

02-713 Review

Midterm 1

* I took some images from Prof Kingsford's slides

- *Disclaimer:* I have not seen the midterm you will take.
- But we would like to recap some important points and try our best to answer questions you may have.

Anything is fair game, but ...

- I always like using slides as a starting point for what could be asked.
- See what theorems could be handy w/ each algorithm: they are useful tools in the design of algorithms.
- Branch out to the book for sup info.

For the test ...

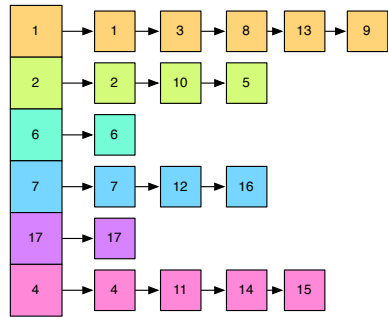
- On anything that's more open-ended, describe your primary strategy.
- Pseudocode is good for being more specific.

- Basic data structures
(Arrays, Lists, Trees, Graphs, Heaps, Union-Find)
- Analyze asymptotic run-time of an algorithm (Big Oh)
- 2 sorting algorithms
(HeapSort, MergeSort)
- 3 Optimal Algorithms for MST
(Prim's, Reverse-Delete, Kruskal's)
- 5 Algorithms based on Tree Growing
(Prim's, BFS, DFS, Dijkstra's, A*)
- Preview of dynamic programming
(Bellman-Ford)
- Intro to Divide and Conquer
(Counting Inversions, Closest Points)

Heaps

- Finding the minimum item takes constant time.
- Tree property: children are always greater in value than the parent.
- Insertion and deletion take $\log(n)$ time and preserve this property via “sift ups” and “sift downs”.
- Heapsort: Keep grabbing the minimum element from the top of the heap and delete it.

UF Items:



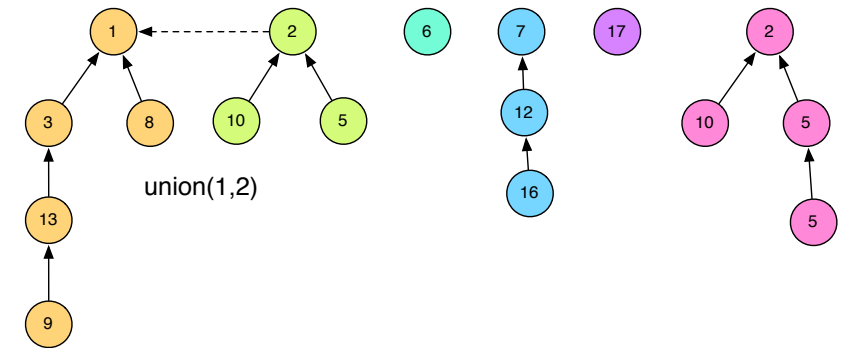
UF Sizes:

1	5
2	3
6	1
7	3
17	1
4	4

UF Sets Array:

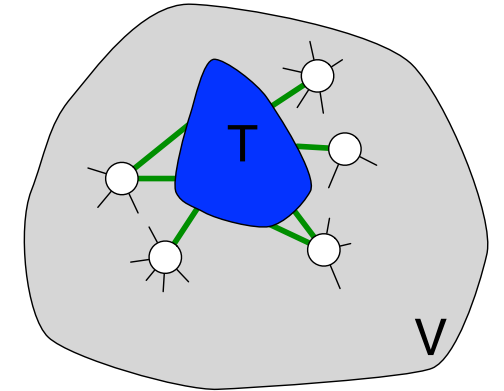
1	2	1	4	2	6	7	1	1	2	4	7	1	4	4	7	17
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17

Union-Find



- Given: a partition of a set
(collection of sets are disjoint)
- Goal: efficiently find which set an element belongs to and efficiently merge them together.
- During a union, updating the array that says which set an element is a member of can loop through entire array.
- However, k union operations is bounded by $k \log(k)$
(set sizes “double”)

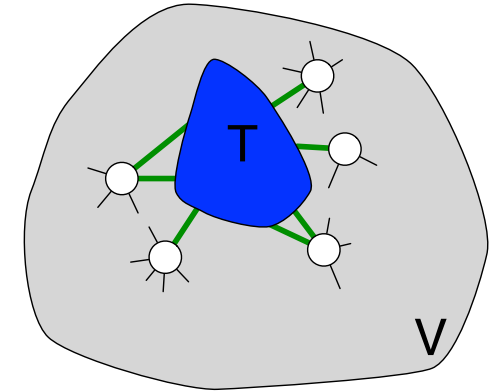
MST Key Points (1)



- Find the tree in a graph with the minimum total edge cost.
- **Prim's algorithm**: tree grow by adding the lowest cost edge to the tree.
- Cut property can be used to prove their correctnesses.

Theorem (MST Cut Property). *Let S be a subset of nodes, with $|S| \geq 1$ and $|S| < n$. **Every** MST contains the edge $e = \{v, w\}$ with $v \in S$ and $w \in V - S$ that has minimum weight.*

MST Key Points (2)



- **Reverse-Delete algorithm**: Remove edges and avoid disconnecting the graph.
- **Kruskal's algorithm**: Add edges avoiding cycles.
- Cycle property can be used to prove the correctness of both of these.

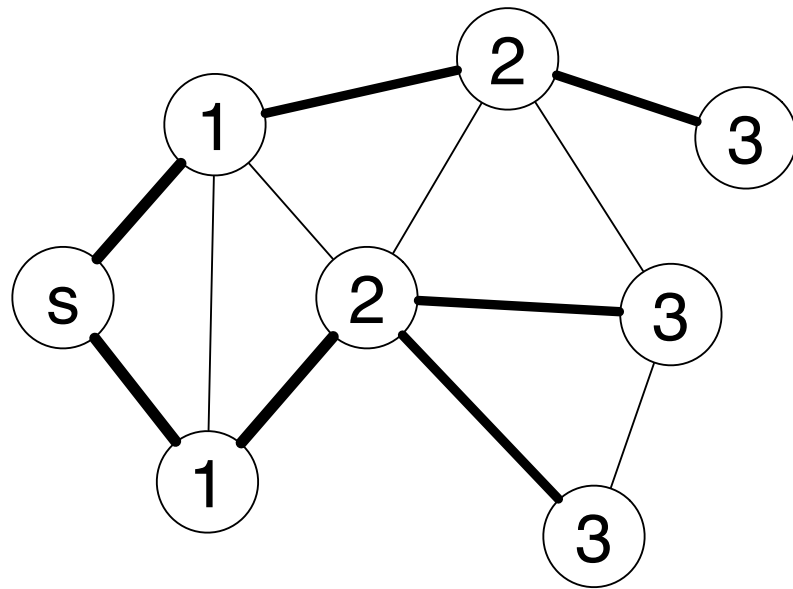
Theorem (Cycle Property). *Let C be a cycle in G . Let $e = (u, v)$ be the edge with maximum weight on C . Then e is **not** in **any** MST of G .*

Big Oh

- Big Oh used often in practice to describe runtime of algorithms
- Ideally find the “best” Oh (i.e. the *lowest* upper bound)
- When proving statements in asymptotic analysis, start with the definition and make sure you specify constants

Definition (O). A runtime $T(n)$ is $O(f(n))$ if there exist constants $n_0 \geq 0$ and $c > 0$ such that:

$$T(n) \leq cf(n) \quad \text{for all } n \geq n_0$$



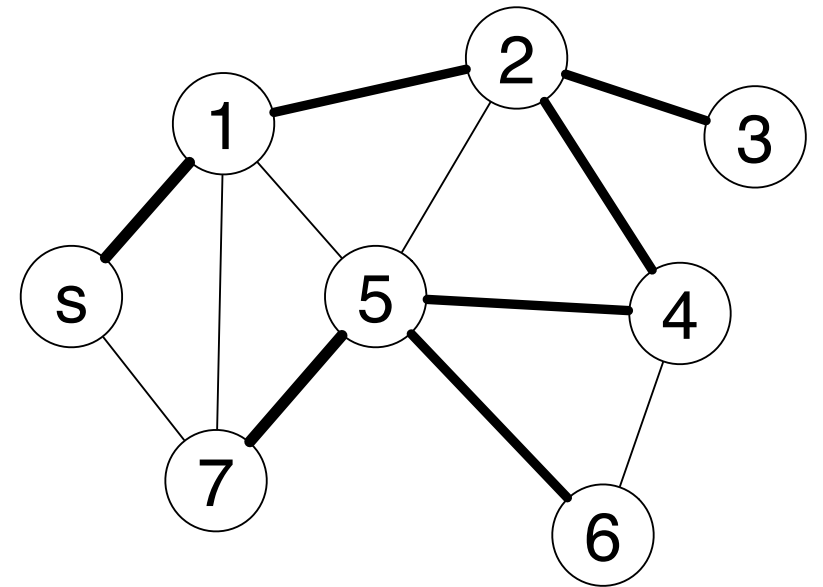
BFS

- Traverse the graph in 'layers'
- Add visited nodes to queue
(FIFO, TreeGrowing process *earliest* discovered node)

Non-tree edge property:

Theorem. Choose $x \in L_i$ and $y \in L_j$ such that $\{x, y\}$ is an edge in undirected graph G . Then i and j differ by at most 1.

DFS

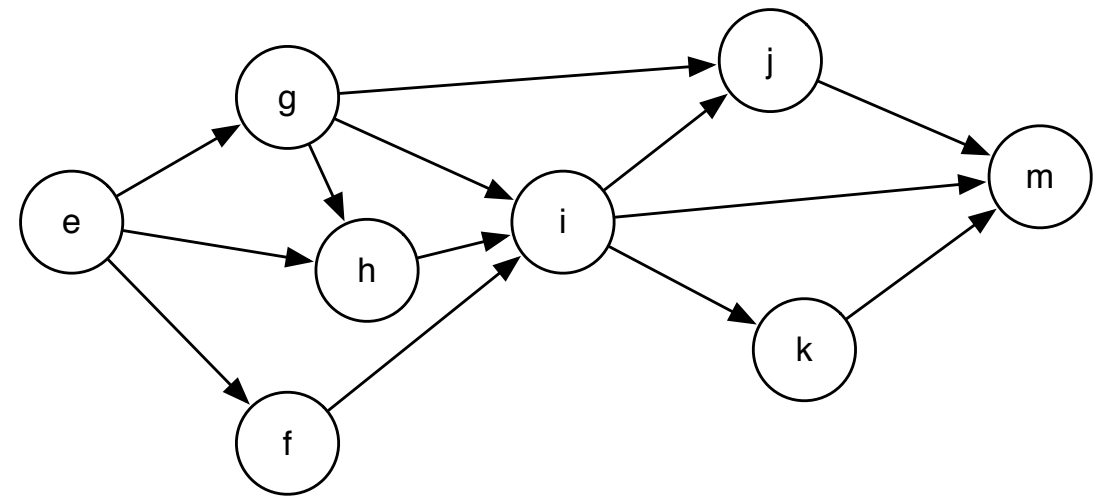


- Keep walking down a path until you are forced to backtrack.
- Add edges to a stack
(LIFO, TreeGrowing: process *most recently* discovered node)

Non-tree edge property:

Theorem. Let x and y be nodes in the DFS tree T_G such that $\{x, y\}$ is an edge in undirected graph G . Then one of x or y is an ancestor of the other in T_G .

DAG

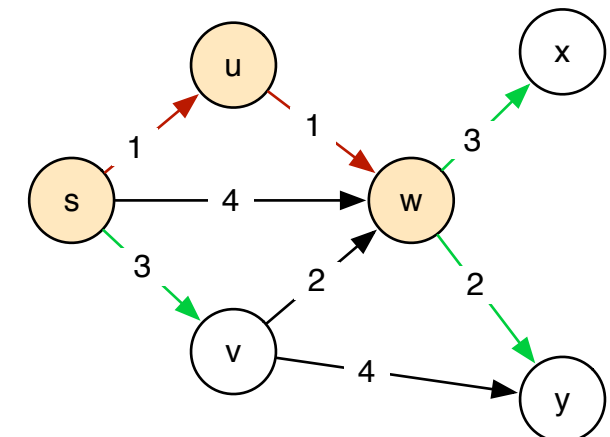
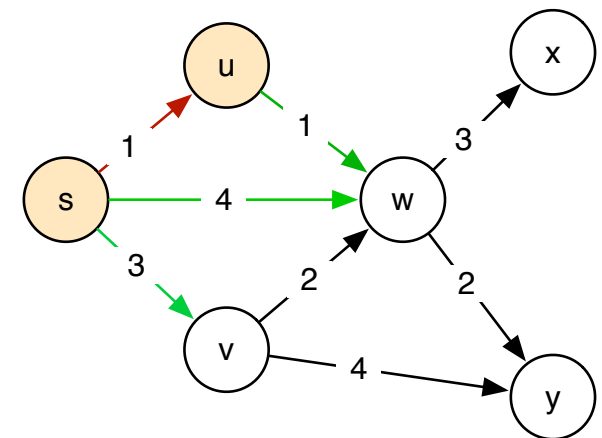


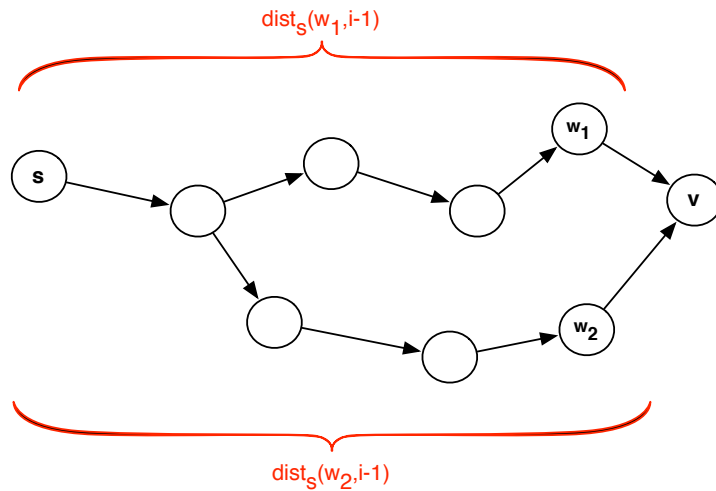
- Key property: Directed, no cycles!
- You can ‘topologically sort a DAG’ so that there are no ‘backwards’ edges.

Theorem. *Every DAG contains a vertex with no incoming edges.*

Dijkstra

- Tree Growing: instead of choosing min-weight edge like Prim's, choose the minimum of $d(u) + \text{length}(u,v)$
- Only positive weights





Bellman-Ford

- Handles negative weights
(assume no negative cycles)
- 1 pass applies the Ford rule to all edges
- Can make at most $n-1$ passes
- Not 'greedy' like Dijkstra's algorithm

Ford step. Find an edge (u, v) such that

$$\text{dist}_s(u) + d(u, v) \leq \text{dist}_s(v)$$

and set $\text{dist}_s(v) = \text{dist}_s(u) + d(u, v)$.



A^*

- Another Tree Growing, but with a goal node and a heuristic to help get us there
- Heuristic guarantees we will find optimal solution
- Heuristic *must* be less than true distance
- Ideally it is closer to the real distance

Divide and Conquer

- Try to divide into 'equal' parts to get $O(n \log n)$
- Assume the problem is solved for each part and the trick is to design an efficient merge step.
- Need a base case for the 'leaf' of the recursion tree.