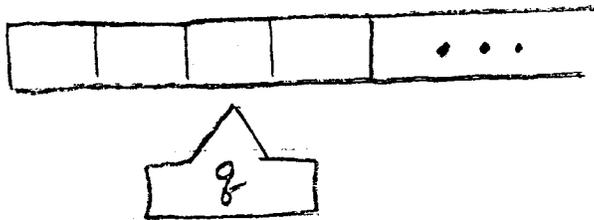


①

Different Turing Machine Models

1. One way infinite tape

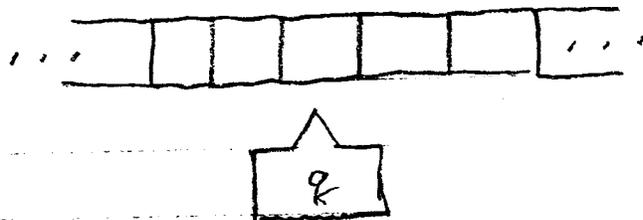


$M = (Q, X, q_0, F, \delta)$ as before.

No successor ID is defined

for $q x w$ when $\delta(q, x) = (q', x', L)$.

2. two way infinite tape



what we defined previously.

(2)

Theorem: L is recognized by a Turing machine with a two-way infinite tape if and only if it is recognized by a TM with a one way infinite tape.

proof sketch:

(\Leftarrow) clear

(\Rightarrow)

Basic idea: Let M_2 be the machine with the two-way infinite tape that recognizes L .

We will construct a TM M_1 with a one way infinite tape that recognizes L . M_1 will have two "tracks", one representing the

③

cells of M_2 's tape to the right of, and including, the tape cell initially scanned, the other representing (in reverse order) the cells to the left of the initial cell.

| | | | | | | | | |
|-----|----------|----------|----------|-------|-------|-------|-------|-----|
| ... | a_{-3} | a_{-1} | a_{-1} | a_0 | a_1 | a_2 | a_3 | ... |
|-----|----------|----------|----------|-------|-------|-------|-------|-----|

M_2 's tape

| | | | | |
|-------|----------|----------|----------|-----|
| a_0 | a_1 | a_2 | a_3 | ... |
| $\$$ | a_{-1} | a_{-2} | a_{-3} | ... |

M_1 's tape

M_1 is constructed to simulate M_2 so that when the read head of M_2 is to the right of its initial

(4)

position, M_1 uses its "upper track", and when the read head of M_2 is to the left of its initial position, M_1 works on its lower track and moves in the direction opposite to which M_2 moves.

If the initial tape of M_2 is

| | | | | | | | | |
|-----|---|---|---|-------|-------|-------|-------|-----|
| ... | B | B | B | a_0 | a_1 | a_2 | a_3 | ... |
|-----|---|---|---|-------|-------|-------|-------|-----|

then the initial tape of M_1

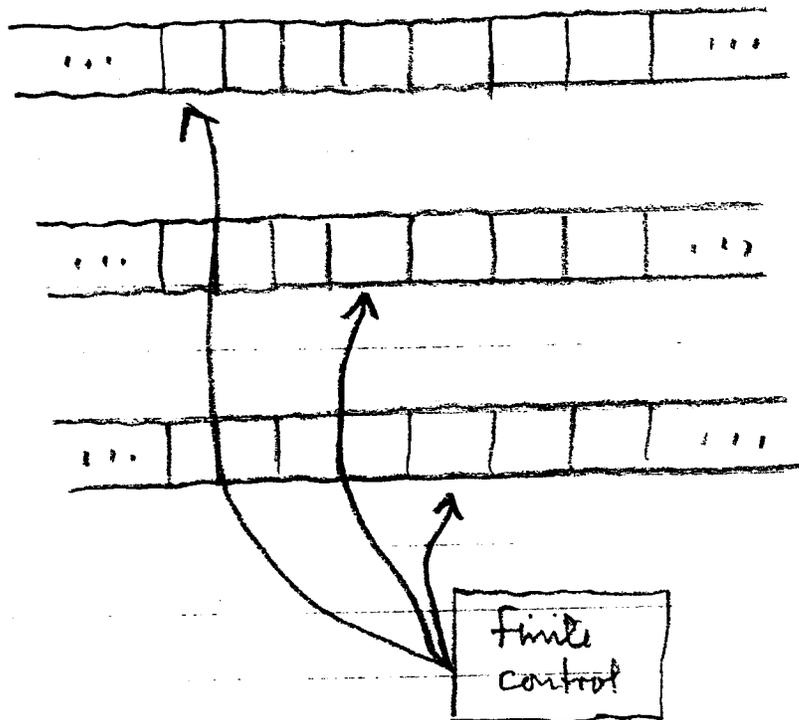
will be

| | | | | |
|-------|-------|-------|-------|-----|
| a_0 | a_1 | a_2 | a_3 | ... |
| \$ | B | B | B | ... |

(The details of the construction are given in your text).

(5)

3. Multi tape Turing Machines



On a single move, depending on the state of its finite control and the symbol scanned on each tape, the machine can

(1) change state

(2) print a new symbol on each of the cells scanned by its

(6)

tape heads, and

(3) move each of its tape heads, one all to the left or right or remain stationary.

Initially the input appears on the first tape and the other tapes are blank.

Theorem: If a language L is accepted by a multitape Turing machine, it is accepted by a single tape Turing machine

proof sketch: If L is accepted by a machine M_1 with K tapes, we will construct a one tape TM

(7)

M_2 with $2K$ tracks, two tracks for each of M_1 's tapes. One track records the contents of the corresponding track of M_1 ; the other records the position of the read head for that track.

| | | | | | |
|--------|-------|-------|-------|-------|-------|
| head 1 | | X | | | |
| tape 1 | a_1 | a_2 | a_3 | a_4 | a_5 |
| head 2 | | | | X | |
| tape 2 | b_1 | b_2 | b_3 | b_4 | b_5 |
| head 3 | X | | | | |
| tape 3 | c_1 | c_2 | c_3 | c_4 | c_5 |

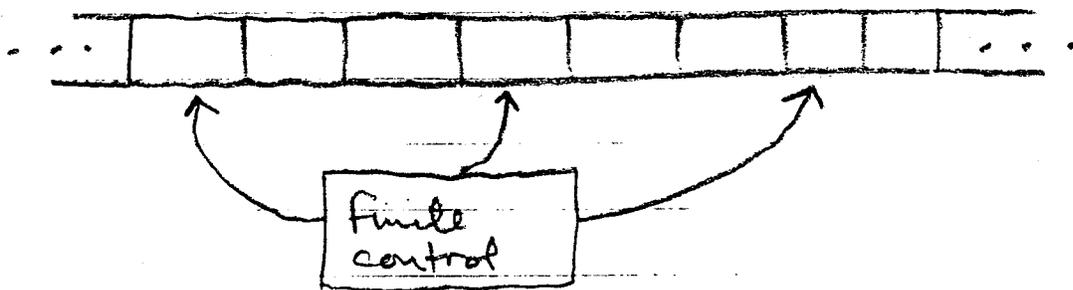
...

This configuration of M_2 's tape indicates that M_1 is scanning a_2 on tape 1, b_4 on tape 2, and c_1 on tape 3. The procedure that M_2 uses to simulate a move of M_1

(8)

is straight forward, but tedious to describe formally. (Again, See your text for details).

4. Multihed Turing Machines



A K -head Turing machine has some fixed number K of heads.

The heads are numbered 1 through

K . A move of the TM depends

on its current state and the

symbol scanned by each of the K

read heads. In one move, the heads

(9)

may move independently left, right, or remain stationary.

Theorem: If L is accepted by some k -head TM M_1 , it is accepted by a one head TM.

Proof ?

(5) Nondeterministic Turing Machines

Like basic one tape model, but

$$\delta: Q \times X' \rightarrow 2^{Q \times X' \times \{L, R, N\}}$$

Theorem: If L is accepted by a nondeterministic Turing Machine, then L is accepted by some

(10)

deterministic Turing machine.

Proof Sketch:

Assume that L is accepted by the nondeterministic Turing machine M_1 .

For any state and tape symbol of

M_1 , there are a finite number of

choices for the next move. Let r

be the maximum number of possible

choices for any state-symbol pair.

Note that with each halting

computation of M_1 , it is possible

to associate a string in $(1+2+\dots+r)^*$

that uniquely determines that computation.

(11)

The deterministic machine M_2 will have three tapes. The first holds the input. The second is used to enumerate strings in $(1+2+\dots+r)^*$. For each sequence generated on tape 2, M_2 will copy the input from tape 1 to tape 3 and use the sequence to determine the appropriate move of M_1 . If M_1 enters an accepting state then M_2 will also. If there is an accepting computation of M_1 , the sequence of moves in the computation will eventually be enumerated on tape 2 of M_2 .

12

Church's Thesis

Minsky: "Any process which could naturally be called an effective procedure can be realized by a Turing Machine."

Boalos + Jeffrey: "Any mechanical routine for symbol manipulation can be carried out in effect by some Turing machine".

Kleene: "every function which would naturally be regarded as computable is computable by a Turing Machine."

Hartmanis: " \exists an alg. $\Leftrightarrow \exists$ T.M."