02-251 Recitation 1 Genome Assembly

Wendy & Hongyu 01/18/2019

Outline

- Solving problems on Stepik
- A review of lecture materials
- Biological side of genome assembly
- More algorithms!!!

Solving problems on Stepik

- Authenticate before you solve!!!!
- https://stepik.org/lesson/201025/step/1?unit=175124

Review of lecture material

Multiple identical copies of a genome

Shatter the genome into reads

Sequence the reads

AGAATATCA TGAGAATAT GAGAATATC

Assemble the genome using overlapping reads

AGAATATCA GAGAATATC TGAGAATAT

..TGAGAATATCA...

Review of lecture material

String Reconstruction Problem. Reconstruct a string from its k-mer composition.

Input: A collection *Patterns* of *k*-mers.

Output: A string *Text* whose *k*-mer composition

is equal to Patterns.

Hamiltonian Cycle Problem

Input: a network with *n* nodes.

Output: "Yes" if there is a cycle visiting every

node in the network; "No" otherwise.

Eulerian Cycle Problem

Input: a network with *n* nodes.

Output: "Yes" if there is a cycle visiting every

edge in the network; "No" otherwise.

Compeau and Pevzner, 2018

Review of lecture material

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Assemble the genome using overlapping reads

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GAGAATATC

TGAGAATAT

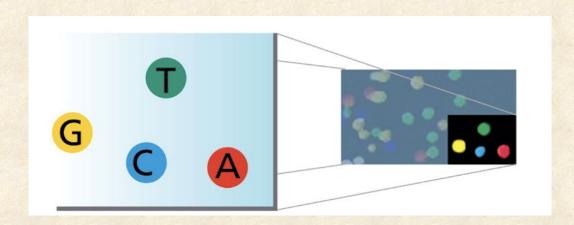
..TGAGAATATCA...

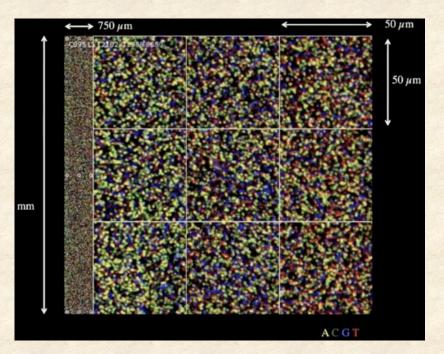
Biological side of genome assembly

How do we get the reads?

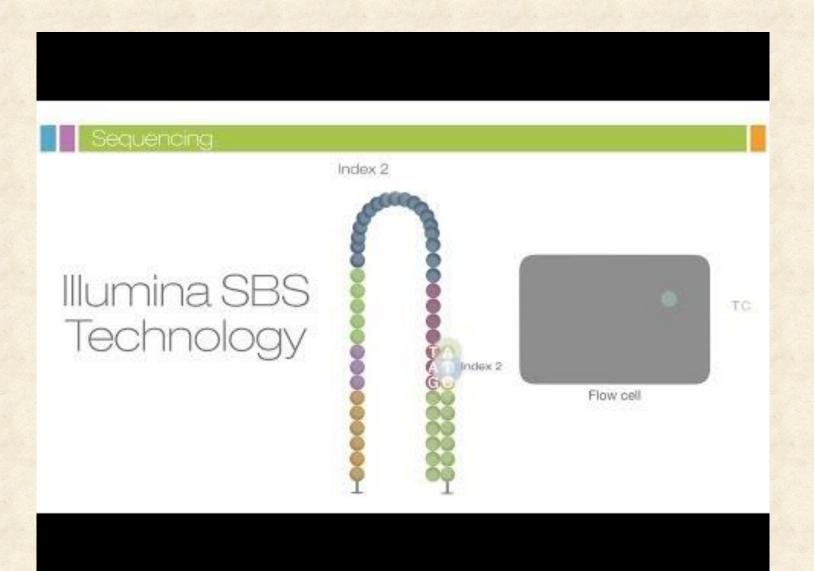
Basic idea: during DNA replication, we can add nucleotides with different fluorescent labels, detect the light emitted, and determine which nucleotide

was attached





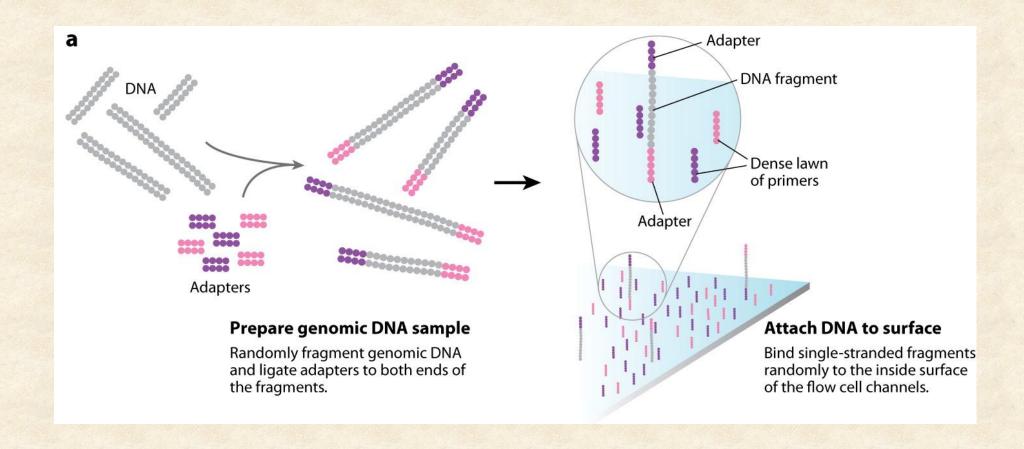
Sequencing by synthesis



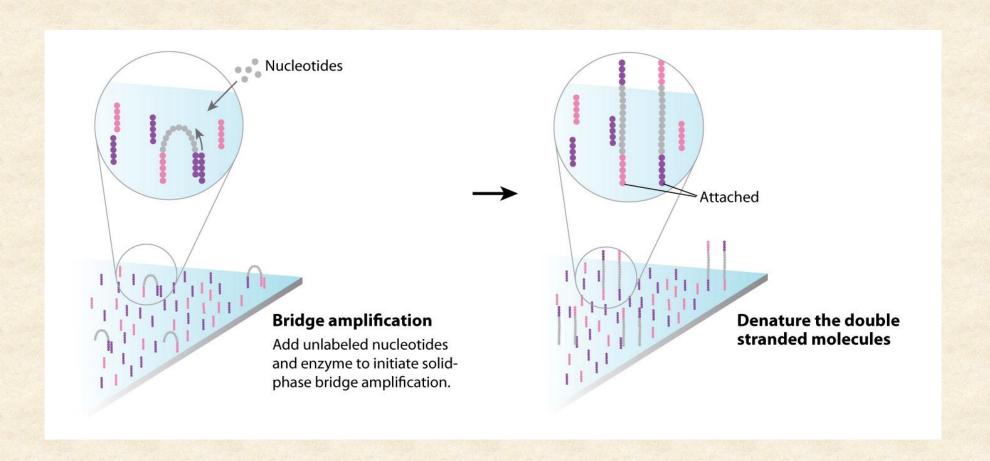
Sequencing by synthesis

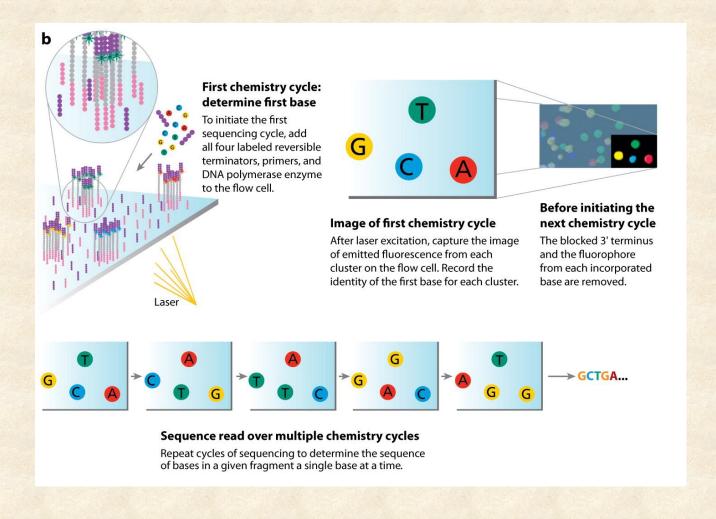


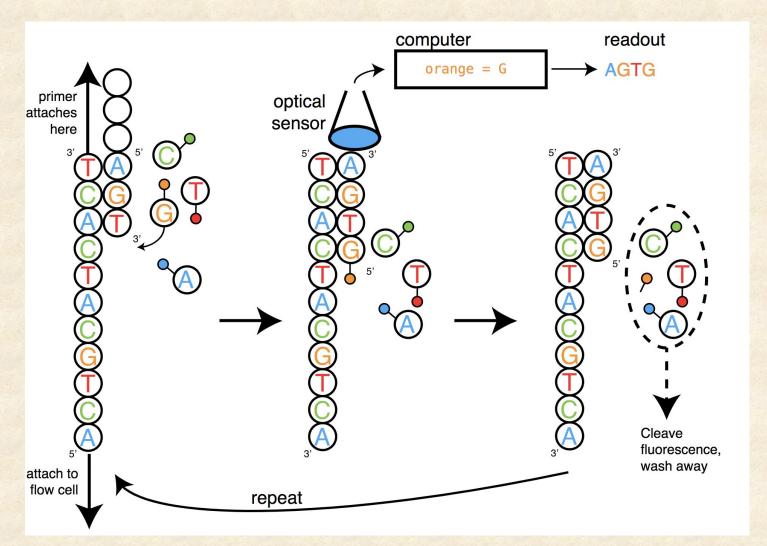
Sequencing by synthesis - Modification



Sequencing by synthesis - Amplification







Chemistry cycle during sequencing:

Reversible terminator binding to DNA template

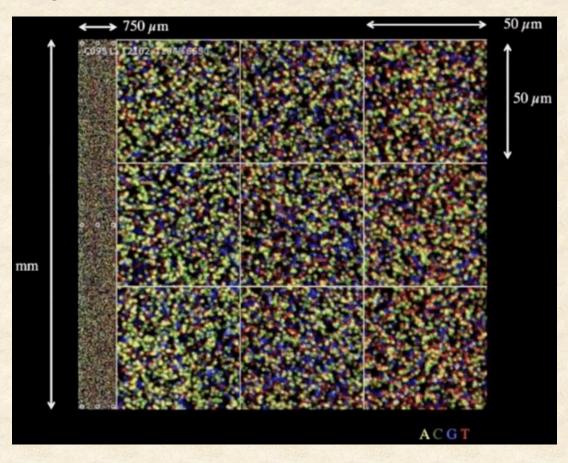


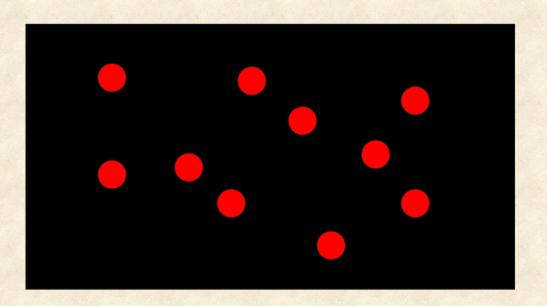
Fluorescent light emitted and captured by the sensor

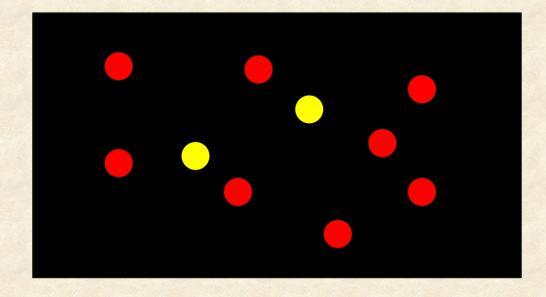


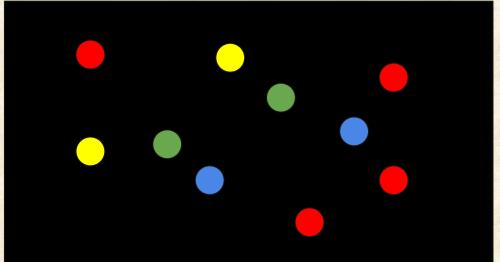
Blocking removed, allowing a new reversible terminator to bind

Tracking the light is also a computational problem!!!









More Background in Assemblies:

- The Old Guards
- Metric of Quality
- The Assemblathon

Basic Algorithms Stuff

- Finding a Eulerian Circuit
- Non-Branching Paths
- FInding All Eulerian Circuits

The OLC Family

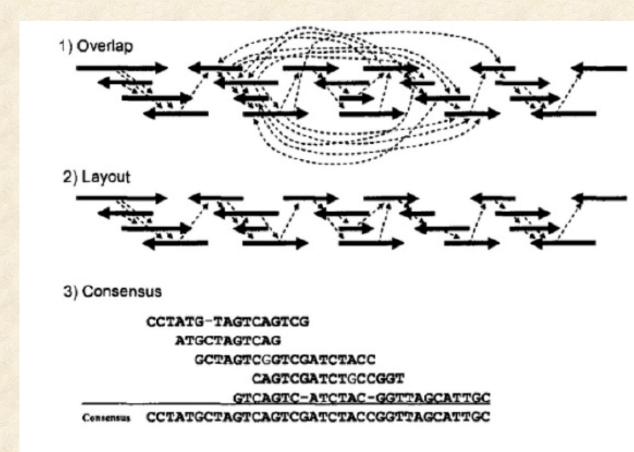
a.k.a <u>Hamiltonian-Circuit Family</u>

Overlap: Align sequences against each other and find overlaps

Layout: Find an arrangement of reads that respect some rules

Consensus: Merge all seen sequences with overlaps

- Mainstream algorithm in early times
- Gets pretty messy with the rules, got scaling issues, and is now superseded by de Burgin graph based algorithms



Credit: Masahiro Kasahara, Large-Scale Genome Sequence Processing,

Imprerial College Press

Reality of Assemblies

You don't get a single sequence for one chromosome every time(or practically, never).

Now say I and Wendy have two assemblies. Each of several contigs/scaffolds.

Think about this: How do you know which one is better?

Quality Assessment

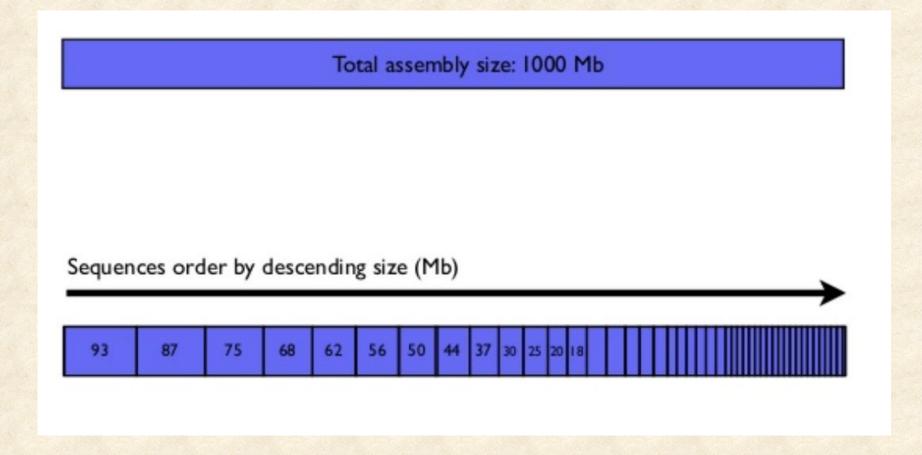
Some simple case.

- Size If you know the expected sequence is 400Mbp(bp = base pair) but I gave you something of 20Mbp...
- Coverage If I don't even most of the inputs in your assembles...

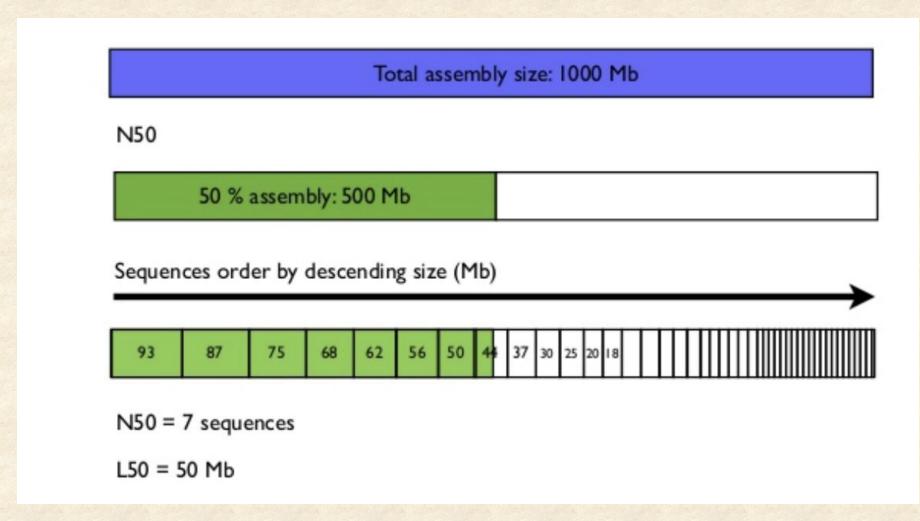
Most people don't make this type of mistakes.

- Mean Fragment Size Trick the judge by throwing out short fragments
- The most accepted metric for nowadays is N50/L50

Setting Up



N50/L50



The Assemblathon

Question: What is the best assembler in the world?

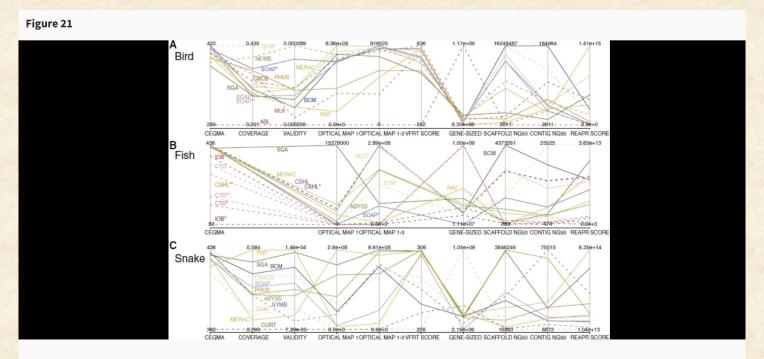
If everyone claims their assembly method is the best, then let's hold a contest. They got a cool logo. At least by 2007 standards, I guess.



The Assemblathon (The Sequel)

Species	Estimated genome size	Illumina	Roche 454	Pacific biosciences
Bird (Melopsittacus undulatus)	1.2 Gbp	285x coverage from 14 libraries (mate pair and paired-end)	16x coverage from 3 library types (single end and paired-end)	10x coverage from 2 librarie
Fish (<i>Maylandia zebra</i>)*	1.0 Gbp	192x coverage from 8 libraries (mate pair and paired-end)	NA	NA
Snake (Boa constrictor constrictor)	1.6 Gbp	125x coverage from 4 libraries (mate pair and paired-end)	NA	NA

The Assemblathon (The Sequel)



Parallel coordinate mosaic plot showing performance of all assemblies in each key metric. Performance of bird, fish, and snake assemblies (panels A–C) as assessed across ten key metrics (vertical lines). Scales are indicated by values at the top and bottom of each axis. Each assembly is a colored, labeled line. Dashed lines indicate teams that submitted assemblies for a single species whereas solid lines indicate teams that submitted assemblies for multiple species. Key metrics are CEGMA (number of 458 core eukaryotic genes present); COVERAGE and VALIDITY (of validated Fosmid regions, calculated using COMPASS); OPTICAL MAP 1 and OPTICAL MAP 1–3 (coverage of optical maps at level 1 or at all levels); VFRT SCORE (summary score of validated Fosmid region tag analysis), GENE-SIZED (the amount of an assembly's scaffolds that are 25 Kbp or longer); SCAFFOLD NG50 and CONTIG NG50 (the lengths of the scaffold or contig that takes the sum length of all scaffolds/contigs past 50% of the estimated genome size); REAPR SCORE (summary score of scaffolds from REAPR tool).

The Assemblathon (The Sequel)

Can't get enough authors!

Results?

 However, the high degree of variability between the entries suggests that there is still much room for improvement in the field of genome assembly and that approaches which work well in assembling the genome of one species may not necessarily work well for another.

Basically there are no overall winner

Assemblathon 2: evaluating *de novo* methods of genome assembly in three vertebrate species 3

Keith R Bradnam ▼, Joseph N Fass, Anton Alexandrov, Paul Baranay, Michael Bechner, Inanç Birol, Sébastien Boisvert, Jarrod A Chapman, Guillaume Chapuis, Rayan Chikhi, Hamidreza Chitsaz, Wen-Chi Chou, Jacques Corbeil, Cristian Del Fabbro, T Roderick Docking, Richard Durbin, Dent Earl, Scott Emrich, Pavel Fedotov, Nuno A Fonseca, Ganeshkumar Ganapathy, Richard A Gibbs, Sante Gnerre, Élénie Godzaridis, Steve Goldstein, Matthias Haimel, Giles Hall, David Haussler, Joseph B Hiatt, Isaac Y Ho, Jason Howard, Martin Hunt, Shaun D Jackman, David B Jaffe, Erich D Jarvis, Huaiyang Jiang, Sergey Kazakov, Paul J Kersey, Jacob O Kitzman, James R Knight, Sergey Koren, Tak-Wah Lam, Dominique Lavenier, François Laviolette, Yingrui Li, Zhenyu Li, Binghang Liu, Yue Liu, Ruibang Luo, Iain MacCallum, Matthew D MacManes, Nicolas Maillet, Sergey Melnikov, Delphine Naquin, Zemin Ning, Thomas D Otto, Benedict Paten, Octávio S Paulo, Adam M Phillippy, Francisco Pina-Martins, Michael Place, Dariusz Przybylski, Xiang Qin, Carson Qu, Filipe J Ribeiro, Stephen Richards, Daniel S Rokhsar, J Graham Ruby, Simone Scalabrin, Michael C Schatz, David C Schwartz, Alexey Sergushichev, Ted Sharpe, Timothy I Shaw, Jay Shendure, Yujian Shi, Jared T Simpson, Henry Song, Fedor Tsarev, Francesco Vezzi, Riccardo Vicedomini, Bruno M Vieira, Jun Wang, Kim C Worley, Shuangye Yin, Siu-Ming Yiu, Jianying Yuan, Guojie Zhang, Hao Zhang, Shiguo Zhou, Ian F Korf 🗷 **Author Notes**

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Theory Homework #1

PSA: <u>For some of these homeworks you are graded on your effort even if your solution is not correct.</u>

Answer #1: Use nodes as k-mers, directed edges to denote (k-1)-mer overlap.

Answer #2: Find a Hamiltonian path over the nodes(assuming no duplicate k-mers).

- What if in #1, I add an edge as long as nodes have some overlap? (Say, if two 5-mers have 3-bp overlap, I add an edge as well.)

Theory Homework #1

You will get suboptimal assemblies. Or blowups. (Boom.)

Example:

Sequence is ATCAT. 3-mers are ATC, TCA, CAT.

Correct/optimal Hamiltonian path is ATC->TCA->CAT.

a valid Hamiltonian path: CAT->TCA->ATC, get the sequence CATCATC instead.

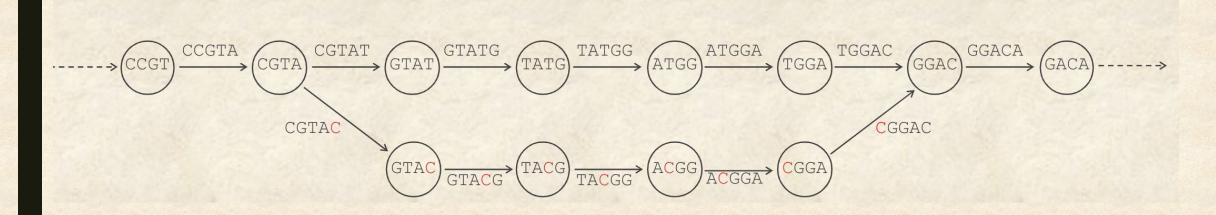
Non-Branching Paths

Input:

A Directed Graph G = (V, E).

Output:

Set of Maximal Non-Branching Paths - Paths that all internal vertices have in degree of 1 and out degree of 1, and is not subpath of any other Non-Branching Paths



Non-Branching Paths

Key observation:

- No two MNBP share starting edge.
- Starting edge of MNBP decides the maximal path itself.

Just iterate over all possible starting edges and be done.

- For each edge (u, v): If u is not a 1-in-1-out node, (u, v) is eligible to start an MNBP.
- Walk from v until current vertex is no longer 1-in-1-out.
- Add visited nodes to results.

Non-Branching Paths

Pitfall: 1-in-1-out edges can start NMBP. It happens in isolated circles.

The **MaximalNonBranchingPaths** pseudocode below generates all non-branching paths in a graph. It iterates through all nodes of the graph the are not 1-in-1-out nodes and generates all non-branching paths starting at each such node. In a final step, **MaximalNonBranchingPaths** finds a isolated cycles in the graph.

Building an Eulerian Circuit

Input:

A Graph G = (V, E). Ensures G have a Eulerian Circuit(strongly connected, each vertex have same in-degree and out-degree).

Output:

A sequence of vertices.

Pick any vertex as a starting point.

Travel on the graph, removing visited edges on the way. Stop when you get back to the starting vertex.

If there are vertices on the tour that have unvisited edges, start from that vertex and join the resulting path.

Proof of Correctness:

- 1. You cannot get stuck at other vertices.
- 2. You don't end up with unvisited cycles.

```
function explore(v) {
    ret := [], cur := v
    while (cur != v) {
        find an outgoing edge: (cur -> next)
            remove edge, ret += [cur], cur := next
    }
    return ret
}
```

```
function explore(v)
function circuit {
     path := explore(0)
     while graph is not empty {
         find v in path that have nonzero degree
         idx = path.index(v)
         path = path[:idx] + explore(v) + path[idx:]
     return path
```

OK, that's not very cool. Concatenating lists take a long time in some cases.

Brainstorming: An O(M) algorithm?

```
tour := []
result := []
function explore(v) {
      cur := v
      while (cur != v) {
            find an outgoing edge: (cur -> next)
            remove edge, <u>push cur to tour</u>, cur := next
```

```
tour := []
result := []
function explore(v) {
      cur := v
      while (cur != v) {
            find an outgoing
edge: (cur -> next)
             remove edge, <u>push</u>
cur to tour, cur := next
```

```
function circuit {
     explore(0)
     while tour is not empty {
         pop v from tour, push v to result
         if v has more edges: explore(v)
     return result # read from top
```

Counting Eulerian Circuits

Input:

A Directed Graph G = (V, E). Ensures G have a Eulerian Circuit(strongly connected, each vertex have same in-degree and out-degree). We also assume G have no duplicate edges.

Output:

Number of Eulerian Circuits in G. Two ECs are same if list of visited vertices are the same after rotation.

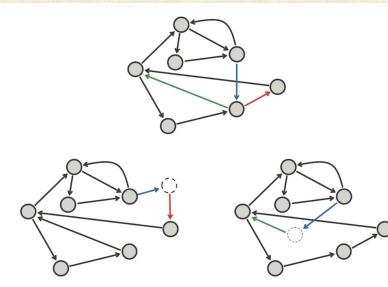
Counting Eulerian Circuits

The core idea: Transform one graph with n possible circuit into n graphs with 1 possible circuit.

Fix edge (u, v). If v have multiple out edges, for each of them (v, w), create a new graph where the edges (u, v) and (v, w) are removed, a new vertex x is added alongside with edges (u, x) and (x, w).

Question 1: Why does this converge?

Question 2: Correctness?



Counting Eulerian Circuits

The core idea: Transform one graph with n possible circuit into n graphs with 1 possible circuit.

Fix edge (u, v). If v have multiple out edges, for each of them (v, w), create a new graph where the edges (u, v) and (v, w) are removed, a new vertex x is added alongside with edges (u, x) and (x, w).

Question 1: Why does this converge?

- Each new graph have one more vertex than the old graph so it can't go on forever.

Question 2: Correctness?

- Fix starting edge, every Eulerian circuit can be mapped to a expanded simple graph and vice versa.

Exercise Break: Show that any Eulerian cycle in *Graph* passing through (u, v) and then (v, w) corresponds to an Eulerian cycle (with the same edge labels) in the (u, v, w)-bypass graph passing through (u, x) and then (x, w).

In general, given an incoming edge (u, v) into v along with k outgoing edges $(v, w_1), \ldots, (v, w_k)$ from v, we can construct k different bypass graphs (the figure in the previous step (bottom)). Note that since no two bypass graphs have the same Eulerian cycle, the total number of Eulerian cycles in all k of these bypass graphs is equal to the number of Eulerian cycles in the original graph.

Our idea, roughly stated, is to iteratively construct every possible bypass graph for *Graph* until we obtain a large family of simple directed graphs; each one of these graphs will correspond to a distinct Eulerian cycle in *Graph*. This idea is implemented by the pseudocode in the next step.

AllEulerianCycles(Graph)

AllGraphs ← the set consisting of a single graph Graph
while there is a non-simple graph G in AllGraphs
v ← a node with indegree larger than 1 in G
for each incoming edge (u, v) into v
for each outgoing edge (v, w) from v
NewGraph ← (u, v, w)-bypass graph of G
if NewGraph is connected
add NewGraph to AllGraphs
remove G from AllGraphs
for each graph G in AllGraphs
output the (single) Eulerian cycle in G

Extra Question...

How many Eulerian Circuits can a graph of M edges have?

Extra Question...

At least (M/2-1)!: the star graph

Group Discussion

- In practice, biologists use multiple libraries of read-pairs with different "insert sizes" (distance between ends of the reads). Why might they do this?
- How might we measure the "quality" of a collection of different assemblies?