

Advanced Sorting

15-121
Introduction to Data Structures

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Objectives

- Understanding quadratic and sub quadratic sorting algorithms
- Learning the algorithmic details about sub quadratic algorithms
- Understanding informal complexity arguments
- Worst case scenarios
- Summary of Sorting Algorithms

So far we learned...

- Sorting a data set can lead to **easy algorithms** for finding
 - Median, mode etc..
- $O(n^2)$ sorting algorithms are **easy to code**, but inefficient for large data sets. However **insertion sort** is used widely in practice for small data sets
- Question : Why are bubble sort and selection sorts do not perform as well as insertion sorts?
- Next we consider
 - $O(n \log n)$ sorting algorithms

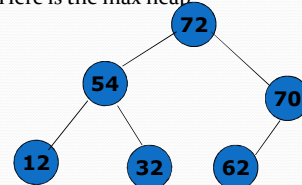
Heap Sort

Heap Sort

- Suppose we have an unsorted array of comparable objects that need to be sorted. Assume that entries are in $1..n$
- First we will build a max heap by percolating down - this time we need to use the larger of the two children
- Then we deleteMax. We will place the max at the end of the array, reduce the size of the heap by 1 and percolate down to maintain maxHeap property

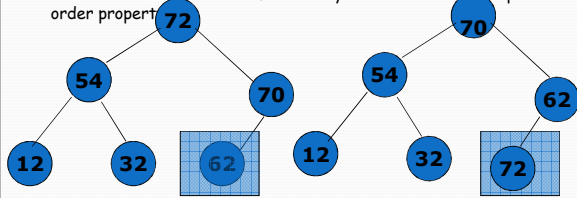
Heap Sort Demo

- Start with 54 32 62 12 72 70
- Here is the max heap



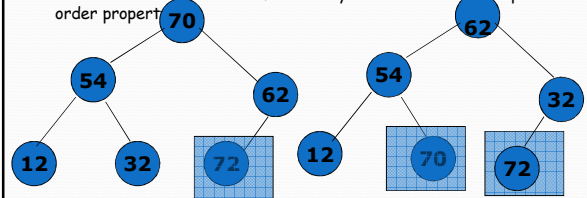
Heap Sort Demo ctd..

- Now move 72 to the back of the array and maintain the heap order property



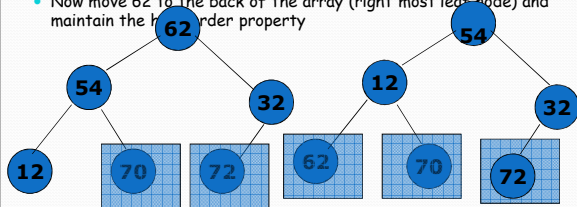
Heap Sort Demo ctd..

- Now move 70 to the back of the array and maintain the heap order property



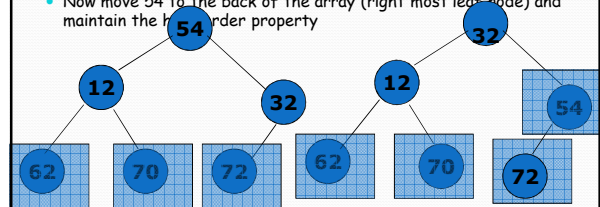
Heap Sort Demo ctd..

- Now move 62 to the back of the array (right most leaf node) and maintain the heap order property



Heap Sort Demo ctd..

- Now move 54 to the back of the array (right most leaf node) and maintain the heap order property



Heap Sort Exercise

- Sort 12 10 15 8 32 20 14 in descending order

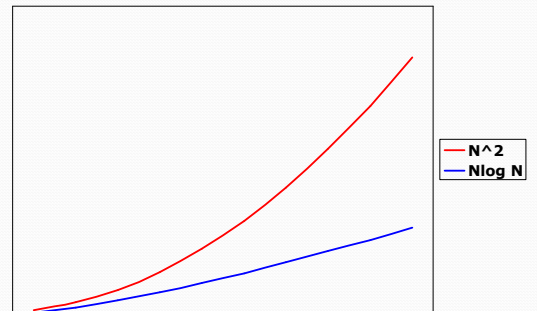
Heap Sort Code

- Pseudo code
 - Build a max/min heap
 - for i from $n-1$ down to 1
 - swap($A[i]$, $A[1]$)
 - Percolate $A[1]$ down

Heapsort Analysis

- Recall from last time about *heaps*:
 - `buildHeap` has $O(N)$ worst-case running time.
 - `removeMax` has $O(\log N)$ worst-case running time.
- Heapsort:
 - Build heap. $O(N)$
 - DeleteMax until empty. $O(N \log N)$
 - Total worst case: $O(N \log N)$

N^2 vs $N \log N$



Sorting in $O(N \log N)$

- Heapsort establishes the fact that sorting can be accomplished in $O(N \log N)$ worst-case running time.
- The average-case analysis for heapsort is somewhat complex.
 - Beyond the scope

Heapsort in practice

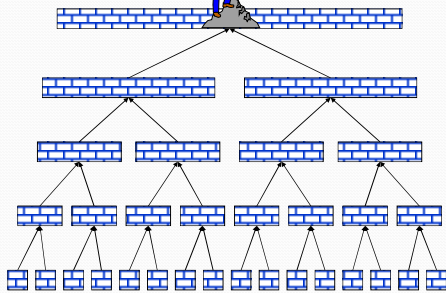
- In practice, heapsort consistently tends to use nearly $N \log N$ comparisons.
- So, while the worst case is better than N^2 , other algorithms sometimes work better.

Recursive Sorting

Merge Sort

- Intuitively, *divide* the problem into pieces and then *recombine* the results.
 - If array is length 1, then done.
 - If array is length $N > 1$, then split in half and sort each half.
 - Then combine the results.
- An example of a *divide-and-conquer* algorithm.

Divide-and-conquer



Merge Sort - Code

```
void mergeSort( AnyType [ ] A, AnyType [ ] tmpArray,
int left, int right )
{ if( left < right )
{ int center = ( left + right ) / 2;
mergeSort( A, tmpArray, left, center);
mergeSort( A, tmpArray, center + 1, right );
merge( A, tmpArray, left, center + 1, right );
}
}
```

Merging Two Sorted Arrays

- All the work in merge sort is done at the merge step.
- Example



Exercise

- Write the merge code
- `public void merge(A, tmpArray, left, center + 1, right) ;`
 - Merges two sorted Arrays `A[left, center]` and `A[center+1, right]` using `tmpArray`

Tracing the code

Analysis of Merge Sort

- Suppose it takes time $T(N)$ to sort N elements.
- Suppose also it takes time N to combine the two sorted arrays.
- Then:
 - $T(1) = 1$
 - $T(N) = 2T(N/2) + N$, for $N > 1$
- Solving for T gives the running time for the merge sort algorithm.

Remember recurrence relations?

- Systems of equations such as
 - $T(1) = 1$
 - $T(N) = 2T(N/2) + N$, for $N > 1$are called *recurrence relations* (or sometimes *recurrence equations*).

A solution

- A solution for
 - $T(1) = 1$
 - $T(N) = 2T(N/2) + N$
- is given by
 - $T(N) = N \log N + N$
 - which is $O(N \log N)$.

Generalization of Divide and Conquer

- **Corollary:** Dividing a problem into p pieces, each of size N/p , using only a linear amount of work at each stage, results in an $O(N \log N)$ algorithm.

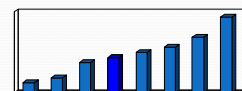
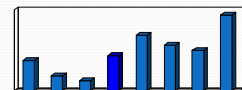
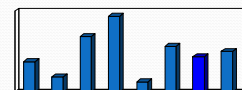
Quicksort

Quicksort

- Quicksort was invented in 1960 by Tony Hoare.
- Quicksort has $O(N^2)$ worst-case performance, and on **average** $O(N \log N)$.
- *More importantly, it is the fastest known comparison-based sorting algorithm in **practice**.*

Quicksort idea

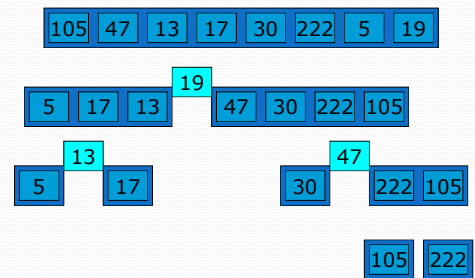
- Choose a pivot.
- Rearrange so that pivot is in the "right" spot.
- Recurse on each half and conquer!



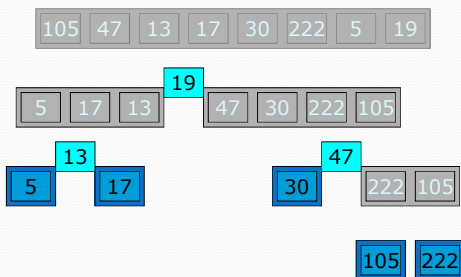
Quicksort algorithm

- If array A has 1 (or 0) elements, then done.
- Choose a *pivot element* x from A.
- Divide A-{ x } into two arrays:
 - $B = \{y \in A \mid y \leq x\}$
 - $C = \{y \in A \mid y \geq x\}$
- Result is $B + \{x\} + C$.
- Recurse on arrays B and C

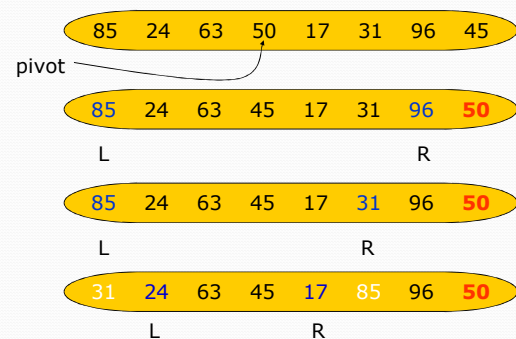
Quicksort algorithm



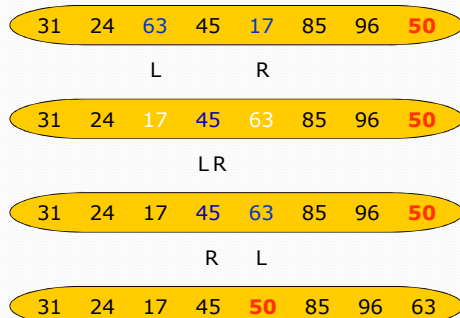
Quicksort algorithm



Rearranging in place



Rearranging in place



Recurse on Smaller Arrays

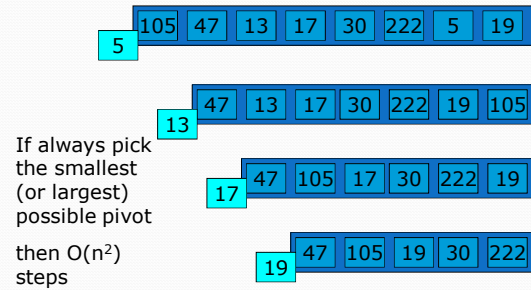
31 24 17 45 50 85 96 63

In practice, insertion sort is used once the arrays get "small enough".

Quicksort is fast but hard to do

- Quicksort, in the early 1960's, was famous for being incorrectly implemented many times.
 - Correctness of the algorithm can be proved using invariants
- Quicksort is very fast in practice.
- Faster than mergesort because Quicksort can be done "in place".

Worst-case behavior



Quicksort implementation

Quick Sort Algorithm

- **Algorithm**
 - Partitioning Step
 - Choose a pivot element say $a = v[j]$
 - Determine its final position in the sorted array
 - $a > v[i]$ for all $i < j$
 - Recursive Step
 - $a < v[i]$ for all $i > j$
 - Perform above step on left array and right array
- **Code**

```
void quicksort(int[] A, int left, int right) {
    int i;
    if (right > left) {
        Pivot(A, left, right);
        i = partition(A, left, right);
        quicksort(A, left, i-1);
        quicksort(A, i+1, right);
    }
}
```

Partitioning

```
int Partition(int[] A, int left, int right) {
    if (A[left] > A[right]) swap(A[left], A[right]);
    int pivot = A[left];
    int i = left;
    int j = right+1;
    do {
        do ++i; while (A[i] < pivot);
        do --j; while (A[j] > pivot);
        if (i < j) Swap(A[i], A[j]);
    } while (i < j);
    Swap(A[j], A[left]);
    return j; // j is the position of the pivot after rearrangement
}
```

Quicksort Implementation

- Quick sort can be very **fast** in practice, but this depends on careful coding
- Three major issues:
 1. dividing the array **in-place**
 2. picking the **right** pivot
 3. avoiding Quicksort on **small arrays**

Dividing the Array in Place

- We can do the following
 - Place the pivot in the **last position** of the array
 - Run two pointers **Left and Right** until $\text{Left} > \text{Right}$
 - Exchange left with pivot when $\text{left} > \text{right}$

Picking the pivot

- In real life, inputs to a sorting routine are often not completely random
- So, picking the first or last element to be the pivot is usually a bad choice
- One common strategy is to pick the middle element
 - this is an OK strategy

Picking the pivot

- A more sophisticated approach is to use random sampling
 - think about opinion polls
- For example, the *median-of-three strategy*:
 - take the median of the first, middle, and last elements to be the pivot
 - We can do this in $O(1)$ time

Avoiding small arrays

- While quicksort is extremely fast for large arrays, experimentation shows that it performs less well on small arrays
- For small enough arrays, a simpler method such as insertion sort works better
- The exact cutoff depends on the language and machine, but usually is somewhere between 10 and 30 elements

Stable Sorting Algorithms

Stable Sorting Algorithm

- **Definition:** A sorting algorithm is **stable** if **relative position** of duplicates are **unchanged** by the algorithm.
 - That is if $A[i] = A[j]$ for $i < j$, then $A[i_s] = A[j_s]$ for $i_s < j_s$ where i_s and j_s are the new positions after algorithm is applied.
- Eg: 10 12 17 18 18 08 90
- What happens to 18, when bubble sort or insertion sort is applied?
- What about Mergesort or Quicksort? Are they stable?

Non-Comparison based Sorting

Non-comparison-based sorting

- If we can do more than just compare pairs of elements, we can sometimes sort more quickly
- What if we can look at the bits of information?
- Two simple examples are *bucket sort* and *radix sort*

Radix Sort

Radix Sort Revisited

World's Fastest Sorters

Sorting competitions

- There are several world-wide sorting competitions
 - Unix CoSort has achieved 1GB in under one minute, on a single Alpha
 - Berkeley's NOW-sort sorted 8.4GB of disk data in under one minute, using a network of 95 workstations
 - Sandia Labs was able to sort 1TB of data in under 50 minutes, using a 144-node multiprocessor machine

Questions?

- Why is bubble sort sloooooow?
- Why is insertion sort seems better than bubble or selection?
- Why is quick sort fast?

Why is quicksort fast?

- Fastest general purpose algorithm
- Only bad case for quicksort is _____
- Better use of virtual memory and cache

Things to do

- Quiz 5 is given Friday in class
 - Covers hashing, heaps and sorting
 - Take the practice quiz
- Start Lab 5 if you already have not
 - Part 1 on implementation of PQ is Due Saturday
 - Part 2 on Web Server simulation on Sunday