

CNBC/IGERT
MATLAB Minicourse:
Lecture 2

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Set Your Working Directory

Make sure you have a directory called `W:\mystuff` and make that your current directory:

```
mkdir W:\mystuff
```

```
cd W:\mystuff
```

Scientific Functions

Trig: sin, cos, tan, asin, acos, atan,
sinh, cosh, tanh,
asinh, acosh, atanh

Rounding: floor, ceil, round, fix

Modular: rem, mod

Exponential: exp, log, log2, log10, sqrt

Primes: factor, primes

Matrix: det, inv, pinv, eig, svd, fft
and many more

Polynomials: roots, polyfit, polyval

Inf and NaN

$3/0$ returns Inf

$0/0$ returns NaN

$3+\text{Inf}$

Inf/Inf

$-\text{Inf}$

$-\text{NaN}$

Predicates

`isreal(3)`

`isprime(17)`

`isnumeric([2 3 5])`

`isempty([])`

`isinf(Inf)`

`isnan(NaN)`

`islogical(1==1)`

`ischar('a')`

`isequal('foo','aardvark')`

Return Values

Functions can return multiple values.

```
A = rand(5,3);
```

```
[rows,cols] = size(A)
```

Functions can return values or not, depending on whether the user is asking for values.

```
plot([1 2 3],[3 1 2])
```

```
h = plot([1 2 3],[3 1 2])
```

```
set(h,'LineStyle','--')
```

```
set(h,'LineWidth',8)
```

Variable No. of Arguments

Some functions take a variable number of arguments.

peaks

peaks(10)

hist(randn(2000,1))

hist(randn(2000,1), 50)

b = hist(randn(2000,1), 50)

[b,c] = hist(randn(2000,1), 50)

nargin and nargsout

Inside a function, **nargin** is the number of input arguments supplied with the call.

nargsout is the number of output arguments requested with the call.

```
function [x,y,z] = test(p,q,r,s,t)
    % inputs are ignored

    if nargsout >= 1
        x = 50;
    if nargsout >= 2
        y = 'foo';
    if nargsout >= 3
        z = 3:7;
    end
    end
end
whos
```


Name Spaces

Base workspace: variables created outside of any function exist in the base workspace.

Local workspaces: each function executes in a separate local workspace holding the arguments, return variables, and any local variables created by the function.

Functions cannot access variables of the base workspace.

Global workspace: variables declared global by a function are accessed in the global workspace. It's a good idea to also declare the variable global in the base workspace.

Global Variables

In the base workspace:

```
global pts  
pts = 0 : pi/20 : 2*pi;
```

Inside a function:

```
function h = circ(x,y)  
  
% h = CIRC(x,y) draw circle at (x,y)  
  
global pts  
hh = plot(x+cos(pts),y+sin(pts));  
  
if nargin > 0, h = hh; end
```

Scripts Called by Functions

Scripts do not have their own workspaces.

A script called from the keyboard executes in the base workspace.

A script called from within a function executes in the function's local workspace.

Resetting Variables

clear x removes variable x
 (and undoes global decl.)

You can also click on a variable in the workspace pane, and hit the Delete key.

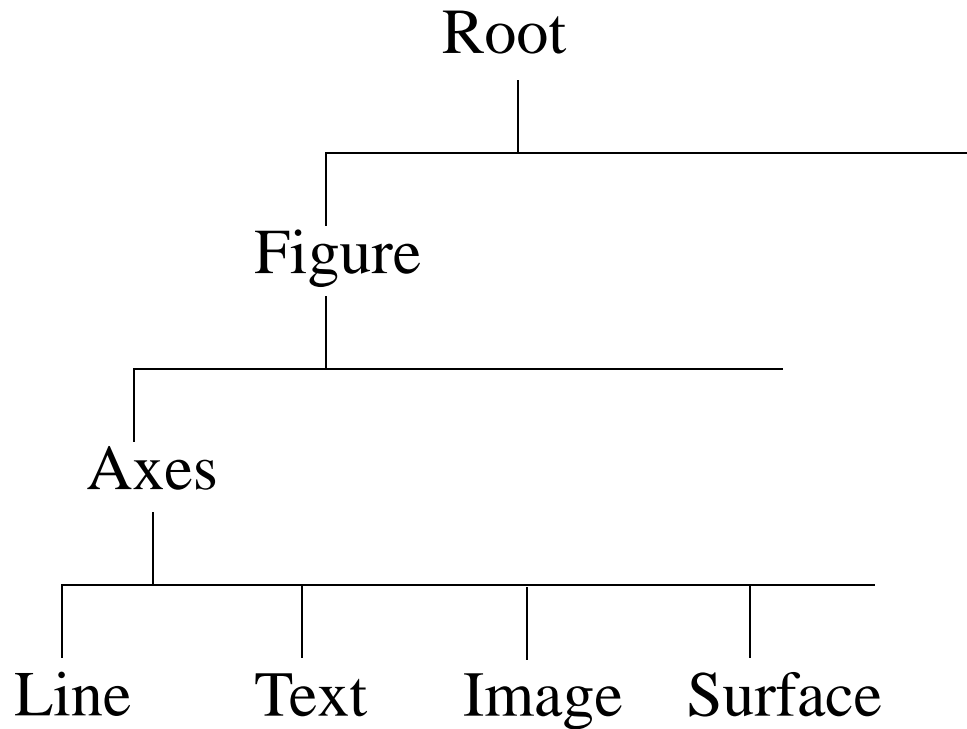
Or right-click on the variable and choose from the menu.

clear all clears everything

clear global clears global declarations

whos global show all global vars.

Handle Graphics



```
clf, plot(rand(5,3))
```

```
ax = get(gcf, 'Children')  
get(ax)
```

```
lines = get(ax, 'Children')  
get(lines(1))
```

Multiple Axes

```
clf
```

```
subplot(2,2,1)    % uses row-major order  
plot(rand(5,5))
```

```
subplot(2,2,2)  
bar3(rand(5,3))
```

```
subplot(2,2,3)  
a = rand(15,1);  
pie(a, a>0.7)
```

```
subplot(2,2,4)  
pts = 0:pi/20:2*pi;  
polar(pts,cos(2*pts))
```

```
set(gca,'Position',[0.32 0.1 0.4 0.4])
```

Exploring Graphic Objects

`propedit(gca)`

Matlab Help: (F1 or select Help pulldown)

Matlab Handle Graphics PropertyBrowser

`set(gca,'Units')`

3D Graphics

peaks

rotate3d on

or click on the rotation arrow in toolbar

set(gca,'CameraViewAngleMode','manual')

or right-click in the figure,

select Rotate Options, then

select Fixed Aspect Ratio Axes

[x,y,z] = peaks;

surf(x,y,z,z)

surf(x,y,z,x)

surf(x,y,z,rand(length(x)))

Plotting in 3D

Don't type all this in! Instead, download the file `helix.m` from:

`www.cs.cmu.edu/~dst/Tutorials/Matlab/helix.m`

and store it in your `W:\mystuff` directory

```
function helix
    pts = 0 : pi/20 : 4*pi;
    x1 = cos(pts); y1 = sin(pts);
    x2 = cos(pts+pi); y2 = sin(pts+pi);
    z = pts/(2*pi);

    clf, whitebg(gcf,[0 0 0])
    hold on
    plot3(x1,y1,z,'y')
    plot3(x2,y2,z,'w')

    axis([-3 3 -3 3 0 2])
    view(95,9)
```

helix (cont.)

```
colors = 'rgbm';

for i = 4 : 4 : length(pts)-4
    plot3([x1(i) x2(i)], [y1(i) y2(i)], z([i i]), ...
          colors(ceil(rand(1)*length(colors))), ...
          'LineWidth',3)
end

axis off
set(gcf,'Color','k')

set(gca,'CameraViewAngleMode','manual')

for az = -180:5:180
    view(az,9)
    drawnow
    pause(0.05)
end
```

Color Maps

clf

peaks

colorbar

m = colormap;

whos m

colormap(autumn)

brighten(0.5)

colormap(jet)

colormap(bone)

colormap(hot)

2D Data

```
[x,y] = meshgrid(-2 : 0.05 : 2);
```

```
z = sin(x) .* cos(y);
```

```
contour(z,20)
```

```
colormap(jet)
```

```
imagesc(z)
```

```
imagesc(x(:),y(:),z)
```

```
surf(z)
```

```
surfc(z)
```

Surface Objects

sphere

```
[x,y,z]=sphere(20);
```

```
x(1 : 5 : 21*21)=NaN;
```

```
surf(x,y,z)
```

*Use the rotate tool to rotate the sphere; set
Fixed Aspect Ratio Axes first.*

```
alpha(0.7)
```

```
surf(x,y,z,rand(21,21))
```

```
shading interp
```

Data From Files

Create a file temps.txt in Desktop*myuserid*:

38	50
42	53
33	57
45	56
44	46
41	40

```
load temps.txt
```

```
whos te*
```

```
plot(temps)
```

Importing Data from Files

You can import data from a variety of external file formats, including Excel, by using the Import Wizard:

- go to the File pulldown menu
- select Import
- select the file you want to import
- the wizard will guide you through the rest

There are also built-in functions specifically for dealing with Excel files:

`doc xlsread`

`doc xlswrite`

Polynomial Curve Fitting

```
load m:expt1.txt  
whos expt1
```

```
x = expt1(:, 1); y = expt1(:,2);
```

```
clf, hold on, plot(x,y,'o')
```

```
c = polyfit(x,y,3)
```

example polynomial representation:

$$c = [5 \ -1 \ 4 \ 3]$$

$$5x^3 - x^2 + 4x + 3$$

```
c(1:2)
```

```
pts = min(x) : max(x);  
plot(pts, polyval(c,pts), 'r')
```

```
doc polyfit
```


Saving Variables

```
clear all
```

```
a = 'aardvark'
```

```
[x,y,z] = sphere(5);
```

```
save stuff.mat
```

```
whos -file stuff.mat
```

```
save junk.dat x y -ascii
```

```
type junk.dat
```

General OS Stuff

pwd

cd

dir

ls *.m

delete stuff.mat

!dir

Debugging

Poor man's debugger:

Remove semicolons from assignments.

Add 'quoted strings' in appropriate places.

Add a call to **keyboard**. Use **return** to return from keyboard input mode.

```
function y = buggy(vec)
```

```
    p = vec > 5
```

```
    'got this far'
```

```
    keyboard
```

```
    z = p*vec
```

```
    v = sin(z);
```

MATLAB Debugger

dbtype helix

dbstop helix 3

helix

dbstep

dbstep 5

whos

dbstep 30

dbquit

dbclean helix

help debug

Formatted Output

```
for i = 1:10
    fprintf('The square-root of %2d is %f\n', ...
           i, sqrt(i))
end
```

```
doc fprintf
```

```
title(sprintf('f(x) over range %g to %g', ...
              -3.5, 5.125))
```