## **Announcements - Homework**

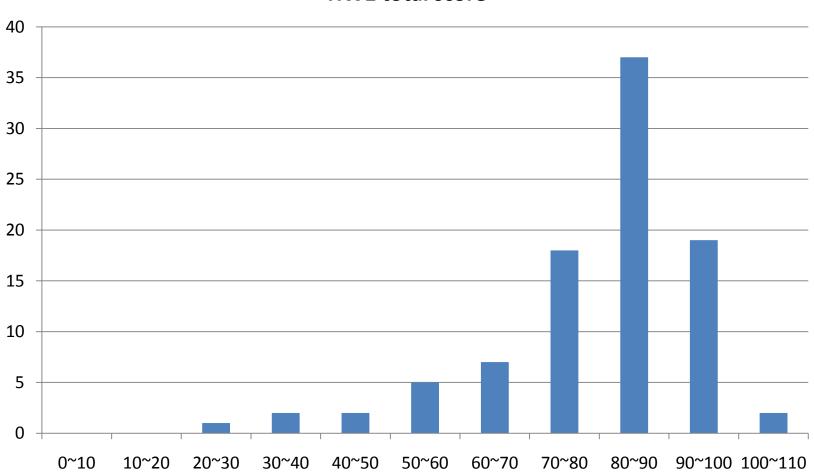
 Homework 1 is graded, please collect at end of lecture

Homework 2 due today

- Homework 3 out soon (watch email)
  - Ques 1 midterm review

## **HW1** score distribution

#### **HW1** total score



## **Announcements - Midterm**

- When: Wednesday, 10/20
- Where: In Class
- What: You, your pencil, your textbook, your notes, course slides, your calculator, your good mood:)
- What NOT: No computers, iphones, or anything else that has an internet connection.
- Material: Everything from the beginning of the semester, until, and including SVMs and the Kernel trick

### **Recitation Tomorrow!**

- Boosting, SVM (convex optimization),
   Midterm review!
- Strongly recommended!!
- Place: NSH 3305 (Note: change from last time)
- Time: 5-6 pm



Rob

## **Support Vector Machines**

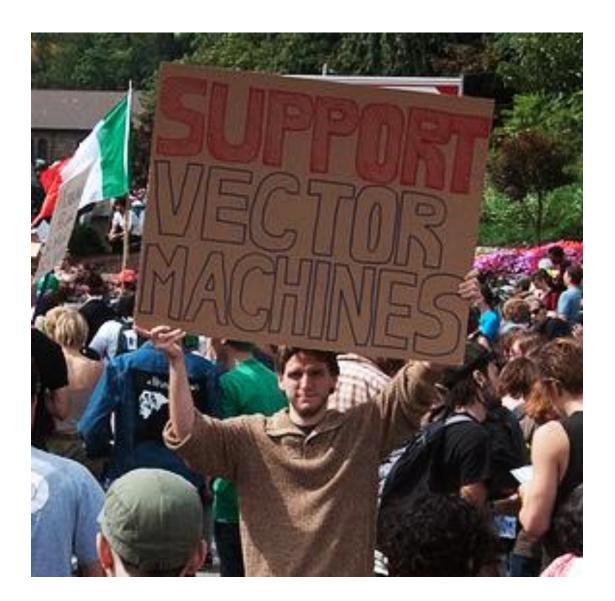
Aarti Singh

Machine Learning 10-701/15-781 Oct 13, 2010

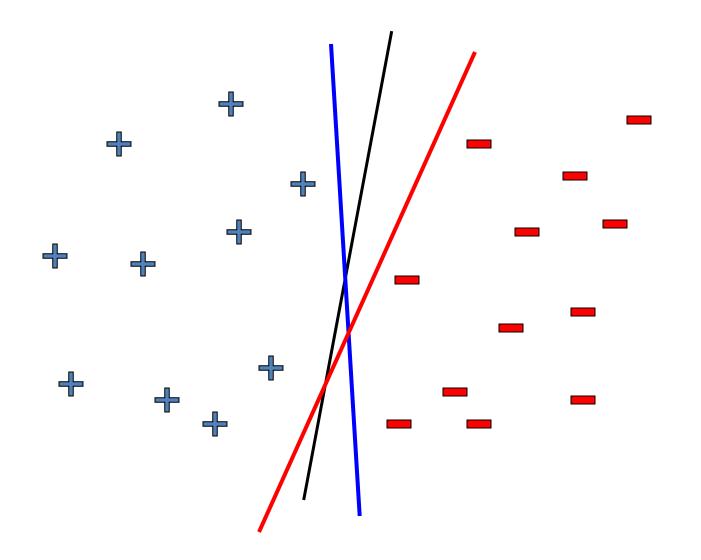




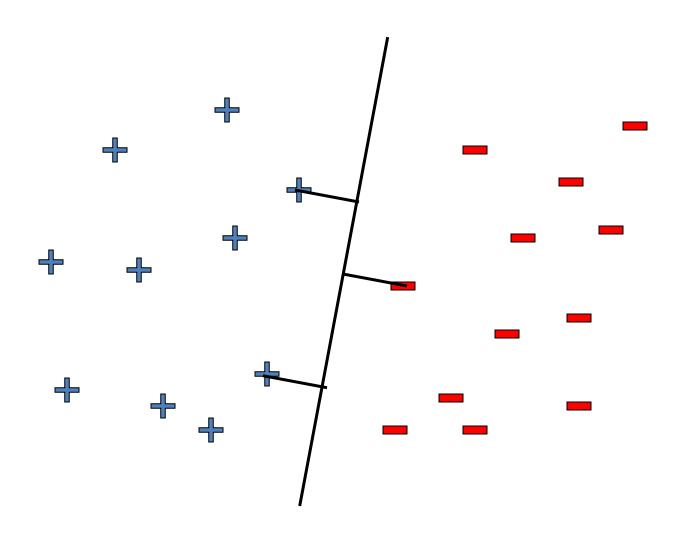
## At Pittsburgh G-20 summit ...



## Linear classifiers – which line is better?



## Pick the one with the largest margin!



## Parameterizing the decision boundary

$$\mathbf{w}.\mathbf{x} = \sum_{j} \mathbf{w}^{(j)} \mathbf{x}^{(j)} \quad \mathbf{w}.\mathbf{x} + \mathbf{b} > 0$$

$$+ \quad \mathbf{w}.\mathbf{x} + \mathbf{b} < 0$$

$$+ \quad \mathbf{w}.\mathbf{x} + \mathbf{b} < 0$$

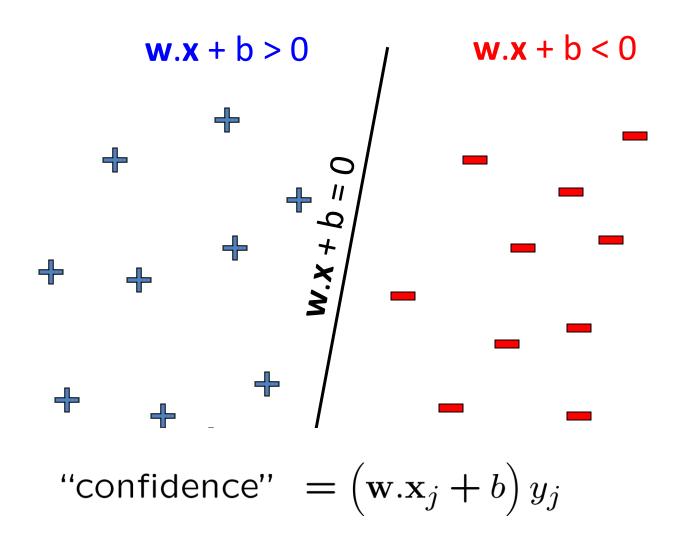
$$\left\langle x_i^{(1)},\dots,x_i^{(m)} \right
angle - m$$
 features  $y_i \in \{-1,+1\}$  — class

Data: 
$$\left\langle x_1^{(1)}, \dots, x_1^{(m)}, y_1 \right\rangle$$

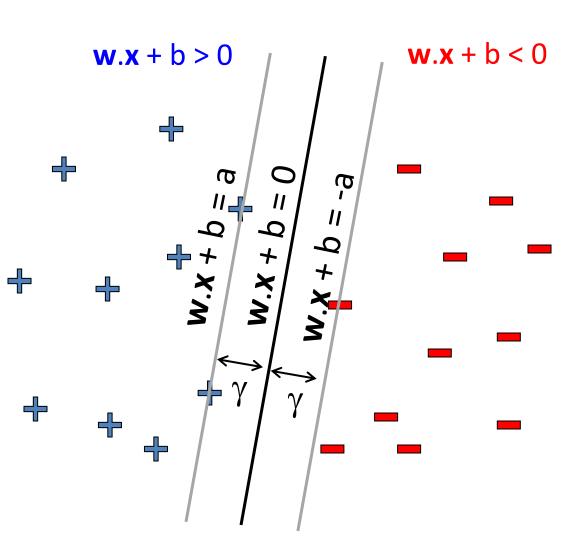
$$\vdots$$

$$\left\langle x_n^{(1)}, \dots, x_n^{(m)}, y_n \right\rangle$$

## Parameterizing the decision boundary



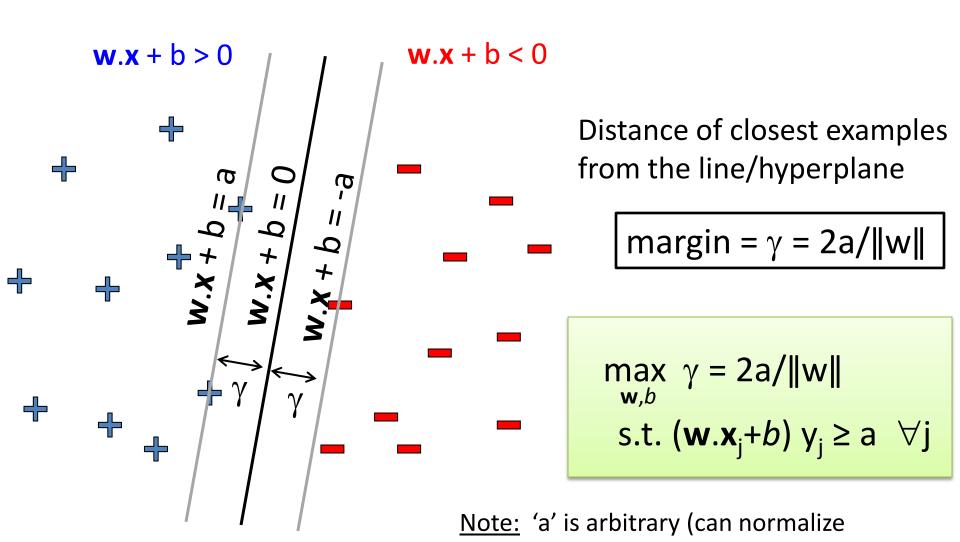
## Maximizing the margin



Distance of closest examples from the line/hyperplane

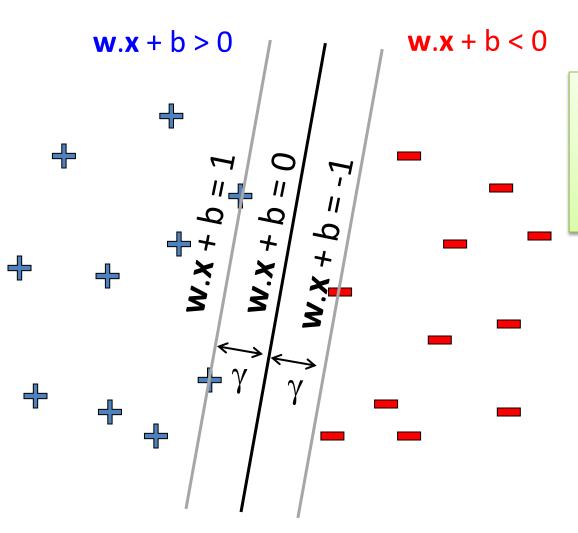
margin = 
$$\gamma$$
 = 2a/ $\|w\|$ 

## Maximizing the margin



equations by a)

## **Support Vector Machines**



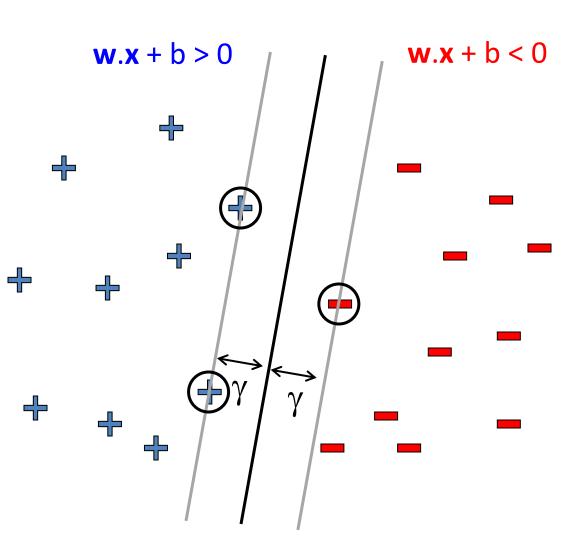
$$\min_{\mathbf{w},b} \mathbf{w}.\mathbf{w}$$
s.t.  $(\mathbf{w}.\mathbf{x}_j+b) \mathbf{y}_j \ge 1 \quad \forall j$ 

Solve efficiently by quadratic programming (QP)

 Well-studied solution algorithms

Linear hyperplane defined by "support vectors"

## **Support Vectors**



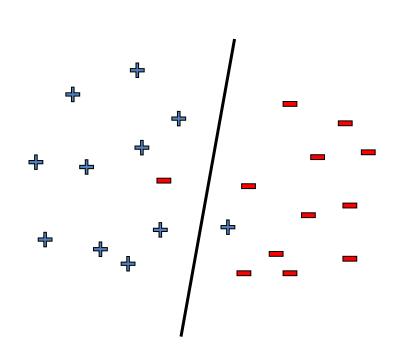
Linear hyperplane defined by "support vectors"

Moving other points a little doesn't effect the decision boundary

only need to store the support vectors to predict labels of new points

How many support vectors in linearly separable case?

## What if data is not linearly separable?



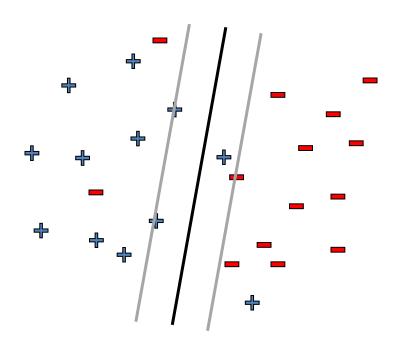
## Use features of features of features of features....

$$x_1^2, x_2^2, x_1x_2, ...., exp(x_1)$$

But run risk of overfitting!

# What if data is still not linearly separable?

Allow "error" in classification



min 
$$\mathbf{w}.\mathbf{w} + C$$
 #mistakes s.t.  $(\mathbf{w}.\mathbf{x}_j+b)$   $\mathbf{y}_j \ge 1 \quad \forall j$ 

Maximize margin and minimize # mistakes on training data

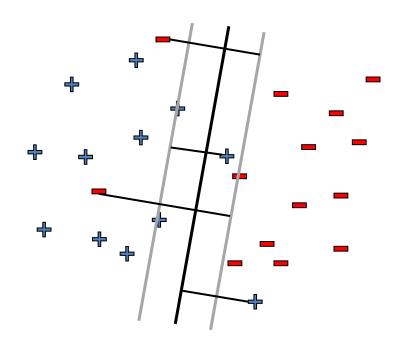
C - tradeoff parameter

Not QP ⊗

0/1 loss (doesn't distinguish between near miss and bad mistake)

## What if data is still not linearly separable?

Allow "error" in classification



Soft margin approach

$$\min_{\mathbf{w},b} \mathbf{w}.\mathbf{w} + C \sum_{j} \xi_{j}$$
s.t.  $(\mathbf{w}.\mathbf{x}_{j}+b) y_{j} \ge 1-\xi_{j} \quad \forall j$ 

$$\xi_{j} \ge 0 \quad \forall j$$

 $\xi_j$  - "slack" variables = (>1 if  $x_j$  misclassifed) pay linear penalty if mistake

C - tradeoff parameter (chosen by cross-validation)

## Slack variables – Hinge loss

#### Complexity penalization

$$\xi_j = \operatorname{loss}(f(x_j), y_j)$$



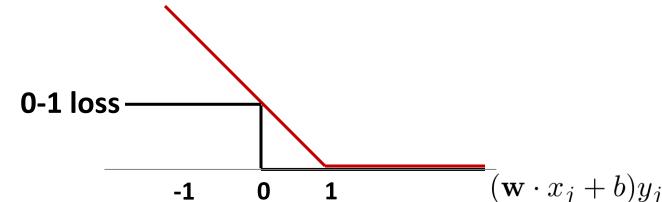
$$f(x_j) = \operatorname{sgn}(\mathbf{w} \cdot \mathbf{x_j} + \mathbf{b})$$

$$\min_{\mathbf{w},b} \mathbf{w}.\mathbf{w} + C \sum_{j} \xi_{j}$$
s.t.  $(\mathbf{w}.\mathbf{x}_{j}+b) y_{j} \ge 1-\xi_{j} \quad \forall j$ 

$$\xi_{j} \ge 0 \quad \forall j$$

$$\xi_j = (1 - (\mathbf{w} \cdot x_j + b)y_j))_+$$

#### **Hinge loss**



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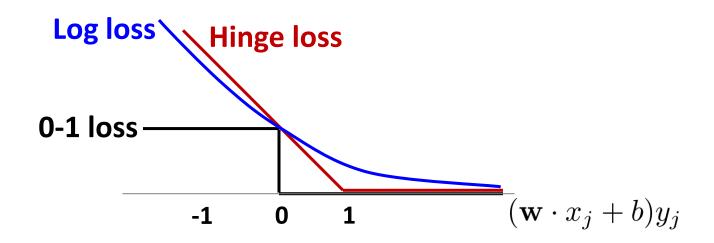
## **SVM vs. Logistic Regression**

#### **SVM**: **Hinge loss**

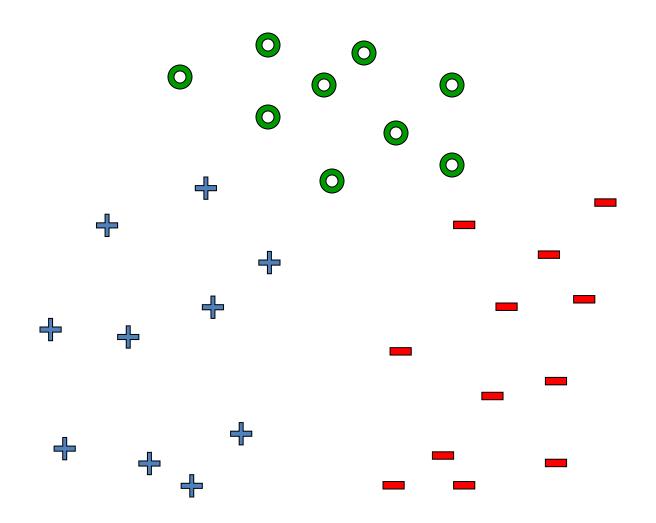
$$loss(f(x_j), y_j) = (1 - (\mathbf{w} \cdot x_j + b)y_j))_+$$

Logistic Regression: Log loss (-ve log conditional likelihood)

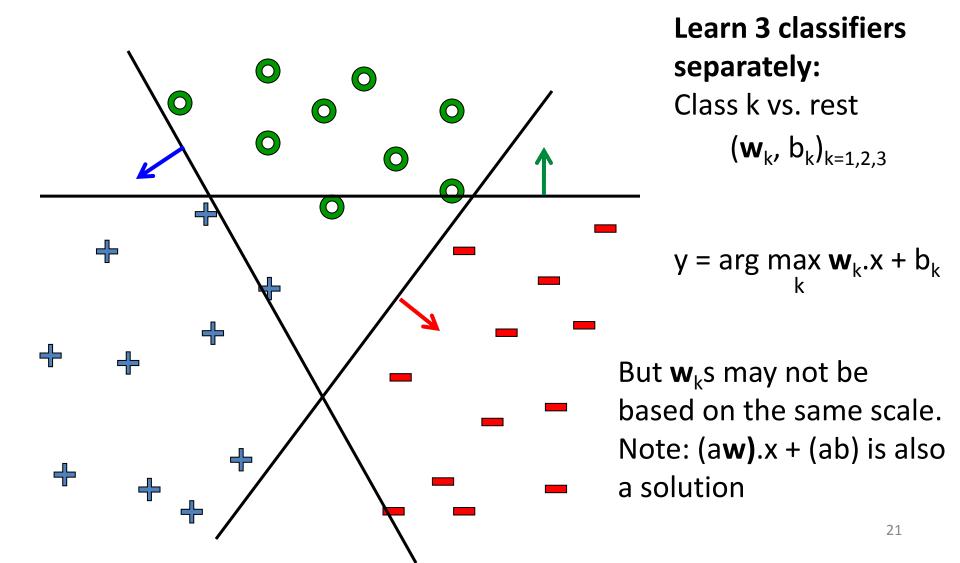
$$loss(f(x_j), y_j) = -\log P(y_j \mid x_j, \mathbf{w}, b) = \log(1 + e^{-(\mathbf{w} \cdot x_j + b)y_j})$$



## What about multiple classes?



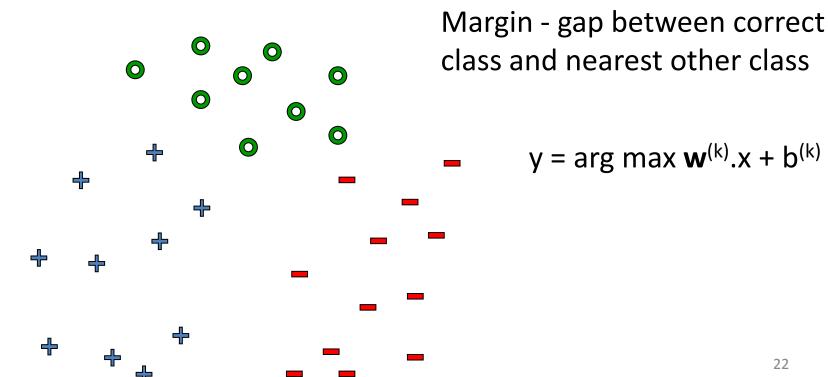
## One against all



## Learn 1 classifier: Multi-class SVM

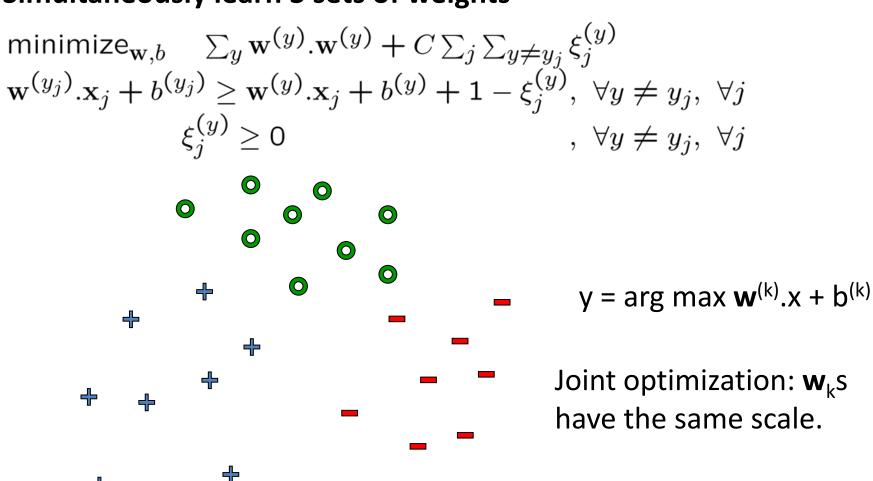
#### Simultaneously learn 3 sets of weights

$$\mathbf{w}^{(y_j)}.\mathbf{x}_j + b^{(y_j)} \ge \mathbf{w}^{(y')}.\mathbf{x}_j + b^{(y')} + 1, \ \forall y' \ne y_j, \ \forall j$$



## Learn 1 classifier: Multi-class SVM

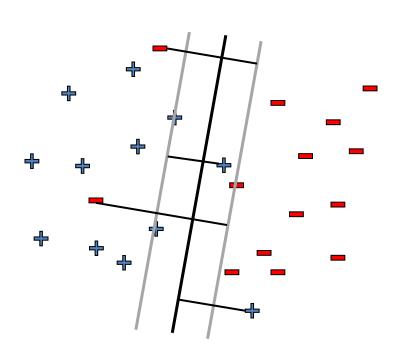
#### Simultaneously learn 3 sets of weights



## What you need to know

- Maximizing margin
- Derivation of SVM formulation
- Slack variables and hinge loss
- Relationship between SVMs and logistic regression
  - -0/1 loss
  - Hinge loss
  - Log loss
- Tackling multiple class
  - One against All
  - Multiclass SVMs

## **SVMs** reminder



#### Regularization Hinge loss

$$\min_{\mathbf{w},b} \mathbf{w} \cdot \mathbf{w} + C \Sigma \xi_{j}$$

$$\text{s.t.} (\mathbf{w} \cdot \mathbf{x}_{j} + b) y_{j} \ge 1 - \xi_{j} \quad \forall j$$

$$\xi_{j} \ge 0 \quad \forall j$$

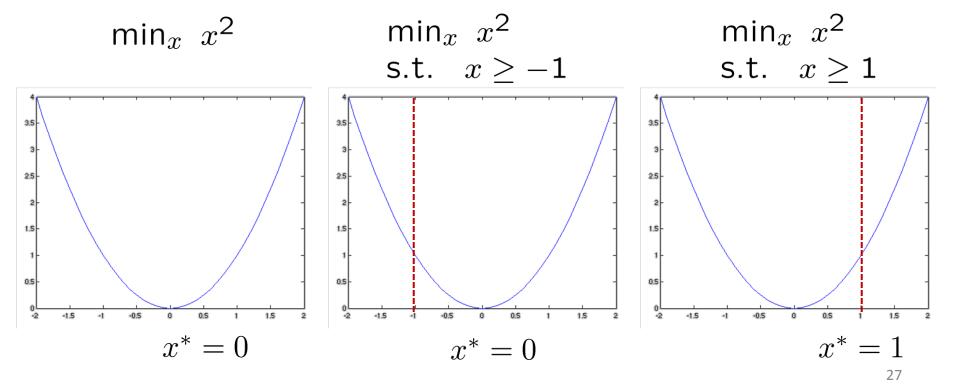
Soft margin approach

## **Today's Lecture**

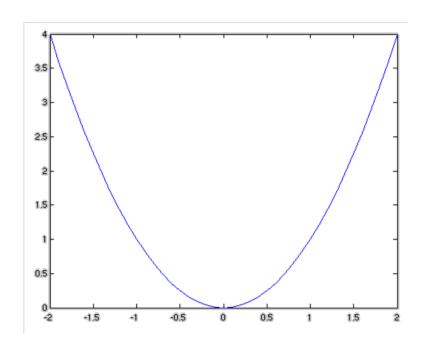
- Learn one of the most interesting and exciting recent advancements in machine learning
  - The "kernel trick"
  - High dimensional feature spaces at no extra cost!
- But first, a detour
  - Constrained optimization!

## **Constrained Optimization**

 $\min_{x} x^{2}$  s.t.  $x \ge b$ 



## **Lagrange Multiplier – Dual Variables**



$$\min_x x^2$$
 s.t.  $x > b$ 

Moving the constraint to objective function Lagrangian:

$$L(x, \alpha) = x^2 - \alpha(x - b)$$
  
s.t.  $\alpha \ge 0$ 

Solve:

$$\min_x \max_{\alpha} \ L(x, \alpha)$$
 s.t.  $\alpha \geq 0$ 

Constraint is tight when  $\alpha > 0$ 

## Duality

#### Primal problem:

$$f^* = \min_x x^2$$
s.t.  $x \ge b$ 

Dual problem:

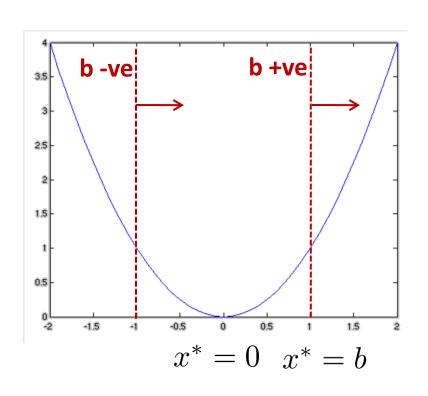
$$f^* = \min_x x^2 \qquad g^* = \min_x \max_\alpha x^2 - \alpha(x - b)$$
 s.t.  $x \ge b$  s.t.  $\alpha \ge 0$ 

## Weak duality – $g^* < f^*$

For all feasible points 
$$\tilde{x}$$
  $g^* \leq g(\tilde{x}) \leq f(\tilde{x})$ 

Strong duality – 
$$q^* = f^*$$
 (holds under KKT conditions)

## **Lagrange Multiplier – Dual Variables**



Solving: 
$$\min_x \max_{\alpha} x^2 - \alpha(x-b)$$
 s.t.  $\alpha \geq 0$ 

$$\frac{\partial L}{\partial x} = 0 \qquad \Rightarrow x^* = \frac{\alpha}{2}$$

$$\frac{\partial L}{\partial \alpha} = 0 \qquad \Rightarrow \alpha^* = \max(2b, 0)$$

When  $\alpha$  > 0, constraint is tight