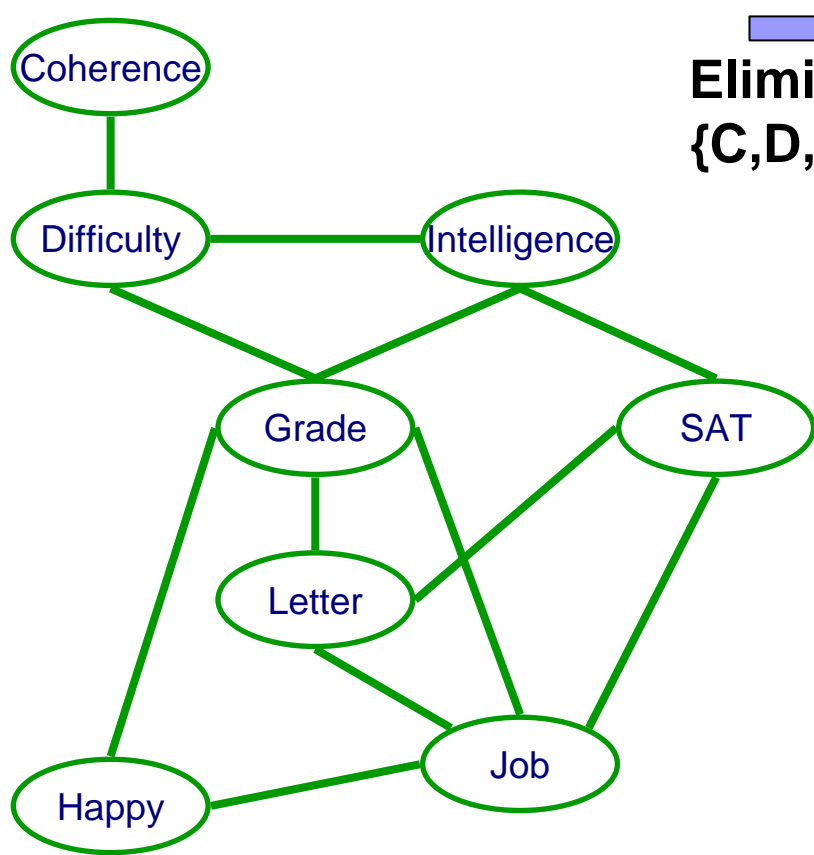
Eliminating a node – Fill edges



→
Eliminate variable
add *Fill Edges*:
Connect neighbors

Induced graph

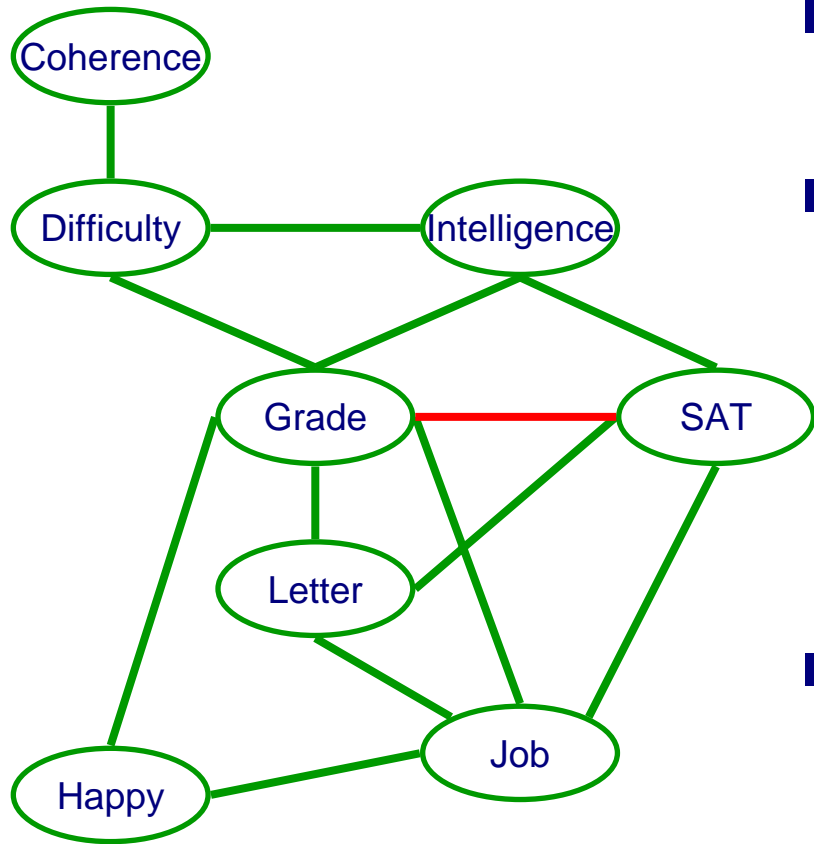
The **induced graph** $I_{F \prec}$ for elimination order \prec has an edge $X_i - X_j$ if X_i and X_j appear together in a factor generated by VE for elimination order \prec on factors F



→
Elimination order:
{C,D,S,I,L,H,J,G}

Induced graph and complexity of VE

Read complexity from cliques in induced graph



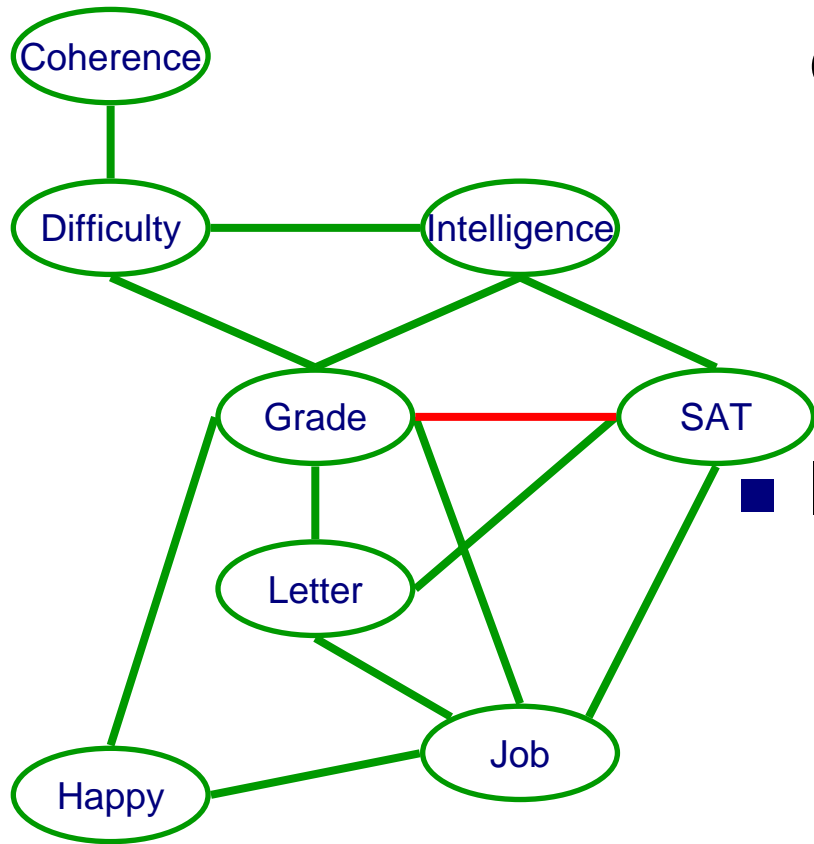
Elimination order:
{C,D,I,S,L,H,J,G}

- Structure of induced graph encodes complexity of VE!!!
- **Theorem:**
 - Every factor generated by VE subset of a maximal clique in $I_{F_{\prec}}$
 - For every maximal clique in $I_{F_{\prec}}$ corresponds to a factor generated by VE
- **Induced width** (or treewidth)
 - Size of largest clique in $I_{F_{\prec}}$ minus 1
 - *Minimal induced width* – induced width of best order \prec

Example: Large induced-width with small number of parents

Compact representation \nRightarrow Easy inference ☹️

Finding optimal elimination order



Elimination order:
{C,D,I,S,L,H,J,G}

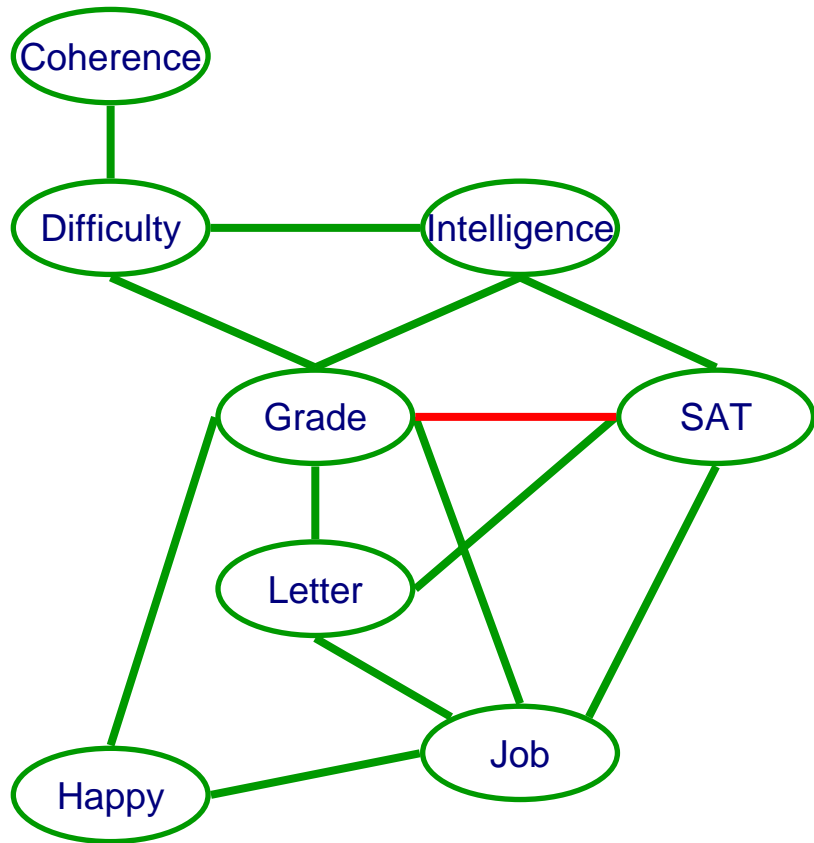
- **Theorem:** Finding best elimination order is NP-complete:

- Decision problem: Given a graph, determine if there exists an elimination order that achieves induced width $\leq K$

- **Interpretation:**

- Hardness of elimination order “orthogonal” to hardness of inference
- Actually, can find elimination order in time exponential in size of largest clique – same complexity as inference (next week)

Induced graphs and chordal graphs



■ Chordal graph:

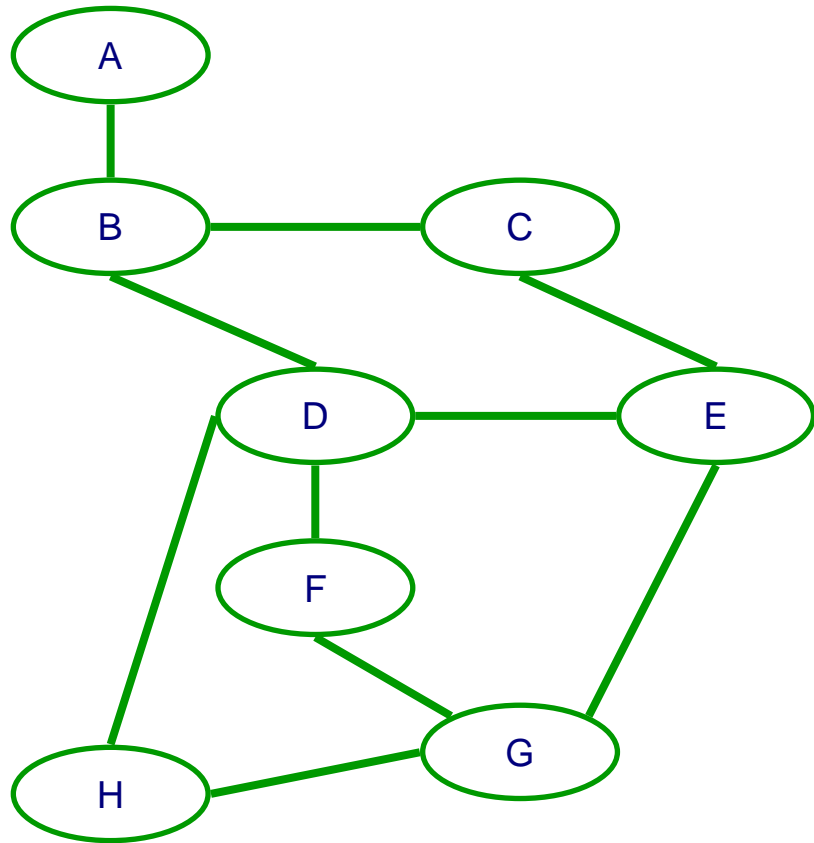
- Every cycle $X_1 - X_2 - \dots - X_k - X_1$ with $k \geq 3$ has a chord
- Edge $X_i - X_j$ for non-consecutive i & j

■ Theorem:

- Every induced graph is chordal

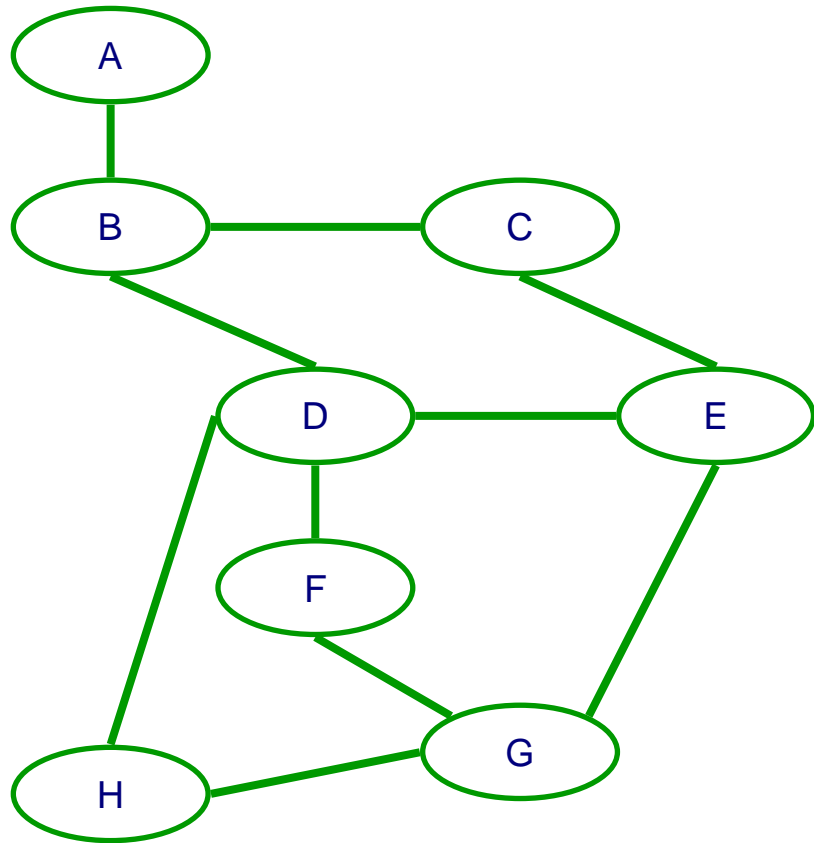
- “Optimal” elimination order easily obtained for chordal graph

Chordal graphs and triangulation



- **Triangulation:** turning graph into chordal graph
- **Max Cardinality Search:**
 - Simple heuristic
- Initialize unobserved nodes **X** as unmarked
- For $k = |\mathbf{X}|$ to 1
 - $X \leftarrow$ unmarked var with most marked neighbors
 - $\prec(X) \leftarrow k$
 - Mark X
- **Theorem:** Obtains optimal order for chordal graphs
- Often, not so good in other graphs!

Minimum fill/size/weight heuristics



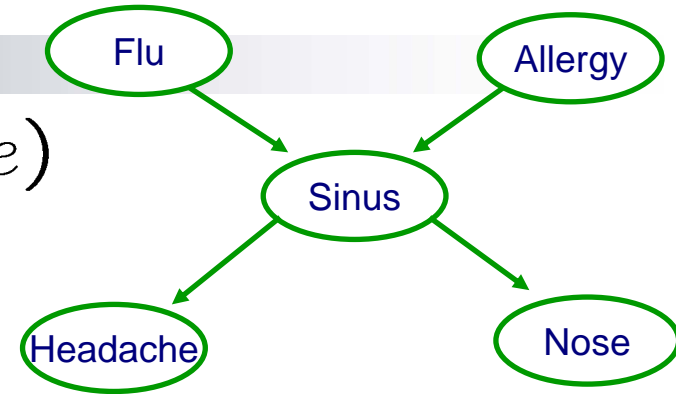
- Many more effective heuristics
 - page 262 of K&F
- **Min (weighted) fill heuristic**
 - Often very effective
- Initialize unobserved nodes **X** as unmarked
- For $k = 1$ to $|\mathbf{X}|$
 - $X \leftarrow$ unmarked var whose elimination adds fewest edges
 - $\prec(X) \leftarrow k$
 - Mark X
 - Add fill edges introduced by eliminating X
- Weighted version:
 - Consider size of factor rather than number of edges

Choosing an elimination order

- Choosing best order is NP-complete
 - Reduction from MAX-Clique
- Many good heuristics (some with guarantees)
- Ultimately, can't beat NP-hardness of inference
 - Even optimal order can lead to exponential variable elimination computation
- In practice
 - Variable elimination often very effective
 - Many (many many) approximate inference approaches available when variable elimination too expensive
 - Most approximate inference approaches build on ideas from variable elimination

Most likely explanation (MLE)

■ Query: $\operatorname{argmax}_{x_1, \dots, x_n} P(x_1, \dots, x_n \mid e)$



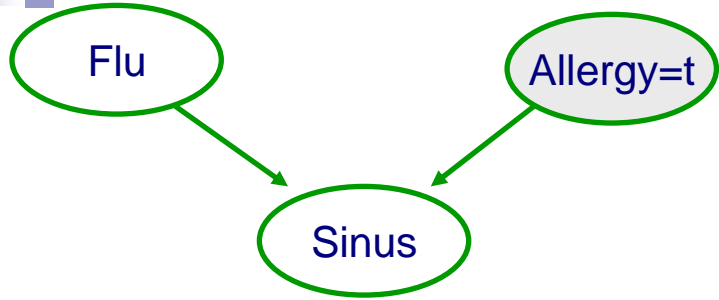
■ Using Bayes rule:

$$\operatorname{argmax}_{x_1, \dots, x_n} P(x_1, \dots, x_n \mid e) = \operatorname{argmax}_{x_1, \dots, x_n} \frac{P(x_1, \dots, x_n, e)}{P(e)}$$

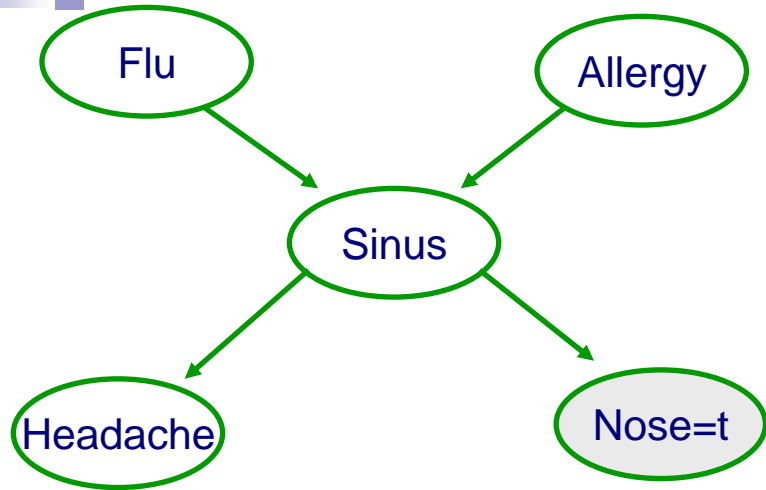
■ Normalization irrelevant:

$$\operatorname{argmax}_{x_1, \dots, x_n} P(x_1, \dots, x_n \mid e) = \operatorname{argmax}_{x_1, \dots, x_n} P(x_1, \dots, x_n, e)$$

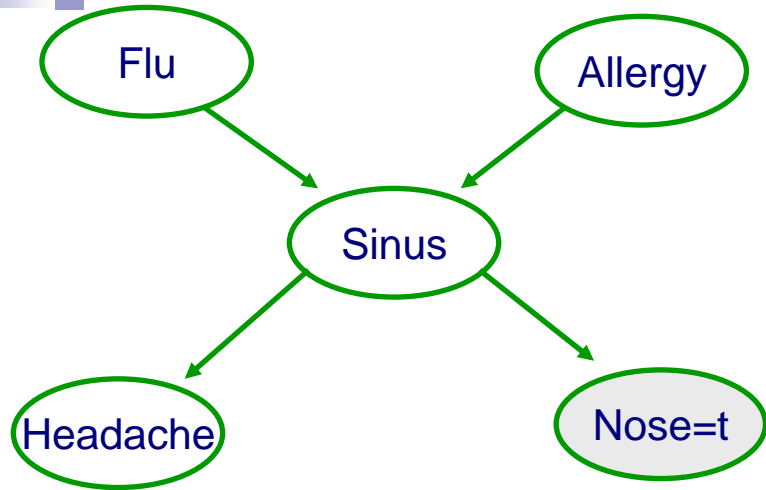
Max-marginalization



Example of variable elimination for MLE – Forward pass



Example of variable elimination for MLE – Backward pass



MLE Variable elimination algorithm

– Forward pass

- Given a BN and a MLE query $\max_{x_1, \dots, x_n} P(x_1, \dots, x_n, \mathbf{e})$
- Instantiate evidence $\mathbf{E}=\mathbf{e}$
- Choose an ordering on variables, e.g., X_1, \dots, X_n
- For $i = 1$ to n , If $X_i \notin \mathbf{E}$
 - Collect factors f_1, \dots, f_k that include X_i
 - Generate a new factor by eliminating X_i from these factors

$$g = \max_{x_i} \prod_{j=1}^k f_j$$

- Variable X_i has been eliminated!

MLE Variable elimination algorithm

– Backward pass

- $\{x_1^*, \dots, x_n^*\}$ will store maximizing assignment
- For $i = n$ to 1 , If $X_i \notin \mathbf{E}$
 - Take factors f_1, \dots, f_k used when X_i was eliminated
 - Instantiate f_1, \dots, f_k , with $\{x_{i+1}^*, \dots, x_n^*\}$
 - Now each f_j depends only on X_i
 - Generate maximizing assignment for X_i :

$$x_i^* \in \operatorname{argmax}_{x_i} \prod_{j=1}^k f_j$$

What you need to know

■ Variable elimination algorithm

□ Eliminate a variable:

- Combine factors that include this var into single factor
- Marginalize var from new factor

□ Cliques in induced graph correspond to factors generated by algorithm

□ Efficient algorithm (“only” exponential in induced-width, not number of variables)

- If you hear: “Exact inference only efficient in tree graphical models”
- You say: “No!!! Any graph with low induced width”
- And then you say: “And even some with very large induced-width” (next week)

■ Elimination order is important!

- NP-complete problem
- Many good heuristics

■ Variable elimination for MLE

- Only difference between probabilistic inference and MLE is “sum” versus “max”