

Lecture 6: The Data Stream Model

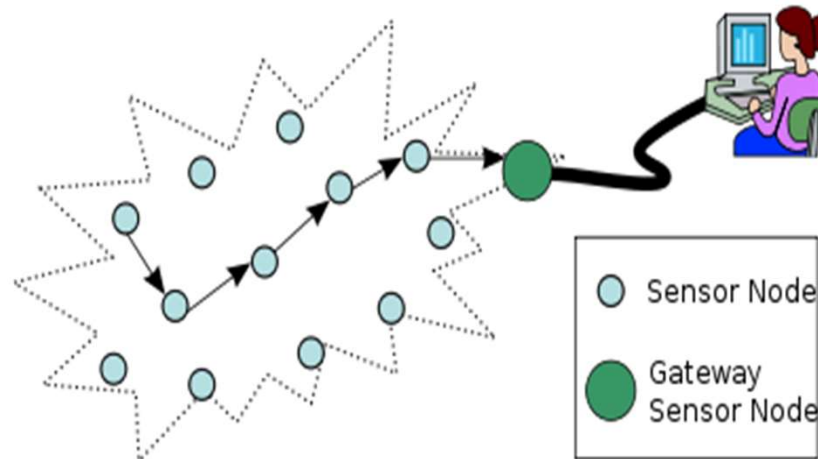
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Data Streams

- A stream is a sequence of data, that is too large to be stored in available memory

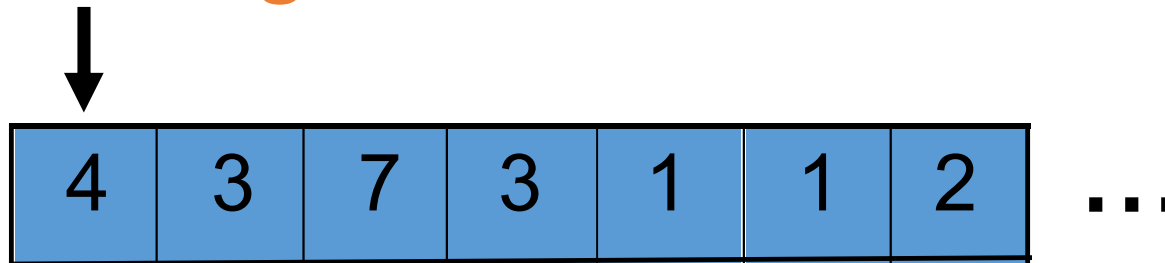
- Examples

- Internet search logs
- Network Traffic
- Sensor networks



- Scientific data streams (astronomical, genomics, physical simulations)...

Streaming Model



- Stream of elements a_1, \dots, a_i, \dots each from an alphabet Σ and taking b bits to represent
- Single or small number of passes over the data
- Almost all algorithms are randomized and approximate
 - Usually necessary to achieve efficiency
 - Randomness is in the **algorithm**, not the **input**
- **Goals:** minimize space complexity (in bits), processing time

Example Streaming Problems

- Let $a_{[1:t]} = \langle a_1, \dots, a_t \rangle$ be the first t elements of the stream
- Suppose a_1, \dots, a_t are integers in $\{-2^b + 1, -2^b + 2, \dots, -1, 0, 1, 2, \dots, 2^b - 1\}$
 - Example stream: 3, 1, 17, 4, -9, 32, 101, 3, -722, 3, 900, 4, 32
- How many bits do we need to maintain $f(a_{[1:t]}) = \sum_{i=1, \dots, t} a_i$?
 - Outputs on example: 3, 4, 21, 25, 16, 48, 149, 152, -570, -567, 333, 337, 379, ...
 - $O(b + \log t)$
- How many bits do we need to maintain $f(a_{[1:t]}) = \max_{i=1, \dots, t} a_i$?
 - Outputs on example: 3, 3, 17, 17, 17, 32, 101, 101, 101, 101, 900, 900, 900, ...
 - $O(b)$ bits

Example Streaming Problems

- The median of all the numbers we've stored so far
 - Example stream: 3, 1, 17, 4, -9, 32, 101, 3, -722, 3, 900, 4, 32
 - Median: 3, 1, 3, 3, 3, 3, 4, 3, ...
 - This seems harder...
- The number of distinct elements we've seen so far?
 - Outputs on example: 1, 2, 3, 4, 5, 6, 7, 7, 8, 8, 9, 9, 9, ...
- The elements that have appeared at least an ϵ -fraction of the time?
These are the ϵ -heavy hitters
 - Cover today

Many Applications

- Internet router may want to figure out which IP connections are heavy hitters, e.g., the ones that use more than .01% of your bandwidth
- Or maybe the router wants to know the median (or 90-th percentile) of the file sizes being transferred
- Hashing is a key technique

Finding ϵ -Heavy Hitters

- S_t is the multiset of items at time t , so $S_0 = \emptyset$, $S_1 = \{a_1\}$, ..., $S_i = \{a_1, \dots, a_i\}$,
 $\text{count}_t(e) = |\{i \in \{1, 2, \dots, t\} \text{ such that } a_i = e\}|$
- $e \in \Sigma$ is an ϵ -heavy hitter at time t if $\text{count}_t(e) > \epsilon \cdot t$
- Given $\epsilon > 0$, can we output the ϵ -heavy hitters?
 - Let's output a set of size $\frac{1}{\epsilon}$ containing all the ϵ -heavy hitters
- **Note:** can output “false positives” but not allowed to output “false negatives”, i.e., not allowed to miss any heavy hitter, but could output non-heavy hitters

Finding ϵ -Heavy Hitters

- Example: E, D, B, D, D₅ D, B, A, C, B₁₀ B, E, E, E, E₁₅, E
(the subscripts are just to help you count)
- At time 5, the element D is the only $1/3$ -heavy hitter
- At time 11, both B and D are $1/3$ -heavy hitters
- At time 15, there is no $1/3$ -heavy hitter
- At time 16, only E is a $1/3$ -heavy hitter

Can't afford to keep counts of all items, so how to maintain a short summary to output the ϵ -heavy hitters?

Finding a Majority Element

- First find a .5-heavy hitter, that is, a majority element:
memory \leftarrow empty and counter \leftarrow 0
when element a_t arrives
 if (counter == 0)
 memory \leftarrow a_t and counter \leftarrow 1
 else
 if $a_t =$ memory
 counter ++
 else
 counter --
 (discard a_t)
- At end of the stream, return the element in memory

~~3~~ ~~1~~ ~~2~~ ~~1~~ 1

Memory = 3, Count = 1

Memory = 3, Count = 0

Memory = 2, Count = 1

Memory = 2, Count = 0

Memory = 1, Count = 1

Analysis of Finding a Majority Element

- If there is no majority element, we output a false positive, which is OK
- If there is a majority element, we will output it. **Why?**
- When we discard an element a_t , we throw away a different element
- When we throw away a copy of a majority element, we throw away another element
 - Either majority element is in memory, or majority element arrives in stream but some other item is in memory
- Majority element is more than half the total number of elements, so can't throw away all of them

Extending to ϵ -Heavy Hitters

Set $k = \left\lceil \frac{1}{\epsilon} \right\rceil - 1$

Array $T[1, \dots, k]$, where each location can hold one element from Σ

Array $C[1, \dots, k]$, where each location can hold a non-negative integer

$C[i] \leftarrow 0$ and $T[i] \leftarrow \perp$ **for** all i

If there is $j \in \{1, 2, \dots, k\}$ such that $a_t = T[j]$, **then** $C[j] + +$

Else if some counter $C[j] = 0$ **then** $T[j] \leftarrow a_t$ and $C[j] \leftarrow 1$

Else decrement all counters by 1 (and discard element a_t)

$\text{est}_t(e) = C[j]$ if $e == T[j]$ for some j , and $\text{est}_t(e) = 0$ otherwise

Analyzing Counts

- **Lemma:** $0 \leq \text{count}_t(e) - \text{est}_t(e) \leq \frac{t}{k+1} \leq \epsilon \cdot t$
- **Proof:** $\text{count}_t(e) \geq \text{est}_t(e)$ since we never increase a counter for e unless we see e

If we don't increase $\text{est}_t(e)$ by 1 when we see an update to e , we decrement k counters and discard the current update to e

So we drop $k+1$ distinct stream updates, but there are t total updates, so we won't increase $\text{est}_t(e)$ by 1, when we should, at most $\frac{t}{k+1} \leq \epsilon \cdot t$ times

Heavy Hitters Guarantee

- At any time t , all ϵ -heavy hitters e are in the array T . **Why?**
- For an ϵ -heavy hitter e , we have $\text{count}_t(e) > \epsilon \cdot t$
- But $\text{est}_t(e) \geq \text{count}_t(e) - \epsilon \cdot t$
- So $\text{est}_t(e) > 0$, so e is in array T
- Space is $O(k (\log(\Sigma) + \log t)) = O(1/\epsilon) (\log(\Sigma) + \log t)$ bits

Heavy Hitters with Deletions

- Suppose we can delete elements e that have already appeared
- Example: (add, A), (add, B), (add, A), (del, B), (del, A), (add, C)
- Multisets at different times
$$S_0 = \emptyset, S_1 = \{A\}, S_2 = \{A, B\}, S_3 = \{A, A, B\}, S_4 = \{A, A\}, S_5 = \{A\}, S_6 = \{A, C\}, \dots$$
- “active” set S_t has size $|S_t| = \sum_{e \in \Sigma} \text{count}_t(e)$ and can grow and shrink

Data Structure for Approximate Counts

- Query “What is $\text{count}_t(e)$?”, should output $\text{est}_t(e)$ with:
$$\Pr[|\text{est}_t(e) - \text{count}_t(e)| \leq \epsilon |S_t|] \geq 1 - \delta$$
- Want space close to our previous $O(1/\epsilon) (\log(\Sigma) + \log t)$ bits
- Let $h: \Sigma \rightarrow \{0, 1, 2, \dots, k - 1\}$ be a hash function (will specify later)
- Maintain an array $A[0, 1, \dots, k-1]$ to store non-negative integers

when update a_t arrives:

if $a_t = (\text{add}, e)$ **then** $A[h(e)] ++$
else $a_t = (\text{del}, e)$, and $A[h(e)] --$

- $\text{est}_t(e) = A[h(e)]$

Data Structure for Approximate Counts

- $A[h(e)] = \sum_{e' \in \Sigma} \text{count}_t(e') \cdot \mathbf{1}(h(e') = h(e))$, where $\mathbf{1}(\text{condition})$ evaluates to 1 if the condition is true, and evaluates to 0 otherwise
- $A[h(e)] = \text{count}_t(e) + \sum_{e' \neq e} \text{count}_t(e') \cdot \mathbf{1}(h(e') = h(e))$,
- $\text{est}_t(e) - \text{count}_t(e) = \sum_{e' \neq e} \text{count}_t(e') \cdot \mathbf{1}(h(e') = h(e))$
- Since we have a small array A with k locations, there are likely many $e' \neq e$ with $h(e') = h(e)$, but can we bound the expected error?

Data Structure for Approximate Counts

- **Recall:** Family H of hash functions $h: U \rightarrow \{0, 1, \dots, k-1\}$ is universal if for all $x \neq y$,

$$\Pr_{h \leftarrow H} [h(x) = h(y)] \leq \frac{1}{k}$$

- Gave a simple family where h can be specified using $O(\log |U|)$ bits. Here, $|U| = |\Sigma|$

- $$\begin{aligned} E[\text{est}_t(e) - \text{count}_t(e)] &= E[\sum_{e' \neq e} \text{count}_t(e') \cdot \mathbf{1}(h(e') = h(e))] \\ &= \sum_{e' \neq e} \text{count}_t(e') \cdot E[\mathbf{1}(h(e') = h(e))] \\ &= \sum_{e' \neq e} \text{count}_t(e') \cdot \Pr[h(e') = h(e)] \\ &\leq \sum_{e' \neq e} \text{count}_t(e') \cdot \left(\frac{1}{k}\right) \\ &= \frac{|S_t| - \text{count}_t(e)}{k} \leq \frac{|S_t|}{k} \end{aligned}$$

$k = 1/\epsilon$ makes this at most $\epsilon \cdot |S_t|$. Space is $O\left(\frac{1}{\epsilon}\right)$ counters plus storing hash function

High Probability Bounds for CountMin

- Have $0 \leq \text{est}_t(e) - \text{count}_t(e) \leq |S_t|/k$ in expectation from CountMin
 - With probability $1/2$, $\text{est}_t(e) - \text{count}_t(e) \leq 2|S_t|/k$ **Why?**
- Can we make the success probability $1-\delta$?
 - Independent repetition: pick m hash functions h_1, \dots, h_m with $h_i: \Sigma \rightarrow \{0, 1, 2, \dots, k-1\}$ independently from H . Create array A_i for h_i when update a_t arrives:
 - for** each i from 1 to m
 - if** $a_t = (\text{add}, e)$ **then** $A_i[h_i(e)] ++$
 - else** $a_t = (\text{del}, e)$ and $A_i[h_i(e)] --$

High Probability Bounds and Overall Space

What is our new estimate of $\text{count}_t(e)$?

$$\text{best}_t(e) := \min_{i=1}^m A_i[h_i(e)].$$

- Each $A_i[h_i(e)]$ is an *overestimate* to $\text{count}_t(e)$
- By independence, $\Pr[\text{for all } i, A_i[h_i(e)] - \text{count}_t(e) \geq 2|S_t|/k] \leq \left(\frac{1}{2}\right)^m$
- For $k = \frac{2}{\epsilon}$ and $m = \log_2\left(\frac{1}{\delta}\right)$, the error is at most $\epsilon|S_t|$ with probability $1-\delta$
- Space: $m \cdot k = O\left(\frac{\log\left(\frac{1}{\delta}\right)}{\epsilon}\right)$ counters each of $O(\lg t)$ bits
 $m \cdot O(\log |\Sigma|) = O\left(\log\left(\frac{1}{\delta}\right) \log|\Sigma|\right)$ bits to store hash functions

ϵ -Heavy Hitters

- Our new estimate $\text{best}_t(e)$ satisfies
$$\Pr[|\text{best}_t(e) - \text{count}_t(e)| \leq \epsilon |S_t|] \geq 1 - \delta$$

and uses $O\left(\frac{\log\left(\frac{1}{\delta}\right) \log t}{\epsilon} + \log\left(\frac{1}{\delta}\right) \log |\Sigma|\right)$ bits of space

- What if we want with probability 9/10, simultaneously for all e , $|\text{best}_t(e) - \text{count}_t(e)| \leq \epsilon |S_t|$?
- Set $\delta = \frac{1}{10|\Sigma|}$ and apply a union bound over all $e \in \Sigma$