

# Fixed Parameter Algorithms

Given a problem  $\Pi$ , and also some parameter  $k$ , the problem is FPT with parameter  $k$  if it can be solved in time  $f(k) \cdot \text{poly}(n)$  where  $n$  is the instance size.

So if  $n$  is graph size,  $k$  is the vertex cover size then

- $n^k$  is not FPT
- $f(k) \cdot n^{100}$  is FPT
- $\text{poly}(n, k)$  is definitely FPT.

Really a function of the parameter: eg graph coloring with parameter  $k = \text{color set size}$  is not believed to be solvable in time  $n^k$  even. ~~But if~~ Or clique, size of clique is parameter, then it is believed that  $\frac{2^k}{n}$  is close to best, but maybe with some other parameter we could do better. Eg. with parameter = max degree  $\Delta$ , there is a  $(2^{\Delta} \cdot \Delta^2 n)$  time algo for clique.

OK. Several techniques. Also a lot of crossover with exact (fast) algorithms for NP-hard problems. Will see some of them in these 2 lectures

1. Kernelization: apply simple "reduction" rules to get an instance that is of size  $g(k)$ . <sup>in time  $\text{poly}(n, k)$</sup>  which we can use a brute force algo to get  $\text{poly}(n(k)) + f(k)$  algo.   
  $\uparrow$  if  $g(k) = \text{poly}(k)$  this is "poly sized kernel".

Notation: reduction rule gives  $(I, k) \Leftrightarrow (I', k')$  and is "safe" or "sound" if  $(I, k)$  is a YES instance  $\Leftrightarrow (I', k')$  is a YES instance.   
 denoted by  $(G, k) \Leftrightarrow (G', k')$

Let's take a simple example. Vertex Cover.  <sup>$(k = \text{OPT VC size})$</sup>  Here are two simple reduction rules.

(V1) if  $v$  is isolated vertex, drop it; not in any VC.

$$(G, k) \Leftrightarrow (G - \text{isolated vertex } v, k).$$

(V2) if  $v$  has degree  $> k$  then  $v$  is in every VC.

$$(G, k) \Leftrightarrow (G - v, k - 1).$$

This means: When no more reduction rules apply, graph is of min-degree 1 and max degree  $\Delta = k$ .

Fact: A vertex cover of such a graph can cover at most  $k^2$  edges. (of size  $k$ )

So at end: if  $G^{final}$  has more than  $(k^{final})^2$  edges,  $\tilde{G}$  = matching with  $k+1$  disjoint edges.  
 else  $\tilde{G} = G^{final}$ .

Follows that  $(G, k) \Leftrightarrow (\tilde{G}, k^{final})$ .  
 and  $\tilde{G}$  has  $\leq (k^{final})^2$  edges ~~and~~  
 $\leq k^2$  and hence  $\leq 2k^2$  vertices.

Thm: VC has a kernel of size  $\leq 2k^2$  vertices ( $k^2$  edges).

Can we do better? YES:- (and no)

Thm: VC has kernel of size  $\leq 2k$  vertices.

Pf: write LP for VC.  $\min \sum x_v$   
 st  $x_u + x_v \geq 1 \forall u \sim v$   
 $x_u, x_v \geq 0$ .

No? Dell & van Melkebeek 2002 showed that unless  $co NP \subseteq NP/poly$  VC cannot have  $O(k^2)$  edge kernels

HW 6

Thm: [Nemhauser-Prottel] Any basic feasible solution to this LP has  
 (a)  $x_v \in \{0, \frac{1}{2}, 1\}$  for all vertices  
 And if  $x^*$  is optimal fractional soln then  $V_0 = \{v : x_v^* = 0\}$   
 $V_{\frac{1}{2}} = \{v : x_v^* = \frac{1}{2}\}$   
 $V_1 = \{v : x_v^* = 1\}$   
 then  $\exists$  optimal solution st  $V_0 \cap OPT = \emptyset, V_1 \subseteq OPT$  and OPT contains rest of the rest.

Note:  $|OPT_{LP}| \leq |OPT| \Rightarrow |V_{\frac{1}{2}}| \leq 2|OPT| = 2k$ .

So reduction rule: drop  $V_0$ , pick  $V_1$ ,  $(G, k) \Leftrightarrow (G \setminus (V_0 \cup V_1), k - |V_1|)$ .

And size of new instance  $\leq 2k$  vertices!



Can solve LP using matchings in this case

Kernelization is a good way to do things, and it is "complete" in some sense.

Thm: problem  $\Pi$  with parameter  $k$  is FPT  $\Leftrightarrow$  it has a ~~polynomial~~ kernelization algo.

Pf: one direction is immediate. other side:- sps it has  $f(k)n^c$  algo. then either instance size  $\leq f(k)$  than output instance. else size  $\geq f(k)$  then run algo with time  $f(k)n^c \leq n^{O(1)}$  and output a trivial instance depending on answer.

But this is not an interesting thm. Would like poly sized kernels. And that's the best goal to aim for. But let's look at other techniques.

Aside: Sunflower lemma [Erdos-Rado].

gives:-  $d$ -uniform hypergraph vertex cover (aka  $d$ -hitting set) has kernel with at most  $d!k^d$  sets.

II Bounding the Branching Factor in Exhaustive Search.

• Observation: in each <sup>VC</sup> solution, either a node is in OPT or all its nbrs are in OPT.

So  $Alg(G, k) = \min (Alg(G-v, k-1), Alg(G-N(v)-v, k-|N(v)|))$

And when max degree of nodes = 1, problem is trivial (graph is a matching).

Algo: branch by picking highest degree vertex (degree  $\geq 2$ )

$\Rightarrow T(k) \leq T(k-1) + T(k-2) + O(m)$   
 $\uparrow N(v) \geq 2.$

Solve to get  $T(k) \leq O(m) \cdot \phi^k$  where  $\phi \approx 1.618 \dots$  golden ratio.

• Easy improvement: what if graph has <sup>max</sup> degree = 2. Paths and cycles. Also easy. so can stop when min degree = 2.

$T(k) \leq T(k-1) + T(k-3) + O(m)$   
solves to  $T(k) \leq O(m) \cdot (1.46)^k$ .

Can combine with kernelization to get (time for kernelization) +  $O(k) (1.46)^k$ .

Branch factor was studied for 3-SAT problems exactly (DPLL procedure) (4)

(Davis Putnam (Logemann Loveland))

Exact  $(1.839)^n$  algo for 3SAT:-

If  $T$  has 3 variable clause then use 2SAT algo to check satisfiability.

Else  $(l_1, \vee l_2, \vee l_3)$  :-

either  $l_1$  is true or

$l_1 F, l_2 T$  or

$l_1 F, l_2 F, l_3 T$

# variables  
 $T(n) \leq T(n-1) + T(n-2) + T(n-3) + O(n)$

$T(n) \leq \alpha^n \cdot O(n)$

$\alpha$  is the real root of  $\alpha^3 = \alpha^2 + \alpha + 1$   
 $\alpha \approx 1.839...$

Many improvements: Monien Speckmeyer '85, Schönig '99

Patric Pudlak Zane, Williams etc.  
(+ Saks)

Another (better) one: Suppose  $a^*$  is a sat'ing assignment.

Then suppose #1's in  $a^*$  is  $\leq n/2$  (else start with the all 1's solution)

- start with all zero solution:

- while current solution is not sat'ing, pick unsat'd clause

- ~~try each~~ recurse with  $a \oplus e_i$  for each  $i$  in that clause.

- recursion depth  $\leq n/2$ .

total time  $\leq 3^{n/2} \cdot O(n) = 1.732^n \cdot O(n)$  better than above, but not best possible (by any means).

[Schönig 99]: Pick the first clause not sat'd by  $a$ , and flip a random variable and repeat.

for depth  $T = O(n)$ .

[on opposite side]

Claim:  $P[\text{success}] \geq \frac{2(1-\epsilon)}{\sqrt{n}} (3/4)^n \Rightarrow$  repeat  $O(\sqrt{n}) \cdot \text{poly}(n)$  times.  $\approx (1.33)^n$

[PPZ] deal with unit clauses: random permutation on variables, random "default" assignment.

If current variable is in some unit clause, set that clause (if no way to sat all unit clauses, abort).

Else set current var to the default value,

and move to next variable in random order.  $(1.58)^n$  etc.

Color Coding: [Alon Yuster Zwick] powerful yet simple technique to obtain algo via randomization. Eg. easy algorithm to find paths of length k in time  $O(k!)$  and  $O(2e)^k$ . See HWS.

Inclusion Exclusion:

(can be used to find if  $\exists$  a Hamilton cycle.)

Want to find TSP on a given metric. Trivial sol<sup>n</sup>:  $n!$  poly(n).  $(n-1)! \text{ poly}(n)$ .

just basic DP.

starts at s.

$$TSP(\text{ends at } t, \text{ visits vertices } U) = \min_x \left\{ TSP(\text{ends at } x, \text{ visits vertices } U-t) + d(x,t) \right\}$$

a path from s to t having visited vertices in U exactly once.

takes time (and space)  $O(2^n \cdot \text{poly}(n))$

Actually space  $O(2^n \cdot n)$   
time  $2^n \cdot n \times n$  per table lookup.

Suppose now we want to count # of solutions (Hamilton cycles).

Let  $A_u$  be the set of all n-length "closed" walks that start at s and pass through vertex  $u \in V \setminus s$ .

Note that  $|HAM| = \left| \bigcap_{u \in V \setminus s} A_u \right| = \sum_{X \subseteq V \setminus s} (-1)^{|X|} \left| \bigcap_{i \in X} \bar{A}_i \right|$

$\Rightarrow$  easier problem:  $\left| \bigcap_{u \in X} \bar{A}_u \right| = \#$  of closed walks (of length n) within  $(V \setminus X)$ . (starting from s.)

eg.  $|A \cap B| = |U| - |A| - |B| + |A \cap B|$  etc.  
see over

can be computed using "matrix multiplication" type ideas.

compute  $(A|_{V \setminus X})^n$ .

$\Rightarrow$  compute all simpler problems in time  $O(n^3 \cdot 2^n)$

but now space polynomial !!

# Iterative Compression: [Reed Smith Vetta]

Start of Idea

Vertex cover: s.t. we have  $A = \text{approx VC of size } \leq 2k$ .

① guess how  $C^* \cap A$  looks like (call this  $C_A$ ).

$R_A = \text{rest of } A = A \setminus C_A$ .

- if  $G[R_A]$  has an edge, fail for this  $C_A$ .
- else  $N(R_A)$  must be all in the  $C^*$ . (Else some edge not covered)



$N(R_A) = \text{Neighbors of } R_A \text{ not in } A$ .

$\Rightarrow$  if  $|N(R_A)| + |C_A| > k$  fail for this  $C_A$ .

$\Rightarrow$  if  $\exists C_A \subseteq A$  s.t.  $|C_A| + |N(R_A)| \leq k$  this is a VC of size  $\leq k$  else fail.

Time:  $O^*(2^A) \leq O^*(4^k)$ .

Much worse than previous ideas. Can we improve? YES. (~~but get out of~~ iterative compression).

Iterative Compression

Let  $G_i = G[v_1, \dots, v_i]$ .

s.t. we have a VC of  $G_i$ , called  $R_i$ , of size  $k$ .

then get a VC  $A_{i+1}$  of  $G_{i+1}$  of size  $k+1$ .

Now use the algo from previous part to get VC  $C_{i+1}$  of size  $k$  in time  $O^*(2^{|A_{i+1}|}) = O^*(2^{k+1})$ .

$\Rightarrow$  whole thing takes  $O^*(2^k)$  time!  $\text{☺}$ .

loss is a factor  $n$  in the runtime.

BTW: very general, but why did it work? We had a sol<sup>n</sup>  $A$ , we said that we wanted to extend  $C_A$  for another sol<sup>n</sup> of size  $k$ , but it had to be disjoint from  $R = A \setminus C_A$ . this gave a lot of structure, make it trivial in the VC case. But this disjointness requirement makes it easy in other cases too.

Longest path in  $O^*(k)$  time

Want a polynomial  $P(x) \neq 0$  iff  $G$  has a  $k$ -path.

for every  $k$ -walk  $v_1 e_1 v_2 e_2 \dots e_{k-1} v_k$  in the graph we have a monomial  $\prod_{i=1}^k x_{e_i} \prod_{i=1}^{k-1} y_{v_i}$  }  $x_e$  for edges  
}  $y_v$  for vertices.

note: for a path, the monomial is multilinear (each variable has degree  $\leq 1$ )

so instead of checking for existence of some monomial, want to check existence of multilinear monomial.

Idea: Label vertices with a unique label. Now define polynomial over labeled walks.

$W =$  walk  
 $l =$  labeling  $[k] \rightarrow [k]$  bijection.

$\forall e = (u, v) \in E, x_{uv}$   
 $\forall v \in V, \forall a \in [k] y_{v,a}$

$$P(\bar{x}, \bar{y}) = \sum_{\substack{\uparrow \\ |E| \\ \text{vars}}} \sum_{\substack{\uparrow \\ |V| \times k \\ \text{vars}}} \prod_{i=1}^{k-1} x_{e_i, v_{i+1}} \prod_{i=1}^k y_{v_i, l(i)}.$$

walks  $W = (v_1, \dots, v_k)$     labelings  $l: [k] \rightarrow [k]$  bijection    // def.

$$= \sum_W \sum_l \text{MONO}_{W, l}(\bar{x}, \bar{y})$$

View as a multivariate polynomial over  $GF(2^{\log_2 k})$ .

**Critical Facts**

\*  $GF(2^t)$  has characteristic 2 (i.e.  $a+a=0 \forall a \in GF(2^t)$ )

\* has a correspondence with  $t$ -bit vectors, but the operations are based on irreducible polys. See an algebra book

**Main Lemma:**

$$P(\bar{x}, \bar{y}) = \sum_P \sum_l \text{MONO}_{P, l}(\bar{x}, \bar{y}).$$

We will see its proof soon, but for now let's use it.

note: not sum over walks but over paths

note that for two different paths  $P, P'$   $\text{MONO}_{P,e}(\bar{x}, \bar{y})$  cannot cancel  $\text{MONO}_{P',e'}(\bar{x}, \bar{y})$  for any  $l, e'$ . (since the  $x$  parts are just different).

⇒ Corollary:  $P$  is non zero polynomial iff  $\exists$  a  $k$ -path in  $G$ .

How to compute  $P$  at  $(\bar{x}, \bar{y})$  efficiently?

Evaluation Lemma: Given assignments to  $\bar{x}, \bar{y}$ ,  $P(\cdot)$  can be calculated in time  $O(2^k \cdot km)$  field operations.

Thm:  $\exists$  an algorithm for LONGEST path in time  $O^*(2^k)$ .

PF: want to check if  $P(\cdot)$  is non-zero polynomial.  
(key Corollary  $\Leftrightarrow G$  has a  $k$  path).

Use Schwartz-Zippel, evaluation lemma says takes time  $O^*(2^k)$  to evaluate it at random points. And if  $P(\cdot) \neq 0$  then w/h this will give non zero value. ■

How to prove the Lemmas:

① Proof of Main Lemma: let  $W$  be a walk (non-path) and  $R$  bijection.

Say  $v$  is repeated, the first one. Flip the labels of those two locations, to get  $l'$ . note  $\text{MONO}_{W,e} = \text{MONO}_{W,e'}$ . hence they'll cancel each other out (b/c  $\text{GF}(2^t)$  has characteristic 2). ■

② Proof of Evaluation Lemma:



N.b. With inclusion Exclusion:  $w(\bigcap_{i \in S} A_i) = \sum_{X \subseteq [k]} (-1)^{|X|} w(\bigcap_{j \in X} \bar{A}_j)$   $w(\bigcap_{j \in \emptyset} \bar{A}_j) = w(V)$

Claim 1:  $\forall$  walks  $W, \bar{x}, \bar{y}$  for any weight  $f^n$ .

$$\sum_{\substack{l \text{ bijective} \\ [k] \rightarrow [k]}} \text{MONO}_{w,e}(\bar{x}, \bar{y}) = \sum_{X \subseteq [k]} \sum_{l: \text{maps from } [k] \rightarrow X} \text{MONO}_{w,e}(\bar{x}, \bar{y})$$

Pf: let  $U$  be set of all maps from  $[k]$  to  $[k]$ .

$A_i =$  set of maps that map at least one thing to  $i$

Fix  $W, \bar{x}, \bar{y}$   
 $w(l) = \text{MONO}_{w,e}(\bar{x}, \bar{y})$

we want = LHS  $w(\bigcap_{i \in K} A_i) = \sum_{X \subseteq [k]} (-1)^{|X|} w(\bigcap_{j \in X} \bar{A}_j)$

$$= \sum_{X \subseteq [k]} (-1)^{|X|} \sum_{l: \text{maps from } [k] \text{ to } [k] \setminus X} \text{MONO}_{w,e}(\bar{x}, \bar{y})$$

Char 2 ↙

$$= \sum_{X \subseteq [k]} \sum_{l: \text{maps from } [k] \text{ to } X} \text{MONO}_{w,e}(\bar{x}, \bar{y})$$

$$\Rightarrow P(\bar{x}, \bar{y}) = \sum_{\text{walk } W} \sum_{X \subseteq [k]} \sum_{l: \text{maps from } [k] \rightarrow X} \text{MONO}_{w,e}(\bar{x}, \bar{y})$$

$$= \sum_{X \subseteq [k]} P_X(\bar{x}, \bar{y}) = 2^k \text{ polynomials of the form } \sum_{\text{walks}} \sum_{\substack{\text{maps from} \\ k \rightarrow X}} \text{MONO}_{w,e}(\bar{x}, \bar{y})$$

Claim 2:  $P_X(\bar{x}, \bar{y})$  can be computed in time  $\text{poly}(n, k)$ .

Pf: just a simple DP on the length of the walk.

length 1:  $M(v, 1) = \sum_{\substack{\text{labels} \\ \text{from } [k] \rightarrow X}} y_{v,e}$  and then

$$M(v, i) = \sum_{\substack{u \neq v \\ \text{labels for } k-i-1}} y_{v,e} \cdot x_{vu} M(u, i-1) \text{ etc.}$$

$O(kn^2)$  time.