Announcement

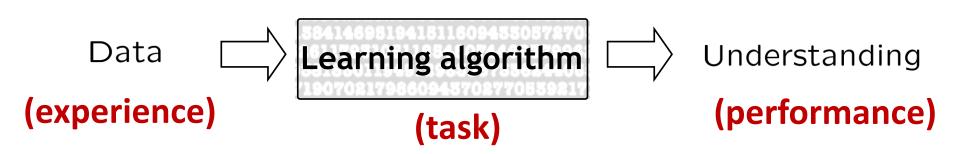
HW 1 out TODAY – Watch your email

What is Machine Learning? (Formally)

What is Machine Learning?

Study of algorithms that

- improve their <u>performance</u>
- at some task
- with <u>experience</u>

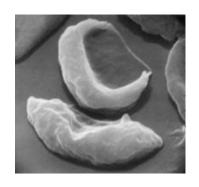


Supervised Learning Task

Task: Given $X \in \mathcal{X}$, predict $Y \in \mathcal{Y}$.

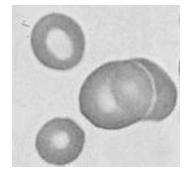
X - test data

 \equiv Construct **prediction rule** $f: \mathcal{X} \rightarrow \mathcal{Y}$





"Anemic cell (0)"





"Healthy cell (1)"

Performance:

loss(Y, f(X)) - Measure of closeness between true label Y and prediction f(X)

 $loss(Y, f(X)) = 1_{\{f(X) \neq Y\}}$

0/1 loss

Performance:

loss(Y, f(X)) - Measure of closeness between true label Y and prediction f(X)

X	Share price, Y	f(X)	loss(Y, f(X))
Past performance, trade volume etc. as of Sept 8, 2010	"\$24.50"	"\$24.50"	0
		"\$26.00"	1?
		"\$26.10"	2?

$$loss(Y, f(X)) = (f(X) - Y)^2$$
 square loss

Performance:

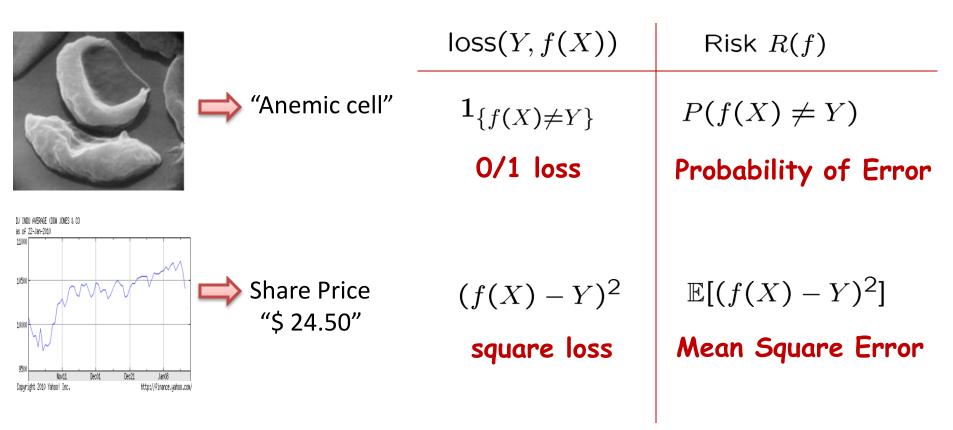
loss(Y, f(X)) - Measure of closeness between true label Y and prediction f(X)

Don't just want label of one test data (cell image), but any cell image $X \in \mathcal{X}$ $(X,Y) \sim P_{XY}$

Given a cell image drawn randomly from the collection of all cell images, how well does the predictor perform on average?

$$\mathsf{Risk}\ R(f) \equiv \mathbb{E}_{XY}\left[\mathsf{loss}(Y, f(X))\right]$$

Performance: Risk $R(f) \equiv \mathbb{E}_{XY} [loss(Y, f(X))]$



Bayes Optimal Rule

<u>Ideal goal</u>: Construct **prediction rule** $f^*: \mathcal{X} \to \mathcal{Y}$

$$f^* = \arg\min_{f} \mathbb{E}_{XY} \left[loss(Y, f(X)) \right]$$

Bayes optimal rule

Best possible performance:

Bayes Risk
$$R(f^*) \leq R(f)$$
 for all f

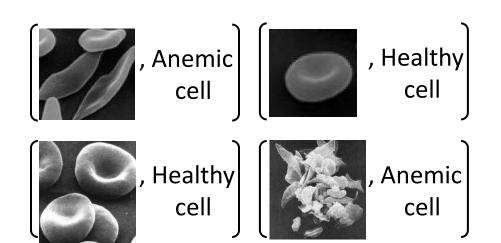
BUT... Optimal rule is not computable - depends on unknown Pxy!

Experience - Training Data

Can't minimize risk since P_{XY} unknown!

Training data (experience) provides a glimpse of P_{XY}

(observed)
$$\{(X_i,Y_i)\}_{i=1}^n \overset{i.i.d.}{\sim} P_{XY}$$
 (unknown) independent, identically distributed



Provided by expert, measuring device, some experiment, ...

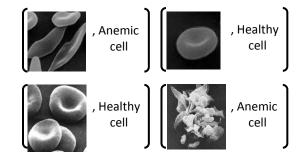
Supervised Learning

Task: Given $X \in \mathcal{X}$, predict $Y \in \mathcal{Y}$.

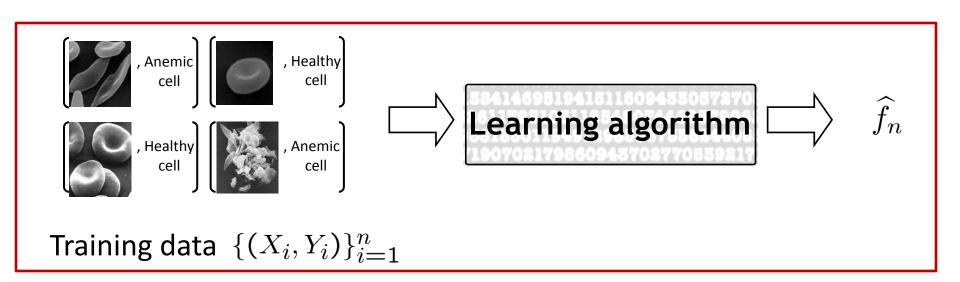
 \equiv Construct **prediction rule** $f: \mathcal{X} \rightarrow \mathcal{Y}$

Performance: Risk $R(f) \equiv \mathbb{E}_{XY} \left[loss(Y, f(X)) \right]$ $(X, Y) \sim P_{XY}$

Experience: Training data $\{(X_i, Y_i)\}_{i=1}^n \stackrel{i.i.d.}{\sim} P_{XY}$ (unknown)



Machine Learning Algorithm

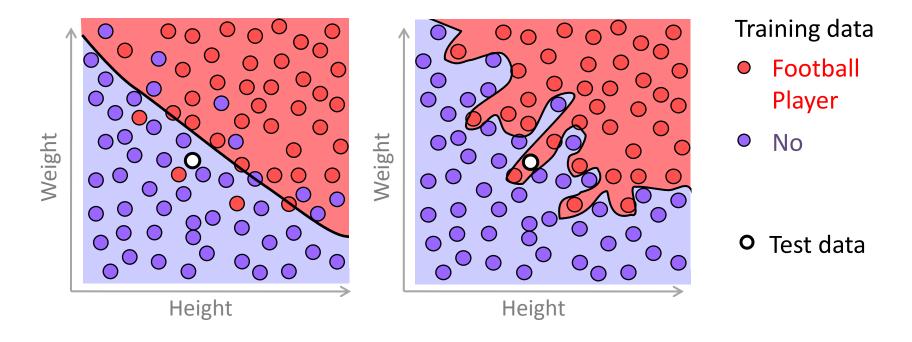


$$\widehat{f}_n$$
 is a mapping from $\mathcal{X} o \mathcal{Y}$ \widehat{f}_n $\left[\begin{array}{c} \widehat{f}_n \end{array} \right]$ = "Anemic cell" Test data X

Note: test data ≠ training data

Issues in ML

- A good machine learning algorithm
 - Does not overfit training data



Generalizes well to test data

More later ...

Performance Revisited

Performance: (of a learning algorithm)

How well does the algorithm do on average

- 1. for a test cell image X drawn at random, and
- 2. for a set of training images and labels $D_n = \{(X_i, Y_i)\}_{i=1}^n$ drawn at random

Expected Risk (aka **Generalization Error**)

$$\mathbb{E}_{D_n}\left[R(\widehat{f}_n)\right] \equiv \mathbb{E}_{D_n}\left[\mathbb{E}_{XY}\left[\mathsf{loss}(Y,\widehat{f}_n(X))\right]\right]$$

How to sense Generalization Error?

- Can't compute generalization error. How can we get a sense of how well algorithm is performing in practice?
- One approach -
 - Split available data into two sets $\{(X_i, Y_i)\}_{i=1}^n \{(X_i', Y_i')\}_{i=1}^n$
 - Training Data used for training the algorithm

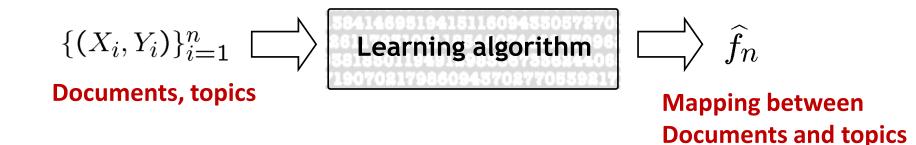
$$\{(X_i, Y_i)\}_{i=1}^n \Longrightarrow \boxed{\text{Learning algorithm}} \Longrightarrow \widehat{f}_n$$

 Test Data (a.k.a. Validation Data, Hold-out Data) – provides estimate of generalization error

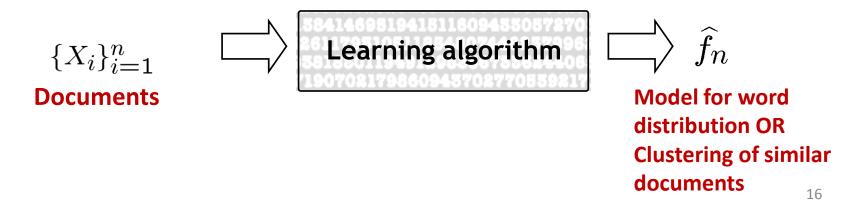
Test Error =
$$\frac{1}{n} \sum_{i=1}^{n} \left[loss(Y'_i, \widehat{f}_n(X'_i)) \right]$$
 Why not use Training Error?

Supervised vs. Unsupervised Learning

Supervised Learning – Learning with a teacher



Unsupervised Learning – Learning without a teacher



Lets get to some learning algorithms!

Learning Distributions (Parametric Approach)

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Machine Learning 10-701/15-781 Sept 13, 2010





Your first consulting job

- A billionaire from the suburbs of Seattle asks you a question:
 - He says: I have a coin, if I flip it, what's the probability it will fall with the head up?
 - You say: Please flip it a few times:



- You say: The probability is: 3/5
- He says: Why???
- You say: Because...

Bernoulli distribution

- P(Heads) = θ , P(Tails) = $1-\theta$
- Flips are i.i.d.:
 - Independent events
 - Identically distributed according to Bernoulli distribution

Choose θ that maximizes the probability of observed data

Maximum Likelihood Estimation

Choose θ that maximizes the probability of observed data

$$\widehat{\theta}_{MLE} = \arg \max_{\theta} P(D \mid \theta)$$

MLE of probability of head:

$$\hat{\theta}_{MLE} = \frac{\alpha_H}{\alpha_H + \alpha_T} = 3/5$$

"Frequency of heads"

How many flips do I need?

$$\widehat{\theta}_{MLE} = \frac{\alpha_H}{\alpha_H + \alpha_T}$$

- Billionaire says: I flipped 3 heads and 2 tails.
- You say: $\theta = 3/5$, I can prove it!
- He says: What if I flipped 30 heads and 20 tails?
- You say: Same answer, I can prove it!
- He says: What's better?
- You say: Hmm... The more the merrier???
- He says: Is this why I am paying you the big bucks???

Simple bound (Hoeffding's inequality)

• For
$$n = \alpha_H + \alpha_T$$
, and $\widehat{\theta}_{MLE} = \frac{\alpha_H}{\alpha_H + \alpha_T}$

• Let θ^* be the true parameter, for any ε >0:

$$P(||\widehat{\theta} - \theta^*| > \epsilon) < 2e^{-2n\epsilon^2}$$

PAC Learning

- PAC: Probably Approximate Correct
- Billionaire says: I want to know the coin parameter θ , within ϵ = 0.1, with probability at least 1- δ = 0.95. How many flips?

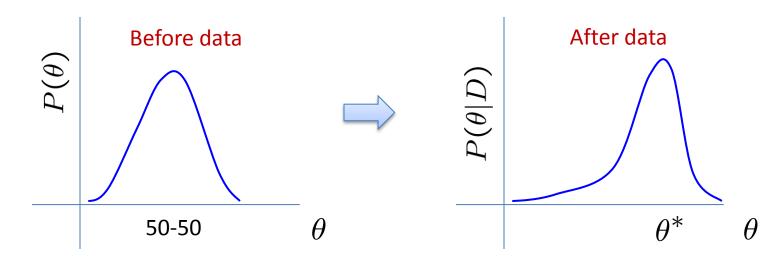
$$P(||\widehat{\theta} - \theta^*| \ge \epsilon) \le 2e^{-2n\epsilon^2}$$

Sample complexity

$$n \ge \frac{\ln(2/\delta)}{2\epsilon^2}$$

What about prior knowledge?

- Billionaire says: Wait, I know that the coin is "close" to 50-50. What can you do for me now?
- You say: I can learn it the Bayesian way...
- Rather than estimating a single θ , we obtain a distribution over possible values of θ



Bayesian Learning

Use Bayes rule:

$$P(\theta \mid \mathcal{D}) = \frac{P(\mathcal{D} \mid \theta)P(\theta)}{P(\mathcal{D})}$$

Or equivalently:

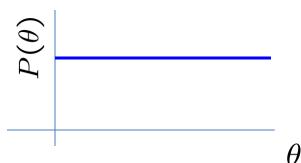
$$P(\theta \mid \mathcal{D}) \propto P(\mathcal{D} \mid \theta) P(\theta)$$
 posterior likelihood prior



Bayes, Thomas (1763) An essay towards solving a problem in the doctrine of chances. *Philosophical Transactions of the Royal Society of London*, 53:370-418

Prior distribution

- What about prior?
 - Represents expert knowledge (philosophical approach)
 - Simple posterior form (engineer's approach)
- Uninformative priors:
 - Uniform distribution



- Conjugate priors:
 - Closed-form representation of posterior
 - $P(\theta)$ and $P(\theta \mid D)$ have the same form

Conjugate Prior

• $P(\theta)$ and $P(\theta \mid D)$ have the same form

Eg. 1 Coin flip problem

Likelihood is ~ Binomial

$$P(\mathcal{D} \mid \theta) = \theta^{\alpha_H} (1 - \theta)^{\alpha_T}$$



If prior is Beta distribution,

$$P(\theta) = \frac{\theta^{\beta_H - 1} (1 - \theta)^{\beta_T - 1}}{B(\beta_H, \beta_T)} \sim Beta(\beta_H, \beta_T)$$

Then posterior is Beta distribution

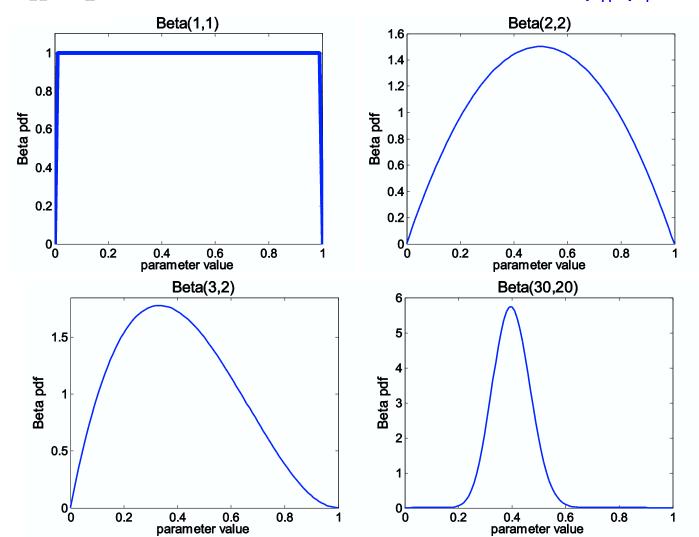
$$P(\theta|D) \sim Beta(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

For Binomial, conjugate prior is Beta distribution.

Beta distribution

 $Beta(\beta_H, \beta_T)$

More concentrated as values of β_H , β_T increase



Beta conjugate prior

$$P(\theta) \sim Beta(\beta_H, \beta_T) \qquad P(\theta|D) \sim Beta(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

$$P(\theta|D) \sim Beta(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

$$P(\theta|D)$$

increases

As $n = \alpha_H + \alpha_T$

As we get more samples, effect of prior is "washed out"

Conjugate Prior

- $P(\theta)$ and $P(\theta | D)$ have the same form
- Eg. 2 Dice roll problem (6 outcomes instead of 2)



Likelihood is ~ Multinomial($\theta = \{\theta_1, \theta_2, ..., \theta_k\}$)

$$P(\mathcal{D} \mid \theta) = \theta_1^{\alpha_1} \theta_2^{\alpha_2} \dots \theta_k^{\alpha_k}$$

If prior is Dirichlet distribution,

$$P(\theta) = \frac{\prod_{i=1}^{k} \theta_i^{\beta_i - 1}}{B(\beta_1, \dots, \beta_k)} \sim \text{Dirichlet}(\beta_1, \dots, \beta_k)$$

Then posterior is Dirichlet distribution

$$P(\theta|D) \sim \text{Dirichlet}(\beta_1 + \alpha_1, \dots, \beta_k + \alpha_k)$$

For Multinomial, conjugate prior is Dirichlet distribution.

Maximum A Posteriori Estimation

Choose θ that maximizes a posterior probability

$$\widehat{\theta}_{MAP} = \arg \max_{\theta} P(\theta \mid D)$$

$$= \arg \max_{\theta} P(D \mid \theta)P(\theta)$$

MAP estimate of probability of head:

$$P(\theta|D) \sim Beta(\beta_H + \alpha_H, \beta_T + \alpha_T)$$

$$\widehat{ heta}_{MAP} = rac{lpha_H + eta_H - 1}{lpha_H + eta_H + lpha_T + eta_T - 2}$$
 Mode of Beta distribution