

Image filtering



Frequency domain

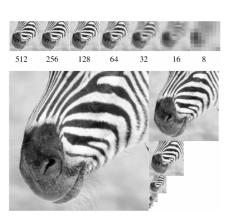


image pyramids

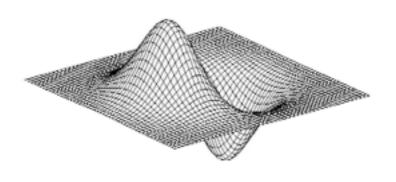
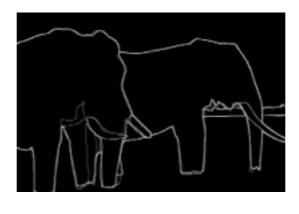
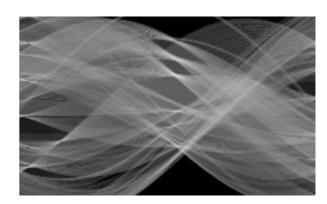


Image gradients



Boundaries



Hough Transform

Image Manipulation

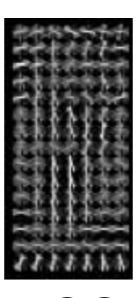




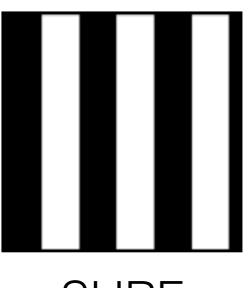
Corner detection Multi-scale detection



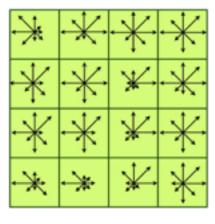
Haar-like



HOG



SURF

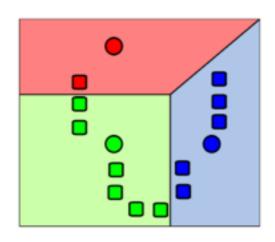


SIFT

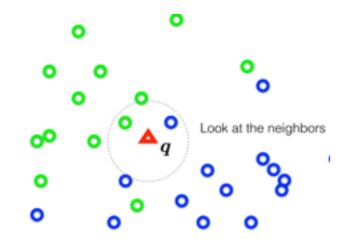
Image Features



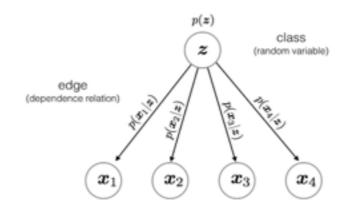
Bag-of-words



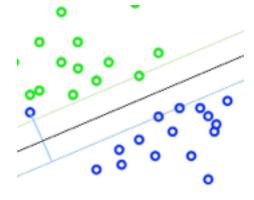
K-means



Nearest Neighbor



Naive Bayes



SVM

Object Recognition

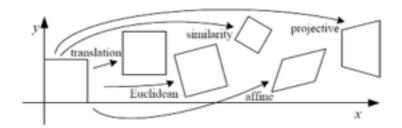


Figure 1: Basic set of 2D planar transformations

2D Transforms

DLT



RANSAC

2D Alignment

x = PX

P

X

camera matrix

pose estimation

triangulation

H

Potential matches for $oldsymbol{x}$ lie on the epipolar line $oldsymbol{l}'$



fundamental matrix

epipolar geometry

Reconstruction

2 view geometry



Block matching



Energy minimization

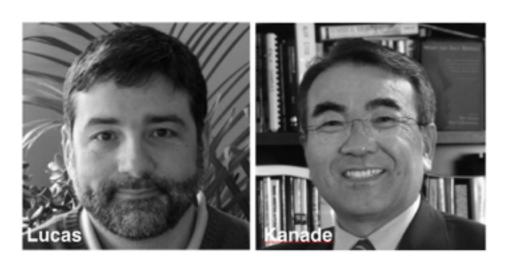
Stereo

$$\begin{bmatrix} I_x(\boldsymbol{p}_1) & I_y(\boldsymbol{p}_1) \\ I_x(\boldsymbol{p}_2) & I_y(\boldsymbol{p}_2) \\ \vdots & \vdots \\ I_x(\boldsymbol{p}_{25}) & I_y(\boldsymbol{p}_{25}) \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = -\begin{bmatrix} I_t(\boldsymbol{p}_1) \\ I_t(\boldsymbol{p}_2) \\ \vdots \\ I_t(\boldsymbol{p}_{25}) \end{bmatrix} \qquad \qquad \mathbf{min} \\ \boldsymbol{u}, \boldsymbol{v} \sum_{ij} \left\{ E_d(i,j) + \lambda E_s(i,j) \right\}$$

Constant Flow

Horn Schunck

Optical Flow



Lucas Kanade (Forward additive)



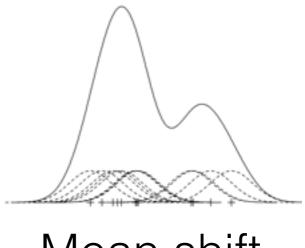


Baker Matthews (Inverse Compositional)

Image Alignment



KLT



Mean shift

Tracking

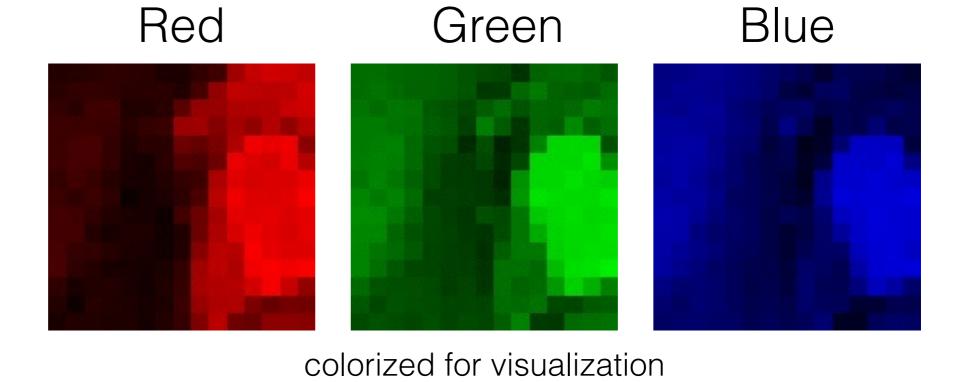


Image Filtering

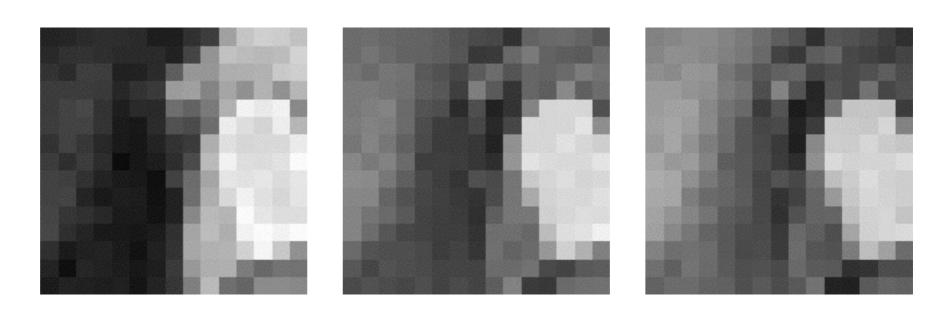
16-385 Computer Vision







color image patch



actual intensity values per channel (quantized to 256 values)

how many bits?

What kind of image transformations can we perform?

Filtering Warping

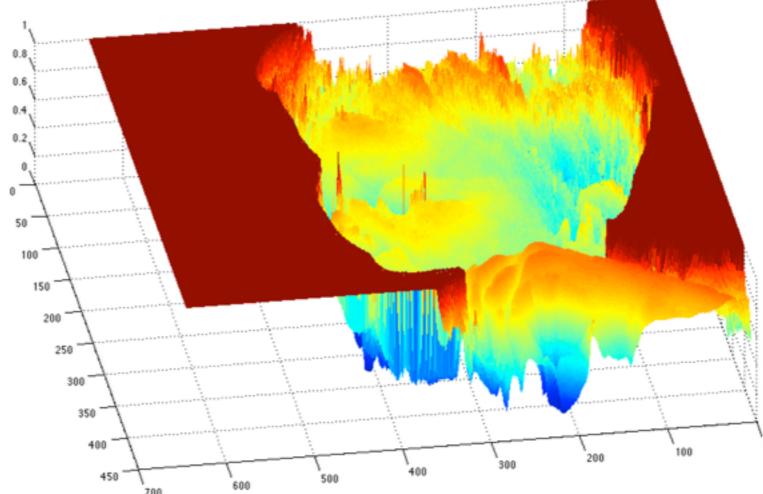
changes the pixel values

changes the pixel location

An image as a 2D function



$$f(x)$$
 $x = \begin{bmatrix} x \\ y \end{bmatrix}$

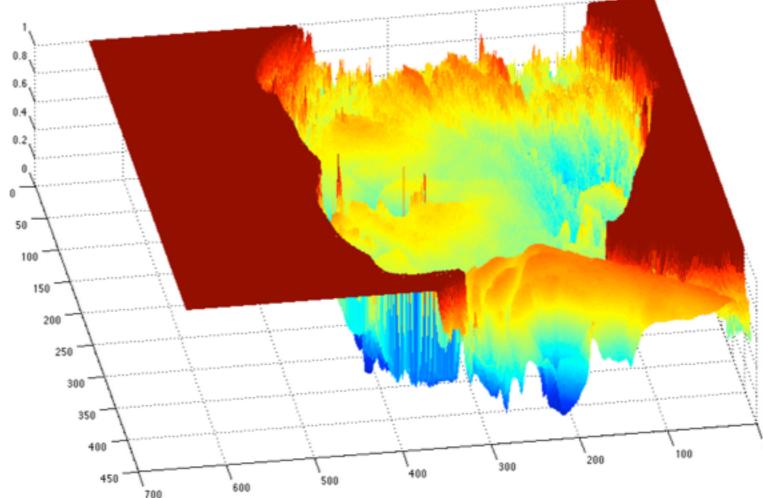


An image as a 2D function



What is the range of $f(oldsymbol{x})$?

$$f(x)$$
 $x = \begin{bmatrix} x \\ y \end{bmatrix}$



An image as a 2D function

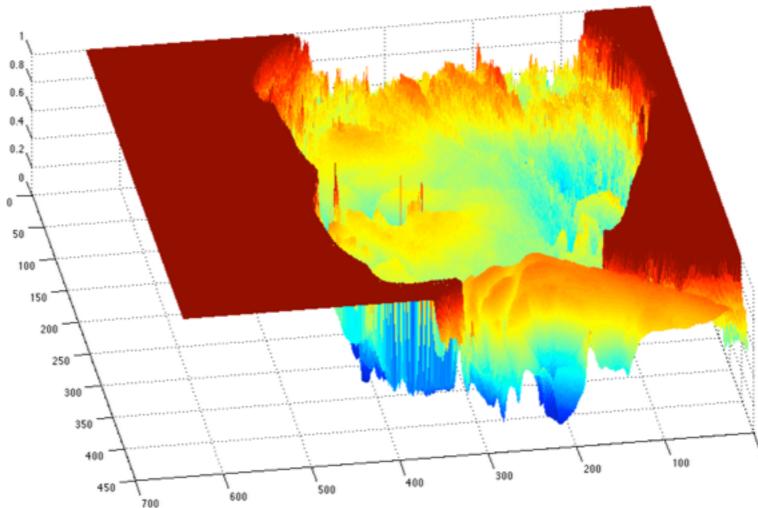


f(x)

 $oldsymbol{x} = \left| egin{array}{c} x \ y \end{array} \right|$

What is the range of $f(m{x})$?

8-bit image: 256 values



What kind of image transformations can we perform?

Filtering



$$G(\boldsymbol{x}) = h\{F(\boldsymbol{x})\}$$



changes the **range** of image

Warping



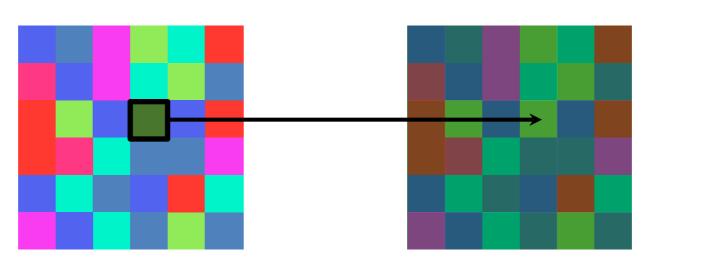
$$G(\boldsymbol{x}) = F(h\{\boldsymbol{x}\})$$



changes the **domain** of image

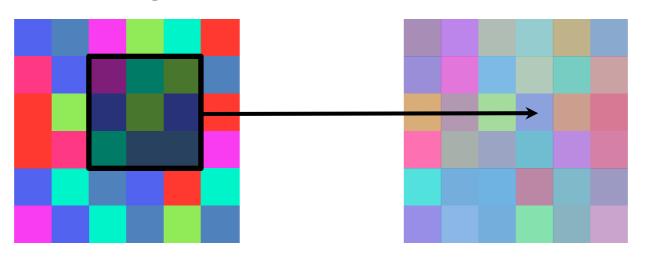
What kind of image filtering can we perform?

Point Operation



point processing

Neighborhood Operation

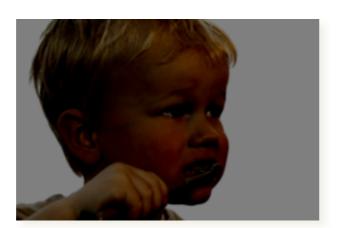


filtering

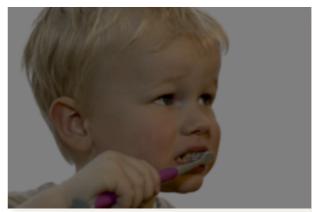
Examples of Point Processing







Darken



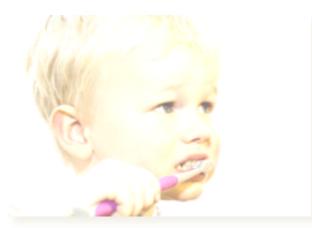
Lower Contrast



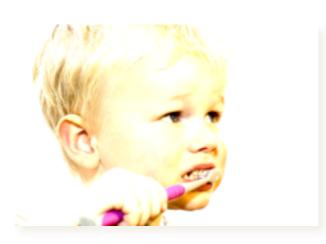
Nonlinear Lower Contrast



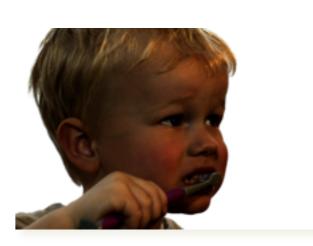
Invert



Lighten

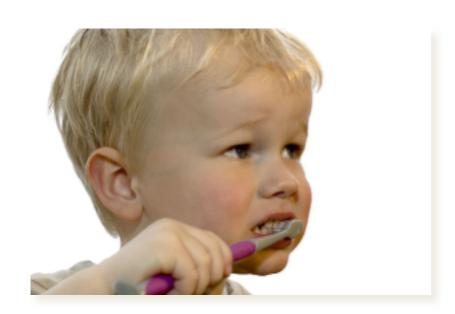


Raise Contrast

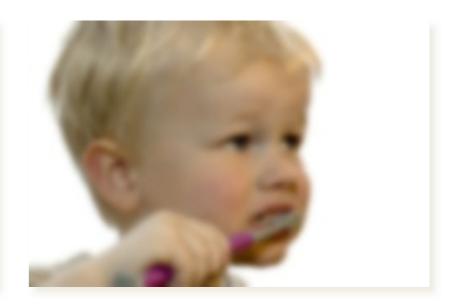


Nonlinear Raise Contrast

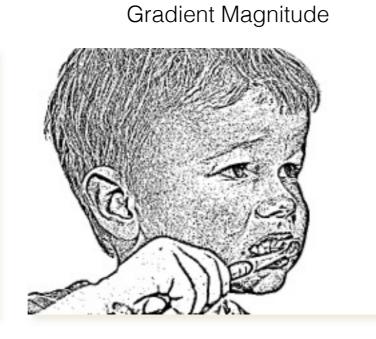
Examples of filtering







Original







Median

Adaptive Thresholding

Bilateral

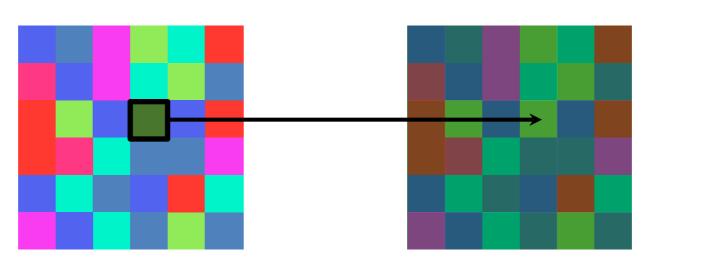


Point Processing

16-385 Computer Vision

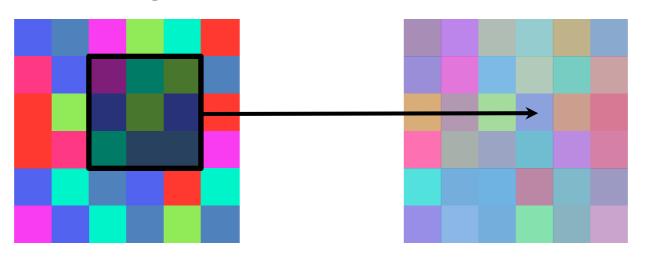
What kind of image filtering can we perform?

Point Operation



point processing

Neighborhood Operation



filtering

Original



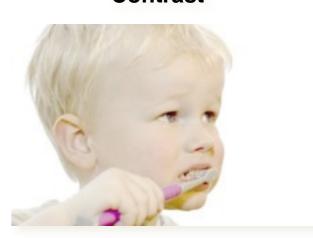
Darken



Lower Contrast



Nonlinear Lower Contrast

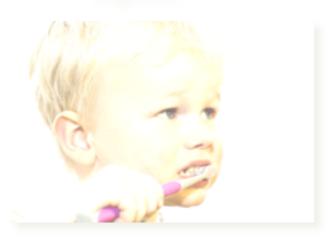


x pixel value

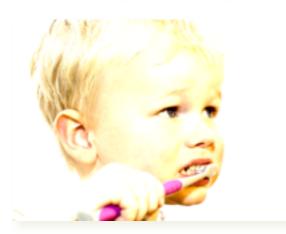
Invert



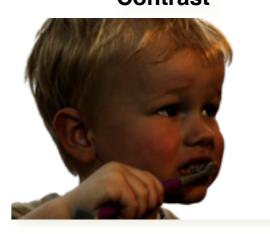
Lighten



Raise Contrast



Nonlinear Raise Contrast



Original

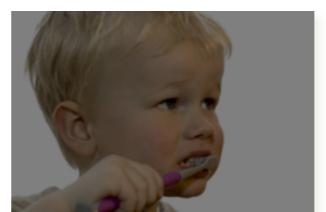


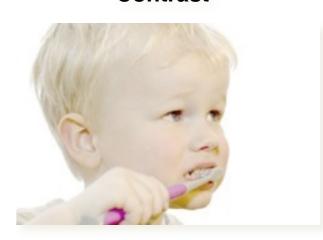
Lower Contrast

Nonlinear Lower Contrast









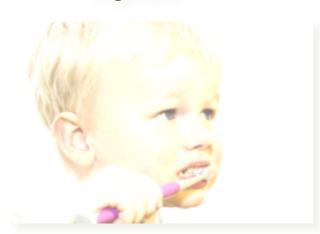
 \mathcal{X}

x-128 how would you code this?

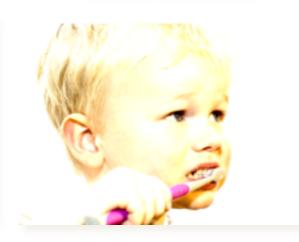
Invert



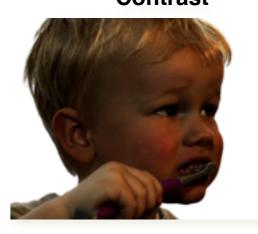
Lighten



Raise Contrast



Nonlinear Raise Contrast



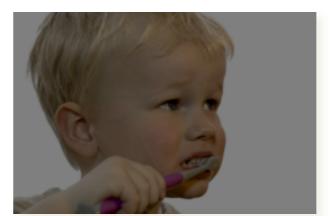


Lower Contrast

Nonlinear Lower Contrast









 \mathcal{X}

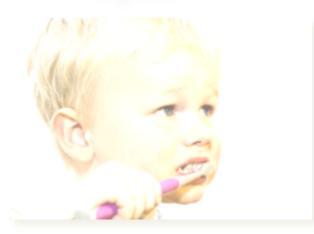
x - 128

 $\frac{x}{2}$

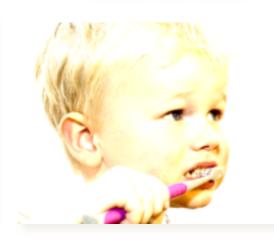
Invert



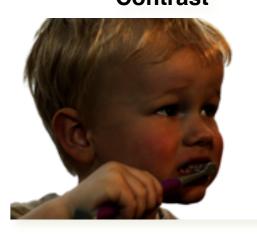
Lighten



Raise Contrast



Nonlinear Raise Contrast









Nonlinear Lower Contrast







 \mathcal{X}

x - 128

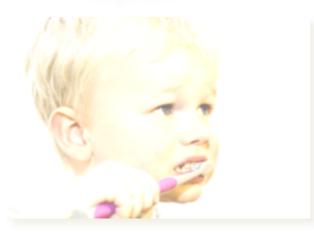
 $\frac{x}{2}$

 $\left(\frac{x}{255}\right)^{1/3} \times 255$

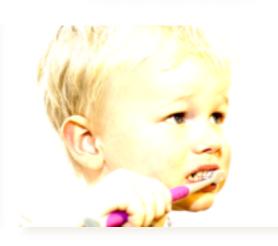
Invert



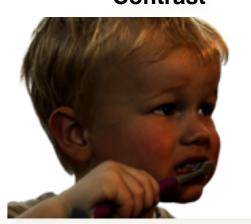
Lighten



Raise Contrast



Nonlinear Raise Contrast



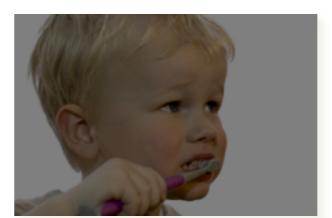


Lower Contrast

Nonlinear Lower Contrast









 \boldsymbol{x}

x - 128

 $\frac{x}{2}$

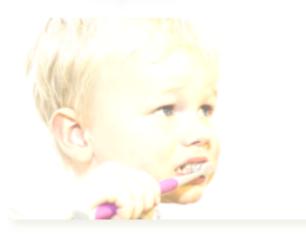
 $\left(\frac{x}{255}\right)^{1/3} \times 255$

Invert

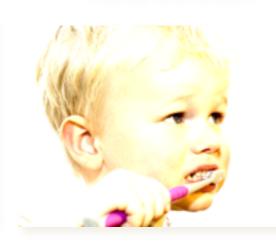




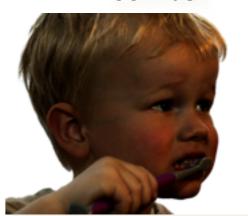
Lighten



Raise Contrast



Nonlinear Raise Contrast



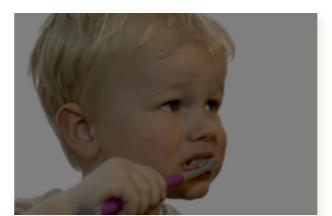


Lower Contrast

Nonlinear Lower Contrast









 \boldsymbol{x}

x - 128

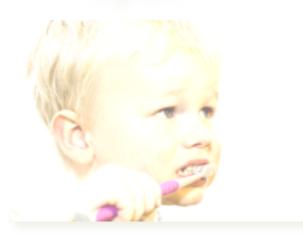
 $\frac{x}{2}$

 $\left(\frac{x}{255}\right)^{1/3} \times 255$

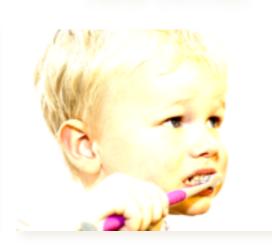
Invert



Lighten



Raise Contrast



Nonlinear Raise Contrast



255 - x

x + 128

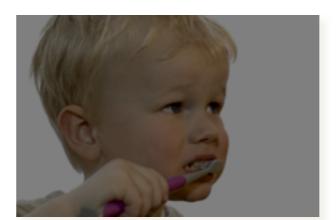


Lower Contrast

Nonlinear Lower Contrast









 \boldsymbol{x}

x - 128

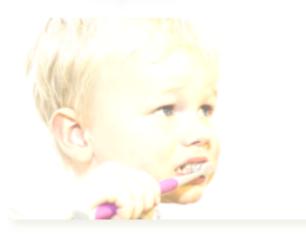
 $\frac{x}{2}$

 $\left(\frac{x}{255}\right)^{1/3} \times 255$

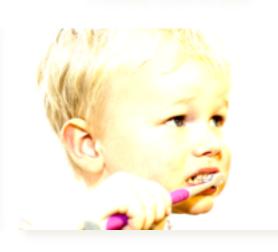
Invert



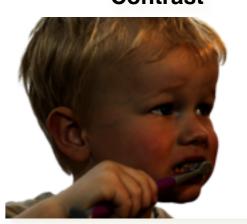
Lighten



Raise Contrast



Nonlinear Raise Contrast



$$255 - x$$

$$x + 128$$

$$x \times 2$$

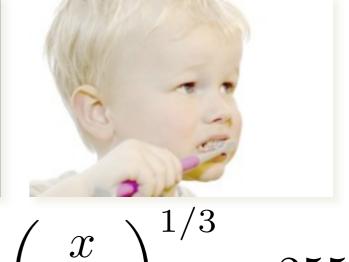
Original x



Darken



Lower Contrast



Nonlinear Lower

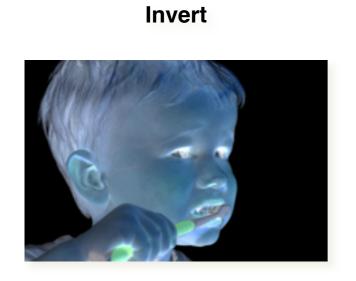
Contrast

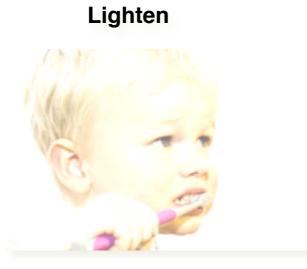
$$x - 128$$

 $\frac{x}{2}$

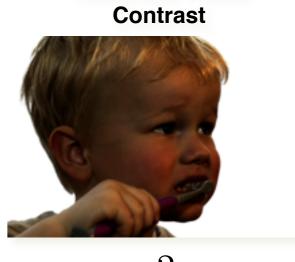
 $\left(\frac{x}{255}\right)^{1/3} \times 255$

Nonlinear Raise









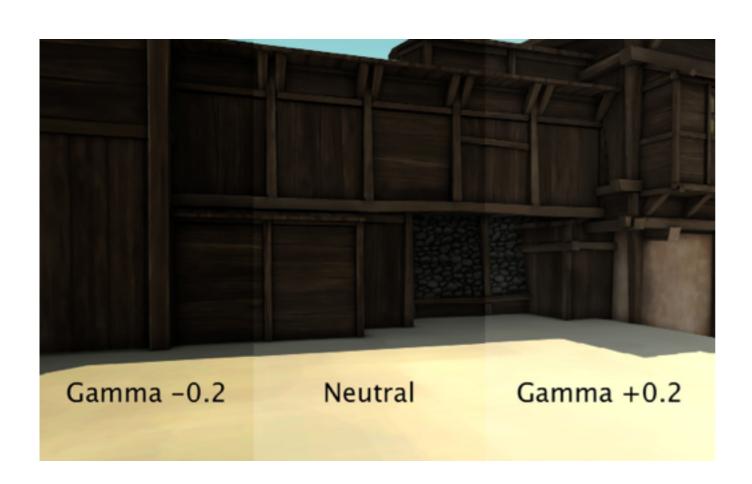
$$255 - x$$

x + 128

 $x \times 2$

$$\left(\frac{x}{255}\right)^2 \times 255$$

Other point processes









Box Filter

The 'Box' filter

$$g[\cdot,\cdot] = \frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ \hline 1 & 1 & 1 \end{bmatrix}$$

replaces pixel with local average has a smoothing effect

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

image $f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0	
0	0	0	0	0	0	0	0	0	0	
0	0	0	90	90	90	90	90	0	0	
0	0	0	90	90	90	90	90	0	0	
0	0	0	90	0	90	90	90	0	0	
0	0	0	90	90	90	90	90	0	0	
0	0	0	0	0	0	0	0	0	0	
0	0	0	0	0	0	0	0	0	0	
0	0	90	0	0	0	0	0	0	0	
0	0	0	0	0	0	0	0	0	0	

 $h[\cdot,\cdot]$

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:heat}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

image $f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0	
0	0	0	0	0	0	0	0	0	0	
0	0	0	90	90	90	90	90	0	0	
0	0	0	90	90	90	90	90	0	0	
0	0	0	90	0	90	90	90	0	0	
0	0	0	90	90	90	90	90	0	0	
0	0	0	0	0	0	0	0	0	0	
0	0	0	0	0	0	0	0	0	0	
0	0	90	0	0	0	0	0	0	0	
0	0	0	0	0	0	0	0	0	0	

 $h[\cdot,\cdot]$

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:heat}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	image $f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

outp	output $h[\cdot,\cdot]$									
	0									

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	$f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

outp	output									
	0	10								

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	$f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:heat}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	image $f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot,\cdot]$$
filter
$$\frac{1}{9}\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

ima	$f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:heat}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	image $f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

outp	output									
	0	10	20	30						

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	$f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

output									
	0	10	20	30	30				

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline & 1 & 1 & 1 \\\hline \end{array}$$

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:heat}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot,\cdot]$$
filter
$$\frac{1}{9}\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:heat}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline & 1 & 1 & 1 \\\hline \end{array}$$

ima	$f[\cdot,\cdot]$										
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	90	0	90	90	90	0	0		
0	0	0	90	90	90	90	90	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		
0	0	90	0	0	0	0	0	0	0		
0	0	0	0	0	0	0	0	0	0		

output										
	0	10	20	30	30	30	20	10		

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

Output										
	0	10	20	30	30	30	20	10		
	0									

OUTDUT

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	image $f[\cdot,\cdot]$												
0	0	0	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	90	0	90	90	90	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	90	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hamiltonian}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	image $f[\cdot,\cdot]$												
0	0	0	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	90	0	90	90	90	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	90	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hamiltonian}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	image $f[\cdot,\cdot]$											
0	0	0	0	0	0	0	0	0	0			
0	0	0	0	0	0	0	0	0	0			
0	0	0	90	90	90	90	90	0	0			
0	0	0	90	90	90	90	90	0	0			
0	0	0	90	0	90	90	90	0	0			
0	0	0	90	90	90	90	90	0	0			
0	0	0	0	0	0	0	0	0	0			
0	0	0	0	0	0	0	0	0	0			
0	0	90	0	0	0	0	0	0	0			
0	0	0	0	0	0	0	0	0	0			

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hamiltonian}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot,\cdot]$$
filter
$$\frac{1}{9}\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black

$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

ima	image $f[\cdot,\cdot]$											
0	0	0	0	0	0	0	0	0	0			
0	0	0	0	0	0	0	0	0	0			
0	0	0	90	90	90	90	90	0	0			
0	0	0	90	90	90	90	90	0	0			
0	0	0	90	0	90	90	90	0	0			
0	0	0	90	90	90	90	90	0	0			
0	0	0	0	0	0	0	0	0	0			
0	0	0	0	0	0	0	0	0	0			
0	0	90	0	0	0	0	0	0	0			
0	0	0	0	0	0	0	0	0	0			

outp	output											
	0	10	20	30	30	30	20	10				
	0	20	40	60	60	60	40	20				
	0	30	50	80	80	90	60	30				
	0	30	50	80	80	90	60	30				
	0	20	30	50	50	60	40	20				
	0	10	20	30	30	30	20	10				
	10	10	10	10	0	0	0	0				
	10	10	10	10	0	0	0	0				

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

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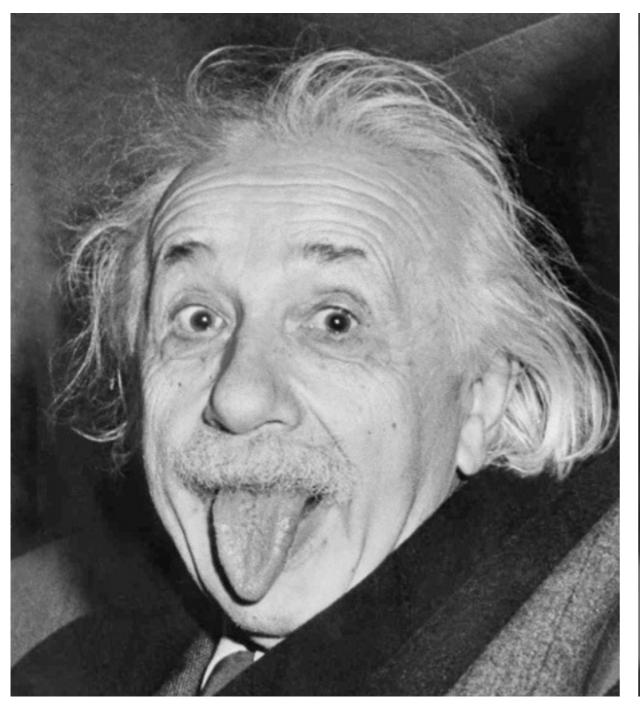
$$g[\cdot, \cdot]$$
filter
$$\frac{1}{9} \begin{array}{|c|c|c|}\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline 1 & 1 & 1 \\\hline \end{array}$$

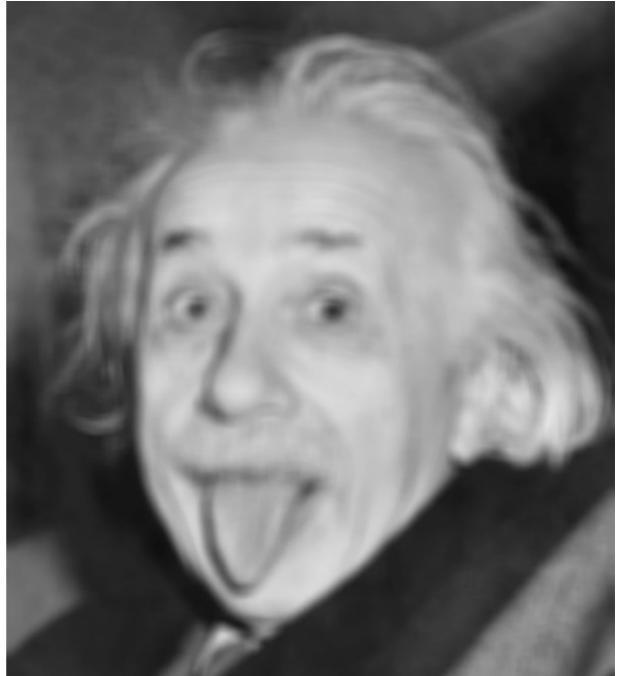
ima	image $f[\cdot,\cdot]$												
0	0	0	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	90	0	90	90	90	0	0				
0	0	0	90	90	90	90	90	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				
0	0	90	0	0	0	0	0	0	0				
0	0	0	0	0	0	0	0	0	0				

outp	out								
	0	10	20	30	30	30	20	10	
	0	20	40	60	60	60	40	20	
	0	30	50	80	80	90	60	30	
	0	30	50	80	80	90	60	30	
	0	20	30	50	50	60	40	20	
	0	10	20	30	30	30	20	10	
	10	10	10	10	0	0	0	0	
	10	10	10	10	0	0	0	0	

$$h[m,n] = \sum_{k,l} g[k,l] f[m+k,n+l] \label{eq:hammer}$$
 output
$$k,l \quad \text{filter} \quad \text{image (signal)}$$

^{*} some zero values are white for visualization but they should be black



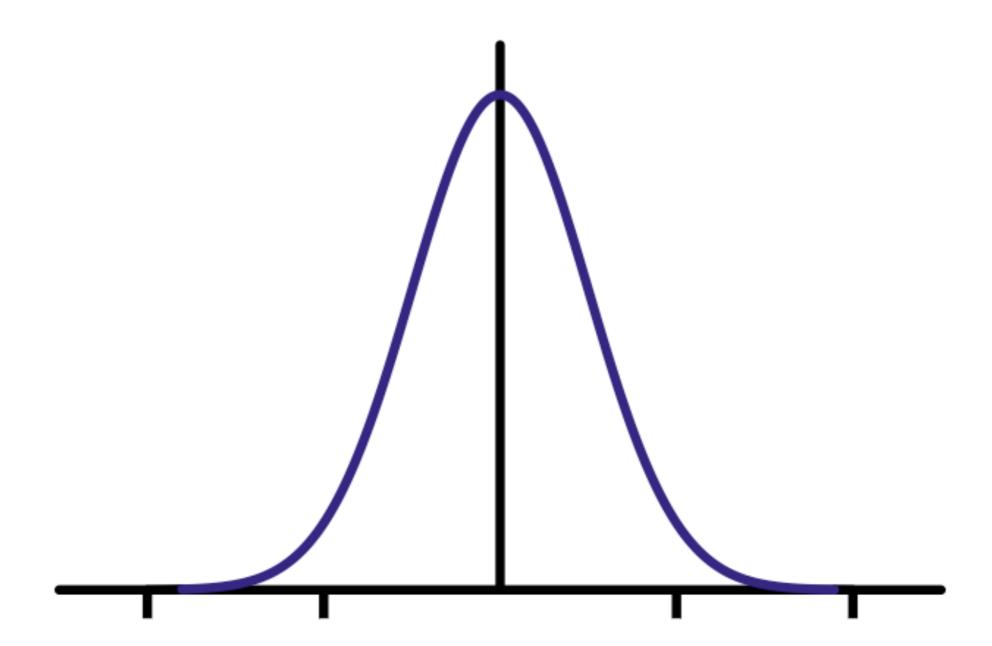












Gaussian Filter

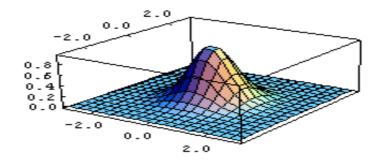
The Gaussian filter

 $\begin{array}{c|cccc}
 & I & 2 & I \\
 & 2 & 4 & 2 \\
 & I & 2 & I \\
\end{array}$

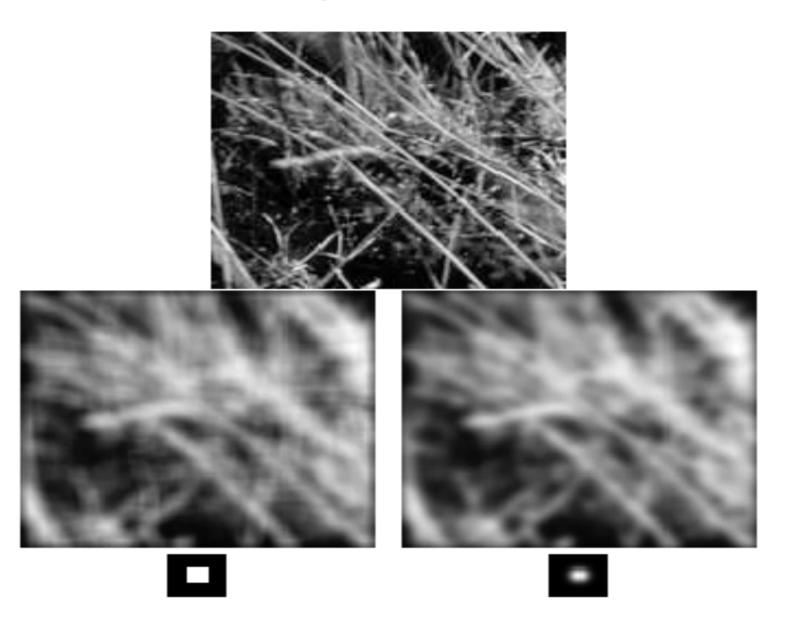
A Gaussian kernel gives less weight to pixels further from the center of the window

$$h(u,v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

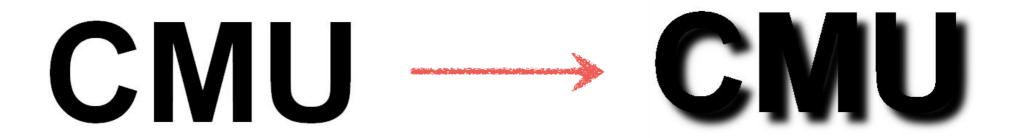
This kernel is an approximation of a Gaussian function



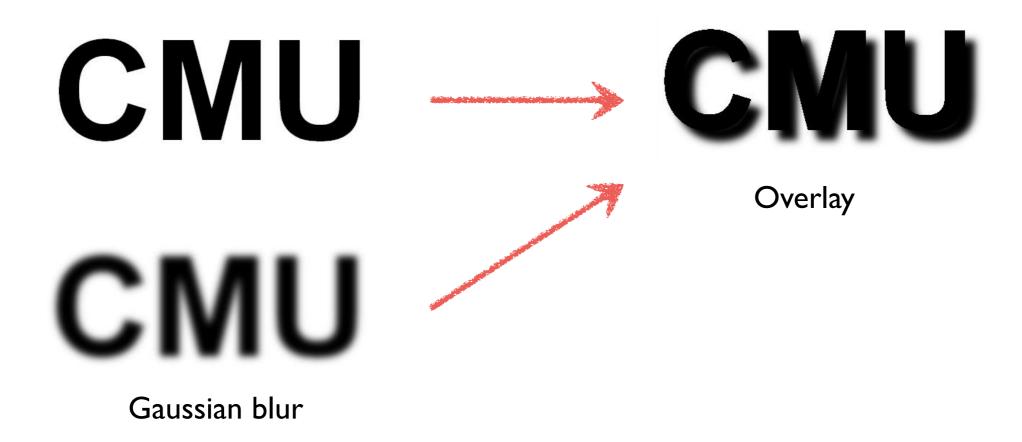
Gaussian filtering versus mean filtering



How would you create a shadow effect?

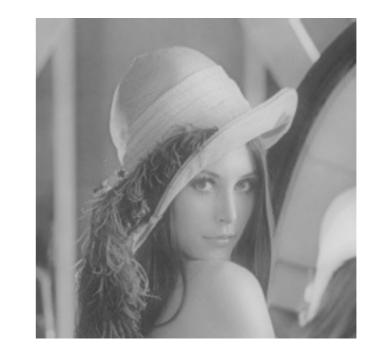


How would you create a shadow effect?



How would you create a soft focus effect?





How would you create a soft focus effect?

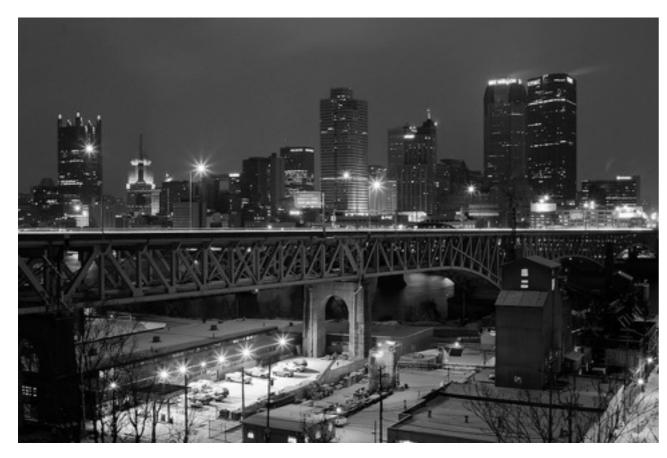


Tilt Shift Effect



http://www.flickr.com/photos/ender079/2704450659/

How would you create a (super low-budget) tilt-shift effect?



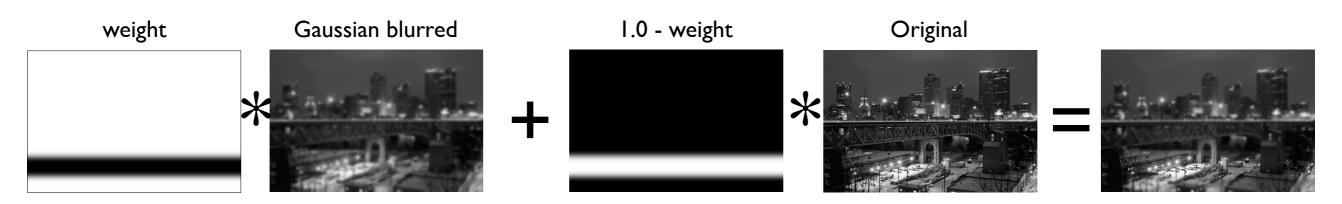


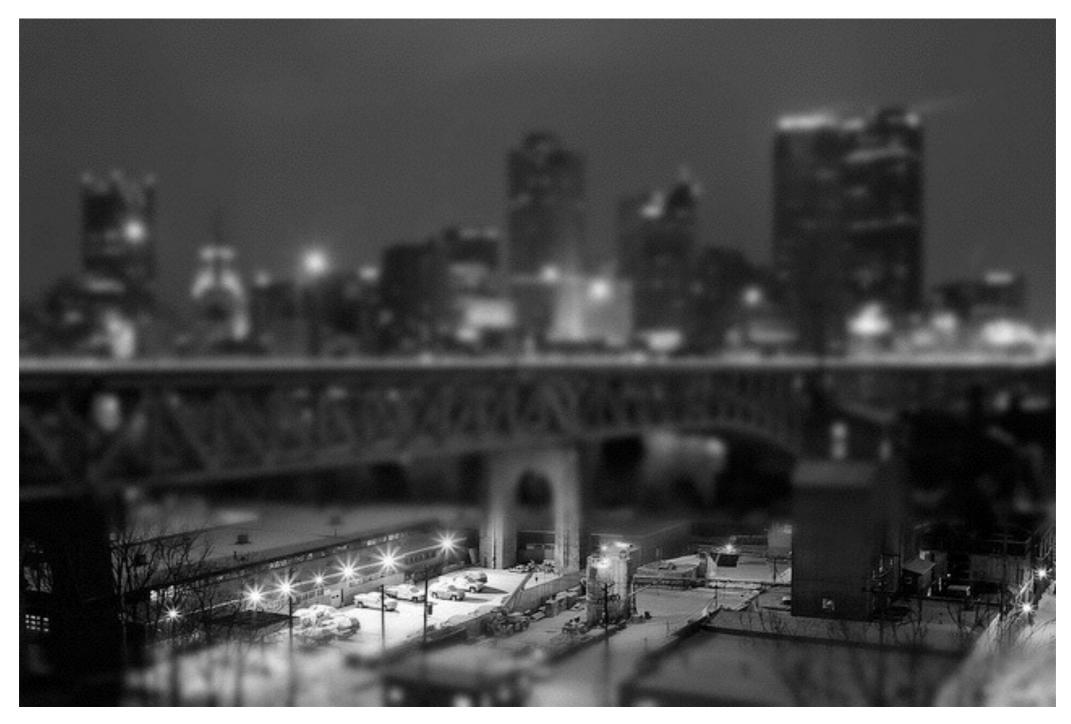
http://farm8.staticflickr.com/7061/6867631897_f8377709b9_z.jpg

How would you create a (super low-budget) tilt-shift effect?

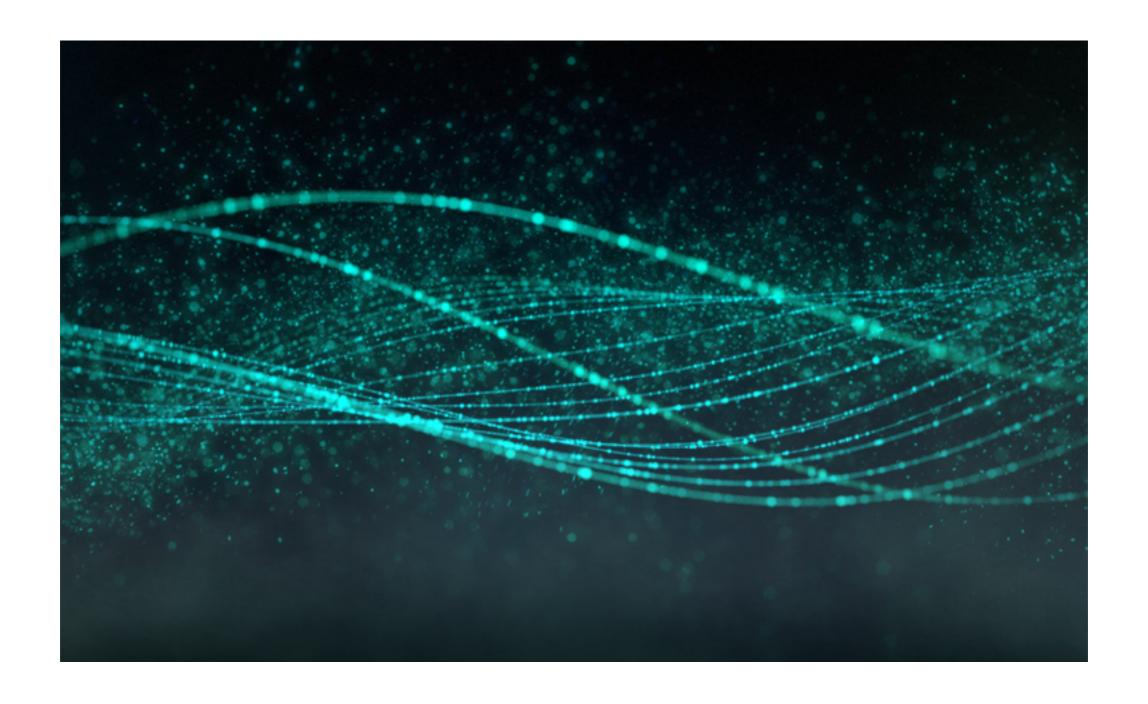








Tell me everything wrong with this wannabe tilt-shift image



Fourier's Claim

It all starts with this guy...



Who is this fellow?



Jean Baptiste Joseph Fourier (1768-1830)



Jean Baptiste Joseph Fourier (1768-1830)

What was his claim?



Jean Baptiste Joseph Fourier (1768-1830)

'Any univariate function can be rewritten as a weighted sum of sines and cosines of different frequencies' (1807)



Jean Baptiste Joseph Fourier (1768-1830)

'Any univariate function can be rewritten as a weighted sum of sines and cosines of different frequencies' (1807)









Laplace

Lagrange

Legendre

Poisson

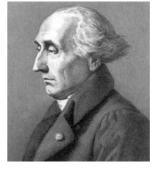
What did these guys think of his claims?



Jean Baptiste Joseph Fourier (1768-1830)

'Any univariate function can be rewritten as a weighted sum of sines and cosines of different frequencies'
(1807)









Laplace

Lagrange

Legendre

Poisson

...the manner in which the author arrives at these equations is not exempt of difficulties and...his analysis to integrate them still leaves something to be desired on the score of generality and even rigour.

- Laplace

Not translated to English until 1878!



Jean Baptiste Joseph Fourier (1768-1830)

'Any univariate function can be rewritten as a weighted sum of sines and cosines of different frequencies'
(1807)









Laplace

Lagrange

Legendre

Poisson

1

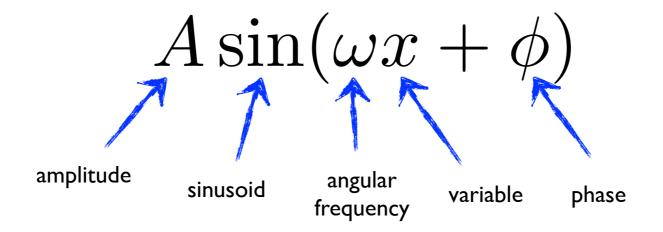
Why is he so angry?



1820 watercolor caricatures of French mathematicians Adrien-Marie Legendre (left) and Joseph Fourier (right) by French artist Julien-Leopold Boilly, watercolor portrait numbers 29 and 30 of Album de 73 Portraits-Charge Aquarelle's des Membres de l'Institute.

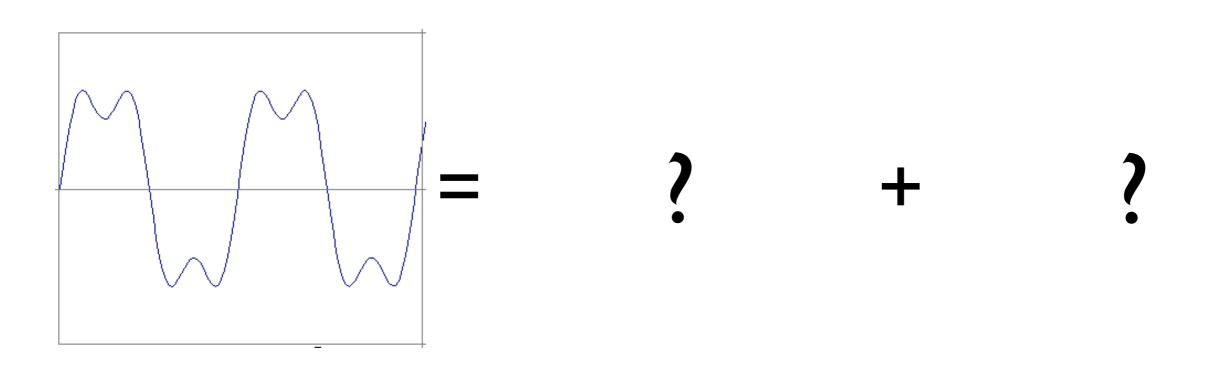
http://en.wikipedia.org/wiki/Joseph_Fourier

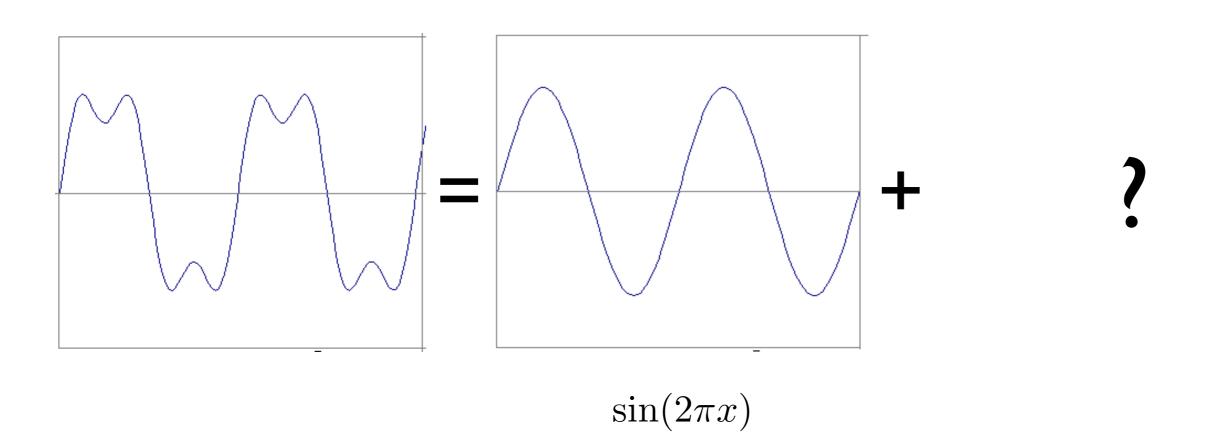
Basic building block

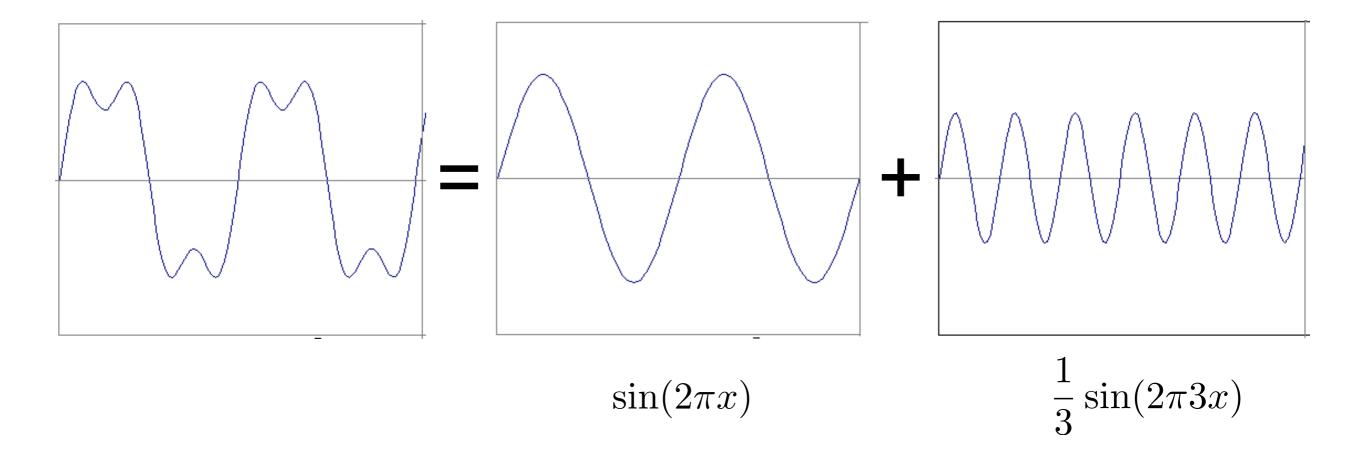


CLAIM:

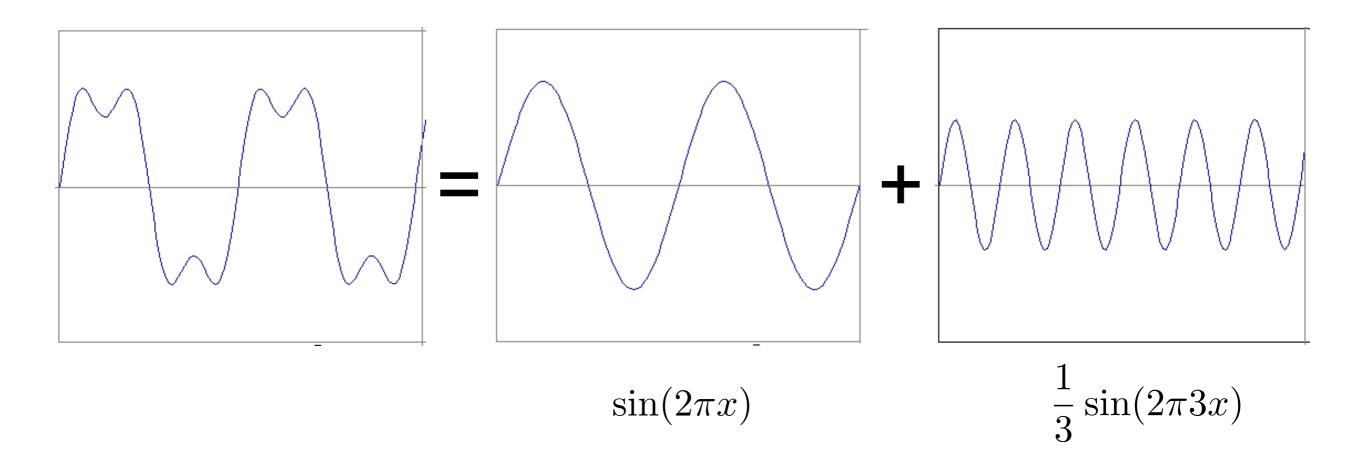
Add enough of them to get any signal you want!

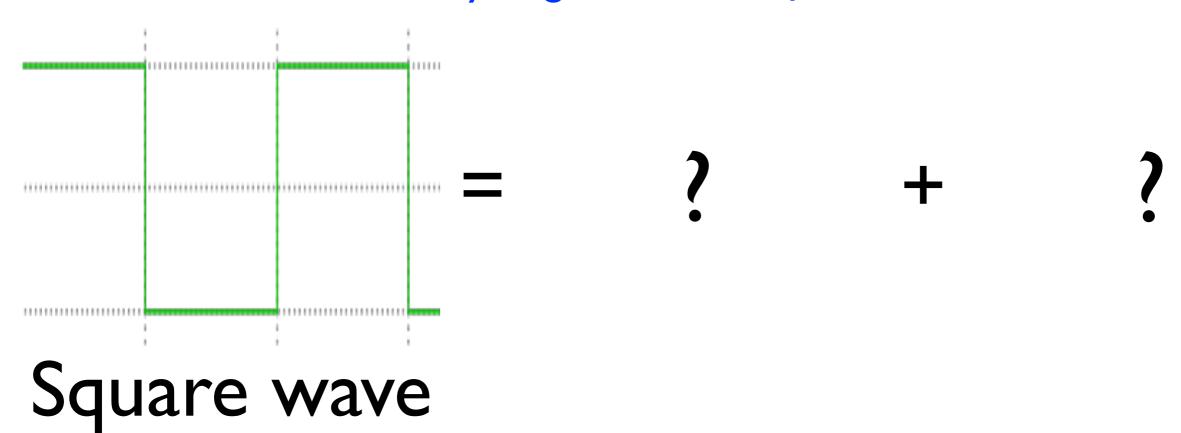


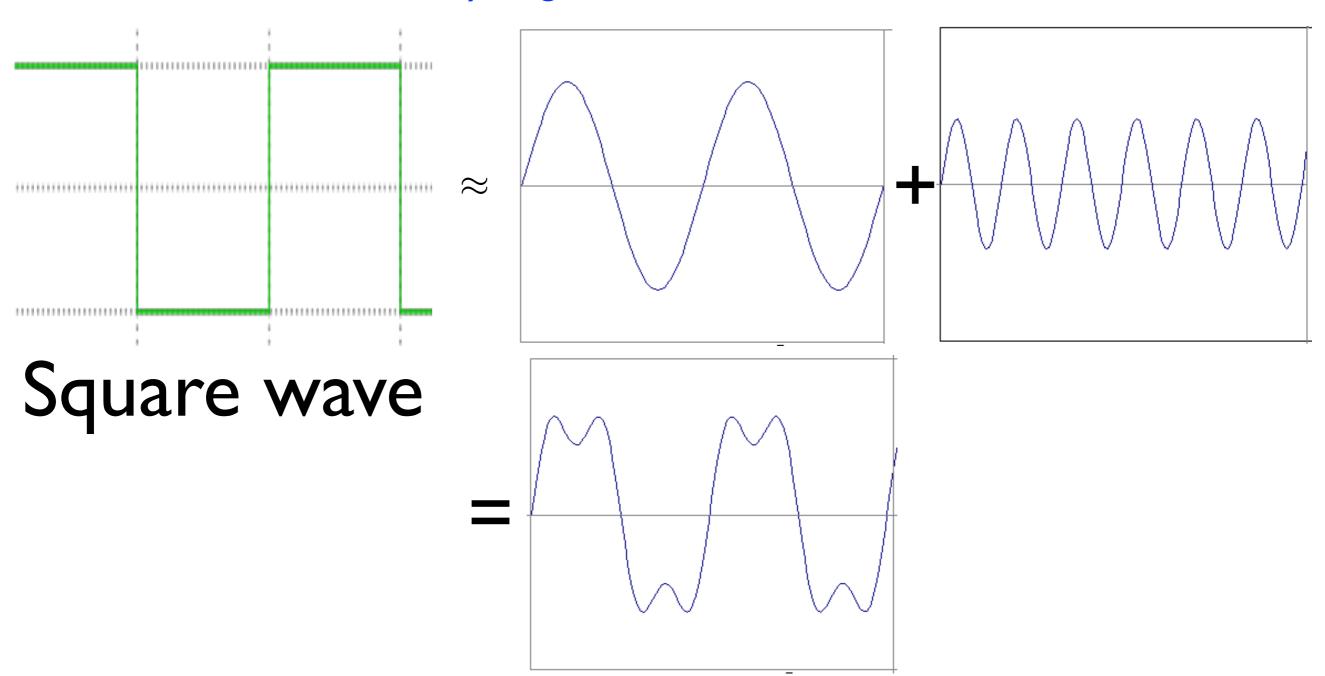


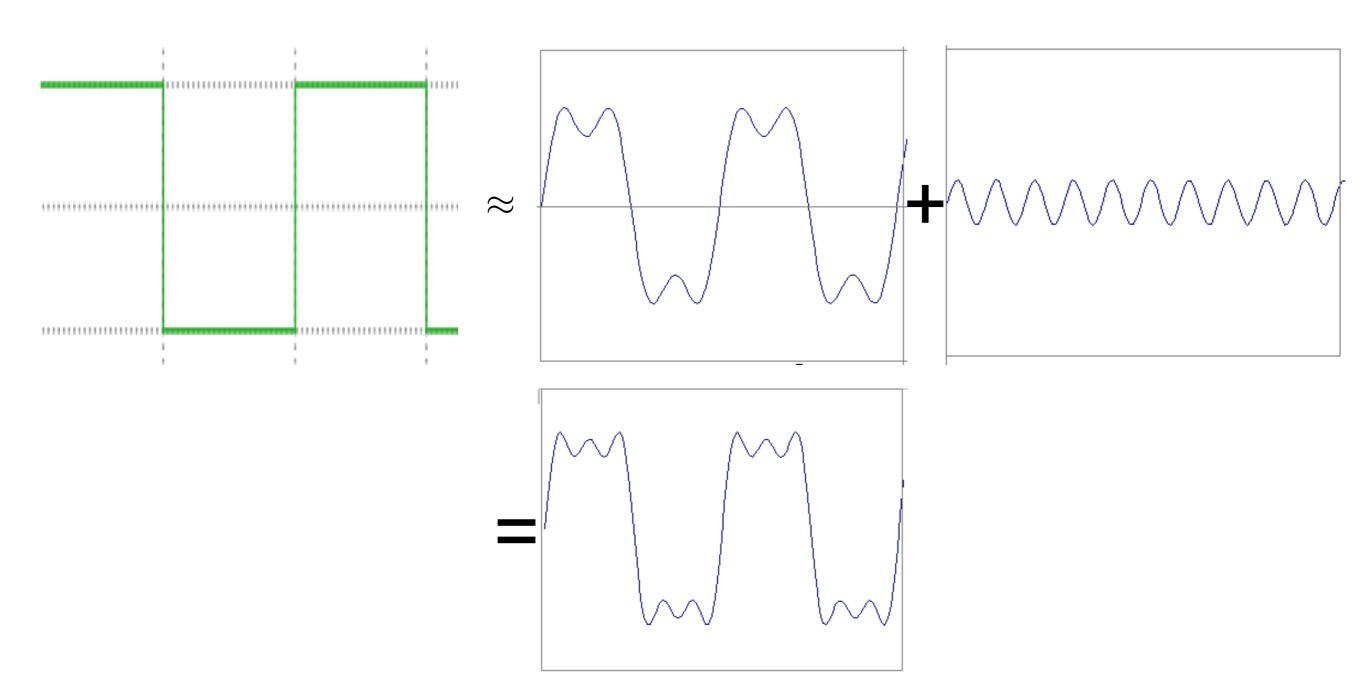


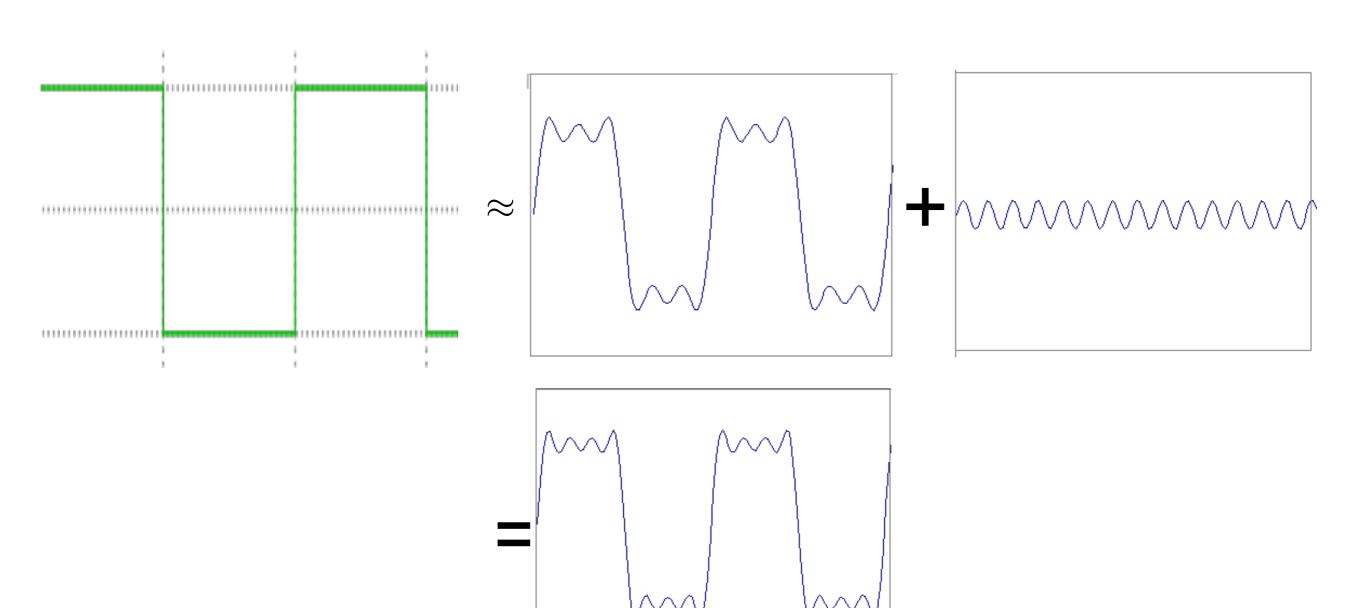
$$f(x) = \sin(2\pi x) + \frac{1}{3}\sin(2\pi 3x)$$

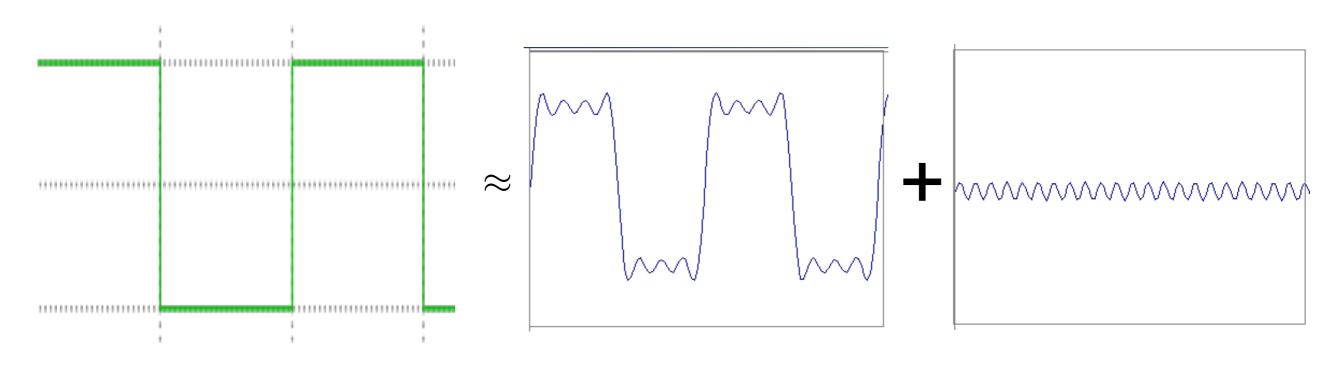




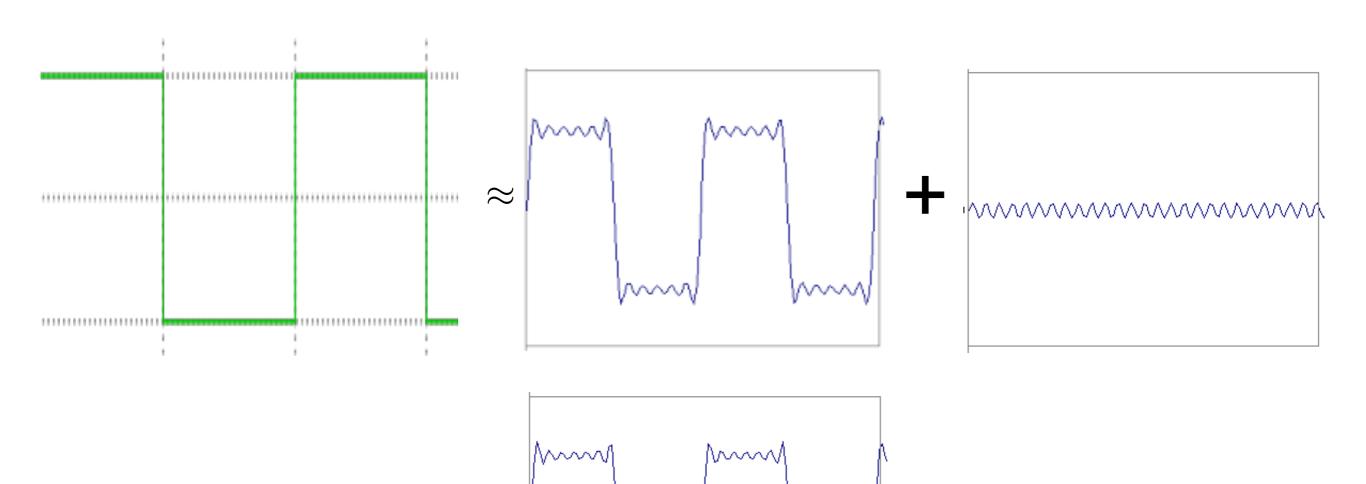


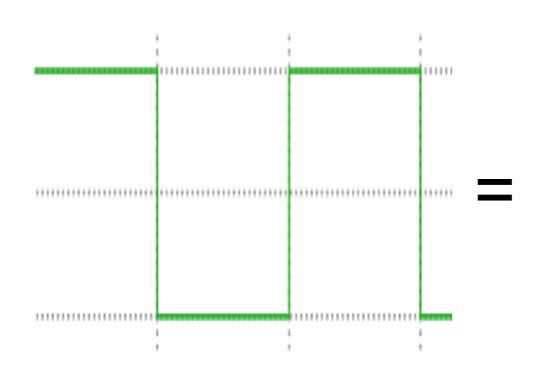






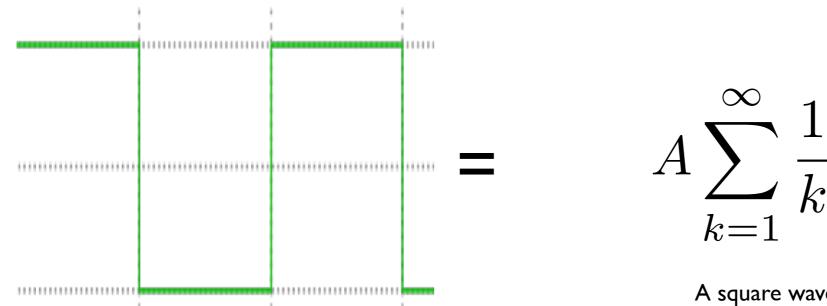






How would you express this mathematically?

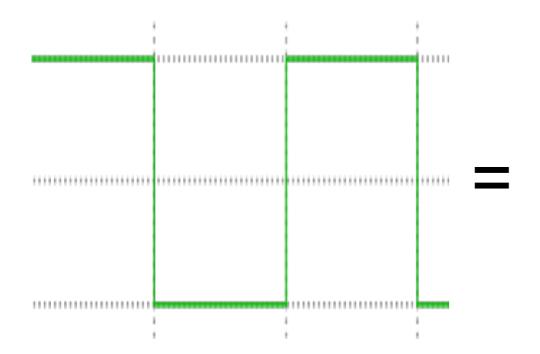
$$\sum_{k=1}^{\infty}$$



$$A\sum_{k=1}^{\infty} \frac{1}{k} \sin(2\pi kx)$$

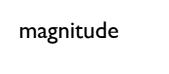
A square wave is an infinite sum of sine waves

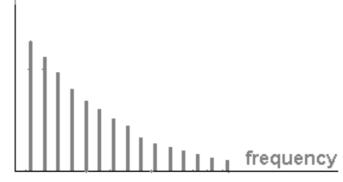
How would could you visualize this in the frequency domain?



$$A\sum_{k=1}^{\infty} \frac{1}{k} \sin(2\pi kx)$$

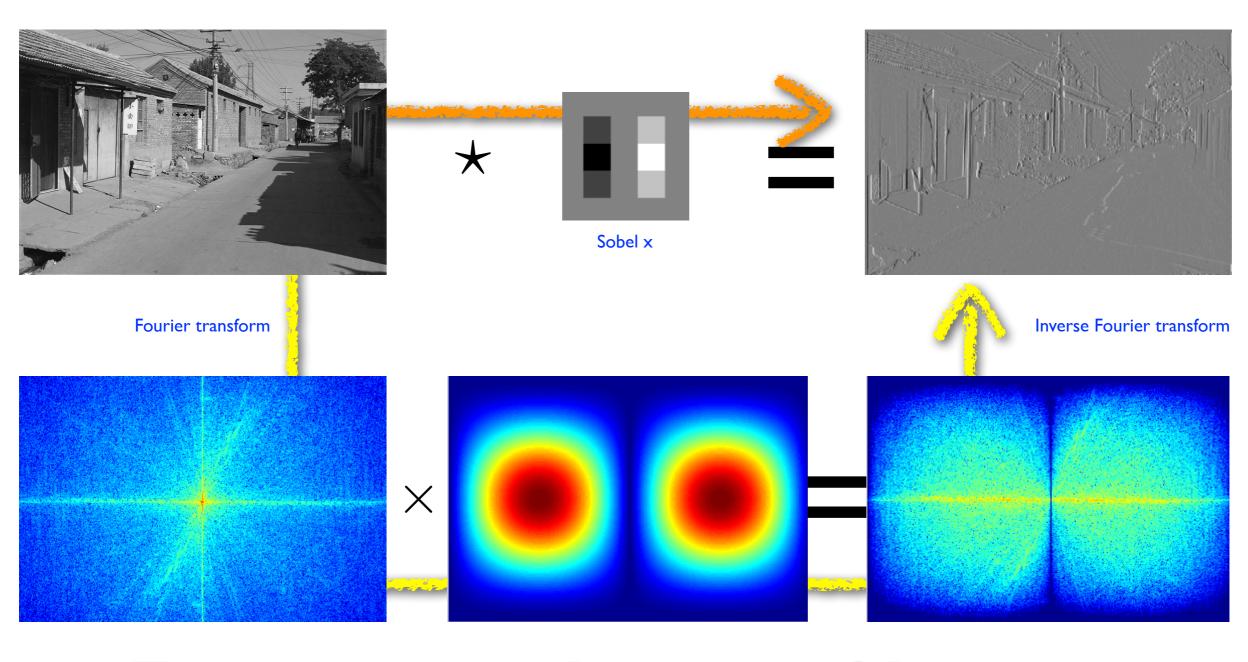
A square wave is an infinite sum of sine waves



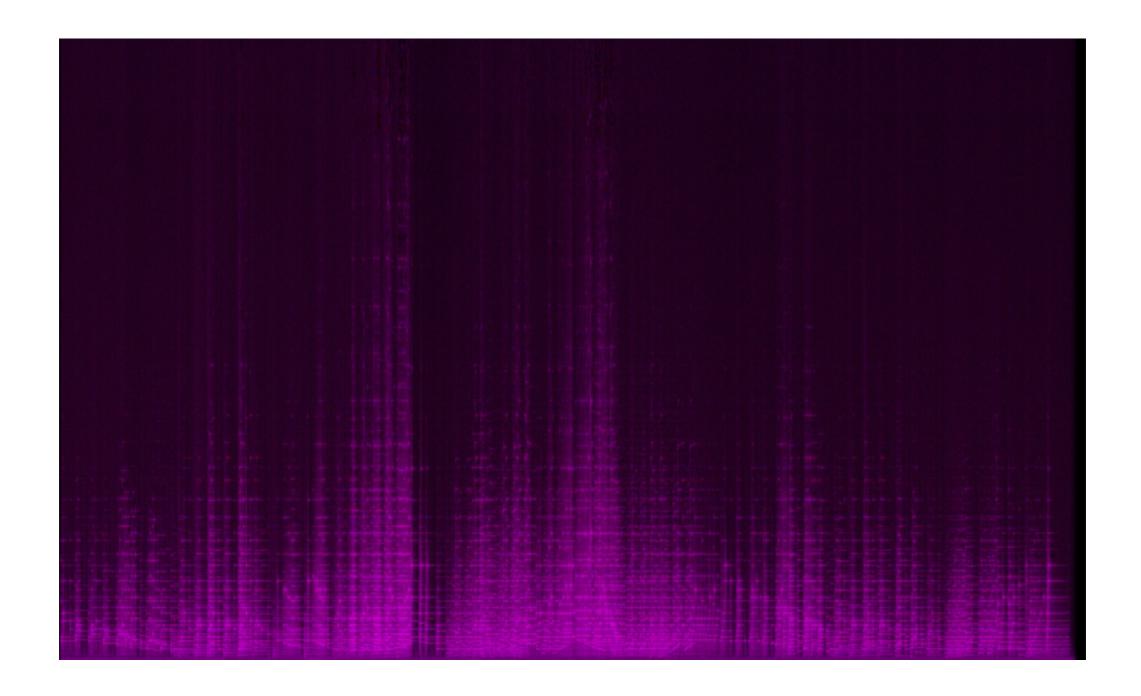


Why does this matter?

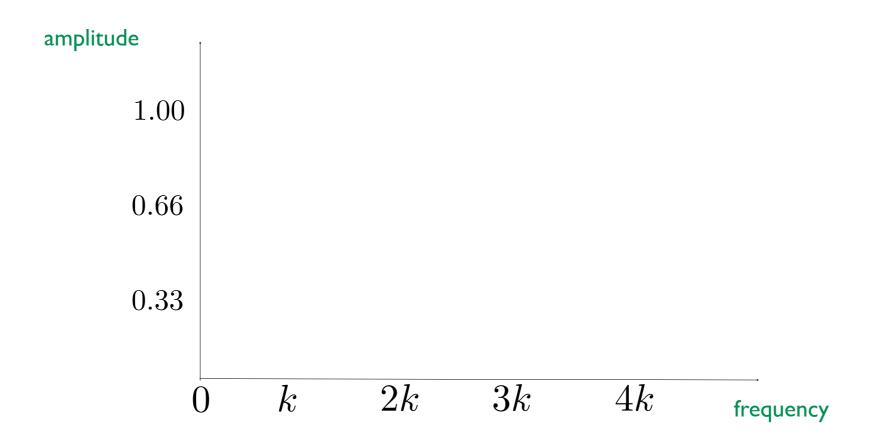
Spatial domain filtering



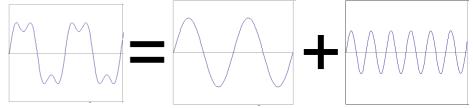
Frequency domain filtering

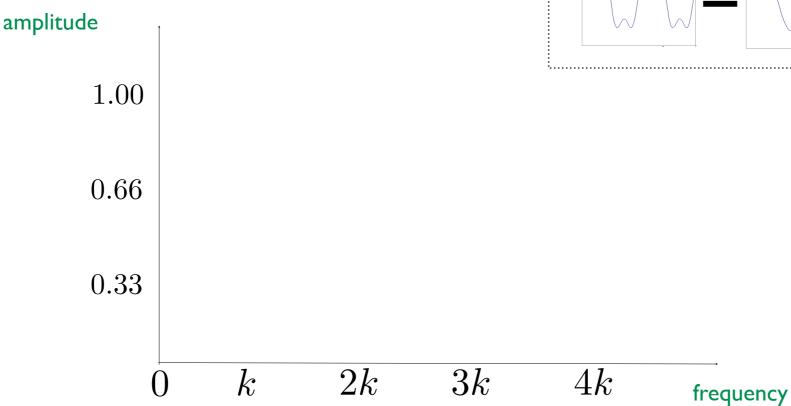


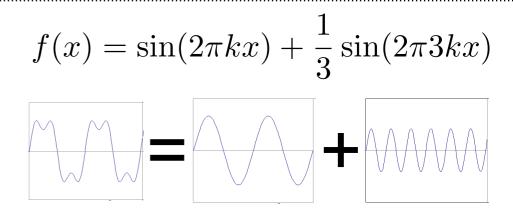
Frequency Spectrum

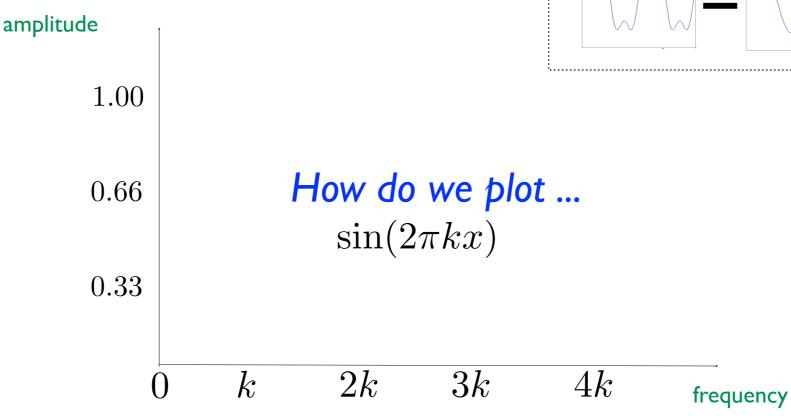


$$f(x) = \sin(2\pi kx) + \frac{1}{3}\sin(2\pi 3kx)$$



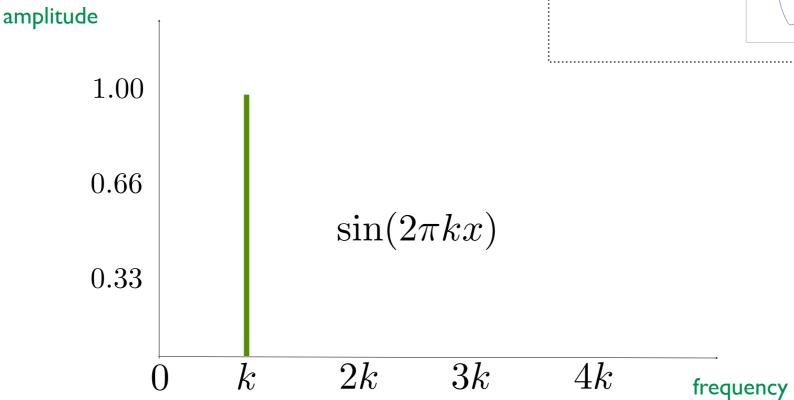






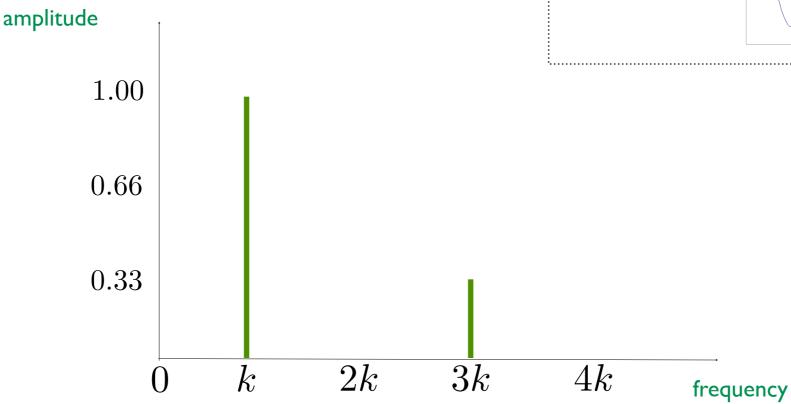
$$f(x) = \sin(2\pi kx) + \frac{1}{3}\sin(2\pi 3kx)$$





$$f(x) = \sin(2\pi kx) + \frac{1}{3}\sin(2\pi 3kx)$$



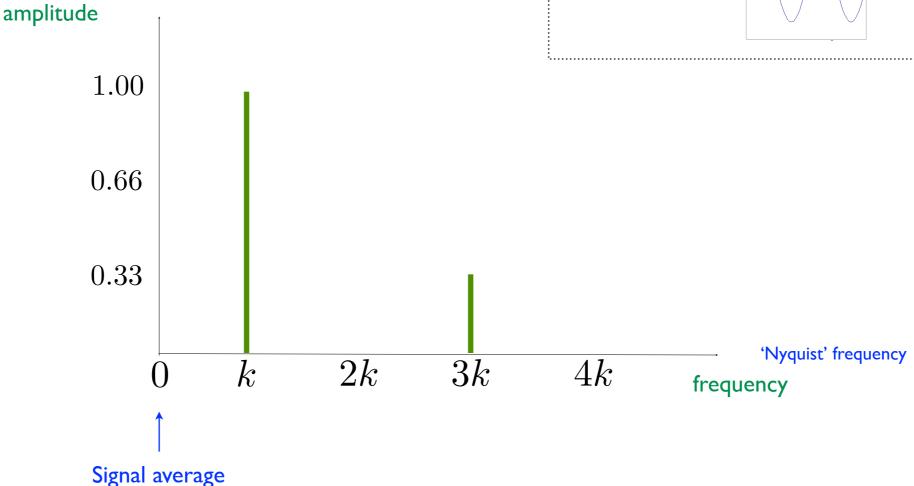


Recall the temporal domain visualization

$$f(x) = \sin(2\pi kx) + \frac{1}{3}\sin(2\pi 3kx)$$



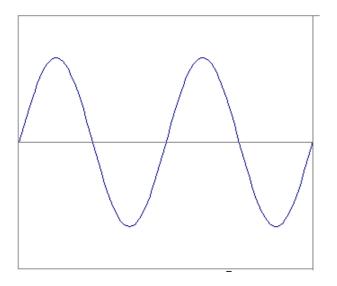
not visualizing the symmetric negative part

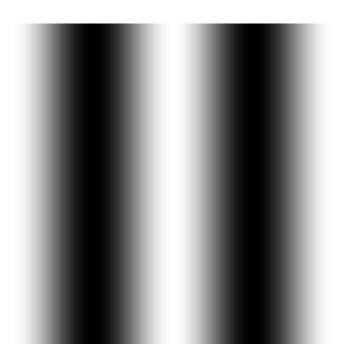


(zero for a sine wave with no offset)

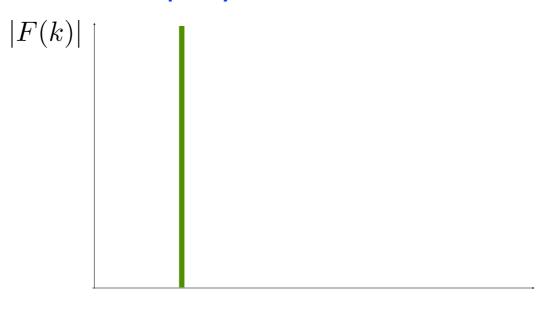
Need to understand this to understand the 2D version...

Spatial domain visualization





Frequency domain visualization

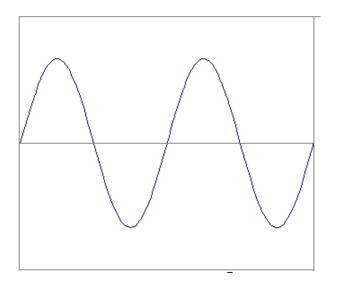


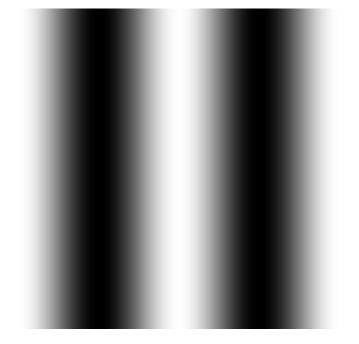
?

2D

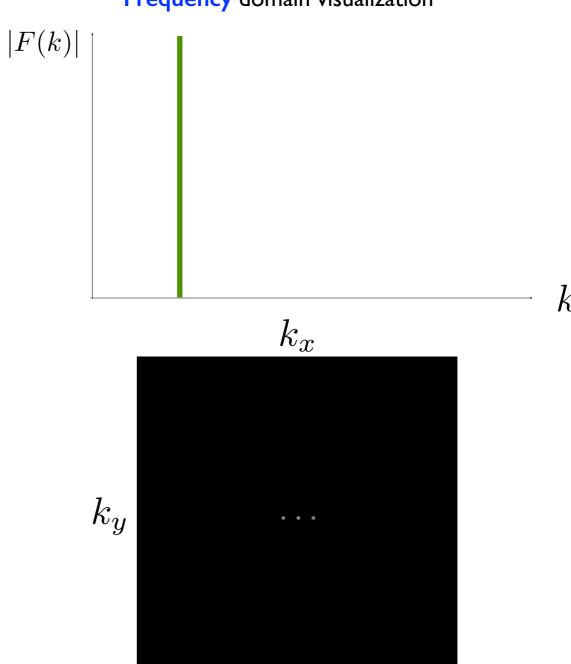
ID

Spatial domain visualization





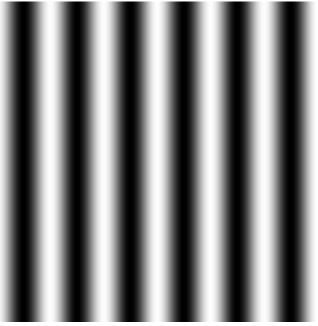
Frequency domain visualization



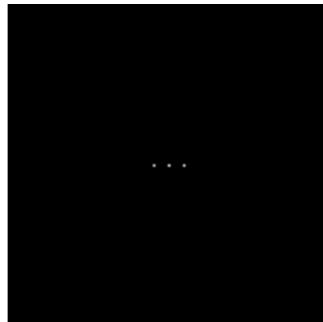
2D

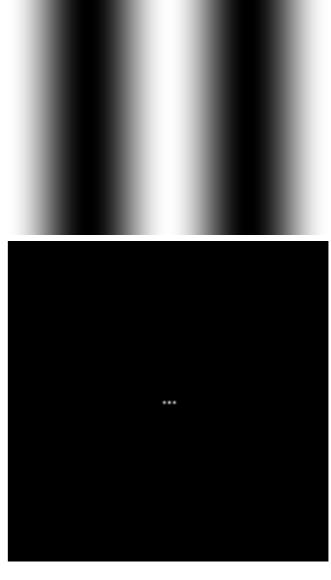
ID

Intensity in the spatial domain



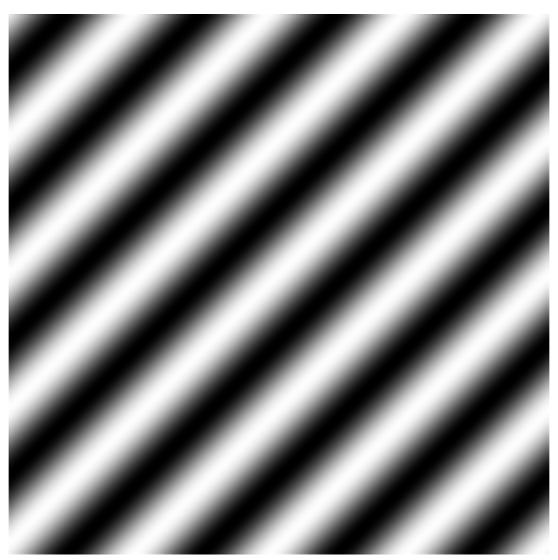
Amplitude in the frequency domain

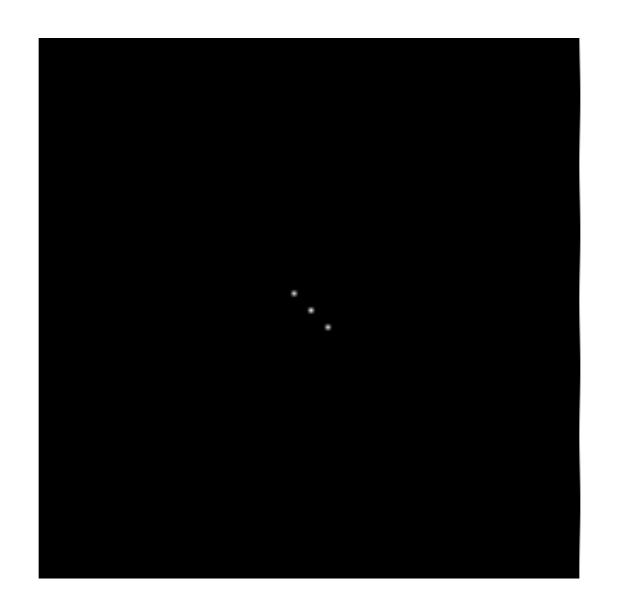




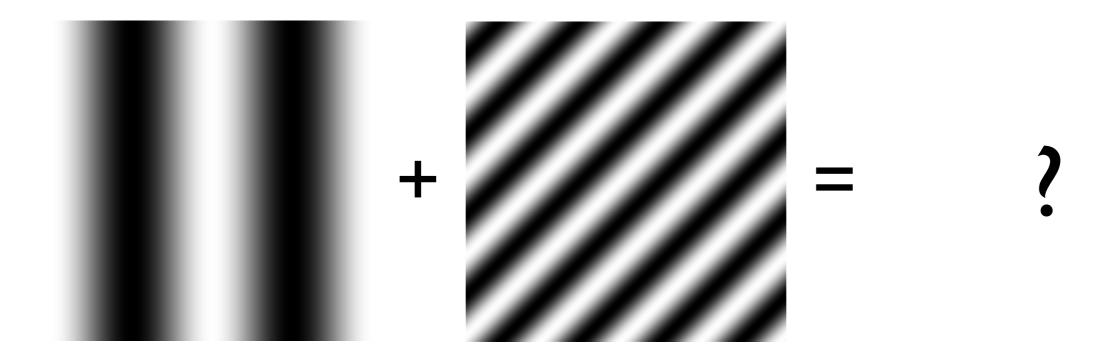
http://cns-alumni.bu.edu/~slehar/fourier/fourier.html

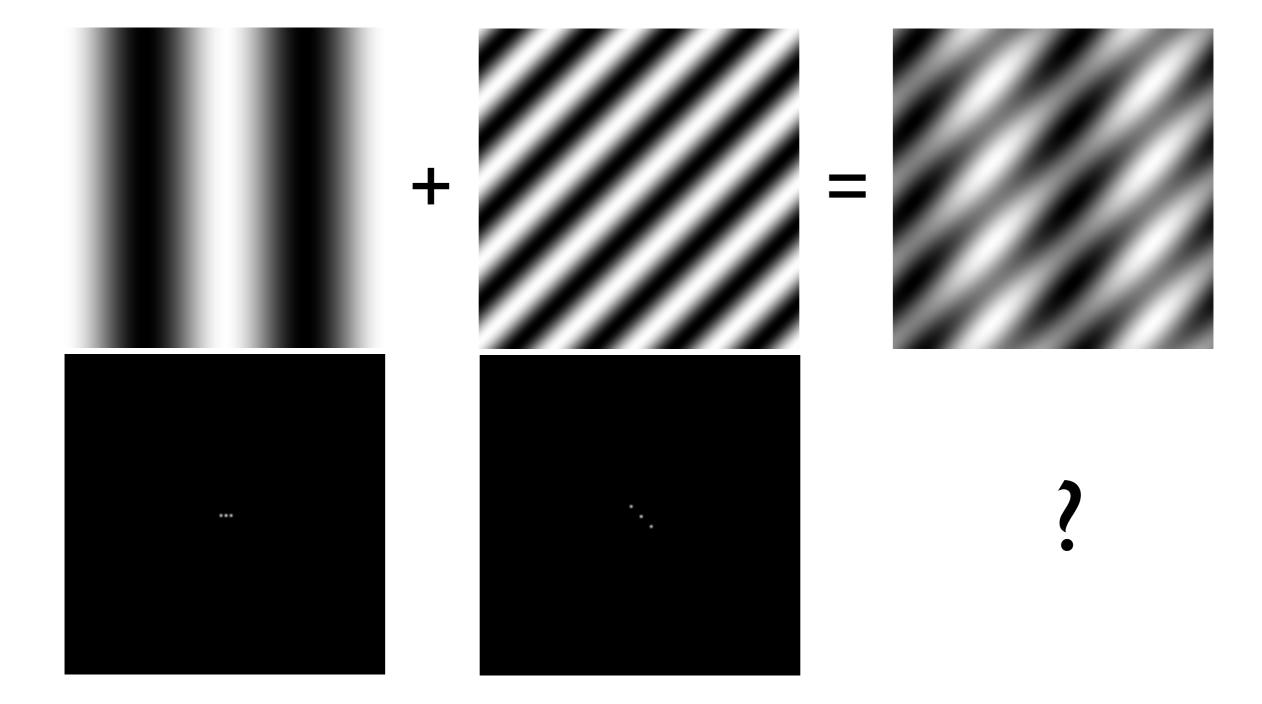
How would you generate this image with sine waves?

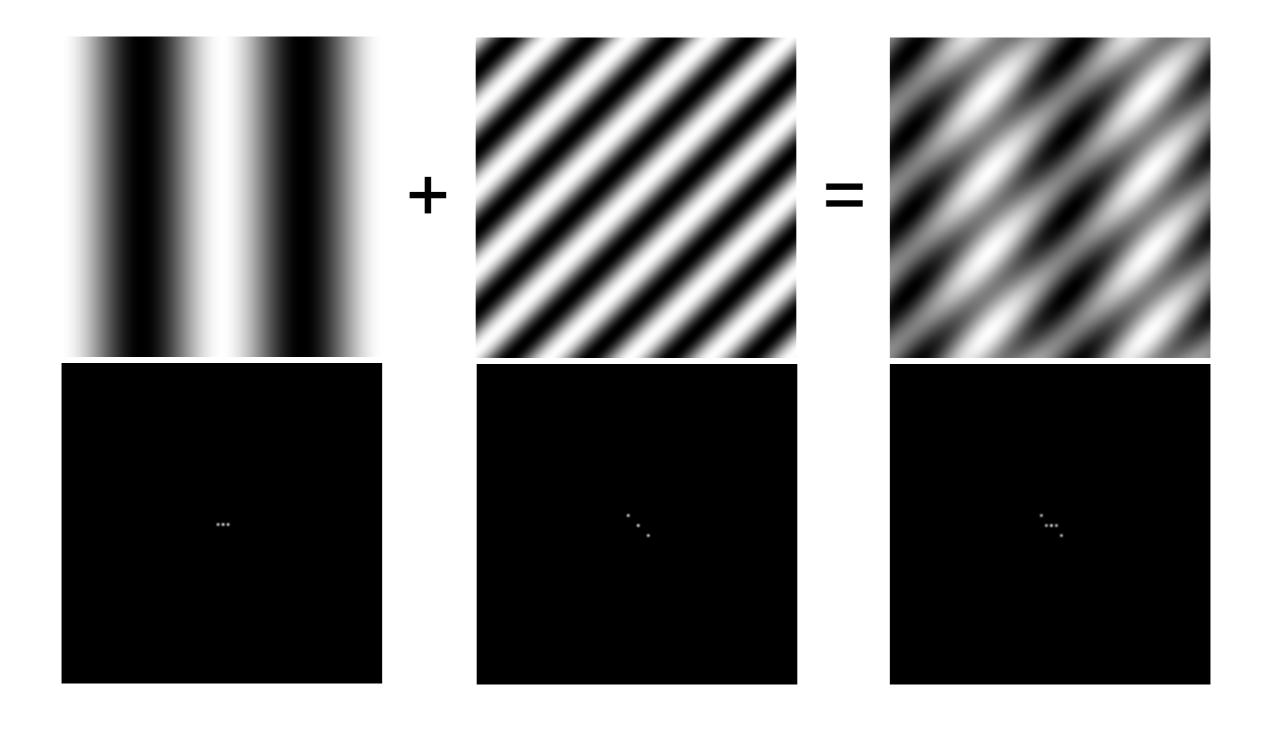




Has both an x and y component







spatial domain visualization

frequency domain visualization





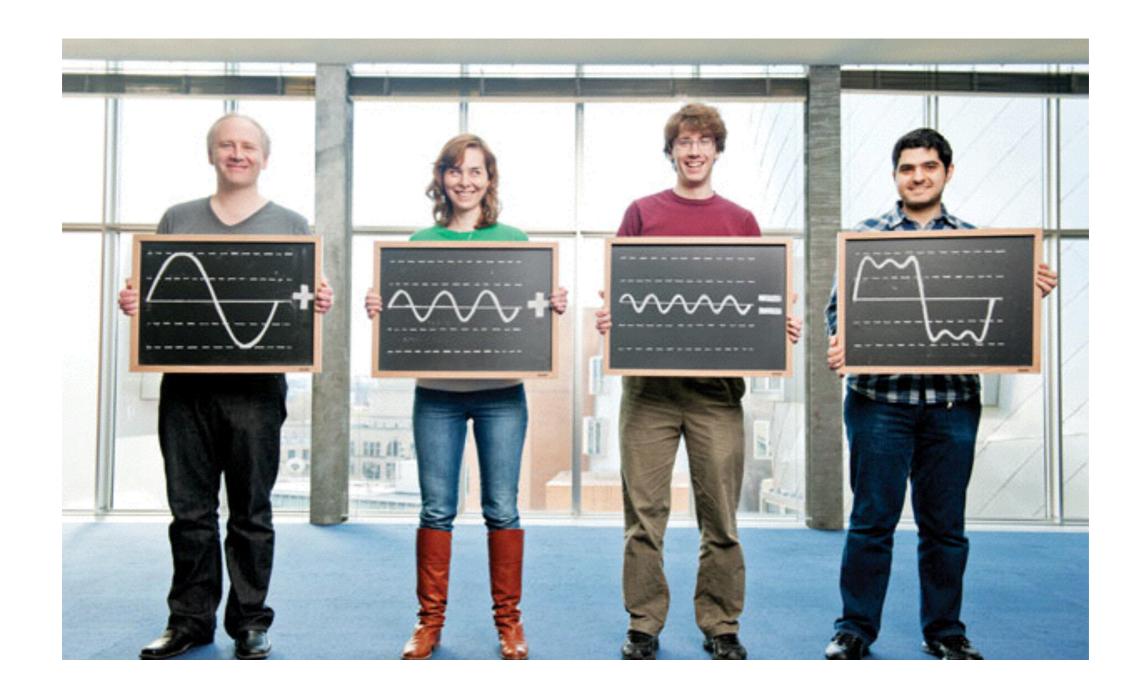
spatial domain visualization

frequency domain visualization



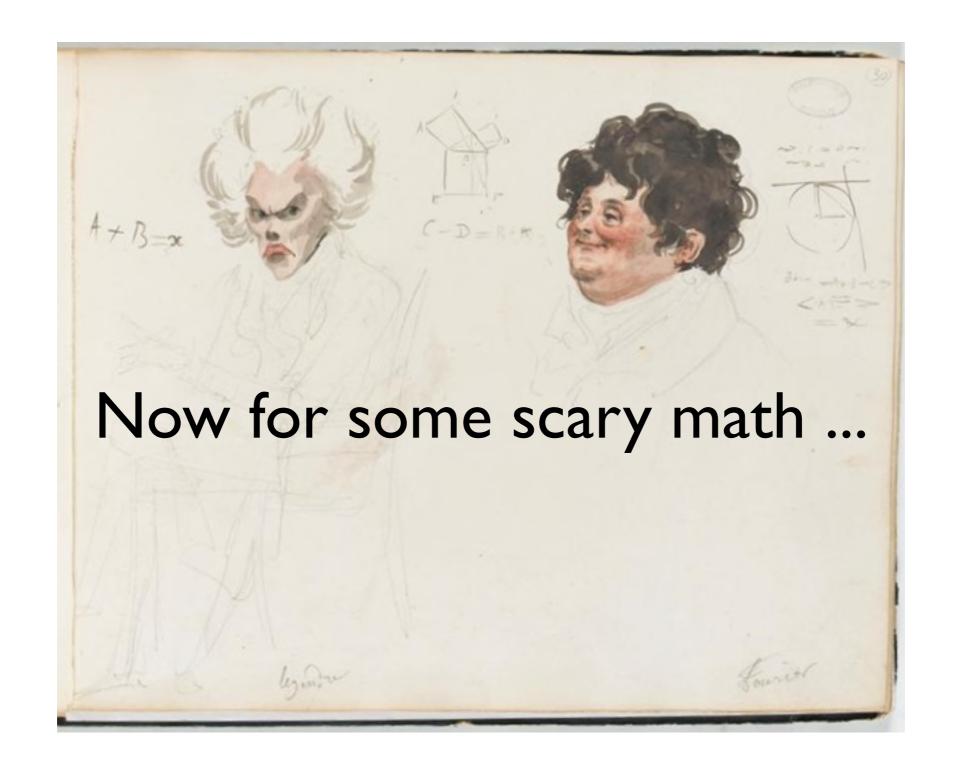


Need to be able to interpret 2D spectra to understand frequency filtering ...



Fourier Transform

16-385 Computer Vision

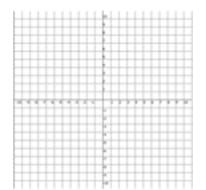


Complex numbers have two parts:

rectangular coordinates

$$R + jI$$

what's this? what's this?

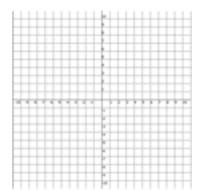


Complex numbers have two parts:

rectangular coordinates

$$R + jI$$

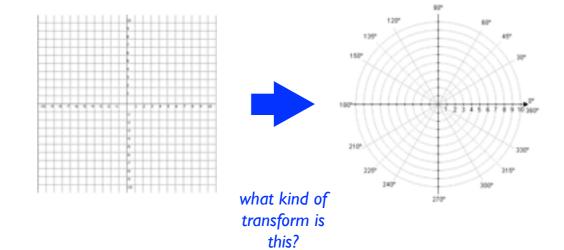
real imaginary



Complex numbers have two parts:

rectangular coordinates

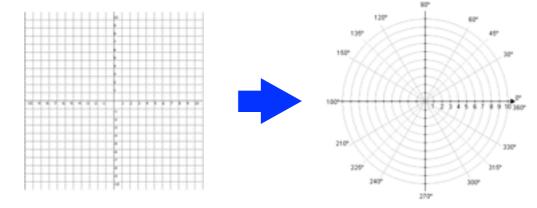
$$R + jI_{_{\rm real}}$$



Complex numbers have two parts:

rectangular coordinates

$$R+jI_{_{\rm real}}$$



Polar

Complex numbers have two parts:

rectangular coordinates

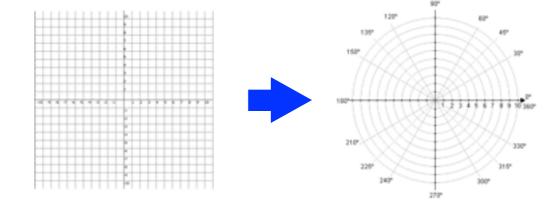
$$R+jI$$

Alternative re-parameterization:

polar coordinates

$$r(\cos\theta + j\sin\theta)$$

How do you compute r and theta?



Complex numbers have two parts:

rectangular coordinates

$$R + jI$$

real imaginary

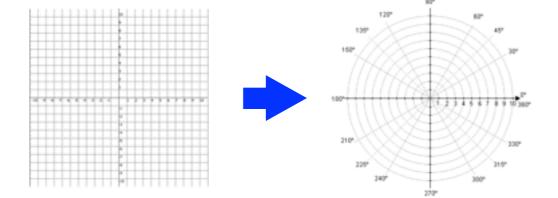
Alternative re-parameterization:

polar coordinates

$$r(\cos\theta + j\sin\theta)$$

polar transform

$$\theta = \tan^{-1}(\frac{I}{R}) \qquad r = \sqrt{R^2 + I^2}$$



Complex numbers have two parts:

rectangular coordinates

$$R + jI$$

real imaginary

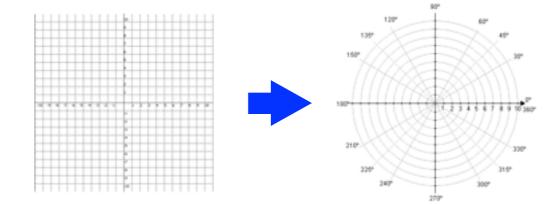
Alternative re-parameterization:

polar coordinates

$$r(\cos\theta + j\sin\theta)$$

polar transform

$$\theta = \tan^{-1}(\frac{I}{R}) \qquad r = \sqrt{R^2 + I^2}$$



How do you write this in exponential form?

Complex numbers have two parts:

rectangular coordinates

$$R+jI$$

1152° 11

Alternative re-parameterization:

polar coordinates

$$r(\cos\theta + j\sin\theta)$$

polar transform

$$\theta = \tan^{-1}(\frac{I}{R}) \qquad r = \sqrt{R^2 + I^2}$$

 $\bigcirc R$

exponential form

$$re^{j\theta}$$

'Euler's formula'

$$e^{j\theta} = \cos\theta + j\sin\theta$$

This will help us understanding of the Fourier transform equations ...

Fourier transform

Inverse Fourier transform

$$F(k) = \int_{-\infty}^{-\infty} f(x)e^{-j2\pi kx}dx \qquad f(x) = \int_{-\infty}^{-\infty} F(k)e^{j2\pi kx}dk$$

$$F(k) = \frac{1}{N} \sum_{x=0}^{N-1} f(x)e^{-j2\pi kx/N}$$

$$f(x) = \sum_{k=0}^{N-1} F(k)e^{j2\pi kx/N}$$

$$k = 0, 1, 2, \dots, N-1$$

$$x = 0, 1, 2, \dots, N-1$$

Where is the connection to the 'summation of sine waves' idea?

Fourier transform

Inverse Fourier transform

$$F(k) = \int_{-\infty}^{-\infty} f(x)e^{-j2\pi kx}dx \qquad f(x) = \int_{-\infty}^{-\infty} F(k)e^{j2\pi kx}dk$$

$$F(k) = \frac{1}{N} \sum_{x=0}^{N-1} f(x)e^{-j2\pi kx/N}$$

$$f(x) = \sum_{k=0}^{N-1} F(k)e^{j2\pi kx/N}$$

$$k = 0, 1, 2, \dots, N-1$$

$$x = 0, 1, 2, \dots, N-1$$

Where is the connection to the 'summation of sine waves' idea?

Where is the connection to the 'summation of sine waves' idea?

frequencies

$$f(x) = \sum_{k=0}^{N-1} F(k) e^{j2\pi kx/N}$$

$$Euler's formula'$$

$$e^{j\theta} = \cos\theta + j\sin\theta$$

$$f(x) = \sum_{k=0}^{N-1} F(k) \bigg\{ \cos(2\pi kx) + j\sin(2\pi kx) \bigg\}$$

wave components

"So how do you actually compute the DFT?"

-A. Student

Computing the Discrete Fourier Transform...

$$F(k) = \frac{1}{N} \sum_{x=0}^{N-1} f(x)e^{-j2\pi kx/N}$$

...is just a matrix multiplication.

$$F = Wf$$

$$\begin{bmatrix} F(0) \\ F(1) \\ F(2) \\ F(3) \\ \vdots \\ F(N-1) \end{bmatrix} = \begin{bmatrix} W^0 & W^0 & W^0 & W^0 & \cdots & W^0 \\ W^0 & W^1 & W^2 & W^3 & \cdots & W^{N-1} \\ W^0 & W^2 & W^4 & W^6 & \cdots & W^{N-2} \\ W^0 & W^3 & W^6 & W^9 & \cdots & W^{N-3} \\ \vdots & & & & \ddots & \vdots \\ W^0 & W^{N-1} & W^{N-2} & W^{N-3} & \cdots & W^1 \end{bmatrix} \begin{bmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \\ \vdots \\ f(N-1) \end{bmatrix}$$

$$W = e^{-j2\pi/N} \qquad W = W^{2N}$$

Example

input signal

$$\begin{bmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \\ 8 \\ 0 \end{bmatrix}$$

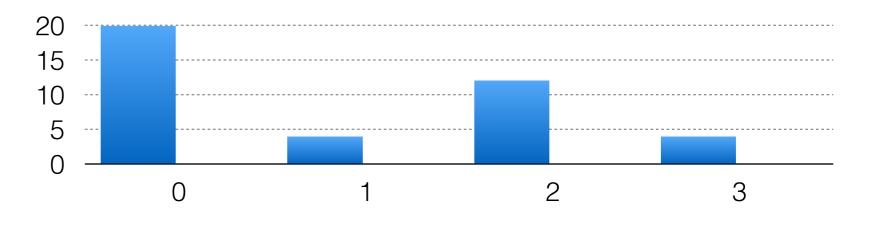
DFT

$$F(k) = \sum_{x=0}^{3} f(x)e^{-j2\pi xk/4}$$
$$= \sum_{x=0}^{3} f(x)(-j)^{xk}$$

Frequency Domain representation

$$\begin{bmatrix} F(0) \\ F(1) \\ F(2) \\ F(3) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \end{bmatrix} = \begin{bmatrix} 20 \\ -j4 \\ 12 \\ j4 \end{bmatrix}$$

Frequency spectrum



The Convolution Theorem

 The Fourier transform of the convolution of two functions is the product of their Fourier transforms

$$\mathcal{F}\{g \star h\} = \mathcal{F}\{g\}\mathcal{F}\{h\}$$

 The inverse Fourier transform of the product of two Fourier transforms is the convolution of the two inverse Fourier transforms

$$\mathcal{F}^{-1}\{gh\} = \mathcal{F}^{-1}\{g\} \star \mathcal{F}^{-1}\{h\}$$

 Convolution in spatial domain is equivalent to multiplication in frequency domain!