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15-826: Multimedia Databases and Data Mining


Lecture #21: Tensor decompositions
C. Faloutsos

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Must-read Material

- Tamara G. Kolda and Brett W. Bader.
[Tensor decompositions and applications.](#)
Technical Report SAND2007-6702, Sandia
National Laboratories, Albuquerque, NM
and Livermore, CA, November 2007

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Outline

Goal: ‘Find **similar** / **interesting** things’

- Intro to DB
- ➡ Indexing - similarity search
- Data Mining


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Indexing - Detailed outline

- primary key indexing
- secondary key / multi-key indexing
- spatial access methods
- fractals
- text
- Singular Value Decomposition (SVD)
 - ...
- ➔ - Tensors
- multimedia
- ...

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Most of foils by

- Dr. Tamara Kolda (Sandia N.L.)

csmr.ca.sandia.gov/~tgkolda
- Dr. Jimeng Sun (CMU -> IBM)

www.cs.cmu.edu/~jimeng

3h tutorial: www.cs.cmu.edu/~christos/TALKS/SDM-tut-07/


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Outline

- Motivation - Definitions
- Tensor tools
- Case studies


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Motivation 0: Why “matrix”?

- Why matrices are important?


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Examples of Matrices: Graph - social network

	John	Peter	Mary	Nick	...
John	0	11	22	55	...
Peter	5	0	6	7	...
Mary
Nick
...


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Examples of Matrices: cloud of n-d points

	chol#	blood#	age
John	13	11	22	55	...
Peter	5	4	6	7	...
Mary
Nick
...

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Examples of Matrices:

Market basket

- market basket as in Association Rules

	milk	bread	choc.	wine	...
John	13	11	22	55	...
Peter	5	4	6	7	...
Mary
Nick
...

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Examples of Matrices:

Documents and terms

	data	mining	classif.	tree	...
Paper#1	13	11	22	55	...
Paper#2	5	4	6	7	...
Paper#3
Paper#4
...

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Examples of Matrices:

Authors and terms

	data	mining	classif.	tree	...
John	13	11	22	55	...
Peter	5	4	6	7	...
Mary
Nick
...

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Examples of Matrices: sensor-ids and time-ticks

	temp1	temp2	humid.	pressure	...
t1	13	11	22	55	...
t2	5	4	6	7	...
t3
t4
...

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Motivation: Why tensors?

- Q: what is a tensor?

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Motivation 2: Why tensor?

- A: N-D generalization of matrix:

KDD'07

	data	mining	classif.	tree	...
John	13	11	22	55	...
Peter	5	4	6	7	...
Mary
Nick
...

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Motivation 2: Why tensor?

- A: N-D generalization of matrix:

	data	mining	classif.	tree	...
John	13	11	22	55	...
Peter	5	4	6	7	...
Mary
Nick
...

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Tensors are useful for 3 or more modes

Terminology: 'mode' (or 'aspect'):

	data	mining	classif.	tree	...
13	11	22	55	...	
5	4	6	7	...	
...	
...	
...	

Mode (#== aspect) #1

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Motivating Applications

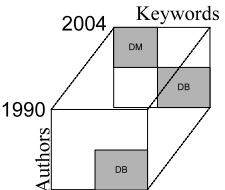
- Why matrices are important?
- Why tensors are useful?
 - P1: social networks
 - P2: web mining

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P1: Social network analysis

- Traditionally, people focus on static networks and find community structures
- We plan to monitor the change of the community structure over time



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P2: Web graph mining

- How to order the importance of web pages?
 - Kleinberg's algorithm HITS
 - PageRank
 - Tensor extension on HITS (**TOPHITS**)
 - context-sensitive hypergraph analysis

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Outline


- Motivation – Definitions
- Tensor tools**
- Case studies

- Tensor Basics
- Tucker
- PARAFAC

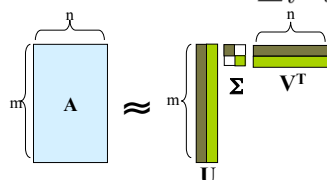
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Tensor Basics


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Reminder: SVD

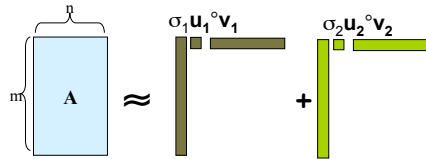
$$A \approx U \Sigma V^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i$$


– Best rank-k approximation in L2

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Reminder: SVD

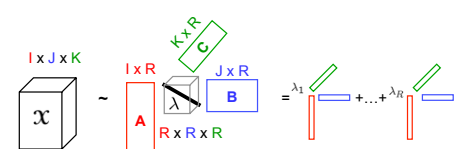
$$A \approx U \Sigma V^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i$$


– Best rank-k approximation in L2


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Goal: extension to ≥ 3 modes


$$\mathcal{X} \approx [\lambda; \mathbf{A}, \mathbf{B}, \mathbf{C}] = \sum_r \lambda_r \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r$$


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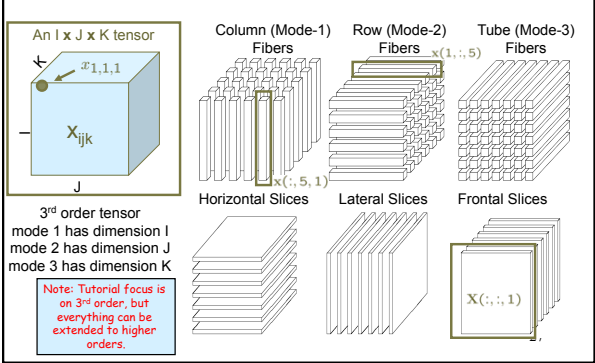
Main points:

- 2 major types of tensor decompositions: PARAFAC and Tucker
- both can be solved with “alternating least squares” (ALS)
- Details follow – we start with terminology:

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A tensor is a multidimensional array



An $I \times J \times K$ tensor

3rd order tensor
mode 1 has dimension I
mode 2 has dimension J
mode 3 has dimension K

Note: Tutorial focus is on 3rd order, but everything can be extended to higher orders.

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Matricization: Converting a Tensor to a Matrix

Matricize (unfolding)

Reverse Matricize

$\mathbf{X}_{(n)}$: The mode- n fibers are rearranged to be the columns of a matrix

$\mathbf{X} = \begin{bmatrix} 1 & 3 & 5 & 7 \\ 2 & 4 & 6 & 8 \end{bmatrix}$

$\mathbf{X}_{(1)} = \begin{bmatrix} 1 & 3 & 5 & 7 \\ 2 & 4 & 6 & 8 \end{bmatrix}$

$\mathbf{X}_{(2)} = \begin{bmatrix} 1 & 2 & 5 & 6 \\ 3 & 4 & 7 & 8 \end{bmatrix}$

$\mathbf{X}_{(3)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{bmatrix}$

Vectorization

$\text{vec}(\mathbf{X}) = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \end{bmatrix}$

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Tensor Mode-n Multiplication

$\mathbf{X} \in \mathbb{R}^{I \times J \times K}$, $\mathbf{B} \in \mathbb{R}^{M \times J}$, $\mathbf{a} \in \mathbb{R}^I$

- Tensor Times Matrix

$\mathbf{Y} = \mathbf{X} \times_2 \mathbf{B} \in \mathbb{R}^{I \times M \times K}$

$y_{imk} = \sum_j x_{ijk} b_{mj}$

$\mathbf{Y}_{(2)} = \mathbf{B} \mathbf{X}_{(2)}$

Multiply each row (mode-2) fiber by \mathbf{B}

- Tensor Times Vector

$\mathbf{Y} = \mathbf{X} \times_1 \mathbf{a} \in \mathbb{R}^{J \times K}$

$y_{jk} = \sum_i x_{ijk} a_i$

Compute the dot product of \mathbf{a} and each column (mode-1) fiber

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Pictorial View of Mode-n Matrix Multiplication

Mode-1 multiplication (frontal slices)

$\mathbf{Y} = \mathbf{X} \times_1 \mathbf{A}$

$\mathbf{Y}_{::k} = \mathbf{X}_{::k} \mathbf{A}^\top$

Mode-2 multiplication (lateral slices)

$\mathbf{Y} = \mathbf{X} \times_2 \mathbf{B}$


$\mathbf{Y}_{:j:} = \mathbf{X}_{:j:} \mathbf{B}^\top$

Mode-3 multiplication (horizontal slices)

$\mathbf{Y} = \mathbf{X} \times_3 \mathbf{C}$

$\mathbf{Y}_{i::} = \mathbf{X}_{i::} \mathbf{C}^\top$

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Mode-n product Example

- Tensor times a matrix

Location

Type

Time

\times_{Time}

Clusters

Time


$=$


Location

Type

Clusters

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Mode-n product Example

- Tensor times a vector

Location

Type

Time

\times_{Time}


Time


$=$

Location

Type

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Outer, Kronecker, & Khatri-Rao Products

3-Way Outer Product

$\mathcal{X} = \mathbf{a} \circ \mathbf{b} \circ \mathbf{c}$
 $x_{ijk} = a_i b_j c_k$

Rank-1 Tensor

Review: Matrix Kronecker Product

$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{11}\mathbf{B} & a_{12}\mathbf{B} & \cdots & a_{1N}\mathbf{B} \\ a_{21}\mathbf{B} & a_{22}\mathbf{B} & \cdots & a_{2N}\mathbf{B} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M1}\mathbf{B} & a_{M2}\mathbf{B} & \cdots & a_{MN}\mathbf{B} \end{bmatrix}$$

$$= \begin{bmatrix} \mathbf{a}_1 \otimes \mathbf{b}_1 & \mathbf{a}_1 \otimes \mathbf{b}_2 & \cdots & \mathbf{a}_N \otimes \mathbf{b}_Q \end{bmatrix}$$


Matrix Khatri-Rao Product

$$\mathbf{A} \odot \mathbf{B} = \begin{bmatrix} \mathbf{a}_1 \otimes \mathbf{b}_1 & \mathbf{a}_2 \otimes \mathbf{b}_2 & \cdots & \mathbf{a}_R \otimes \mathbf{b}_R \end{bmatrix}$$

Observe: For two vectors \mathbf{a} and \mathbf{b} , $\mathbf{a} \otimes \mathbf{b}$ and $\mathbf{a} \cdot \mathbf{b}$ have the same elements, but one is shaped into a matrix and the other into a vector.


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Specially Structured Tensors



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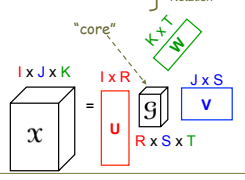
Specially Structured Tensors

Tucker Tensor

$$\mathcal{X} = \mathcal{G} \times_1 \mathbf{U} \times_2 \mathbf{V} \times_3 \mathbf{W}$$
$$= \sum_r \sum_s \sum_t g_{rst} \mathbf{u}_r \circ \mathbf{v}_s \circ \mathbf{w}_t$$
$$\equiv [\mathcal{G}; \mathbf{U}, \mathbf{V}, \mathbf{W}]$$

Our Notation

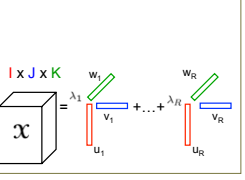
"core"




Kruskal Tensor

$$\mathcal{X} = \sum_r \lambda_r \mathbf{u}_r \circ \mathbf{v}_r \circ \mathbf{w}_r$$
$$\equiv [\lambda; \mathbf{U}, \mathbf{V}, \mathbf{W}]$$

Our Notation



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Specially Structured Tensors

details

Tucker Tensor

$$\mathcal{X} = \mathcal{G} \times_1 \mathbf{U} \times_2 \mathbf{V} \times_3 \mathbf{W}$$
$$= \sum_r \sum_s \sum_t g_{rst} \mathbf{u}_r \circ \mathbf{v}_s \circ \mathbf{w}_t$$
$$\equiv [\mathcal{G}; \mathbf{U}, \mathbf{V}, \mathbf{W}]$$

In matrix form:

$$\mathbf{X}_{(1)} = \mathbf{U} \mathbf{G}_{(1)} (\mathbf{W} \otimes \mathbf{V})^T$$
$$\mathbf{X}_{(2)} = \mathbf{V} \mathbf{G}_{(2)} (\mathbf{W} \otimes \mathbf{U})^T$$
$$\mathbf{X}_{(3)} = \mathbf{W} \mathbf{G}_{(3)} (\mathbf{V} \otimes \mathbf{U})^T$$
$$\text{vec}(\mathcal{X}) = (\mathbf{W} \otimes \mathbf{V} \otimes \mathbf{U}) \text{vec}(\mathcal{G})$$

Kruskal Tensor


$$\mathcal{X} = \sum_r \lambda_r \mathbf{u}_r \circ \mathbf{v}_r \circ \mathbf{w}_r$$
$$\equiv [\lambda; \mathbf{U}, \mathbf{V}, \mathbf{W}]$$

In matrix form:

Let $\Lambda = \text{diag}(\lambda)$
$$\mathbf{X}_{(1)} = \mathbf{U} \Lambda (\mathbf{W} \otimes \mathbf{V})^T$$
$$\mathbf{X}_{(2)} = \mathbf{V} \Lambda (\mathbf{W} \otimes \mathbf{U})^T$$
$$\mathbf{X}_{(3)} = \mathbf{W} \Lambda (\mathbf{V} \otimes \mathbf{U})^T$$
$$\text{vec}(\mathcal{X}) = (\mathbf{W} \otimes \mathbf{V} \otimes \mathbf{U}) \Lambda$$


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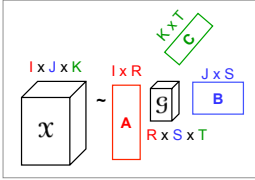
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Tensor Decompositions




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Tucker Decomposition - intuition



- author x keyword x conference
- A: author x author-group
- B: keyword x keyword-group
- C: conf. x conf-group
- \mathcal{G} : how groups relate to each other

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Intuition behind core tensor

- 2-d case: co-clustering
- [Dhillon et al. Information-Theoretic Co-clustering, KDD'03]

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$$m \begin{bmatrix} .05 & .05 & .05 & 0 & 0 & 0 \\ .05 & .05 & .05 & 0 & 0 & 0 \\ 0 & 0 & 0 & .05 & .05 & .05 \\ 0 & 0 & 0 & .05 & .05 & .05 \\ .04 & .04 & 0 & .04 & .04 & .04 \\ .04 & .04 & .04 & 0 & .04 & .04 \end{bmatrix} \begin{matrix} \text{eg, terms} \\ \text{x documents} \end{matrix}$$

$$k \begin{bmatrix} .5 & 0 & 0 \\ .5 & 0 & 0 \\ 0 & .5 & 0 \\ 0 & .5 & 0 \\ 0 & 0 & .5 \\ 0 & 0 & .5 \end{bmatrix} l \begin{bmatrix} .3 & 0 \\ 0 & .3 \\ .2 & .2 \end{bmatrix} n \begin{bmatrix} .36 & .36 & .28 & 0 & 0 & 0 \\ 0 & 0 & .28 & .36 & .36 & .36 \end{bmatrix} = \begin{bmatrix} .054 & .054 & .042 & 0 & 0 & 0 \\ .054 & .054 & .042 & 0 & 0 & 0 \\ 0 & 0 & 0 & .042 & .054 & .054 \\ 0 & 0 & 0 & .042 & .054 & .054 \\ .036 & .036 & .028 & .028 & .036 & .036 \\ .036 & .036 & .028 & .028 & .036 & .036 \end{bmatrix}$$

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[illegible]

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matrix operations

med. doc

.05	.05	.05	0	0	0
.05	.05	.05	0	0	0
0	0	0	.05	.05	.05
0	0	0	.05	.05	.05
.04	.04	0	.04	.04	.04
.04	.04	0	.04	.04	.04

cs doc

.054	.054	.042	0	0	0
.054	.054	.042	0	0	0
0	0	0	.042	.054	.054
0	0	0	.042	.054	.054
.036	.036	.028	.028	.036	.036
.036	.036	.028	.028	.036	.036

term group x doc. group → doc x doc group

med. terms | cs terms | common terms

 CMU SCS[illegible]

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Tucker Decomposition

$\mathcal{X} \approx [\mathcal{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}]$

Given $\mathbf{A}, \mathbf{B}, \mathbf{C}$, the optimal core is:

$$\mathcal{G} = [\mathcal{X}; \mathbf{A}^\dagger, \mathbf{B}^\dagger, \mathbf{C}^\dagger]$$

- Proposed by Tucker (1966)
- AKA: Three-mode factor analysis, three-mode PCA, orthogonal array decomposition
- \mathbf{A}, \mathbf{B} , and \mathbf{C} generally assumed to be orthonormal (generally assume they have full column rank)
- \mathcal{G} is not diagonal
- Not unique

Recall the equations for converting a tensor to a matrix

$$\begin{aligned} \mathbf{X}_{(1)} &= \mathbf{A} \mathbf{G}_{(1)} (\mathbf{C} \otimes \mathbf{B})^\top \\ \mathbf{X}_{(2)} &= \mathbf{B} \mathbf{G}_{(2)} (\mathbf{C} \otimes \mathbf{A})^\top \\ \mathbf{X}_{(3)} &= \mathbf{C} \mathbf{G}_{(3)} (\mathbf{B} \otimes \mathbf{A})^\top \\ \text{vec}(\mathcal{X}) &= (\mathbf{C} \otimes \mathbf{B} \otimes \mathbf{A}) \text{vec}(\mathcal{G}) \end{aligned}$$

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Solving for Tucker

details

$\mathcal{X} \approx [\mathcal{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}]$

Given $\mathbf{A}, \mathbf{B}, \mathbf{C}$ orthonormal, the optimal core is:

$$\mathcal{G} = [\mathcal{X}; \mathbf{A}^\top, \mathbf{B}^\top, \mathbf{C}^\top]$$

Tensor norm is the square root of the sum of all the elements squared

Eliminate the core to get:

$$\|\mathcal{X} - [\mathcal{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}]\|^2 = \|\mathcal{X}\|^2 - 2\langle \mathcal{X}, [\mathcal{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}] \rangle + \|\mathcal{G}\|^2$$

Minimize $\|\mathcal{X} - [\mathcal{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}]\|^2$ s.t. $\mathbf{A}, \mathbf{B}, \mathbf{C}$ orthonormal

fixed $\|\mathcal{X}\|^2$ maximize this $\|[\mathcal{X}; \mathbf{A}^\top, \mathbf{B}^\top, \mathbf{C}^\top]\|^2$

If \mathbf{B} & \mathbf{C} are fixed, then we can solve for \mathbf{A} as follows:

$$\|[\mathcal{X}; \mathbf{A}^\top, \mathbf{B}^\top, \mathbf{C}^\top]\| = \|\mathbf{A}^\top \mathbf{X}_{(1)} (\mathbf{C} \otimes \mathbf{B})\|$$

Optimal \mathbf{A} is \mathbf{R} left leading singular vectors for $\mathbf{X}_{(1)} (\mathbf{C} \otimes \mathbf{B})$

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Higher Order SVD (HO-SVD)

details

$\mathcal{X} \approx [\mathcal{G}; \mathbf{A}, \mathbf{B}, \mathbf{C}]$

Not optimal, but often used to initialize Tucker-ALS algorithm.

(Observe connection to Tucker!)

\mathbf{A} = leading \mathbf{R} left singular vectors of $\mathbf{X}_{(1)}$

\mathbf{B} = leading \mathbf{S} left singular vectors of $\mathbf{X}_{(2)}$

\mathbf{C} = leading \mathbf{T} left singular vectors of $\mathbf{X}_{(3)}$

$$\mathcal{G} = [\mathcal{X}; \mathbf{A}^\top, \mathbf{B}^\top, \mathbf{C}^\top]$$

De Lathauwer, De Moor, & Vandewalle, SIMAX, 1980

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Tucker-Alternating Least Squares (ALS)

Successively solve for each component (A,B,C).

- Initialize
 - Choose R, S, T
 - Calculate A, B, C via HO-SVD
- Until converged do...
 - A = R leading left singular vectors of $X_{(1)}(C \otimes B)$
 - B = S leading left singular vectors of $X_{(2)}(C \otimes A)$
 - C = T leading left singular vectors of $X_{(3)}(B \otimes A)$
- Solve for core:

$$G = [X; A^T, B^T, C^T]$$

Kroonenberg & De Leeuw, Psychometrika, 1980

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Tucker in Not Unique details

Tucker decomposition is not unique. Let Y be an $R \times R$ orthogonal matrix. Then...

$$X \approx G \times_1 A \times_2 B \times_3 C = (G \times_1 Y^T) \times_1 (AY) \times_2 B \times_3 C$$

$$X_{(1)} \approx A G_{(1)} (C \otimes B)^T = A Y Y^T G_{(1)} (C \otimes B)^T$$

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Outline

- Motivation – Definitions
- Tensor tools
- Case studies

{

- Tensor Basics
- Tucker
- PARAFAC

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CANDECOMP/PARAFAC Decomposition

$$\mathcal{X} \approx [\lambda; \mathbf{A}, \mathbf{B}, \mathbf{C}] = \sum_r \lambda_r \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r$$

- CANDECOMP = Canonical Decomposition (Carroll & Chang, 1970)
- PARAFAC = Parallel Factors (Harshman, 1970)
- Core is diagonal (specified by the vector λ)
- Columns of \mathbf{A} , \mathbf{B} , and \mathbf{C} are not orthonormal
- If R is minimal, then R is called the **rank** of the tensor (Kruskal 1977)
- Can have $\text{rank}(\mathcal{X}) > \min\{I, J, K\}$

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PARAFAC-Alternating Least Squares (ALS)

Successively solve for each component (A,B,C).

Khatri-Rao Product
(column-wise Kronecker product)

$$\mathbf{C} \odot \mathbf{B} \equiv [\mathbf{c}_1 \otimes \mathbf{b}_1 \quad \mathbf{c}_2 \otimes \mathbf{b}_2 \quad \dots \quad \mathbf{c}_R \otimes \mathbf{b}_R]$$

$$(\mathbf{C} \odot \mathbf{B})^\dagger \equiv (\mathbf{C}^T \mathbf{C} * \mathbf{B}^T \mathbf{B})^\dagger (\mathbf{C} \odot \mathbf{B})^T$$

Hadamard Product

If \mathbf{C} , \mathbf{B} , and $\mathbf{\Lambda}$ are fixed, the optimal \mathbf{A} is given by:

$$\mathbf{A} = \mathbf{X}_{(1)} (\mathbf{C} \odot \mathbf{B}) (\mathbf{C}^T \mathbf{C} * \mathbf{B}^T \mathbf{B})^\dagger \mathbf{\Lambda}^{-1}$$

Repeat for B,C, etc.

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PARAFAC is often unique

$$\mathcal{X} = [\lambda; \mathbf{A}, \mathbf{B}, \mathbf{C}] = \sum_r \lambda_r \mathbf{a}_r \circ \mathbf{b}_r \circ \mathbf{c}_r$$


Assume PARAFAC decomposition is exact.

Sufficient condition for uniqueness (Kruskal, 1977):

$$2R + 2 \leq k_A + k_B + k_C$$

k_A = k-rank of \mathbf{A} = max number k such that every set of k columns of \mathbf{A} is linearly independent

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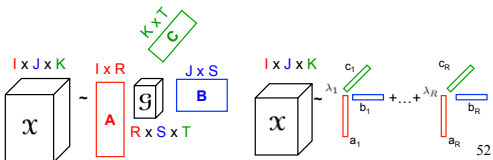
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IMPORTANT


Tucker vs. PARAFAC Decompositions

- Tucker
 - Variable transformation in each mode
 - Core G may be dense
 - A, B, C generally orthonormal
 - Not unique

- PARAFAC
 - Sum of rank-1 components
 - No core, i.e., superdiagonal core
 - A, B, C may have linearly dependent columns
 - Generally unique




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Tensor tools - summary

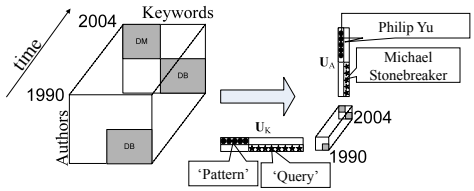
- Two main tools
 - PARAFAC
 - Tucker
- Both find row-, column-, tube-groups
 - but in PARAFAC the three groups are identical
- To solve: Alternating Least Squares
- Toolbox: from Tamara Kolda:
<http://csmr.ca.sandia.gov/~tgkolda/TensorToolbox/>

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P1: Social network analysis

- Multiway latent semantic indexing (LSI)
 - Monitor the change of the community structure over time



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P1: Social network analysis (cont.)

Authors	Keywords	Year
michael carey, michael stonebreaker, h. jagadish, hector garcia-molina	parallel, optimization, concurr, semi	1995
surajit chaudhuri, mitch cherniack, michael stonebreaker, ugru etintemel	distribut, systems, view, storage, service, process, cache	2004
xiaohui han, jian pei, philip s. yu, jianying wang, charu c. aggarwal	stream, support, cluster, query, queri	2004

DB

DM

- Two groups are correctly identified: Databases and Data mining
- People and concepts are drifting over time

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P2: Web graph mining

- How to order the importance of web pages?
 - Kleinberg's algorithm HITS
 - PageRank
 - Tensor extension on HITS (TOPHITS)

Google

Yahoo! Search

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Kleinberg's Hubs and Authorities (the HITS method)

Endangered Species

Jaguar FAQ

Rain Forest Zoo

Online Atlas

Website 1

Website 2

Website 3

Website 4

Sparse adjacency matrix and its SVD:

$$x_{ij} = \begin{cases} 1 & \text{if page } i \text{ links to page } j \\ 0 & \text{otherwise} \end{cases}$$
$$X \approx \sum_r \sigma_r h_r \circ a_r$$

authority scores for 1st topic

authority scores for 2nd topic


hub scores for 1st topic

hub scores for 2nd topic

Kleinberg, JACM, 1999

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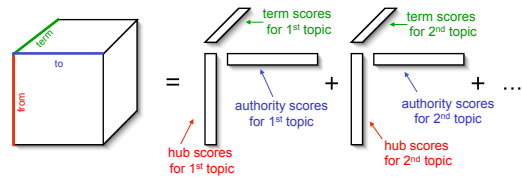
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Topical HITS (TOPHITS)

Main Idea: Extend the idea behind the HITS model to incorporate term (i.e., topical) information.

$$\mathcal{X} \approx \sum_{r=1}^R \lambda_r \mathbf{h}_r \circ \mathbf{a}_r \circ \mathbf{t}_r$$


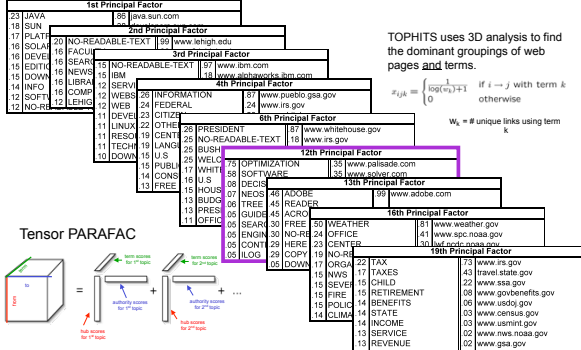
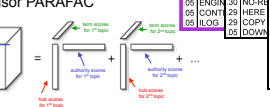
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TOPHITS Terms & Authorities on Sample Data

TOPHITS uses 3D analysis to find the dominant groupings of web pages and terms.

$$x_{ijk} = \begin{cases} \frac{1}{\log(c_{ij}+1)} & \text{if } i \rightarrow j \text{ with term } k \\ 0 & \text{otherwise} \end{cases}$$
$$w_k = \# \text{ unique links using term } k$$


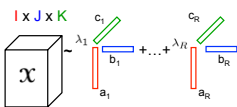
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Conclusions

- Real data are often in high dimensions with multiple aspects (modes)
- Matrices and tensors provide elegant theory and algorithms



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