

15-851 ALGORITHMS FOR BIG DATA — Spring 2025

PROBLEM SET 3 SOLUTIONS

Problem 1: Geometric Mean Estimator for ℓ_1 -Estimation

1. From class we have the property that if we have $\sum_i a_i \cdot C_i$ where each C_i is an i.i.d. Cauchy random variable, then this is distributed as $|a|_1 \cdot C$.

So, we have that $(Sx)_a = |x|_1 \cdot C_1$, $(Sx)_b = |x|_1 \cdot C_2$, and $(Sx)_c = |x|_1 \cdot C_3$ where C_1, C_2 , and C_3 are independent Cauchy random variables. We therefore have that

$$\mathbf{E}[F_i] = |x|_1 \cdot \mathbf{E}[|C_1 C_2 C_3|^{1/3}].$$

So we have to show that $\mathbf{E}[|C_1 C_2 C_3|^{1/3}]$ is a finite scalar that does not depend on x . Clearly $\mathbf{E}[|C_1 C_2 C_3|^{1/3}]$ does not depend on x . Note that $\mathbf{E}[|C_1 C_2 C_3|^{1/3}] = \mathbf{E}[|C_1|^{1/3}] \cdot \mathbf{E}[|C_2|^{1/3}] \cdot \mathbf{E}[|C_3|^{1/3}]$ since C_1, C_2 , and C_3 are independent. We now need to show that it is finite. We have that

$$\mathbf{E}[|C_1 C_2 C_3|^{1/3}] = \int \int \int \frac{|z_1 z_2 z_3|^{1/3}}{\pi^3 (1+z_1^2)(1+z_2^2)(1+z_3^2)} dz_1 dz_2 dz_3$$

which converges to some constant that is strictly greater than 0.

2. Again we have that

$$F_i = ||x|_1^3 C_1 C_2 C_3|^{1/3} = |x|_1 \cdot |C_1 C_2 C_3|^{1/3}.$$

We have that

$$\mathbf{Var}(F_i) = |x|_1^2 \cdot \mathbf{Var}(|C_1 C_2 C_3|^{1/3}).$$

By definition, we know that $\mathbf{Var}(|C_1 C_2 C_3|^{1/3}) = \mathbf{E}[|C_1 C_2 C_3|^{2/3}] - \mathbf{E}[|C_1 C_2 C_3|^{1/3}]^2 \leq \mathbf{E}[|C_1 C_2 C_3|^{2/3}]$. So we have

$$\mathbf{Var}(|C_1 C_2 C_3|^{1/3}) \leq \int \int \int \frac{|z_1 z_2 z_3|^{2/3}}{\pi^3 (1+z_1^2)(1+z_2^2)(1+z_3^2)} dz_1 dz_2 dz_3.$$

This again converges to a constant.

3. Using the first part, we can see that

$$\mathbf{E}[F] = \frac{3}{Ck} \sum_{i=1}^{k/3} \mathbf{E}[F_i] = \frac{3}{Ck} \cdot \frac{k}{3} \cdot C \cdot |x|_1 = |x|_1.$$

Using the second part, we also have

$$\mathbf{Var}[F] = \frac{9}{C^2 k^2} \sum_{i=1}^{k/3} \mathbf{Var}[F_i] \leq \frac{9}{C^2 k^2} \cdot \frac{k}{3} \cdot O(|x|_1^2) = O(|x|_1^2/k).$$

Note that we can move the variance into the summation because all the F_i 's are independent.

Now, using Chebyshev's inequality will give us the result.

$$\Pr(|F - |x|_1| \geq \varepsilon \cdot |x|_1) \leq \frac{O(|x|_1^2/k)}{|x|_1^2 \cdot \varepsilon^2} \leq 1/10$$

for appropriate $k = O(\varepsilon^{-2})$.

Problem 2: Online Leverage Score Sampling plus Merge and Reduce

- Let us say that the approximation factor we use in each coreset is γ . At each level of the tree, we suffer an additional multiplicative $(1 \pm \gamma)$ error in our approximation. So, since the height of the tree is $\Theta(\log(n/2k))$, we have that the final coreset is a $(1 \pm \log(n/2k) \cdot \gamma)$ multiplicative approximation.

Recall that we could assume that $k < n^{0.9}$. Therefore, we have that $\log(n/2k) = \Theta(\log n)$, so we have that the final coreset is a $(1 \pm \log n \cdot \gamma)$ multiplicative approximation. Now, we want $\log n \cdot \gamma \leq \varepsilon$ to get the result. So, we should set $\gamma \leq \varepsilon / \log n$, giving us $k = O(d \log^2 n / \varepsilon^2)$.

We now analyze the space. As per the problem statement, a coreset can be constructed in $O(kd \log n)$ space. In addition, storing a coreset requires $O(kd \log n)$ space since each row has d entries that each take $\log n$ bits to store. We keep at most one coreset per level of the binary tree at one time. So, the total space is

$$O(kd \log^2 n) = O(d^2 \log^4 n / \varepsilon^2).$$

- (a) Let us maintain a $d \times d$ matrix M . Upon seeing a row r in the stream, you can store it exactly in $O(d \log n)$ space. Then we can compute $r^\top r$ using $O(d^2 \log n)$ space, and take $M = M + r^\top r$. Storing M only uses $O(d^2 \log n)$ space, and $M = A_{i-1}^\top A_{i-1}$.

So, given the next row in the stream, we can exactly compute ℓ_i .

- (b) We will first show that the online leverage score upper bounds the actual leverage score of matrix $A' = [A; \sqrt{\lambda}I]$.

We have that

$$\ell_i = \min(a_i^\top (A_{i-1}^\top A_{i-1} + \lambda I)^{-1} a_i, 1)$$

and

$$\tau_i(A') = a_i^\top (A^\top A + \lambda I)^{-1} a_i.$$

We want to show that

$$a_i^\top (A_{i-1}^\top A_{i-1} + \lambda I)^{-1} a_i \geq a_i^\top (A^\top A + \lambda I)^{-1} a_i.$$

If we prove that $A^\top A + \lambda I \succeq A_{i-1}^\top A_{i-1} + \lambda I$, then we also have $(A_{i-1}^\top A_{i-1} + \lambda I)^{-1} \succeq (A^\top A + \lambda I)^{-1}$ as per the hint. This would give us what we want. We first see that

$$A^\top A = A_{i-1}^\top A_{i-1} + \sum_{j=i}^n a_j^\top a_j.$$

Since for each j we have that $a_j^\top a_j$ is PSD, then we have that

$$A^\top A \succeq A_{i-1}^\top A_{i-1}.$$

Now we can use the sampling without replacement bound on A' . As per the hint given on piazza, we have to sample each row of A' (not A). However, we can simply set p_i for all rows of A' that correspond to $\sqrt{\lambda}I$ to 1. Therefore, we simply add these rows to our sample.

In the sampling without replacement bound, for $i \in [n]$, we take $u_i = \ell_i$ and for $i \in (n, n + d]$ we take $u_i = 1$. We also set $\gamma = \varepsilon/3$. So, we have that simultaneously for all x we have

$$\|TA'x\|_2^2 = (1 \pm \varepsilon/3) \|A'x\|_2^2.$$

This gives us

$$\|TAx\|_2^2 + \lambda \|x\|_2^2 = (1 \pm \varepsilon/3) (\|Ax\|_2^2 + \lambda \|x\|_2^2).$$

- (c) We first prove that $\|Ax\|_2^2 / \|x\|_2^2 \geq \sigma_{\min}^2$. Take the SVD of A . This gives us

$$\|Ax\|_2^2 = \|U \Sigma V^\top x\|_2^2 = \|\Sigma V^\top x\|_2^2.$$

Let us set $y = V^\top x$. So we further have

$$\|\Sigma V^\top x\|_2^2 = \|\Sigma y\|_2^2 = \sum_i \sigma_i^2 y_i^2 \geq \sigma_{\min}^2 \sum_i y_i^2 = \sigma_{\min}^2 \|y\|_2^2.$$

So we finally have

$$\frac{\|Ax\|_2^2}{\|x\|_2^2} \geq \frac{\sigma_{\min}^2 \|y\|_2^2}{\|x\|_2^2} = \frac{\sigma_{\min}^2 \|V^\top x\|_2^2}{\|x\|_2^2} = \frac{\sigma_{\min}^2 \|x\|_2^2}{\|x\|_2^2}.$$

So, we have by the previous part that

$$\|TAx\|_2^2 = (1 \pm \varepsilon/3)(\|Ax\|_2^2 \pm \varepsilon \sigma_{\min}^2(A) \|x\|_2^2) = (1 \pm \varepsilon/3)(\|Ax\|_2^2 \pm \varepsilon \|Ax\|_2^2).$$

This gives us the desired result.

- (d) Notice that as proven in the previous part, our space usage to achieve a $(1 \pm \varepsilon)$ approximation after the merge-and-reduce scheme is $O(d^2 \log n / \varepsilon^2)$ times $\text{poly log}(r/2k)$ where r is the number of rows that are being passed in the stream. Recall that the number of rows is equivalent to the number of nonzeros in T . This is, by the sampling without replacement result, the number of rows, r , is

$$O(\varepsilon^{-2} \cdot \log d \cdot d \log(\|A\|_2^2 / \lambda)).$$

Plugging in $\lambda = \varepsilon \cdot \sigma_{\min}^2$, we get that the number of nonzeros in T is

$$O(\varepsilon^{-2} \cdot \log d \cdot d \log(\kappa / \varepsilon)).$$

We know that k has a factor of d and ε^{-2} , so we have that

$$\text{poly log}(r/2k) = O(\text{poly log}(\log d \log(\kappa / \varepsilon))).$$

This gives us the final space result. For the error guarantee, we can simply combine parts 1 and 2c.