Operating System Structure

Joey Echeverria joey42+os@gmail.com

modified by: Matthew Brewer mbrewer@andrew.cmu.edu

modified by: Robert Strickland rstrickl@andrew.cmu.edu

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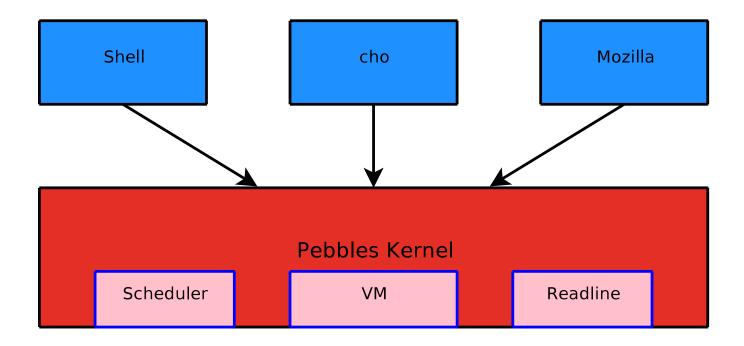
Overview

- Motivations
- Kernel Structures
 - Monolithic Kernels
 - Open Systems
 - Microkernels
 - Provable Kernel Extensions
 - Exokernels
 - More Microkernels
- Summary

Motivations

- Operating systems have 3 hard jobs:
 - 1. Protection boundaries
 - Enforce access policies
 - Highly Complex!
 - 2. Abstraction layers
 - Present a "simple", "uniform" interface to hardware
 - Examples: block devices, CD drives, tty, filesystem, network stack
 - 3. Hardware multiplexing
 - Process Abstraction
 - Resource Allocation
- What framework should we use?

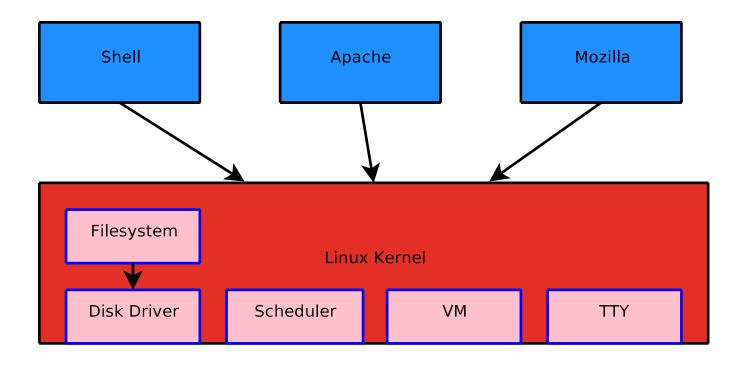
Pebbles Kernel



Pebbles Kernel

- Syscalls ≈ 23
 - fork(), exec(), cas2i_runflag(), yield()
- Lines of trusted code ≈ 2000 to 24000

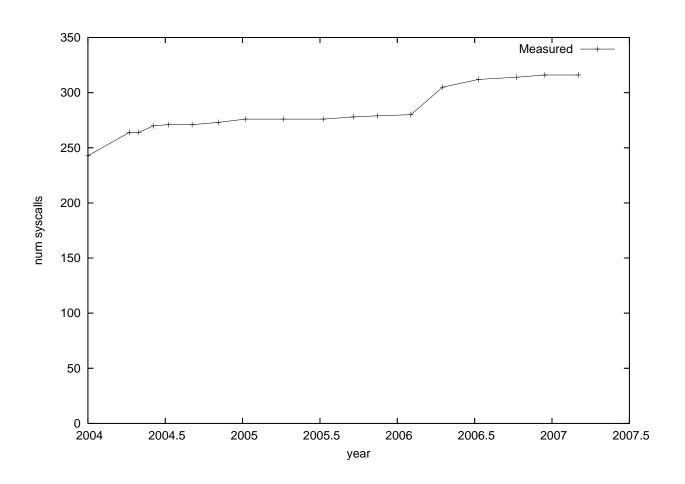
Linux Kernel



Linux Kernel

- Syscalls: ≈ 281 on "Andrew Linux", and increasing fast
 - fork(), exec(), read(), readdir(), ioctl()
- Lines of trusted code $\approx 8-9$ million currently
 - $-\approx 200,000$ are just for USB drivers
 - $-\approx 15,000$ for USB core alone
- Caveats Many archs/subarchs, every driver EVER

Linux System Calls



Monolithic Kernels

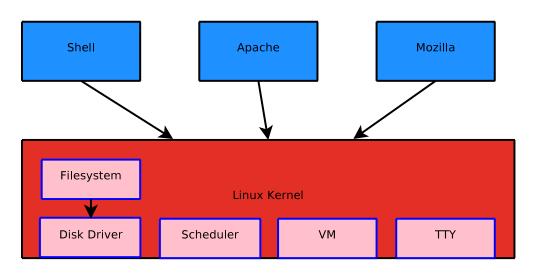
- Examples: UNIX, Mac OS X, Windows XP/Vista, Linux, BSD, i.e., common
- Advantages:
 - + Well understood
 - + Good performance
 - + High level of protection between applications
- Disadvantages:
 - No protection between kernel components
 - LOTS of code is in kernel
 - Not (very) extensible

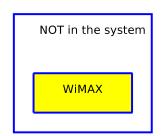
Kernel Extensions

- Problem Bob has a WiMAX card
 - He wants a WiMAX driver
 - No one else wants a (large, unstable) WiMAX driver
- Solution loadable kernel modules!
 - Special binaries compiled with kernel
 - Can be loaded at run-time so we can have LOTS of them
 - Can break kernel, so loadable only by root
- done in: VMS, Windows NT, Linux, BSD, OS X

WiMAX Example

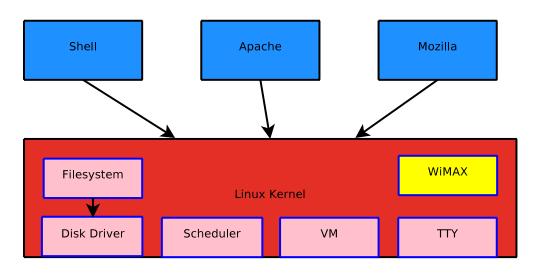
Linux Kernel





WiMAX Example

Linux Kernel with WiMAX module



NOT in the system

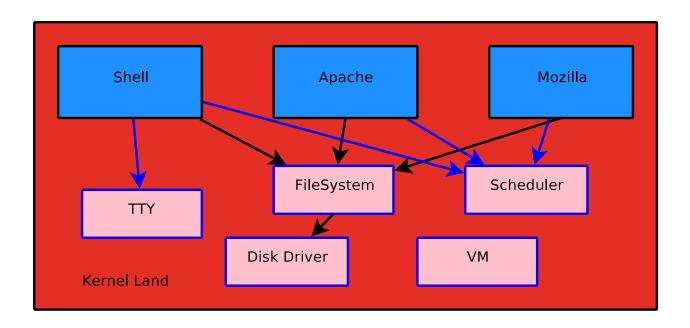
Kernel Extensions

- Advantages
 - + Can extend kernel
 - + Extensions run FAST
- Disadvantages
 - Adding things to kernel can break it
 - Have to ask sysadmin nicely
 - Adds a lot of trusted code
- Protection overhead: system call, address spaces

Open Systems

- Everything in kernel mode!
 - No system calls
 - All code is implicitly trusted
- Everything in one address space!
 - Applications, libraries, and kernel can see each other
 - No context switching
- Used to be *very* common
 - MS-DOS, Mac OS 9 and prior, Windows ME, 98, 95, 3.1, etc, Palm OS,
 Some embedded systems

No Protection!



Open Systems

Advantages:

- + *Very* good performance
- + Very extensible
 - * Undocumented Windows, Schulman et al. 1992
 - * In the case of Mac OS and Palm OS there's an extensions industry
- + Lack of abstractions makes realtime systems easier

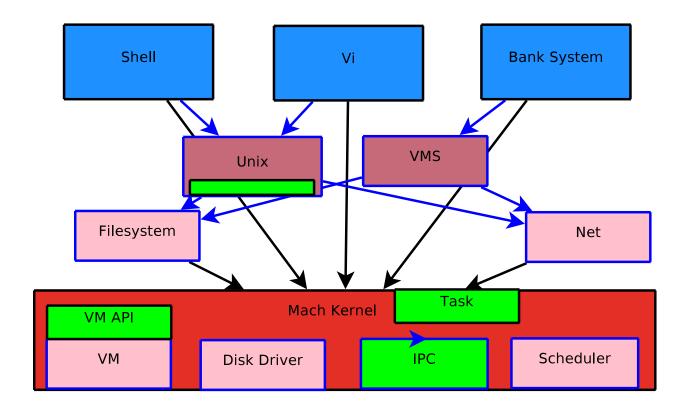
• Disadvantages:

- No protection, and therefore not particularly stable
- Cannot support multiple users
- Composing extensions can result in unpredictable behavior

Microkernels

- Replace the monolithic kernel with a "small, clean, logical" set of abstractions
 - Tasks
 - Threads
 - Virtual Memory
 - Interprocess Communication
- Move the rest of the OS into server processes

Mach Vision



Mach

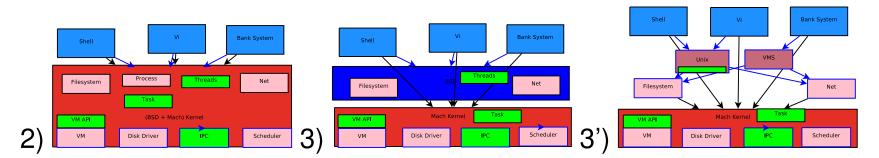
- Syscalls: initially 92, increased slightly later
 - msg_send, port_status, task_resume, vm_allocate
- Lines of trusted code $\approx 484,000$ (Hurd version)
- Caveats several archs/subarchs, some drivers

Mach

Started as a project at CMU (based on RIG project from Rochester)

Plan

- 1. Mach 2: Take BSD 4.1 add VM API, IPC, SMP, and threading support
- 2. Mach 3: saw kernel in half and run as "single-server"
- 3. Mach 3 continued: decompose single server into smaller servers



Mach Results

- 1. Mach 2 completed in 1989
 - Used for Encore, Convex, NeXT, and subsequently OS X
 - success!
- 2. Mach 3 Finished(ish)
 - Mach 2 split in 2
 - Ran on a few systems at CMU, and a few outside
- 3. Mach 3 continued
 - Multi-server systems: Mach-US, OSF
 - Never deployed

Mach 3 (Microkernel)

Advantages:

- + Strong protection (even from itself)
- + Untrusted system services (user-space filesystem... see Hurd)

Disadvantages:

- Performance
 - * It looks like extra context switches and copying would be expensive
 - * Mach 3 ran slow in experiments
 - * Kernel still surprisingly large "It's not micro in size, it's micro in functionality"
 - * Still hasn't REALLY been tried

Mach

- Remember, Mach 3 == microkernel, but Mach 2 == monolithic
- Code ran slow at first, then everyone graduated
- Proved microkernel is feasible
- Stability/Speed of seperation both unproven

Other Microkernels

- From Mach period
 - QNX, competes with VxWorks as a realtime OS
 - ChorusOS, realtime kernel out of Europe, now open sourced by Sun
- Modern
 - Symbian (sort of), OS on many smart phones
 - L4 (discussed later)
 - Xen, VMware ...

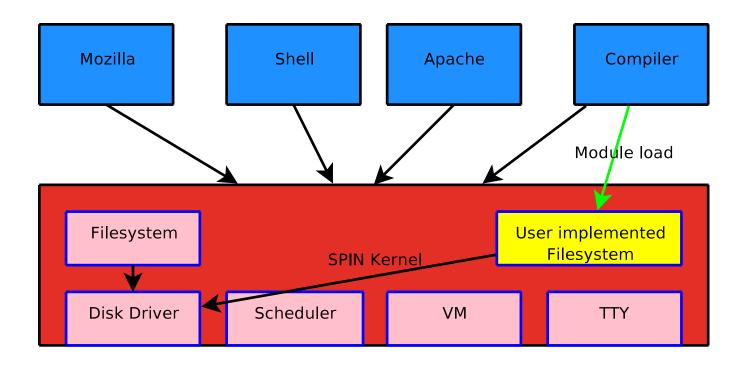
"Hypervisors"

- Why not run multiple operating systems?
- IBM Workplace OS (Mach 3.0)
 - * one kernel for OS/2, OS/400, and AIX
 - * failure
- Call it a "hypervisor" idea is rather popular again
 - * Xen, VMware

More Options?

- We want an extensible OS
- We want extensions to run fast, but be safe for addition by users
- Assume we don't like microkernels (slow, more code, whatever)
- So... other ideas?

Provable Kernel Extensions

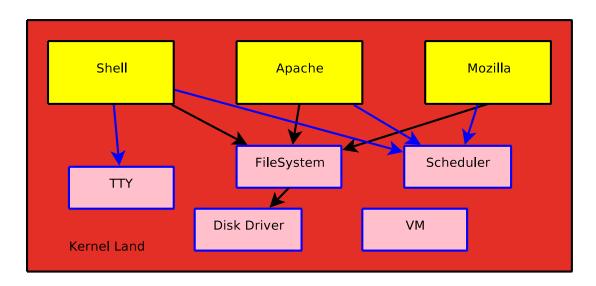


Provable Kernel Extensions

- PROVE the code does what we want
- Checker can be EXTREMELY conservative and careful about what it lets in
 - Interepreter safety (CMU: Acceta)
 - Compiler-checked source safety (UW: Spin: Modula-3)
 - Kernel-verified binary safety (CMU: Proof-carrying code)
 - * More language agnostic just need a compiler that compiles to PCC
- Safe? Guaranteed (if compiler is correct... same deal as a kernel)

Provable Kernel Extensions

What if *x* were a proven kernel extension?



Provable Everything

- What if ALL code was loaded into the "kernel" and just proved to do the "right" thing?... Is this silly, or a good idea?
 - Looks a lot like Open Systems
 - Except compiler can enforce more stability
- Effectiveness strongly dependent on quality of proofs
- Some proofs are HARD, some proofs are IMPOSSIBLE!
- Actual Work: groundwork being done here, MSR's "Singularity" take this as you will

Provable Everything

Advantages:

- + Extensible even by users, just add a new extension/application
- + Safe, provably so
- + Good performance because everything is in the kernel

Disadvantages:

- Proofs are hard and checking can be slow
- We can't actually DO this for interesting code (yet?)
- Constrained implementation language
- Constraints may cause things to run slower than protection boundaries
- Still very limited in scope, not used widely

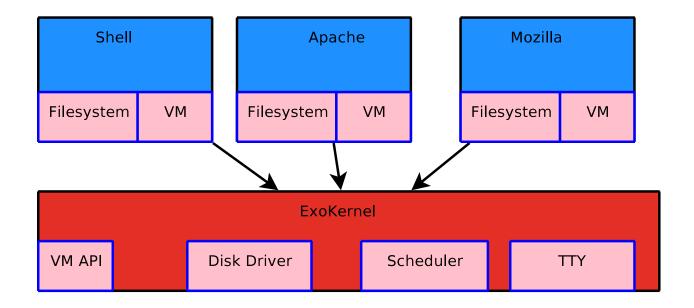
More Options?

- Monolithic kernel
 - Too many abstractions can get in the way
 - Not easily extensible for every application (special kernel mods)
- Microkernel
 - Maybe Mach is still too much kernel?
 - Too heavy an abstraction, too portable, just too much
- Proof systems
 - Useful proof checkers are large & still can't do everything
- If applications control system, can optimize for their usage cases

Exokernels

- Basic idea: Take the operating system out of the kernel and put it into libraries
- Why? Applications know better how to manage active hardware resources than kernel writers do
- Safe? Exokernel is simply a hardware multiplexer, and thus a permissions boundary.
- Separates the security and protection from the management of resources

Xok / ExOS



Xok

Xok (MIT's eXOKernel)

- Syscalls ≈ 120
 - insert_pte, pt_free, quantum_set, disk_request
- Lines of trusted code $\approx 100,000$
- Caveats One arch, few/small drivers

VM Example

- There is no fork()
- There is no exec()
- There is no automatic stack growth
- Exokernel keeps track of physical memory pages
 Assigns them to an application on request
 - Application (via syscall):
 - 1. Requests frame
 - 2. Requests map of Virtual → Physical

Example: simple fork()

- fork():
 - Acquire a new, blank address space
 - Allocate some physical frames
 - Map physical pages into blank address space
 - Copy bits (from us) to the target, blank address space
 - Allocate a new thread and bind it to the address space
 - Fill in new thread's registers and start it running
- The point is that the kernel doesn't provide fork()

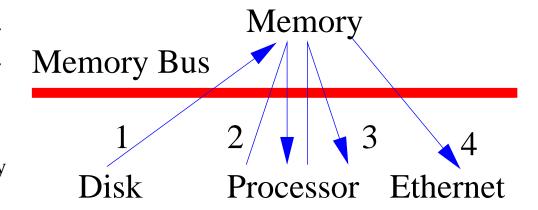
Example: COW fork()

- fork(), advanced:
 - Acquire a new, blank address space
 - Ask kernel to set current space's mappings to R/O
 - Map current space's physical pages R/O into blank space
 - Update copy-on-write table in each address space
 - Application's page-fault handler (like a signal handler) copies/re-maps
- Each process can have its own fork() optimized for it or none at all

- In a typical web server the data must go from:
 - 1. the disk to kernel memory, read()
 - 2. kernel memory to user memory, memcpy()
 - 3. user memory back to kernel memory memcpy()
 - 4. kernel memory to the network device write()
- In an exokernel, the application can have the data go straight from disk to the network interface

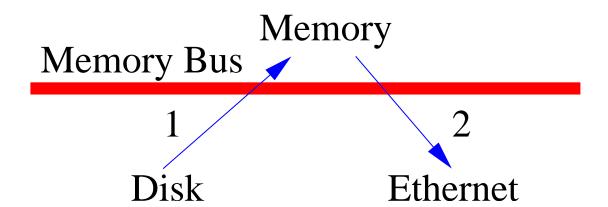
Traditional kernel and web server:

- 1. read() copy from disk to kernel buffer
- 2. read() copy from kernel to user buffer
- 3. send() user buffer to kernel buffer
 - -- data is check-summed
- 4. send() kernel buffer to device memory



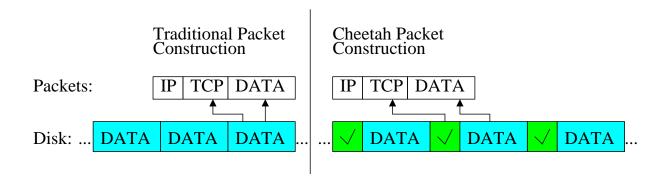
That is: six bus crossovers

- Exokernel and Cheetah:
 - 1. Copy from disk to memory
 - 2. Copy from memory to network device

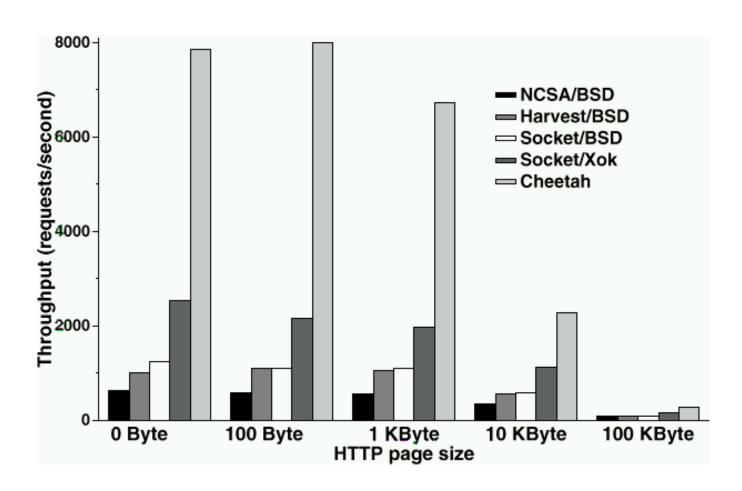


That is: two bus crossovers

- Exokernel and Cheetah:
 - "File system" doesn't store files, stores packet-body streams
 - * Data blocks are collocated with pre-computed data checksums
 - Header is finished when the data is sent out, taking advantage of the ability of TCP check-sums to be "patched"
 - This saves the system from recomputing a check-sum, saves processing power



Exokernels: Cheetah Performance



Exokernels

Advantages:

- + Extensible: just add a new "operating system library"
- + Fast?: Applications intimately manage hardware, no obstruction layers
- + Safe: Exokernel allows safe sharing of resources

• Disadvantages:

- To take advantage of Exo, basically writing an OS for each app
- Nothing about moving an OS into libraries makes it easier to write
- Slow?: Many many small syscalls instead of one big syscall
- send_file(2) Why change when you can steal?
- Requires policy: despite assertions to the contrary

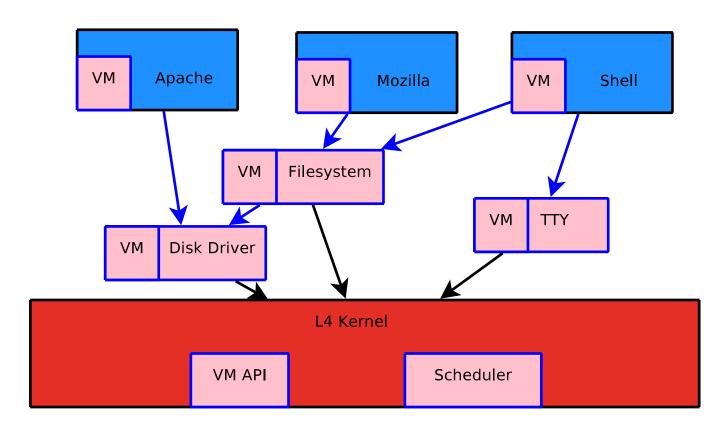
Exokernels

- Xok development is mostly over
- Torch has been passed to L4

Exokernels

- In practice Exokernels still have some abstractions
- Exokernel still missing some abstractions that seem necessary
- Then what do we need?
- The RIGHT set of minimal abstractions (IPC, and VM API)

More Microkernels (L4)



L4

- Syscalls < 20
 - memory_control, start_thread, IPC (send/recv on stringItem, Fpage)
- Lines of trusted code $\approx 37,000$
- Caveats one arch, nearly no drivers (though none necessary)

L4

- Idea: a truly minimal kernel
 - Minimal VM abstraction (protection domains)
 - Processor multiplexing (avoiding DDOS)
 - Synchronous IPC (not Mach IPC™)
- Everything else in userland
 - Kernel lacks device drivers, so we can have untrusted ones
 - like Exo: implement OS in libraries for mere abstractions
 - * Fork, Exec, Filesystem Interface, VM interface
 - new: Implement OS in processes for required protection
 - * Filesystem, Global Namespace, Device Drivers
 - For fun and profit: http://os.inf.tu-dresden.de/L4/

Microkernel OS'n (GNU Hurd Project)

GNU Hurd Project:

- Hurd stands for 'Hird of Unix-Replacing Daemons' and Hird stands for 'Hurd of Interfaces Representing Depth'
- GNU Hurd is the FSF's kernel (Richard M Stallman)
- Work began in 1990 on the kernel, has run on 10's of machines
- Hurd/Mach vaguely runs, so abandoned in favor of Hurd/L4
- Hurd/L4 suspended after two particular OS TAs tried to write their IPC layer.
- Ready for mass deployment Real Soon Now™(comment circa 2006)

Microkernel OS'n (L4Linux, DROPS)

- L4Linux run Linux on L4
 - You get Linux, but a bit slower
 - You get multiple Linux's at a time
 - You get a realtime microkernel too
- DROPS a realtime OS for L4
 - Realtime, and minimal
 - No security
- Combine the two for a realtime OS and linux... (mostly dead)

L4

Advantages:

- + Fast as hypervisor, similar to Mach (L4Linux 4% slower than Linux)
- + VERY good separation (if we want it)
- + Supports multiple OS personalities (hypervisor)
- + Soft realtime

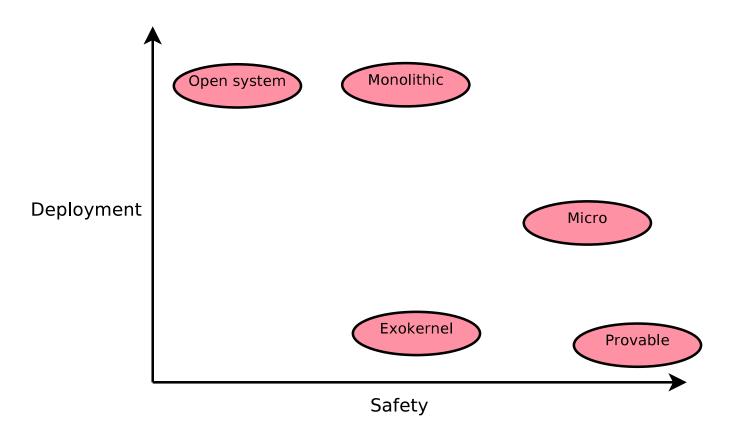
Disadvantages:

- Recreated much of Mach, but smaller, entails same problems
- Still notable missing abstraction: capabilities (more on this later)
- No Micro-OS written for it with protection boundaries
- Still untested with a multiserver topology

Microkernel OS'n

- The literature has between 5 and 50 percent overhead for microkernels
 - See The Performance of μ-Kernel-Based Systems
 - * http://os.inf.tu-dresden.de/pubs/sosp97/

Summing Up



Summing Up

- So why don't we use microkernels or something similar?
- Say we have a micro-(or exo)-kernel, and make it run fast
 - We describe things we can do in userspace faster (like Cheetah)
 - Monolithic developer listens intently
 - Monolithic developer adds functionality to his/her kernel (send_file(2))
 - Monolithic kernel again runs as fast or faster than our microkernel
- So, if monolithic kernel runs as fast, why bother porting to new OS?
 - Stability new device drivers break Linux often, we use them anyway
 - The story above can get painful, hard to write, hard to debug

Summing Up

What's the moral?

- There are many ways to do things
- Many of them even work

Further Reading

- Jochen Liedtke, On Micro-Kernel Construction
- Willy Zwaenepoel, Extensible Systems are Leading OS Research Astray
- Michael Swift, Improving the Reliability of Commodity Operating Systems
- An Overview of the Singularity Project, Microsoft Research MSR-TR-2005-135
- Harmen Hartig, *The Performance of μ-Kernel-Based Systems*

Further Reading

CODE: (in no particular order)

- Minix (micro)
- Plan 9 (midsized)
- NewOS/Haiku (micro'ish)
- L4 pistachio (micro)
- Solaris (monolithic)
- (net/dragonfly)BSD (monolithic)