Searching for Population Structure

Principal Component Analysis and Clustering

Phillip Compeau

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Recall: Mapping Reads against Reference

Multiple identical copies of a genome

Shatter the genome into reads

Sequence the reads (Lab)

AGAATATCA TGAGAATAT GAGAATATC

Then, we "map" these reads against a reference human genome (the most commonly used reference is 70% RP11, or "some guy from Buffalo").

Another Aim: Understanding "Population Structure"

Population structure: genetic differences between subpopulations in a population of individuals (i.e., the human species).

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Checkpoint: any thoughts on how we could use existing approaches we have learned to find population structure?

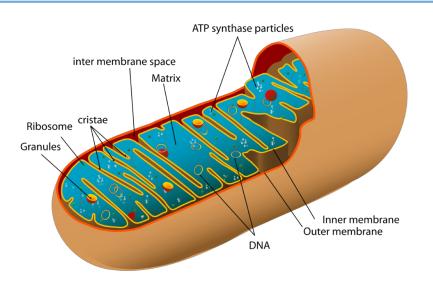
Another Aim: Understanding "Population Structure"

Population structure: genetic differences between subpopulations in a population of individuals (i.e., the human species).

Checkpoint: any thoughts on how we could use existing approaches we have learned to find population structure?

This sounds a lot like evolutionary tree construction.

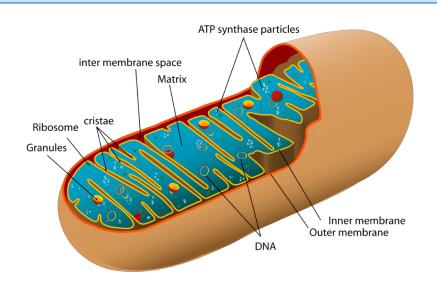
Mitochondrial genome: a 16,569 base-pair circular chromosome replicated independently of "nuclear DNA" in mitochondria and inherited maternally.



https://commons.wikimedia.org/wiki/Mitochondrion#/media/File:Animal_mitochondrion_diagram_en.svg

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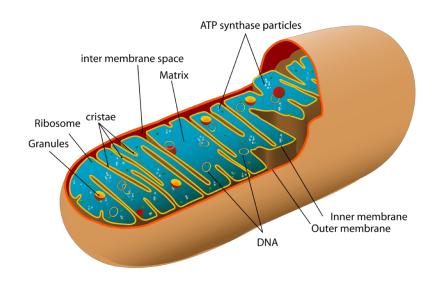
Checkpoint: Where do you think that mitochondria came from?



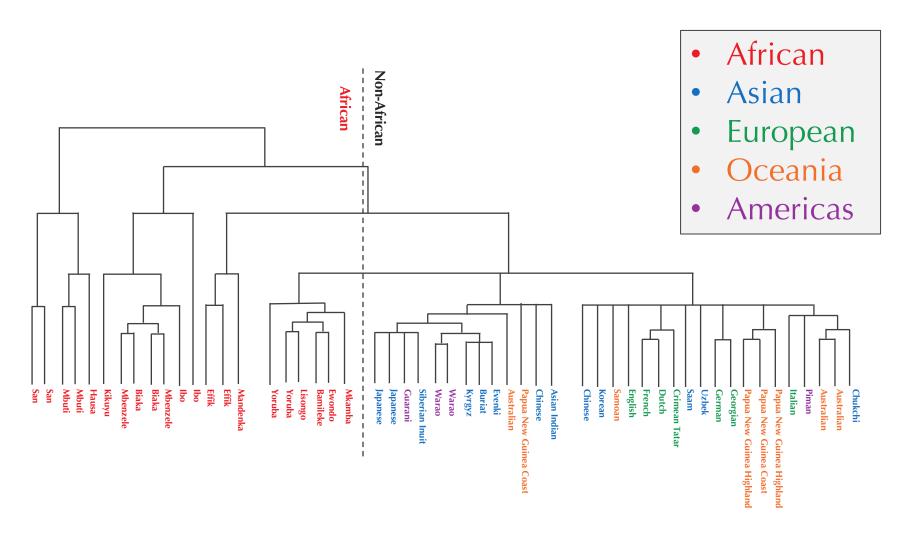
https://commons.wikimedia.org/wiki/Mitochondrion#/media/File:A nimal_mitochondrion_diagram_en.svg

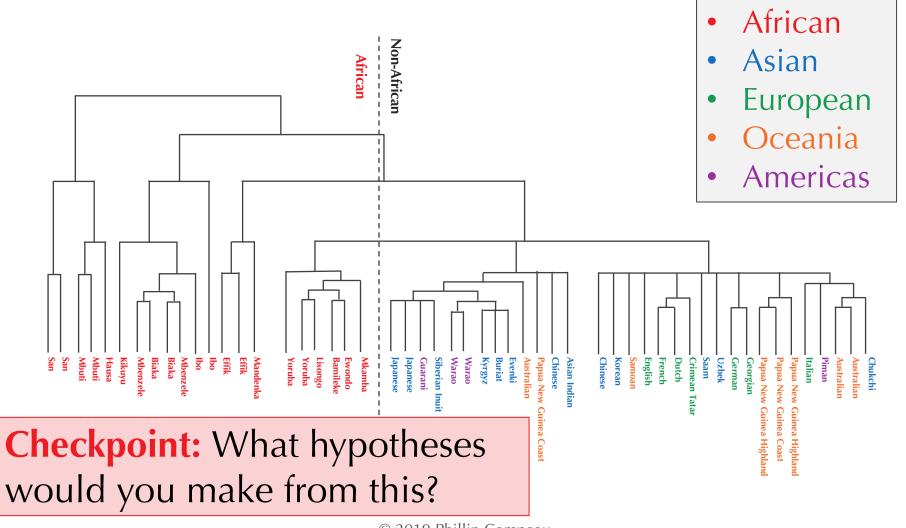
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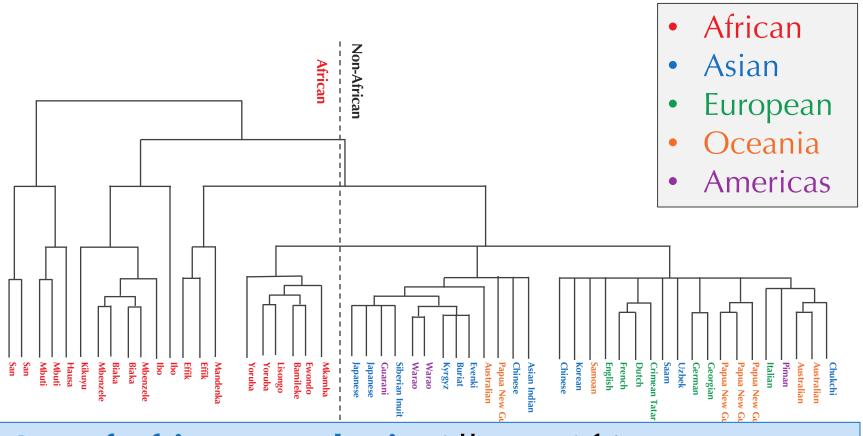
Note: "mtDNA" was used in human studies before cheap full genome sequencing because it is abundant in cells and short.



https://commons.wikimedia.org/wiki/Mitochondrion#/media/File:A nimal_mitochondrion_diagram_en.svg



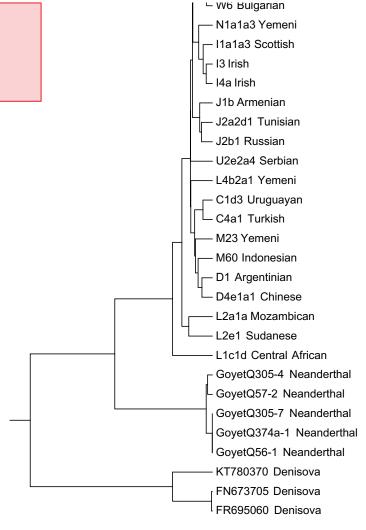




Out of Africa Hypothesis: All non-Africans are descended from a migration ~70,000 years ago.

Adding Neanderthals/Denisovans to the Mix

Checkpoint: What hypotheses would you make from this?

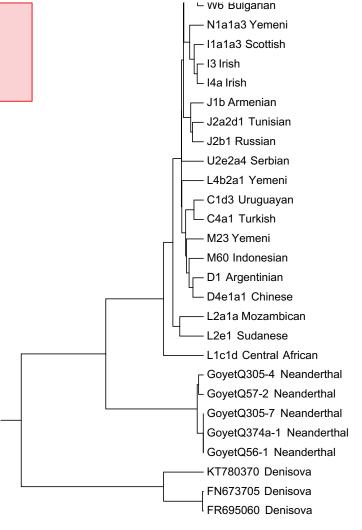


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Neanderthals/Denisovans,

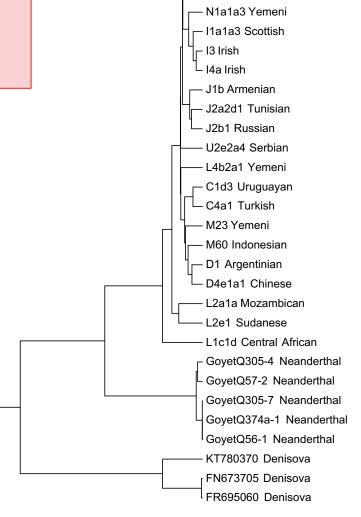
ancient humans living in Europe/Siberia, seem to be distinct from modern humans.



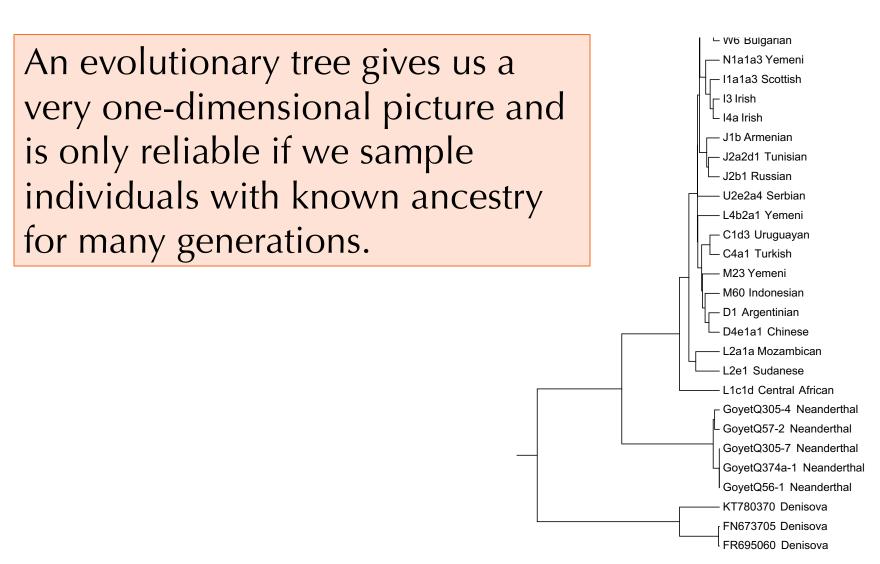
Adding Neanderthals/Denisovans to the Mix

Checkpoint: What hypotheses would you make from this?

Wrong! Europeans may be up to 4% Neanderthal, and Australian aborigines up to 6% Denisovan.



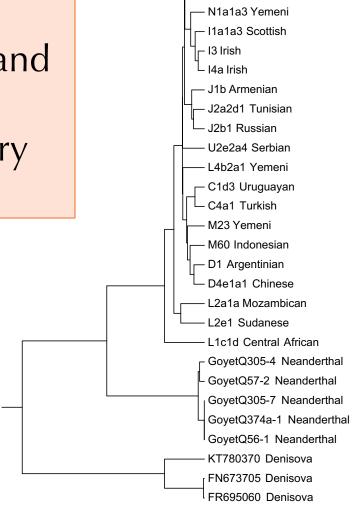
From Strict Population Structure to Admixture



From Strict Population Structure to Admixture

An evolutionary tree gives us a very one-dimensional picture and is only reliable if we sample individuals with known ancestry for many generations.

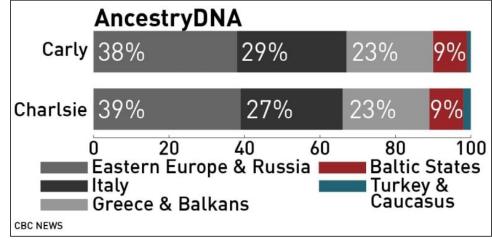
But how can we say that you are x% Eastern European, y% West African, z% Native American, etc.? This is admixture.

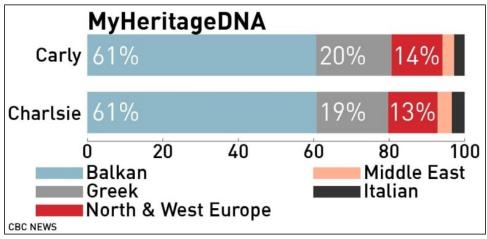


"Twins get 'Mystifying' [Genotyping] Results"

"[Genotyping is] kind of a science and an art" – Paul Maier, population geneticist at FamilyTreeDNA

"Compromise is the shared hypotenuse of the conjoined triangles of success." – Jack Barker, Silicon Valley





https://www.cbc.ca/news/technology/dna-ancestry-kits-twins-marketplace-1.4980976

From Genomics to Genotyping

Genotyping: Identifying a collection of genetic markers that an individual possesses without obtaining full sequencing information.

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- Single-nucleotide polymorphisms (SNPs): single nucleotide variants present in > 1% of population.
- Short tandem repeats (STRs): short number of base pairs repeating a variable number of times consecutively.

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Companies will sample 100K to 1 million markers on the order of \$100.

- Input: A collection of n markers for m individuals.
- Output: an identification of population structure in a multi-dimensional way that makes it easy for us to visualize admixture.

- **Input:** A collection of *n* markers for *m* individuals.
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Checkpoint: How could we represent the *n* markers for a given individual?

- **Input:** A collection of *n* markers for *m* individuals.
- Output: an identification of population structure in a multi-dimensional way that makes it easy for us to visualize admixture.

Answer: Each individual corresponds to a {0, 1, 2}-valued point (vector) in *n*-dimensional space.

(2, 1, 0, 1, 1, 0, 0, 1, 2, 1, 1, 0, 1, 2, 0, 1)

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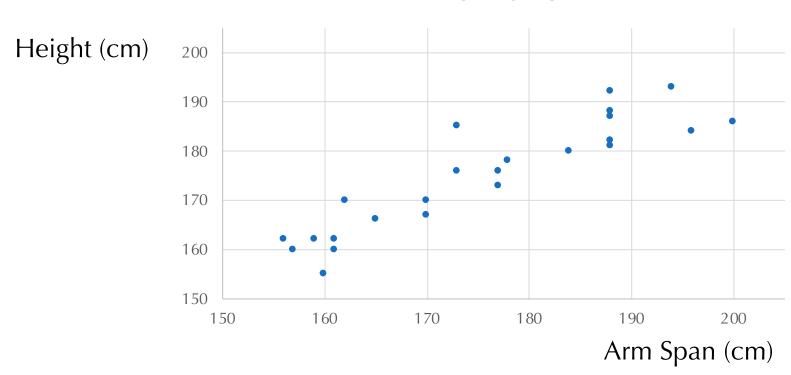
Answer: Each individual corresponds to a {0, 1, 2}-valued point (vector) in *n*-dimensional space.

(2, 1, 0, 1, 1, 0, 0, 1, **2**, 1, 1, 0, 1, 2, 0, 1)

Number of alleles over two chromosomes for kth marker

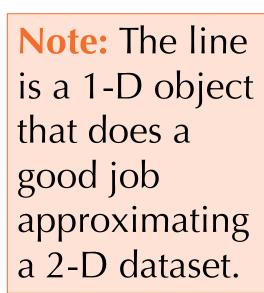
A 2-Dimensional Example

Arm Span vs. Height in Humans

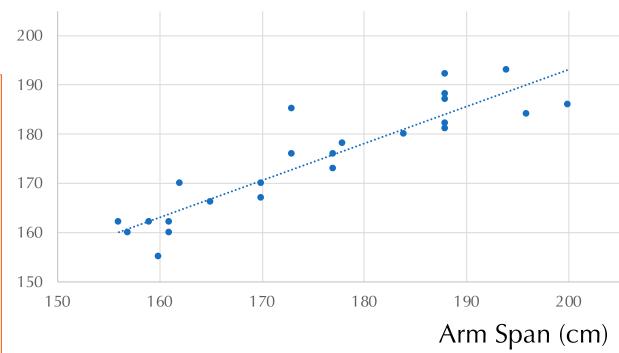


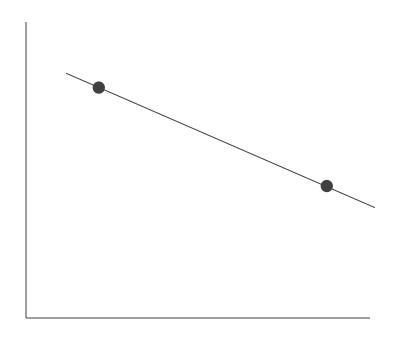
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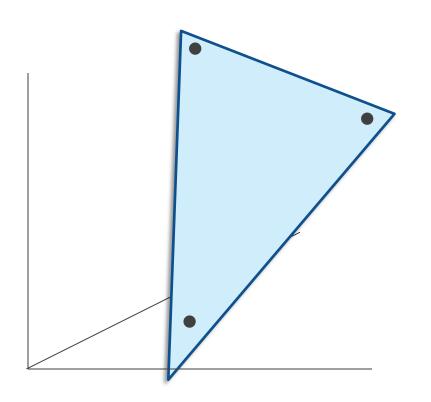


Height (cm)

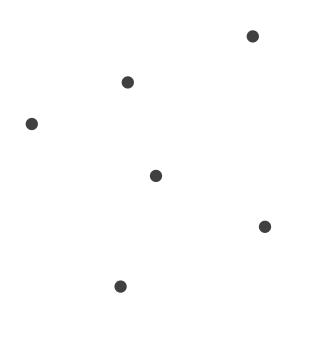




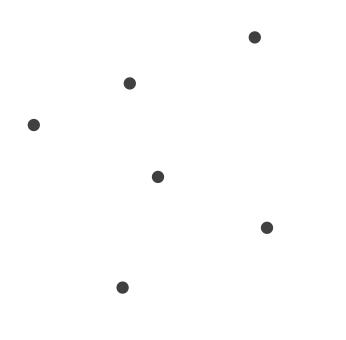
In any dimensional space, I can always find a line that "perfectly explains" two given points.



In any dimensional space, I can always find a line or a plane that "perfectly explains" three given points.



In n dimensional space, I can always find a "hyperplane" of dimension at most k-1 that "perfectly explains" k < n given points.



In n dimensional space, I can always find a "hyperplane" of dimension at most k-1 that "perfectly explains" k < n given points.

Checkpoint: What will happen if we use 1 million markers for a sample of 100,000 people?

Curse of dimensionality: The phenomenon that having more dimensions than samples can produce a space so sparse that any "signal" gets washed out.

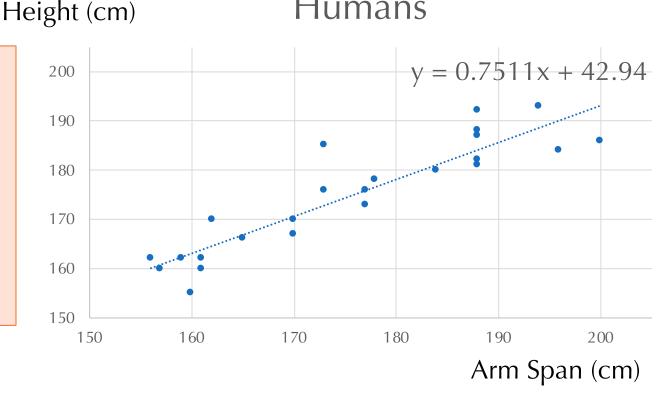
Curse of dimensionality: The phenomenon that having more dimensions than samples can produce a space so sparse that any "signal" gets washed out.

Dimension reduction:

Reducing the number of dimensions of a dataset in order to avoid the "curse" and better visualize its analysis.

Arm Span vs. Height in Humans

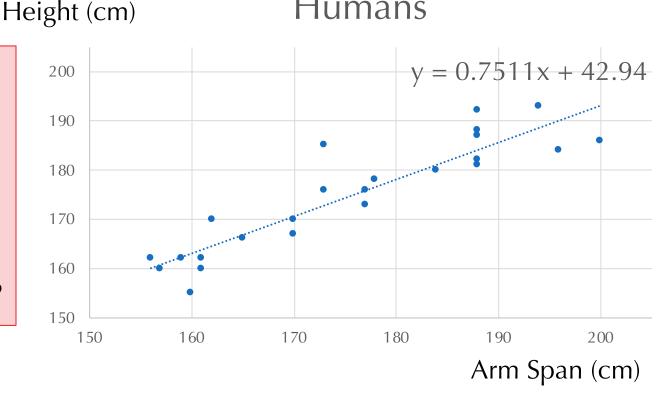
Goal: Find the line explaining "as much variance as possible"



Arm Span vs. Height in Humans

Checkpoint:

Where do you think the equation for the line comes from?

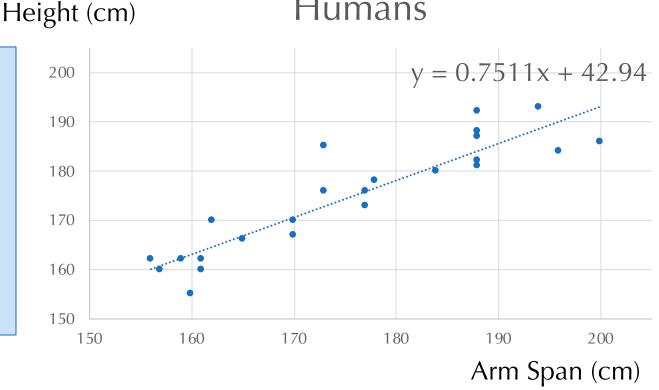


Arm Span vs. Height in Humans

Regression:

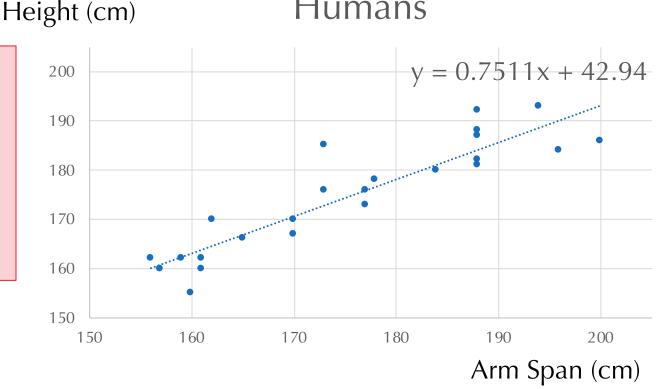
Minimize the sum of

(y_{observed} – y_{predicted})² over all y.



Arm Span vs. Height in Humans

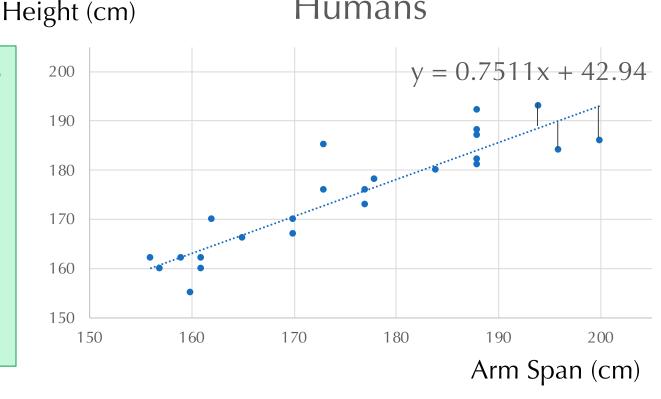
Checkpoint:
where are
the (y_{observed}
- y_{predicted})²
in this plot?



Back to Our Example

Arm Span vs. Height in Humans

Answer: The (square of) vertical distances from each point to the line.

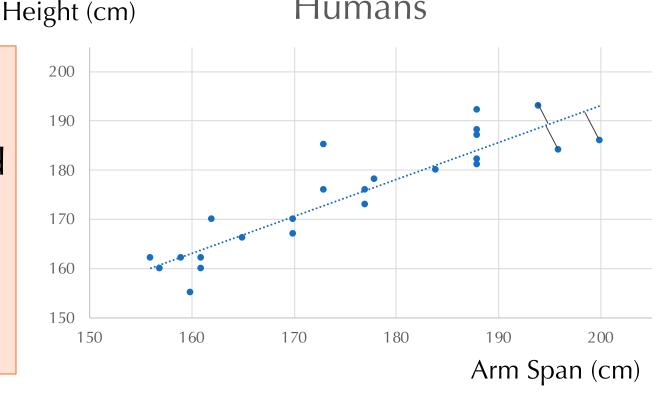


https://www.learner.org/courses/learningmath/data/session7/part_a/further.html

Back to Our Example

Arm Span vs. Height in Humans

If y isn't a function of x, we should minimize squared distances to line.



https://www.learner.org/courses/learningmath/data/session7/part_a/further.html

Principal Component Analysis (PCA) Problem

- Input: A collection of data points Data in ndimensional space and an integer d < n.
- Output: the *d*-dimensional "linear hyperplane" through *Data* minimizing the sum of squared distances from points in *Data* to the hyperplane.

Principal Component Analysis (PCA) Problem

- **Input:** A collection of data points Data in n-dimensional space and an integer d < n.
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Checkpoint: In matrix algebra, Principal Component Analysis is called ______.

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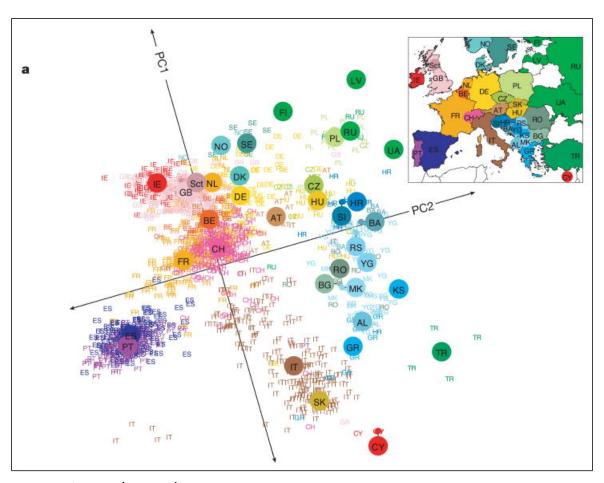
Answer: In matrix algebra, Principal Component Analysis is called "singular value decomposition".

Principal Component Analysis (PCA) Problem

- Input: A collection of data points Data in ndimensional space and an integer d < n.
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Note: we can then associate each point *Datapoint* with its nearest point *Datapoint'* on the hyperplane and "reduce" the dimension of *Data* to *d*.

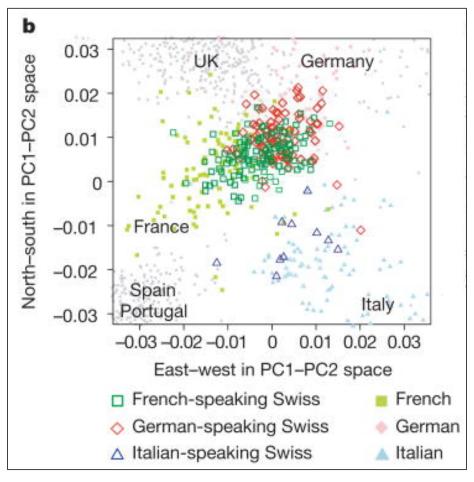
PCA with d = 2 Shows Europe is Inbred



Novembre et al. 2008, https://www.ncbi.nlm.nih.gov/pmc/articles/PMC2735096/

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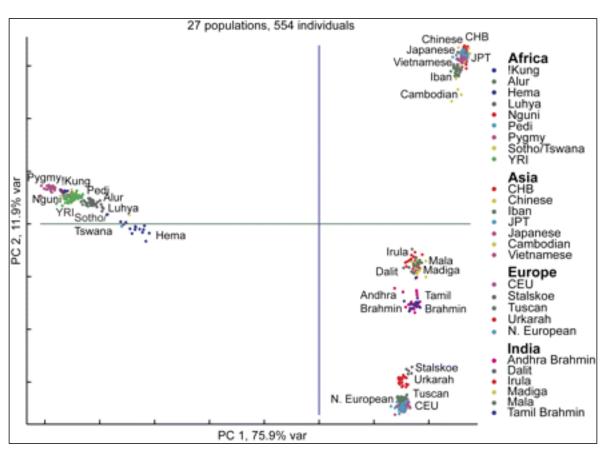
Switzerland's Genes Divide out by Language Spoken



Novembre et al. 2008, https://www.ncbi.nlm.nih.gov/pmc/articles/PMC2735096/

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Continental Structure is Visible Too



Xing et al. 2009, https://genome.cshlp.org/content/19/5/815.full.html

Returning to Our Original Aim

- Input: A collection of n markers for m individuals.
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Returning to Our Original Aim

- **Input:** A collection of *n* markers for *m* individuals.
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Note: dimensionality reduction will help *as an initial step*, but we should address this problem under the assumption that we don't know the ancestry of most or all individuals.

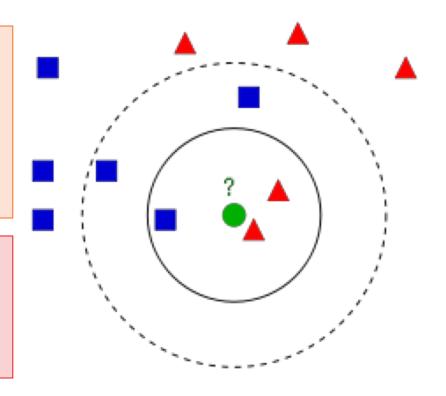
High-Level Overview of Classification

Classification Problem

- Input: A collection of data points divided into a training set (known ancestry) and a test set. (unknown ancestry). Each training data point has a label corresponding to its ancestry.
- Output: a predictive labeling of all the points in the test set.

Say that we have classified training data labeled blue and red, and a new point (green).

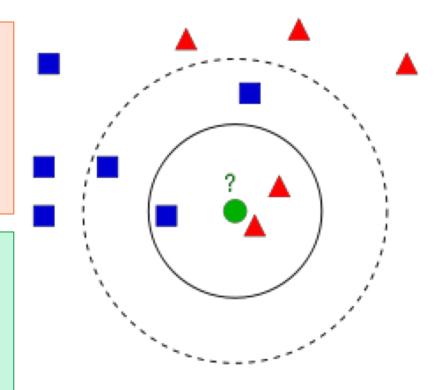
Checkpoint: How would you classify the green point? Why?



https://en.wikipedia.org/wiki/K-nearest_neighbors_algorithm#/media/File:Knn Classification.svg

Say that we have classified training data labeled blue and red, and a new point (green).

The simplest thing we could do would be to assign this point to be red because a red point is its nearest training point.

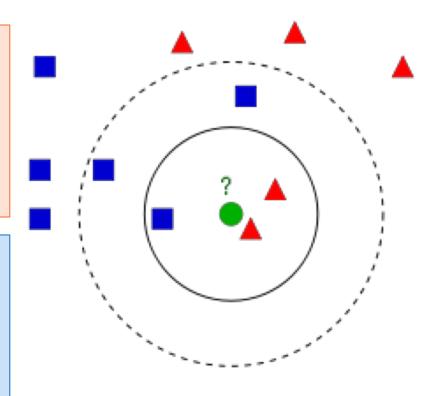


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Say that we have classified training data labeled blue and red, and a new point (green).

k-Nearest Neighbors:

classify the unknown point according to the majority of its *k* nearest neighbors.



https://en.wikipedia.org/wiki/K-nearest_neighbors_algorithm#/media/File:Knn Classification.svg

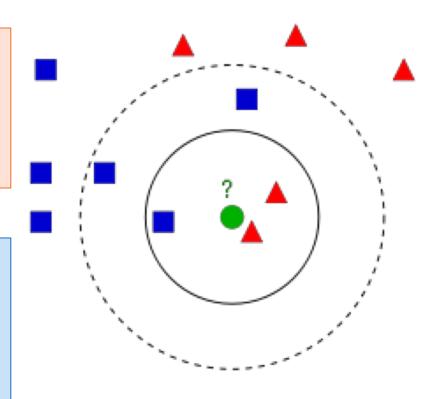
k = 1: point is labeled red.

k = 3: point is labeled red.

k = 5: point is labeled blue.

k-Nearest Neighbors:

classify the unknown point according to the majority of its *k* nearest neighbors.



https://en.wikipedia.org/wiki/K-nearest_neighbors_algorithm#/media/File:Knn Classification.svg

The Problem with Classification

Classification Problem

- Input: A collection of data points divided into a training set (known ancestry) and a test set. (unknown ancestry). Each training data point has a label corresponding to its ancestry.
- Output: a predictive labeling of all the points in the test set.

The problem with genotyping as a classification problem is that we usually don't have many gold standard training samples compared to the test data.

High-Level Overview of Clustering

Clustering Problem

- Input: A collection of (unlabeled) data points in n dimensional space, and an integer k.
- **Output:** An "optimal" assignment of the input points to *k* "clusters" (labels).

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Clustering Problem

- Input: A collection of (unlabeled) data points in n dimensional space, and an integer k.
- **Output:** An "optimal" assignment of the input points to *k* "clusters" (labels).

Note: Just like the classification problem, this isn't well defined and we get different results depending on how we define "optimal".

The **squared error distortion** between *m* points *Data* and *m* points *Centers*:

Distortion(Data, Centers) =

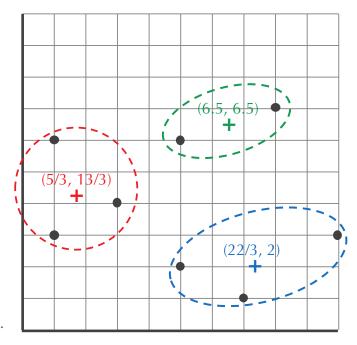
 $\sum_{DataPoint\ from\ Data} d(DataPoint,\ Centers)^2/m$

The **squared error distortion** between *m* points *Data* and *m* points *Centers*:

Distortion(Data, Centers) =

 $\sum_{DataPoint\ from\ Data} d(DataPoint,\ Centers)^2/m$

Exercise: Compute the squared error distortion of the points and centers (shown as crosses) at right.



The **squared error distortion** between *m* points *Data* and *m* points *Centers*:

Distortion(Data, Centers) =

 $\sum_{DataPoint\ from\ Data} d(DataPoint,\ Centers)^2/m$

k-Means Clustering Problem:

- **Input:** A set of points *Data* in *n*-dimensional space and an integer *k*.
- **Output:** A set of *k* points *Centers* that minimizes *Distortion*(*Data*, *Centers*) over all choices of *Centers*.

The **squared error distortion** between *m* points *Data* and *m* points Centers:

Distortion(Data, Centers) =

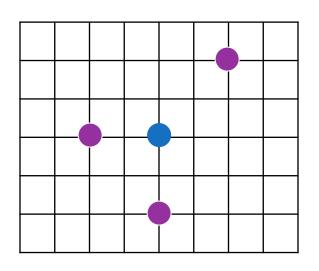
 $\sum_{DataPoint from Data} d(DataPoint, Centers)^2/m$

k-Means Clustering Problem: NP-Hard for k > 1

- **Input:** A set of points *Data* in *n*-dimensional space and an integer k.
- Output: A set of k points Centers that minimizes Distortion(Data, Centers) over all choices of Centers.

Center of Gravity

The **center of gravity** of *m* points *Data* is the point whose *i*-th coordinate is the average of the *i*-th coordinates of all points in *Data*.

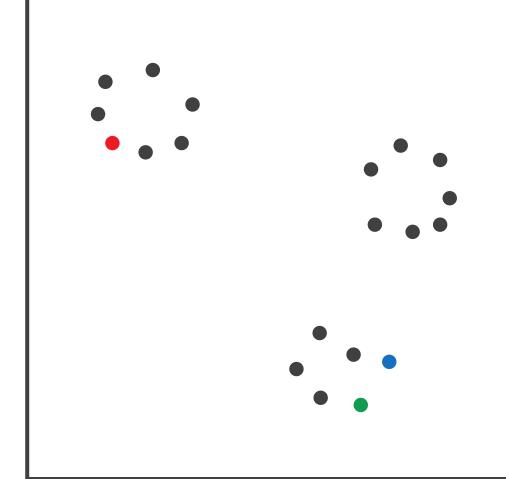


i-th coordinate of center of gravity = average of the *i*-th coordinates of datapoints:

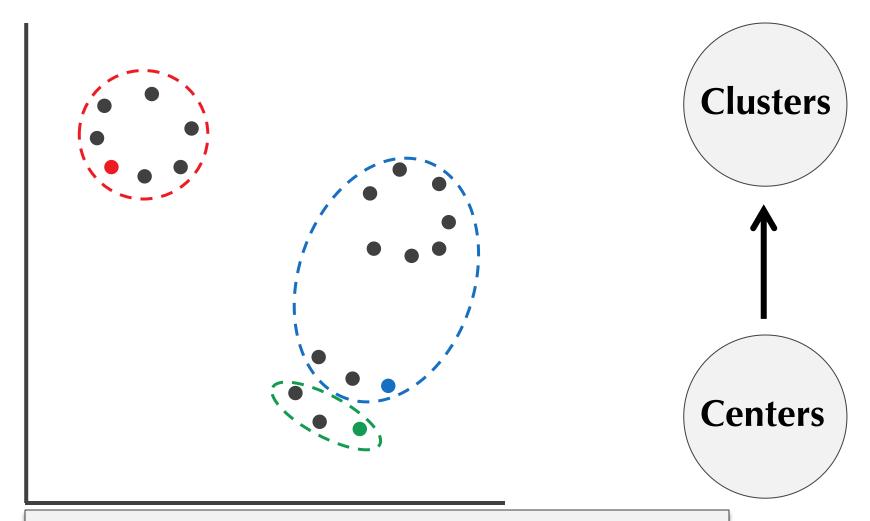
$$((2+4+6)/3, (3+1+5)/3) = (4, 3)$$



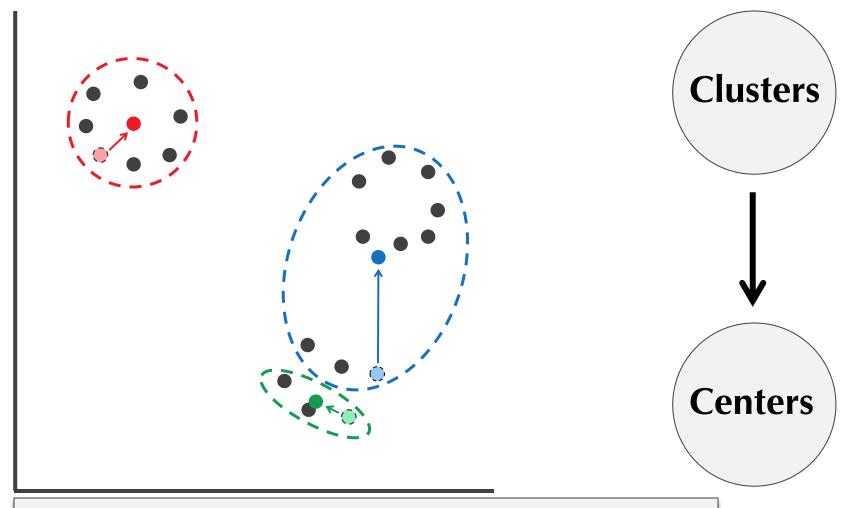
Lloyd algorithm: a clustering heuristic that alternates between updating centers of gravity and assigning points to their nearest centers.



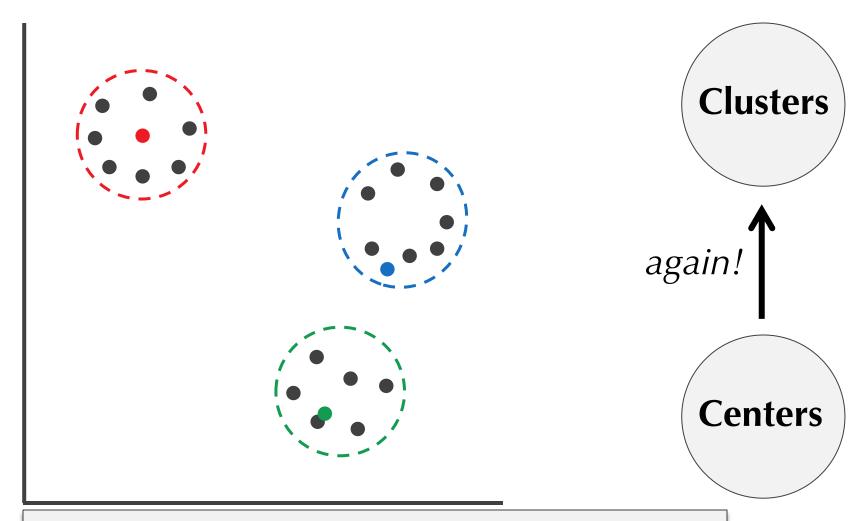
Select *k* arbitrary data points as *Centers*



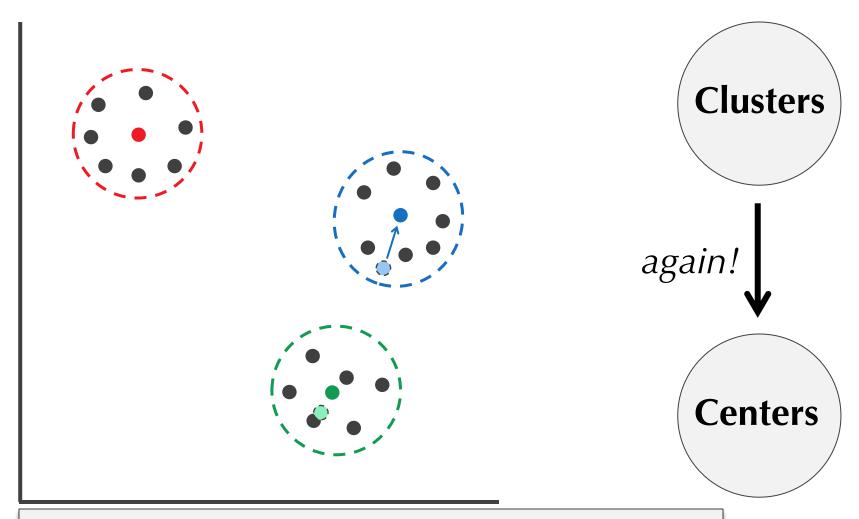
assign each data point to its nearest center



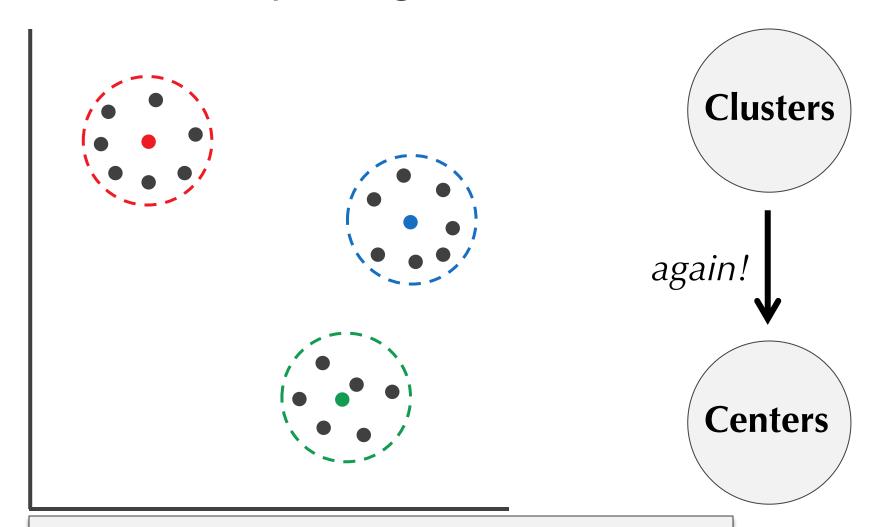
new centers ← clusters' centers of gravity



assign each data point to its nearest center



new centers ← clusters' centers of gravity



assign each data point to its nearest center

Select *k* arbitrary data points as *Centers* and then iteratively perform the following steps:

- Centers to Clusters: Assign each data point to the cluster corresponding to its nearest center (ties are broken arbitrarily).
- Clusters to Centers: After the assignment of data points to *k* clusters, compute new centers as clusters' center of gravity.

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- Centers to Clusters: Assign each data point to the cluster corresponding to its nearest center (ties are broken arbitrarily).
- **Clusters to Centers**: After the assignment of data points to *k* clusters, compute new centers as clusters' center of gravity.

The algorithm terminates when the centers stop moving (convergence).

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- Centers to Clusters: Assign each data point to the cluster corresponding to its nearest center (ties are broken arbitrarily).
- **Clusters to Centers**: After the assignment of data points to *k* clusters, compute new centers as clusters' center of gravity.

Checkpoint: What does the Lloyd algorithm remind you of?

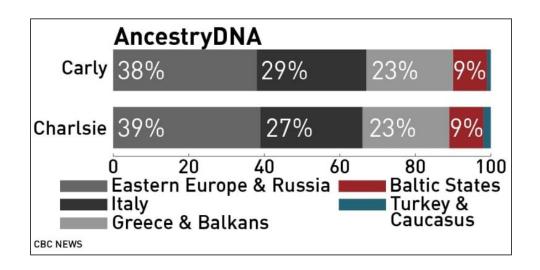
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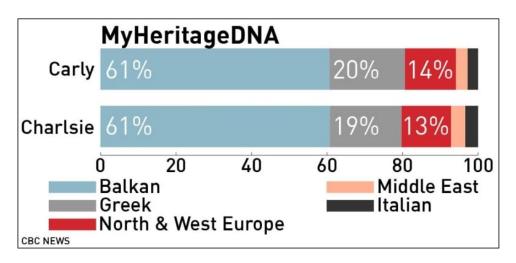
- Centers to Clusters: Assign each data point to the cluster corresponding to its nearest center (ties are broken arbitrarily).
- **Clusters to Centers**: After the assignment of data points to *k* clusters, compute new centers as clusters' center of gravity.

Answer: centers and clusters are both hidden and we try to infer them in stages ... just like EM/Gibbs!

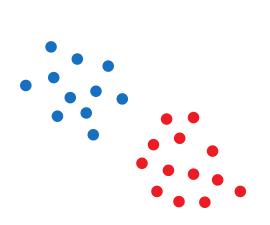
Returning to Admixture

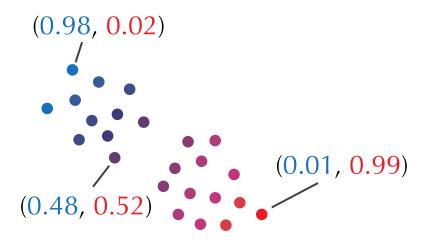
Checkpoint: Clusters give a rigid assignment of individuals to populations. How do you think that we can conclude a collection of percentages for an individual? And why might they differ?





From Hard to Soft Clustering





Hard choices: points are colored red or blue depending on their cluster membership.

Soft choices: points are assigned "red" and "blue" *responsibilities* r_{blue} and r_{red} ($r_{\text{blue}} + r_{\text{red}} = 1$)