| CS 15-851: Algorithms for Big Data | Spring 2024 |
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| Lecture Lecture 02-Jan. 25 |  |
| Prof. David Woodruff | Scribe: Noah Singer |

Notes: Please prove the fact given as a hint in Homework 1, Problem 1.

## 1 Recap: Subspace embeddings

Last week, we defined an important property for matrices:
Definition (Subspace embeddings). Let $A \in \mathbb{R}^{n \times d}$ and $\epsilon>0$. A matrix $S \in \mathbb{R}^{k \times n}$ is an $\epsilon$-subspace embedding for $A$ if for all $x \in \mathbb{R}^{d}$,

$$
\|S A x\|_{2} \in(1 \pm \epsilon)\|A x\|_{2},
$$

where $\alpha \in(1 \pm \epsilon) \beta$ denotes $(1-\epsilon) \beta \leq \alpha \leq(1+\epsilon) \beta$.
Then, we showed a specific construction of such matrices:
Theorem 1 (Dense Gaussian matrices are subspace embeddings). Let $\epsilon>0, k=O\left(d / \epsilon^{2}\right)$. Let $S \in \mathbb{R}^{k \times n}$ be a matrix of i.i.d. $\mathcal{N}(0,1 / k)$ random variables. Then for any fixed $A \in \mathbb{R}^{n \times d}, S$ is an $\epsilon$-subspace embedding w.h.p. over the choice of $S$.

To recap, the proof of this theorem went as follows:

1. Assume WLOG that $A$ has orthonormal columns and $\|x\|_{2}=1$.
2. Show that $S A$ has the distribution of a $k \times d$ matrix of i.i.d. $\mathcal{N}(0,1 / k)$ random variables using sum and independence properties of Gaussians.
3. Show that for a fixed unit vector $x$, w.h.p. $\|S A x\|_{2}^{2} \in 1 \pm \epsilon$ (in particular, w.p. $1-2^{-\Omega(d)}$ ). Specifically, this step uses a concentration inequality for sums of squared Gaussians (" $\chi^{2}$ random variables) called the "Johnson-Lindenstrauss theorem".
4. To extend the concentration of norm to all $x$ simultaneously, first build a $\gamma$-net for the subspace: A set of vectors $M$ such that for all unit vectors $x$, there exists $y \in M$ with $\|y-A x\|_{2} \leq \gamma$. This uses a greedy construction, with a ball-volume-packing argument to show that the net cannot grow too large. Crucially, the size of this net is independent of $n$ (just exponential in d).
5. Apply a union bound to show that w.h.p., the concentration holds for the lengths of all vectors in the net $M$ and their differences.
6. Conditioning on this event, use a "chaining argument" to show that any vector $A x$ is an infinite linear combination of the net vectors with geometrically decreasing weights. Under this assumption and the concentration, $A x$ 's length must also be approximately preserved.

## 2 From subspace embedding to linear regression

Recall, our original goal was to show that the solution to a linear regression problem $\min _{y}\|A y-b\|_{2}$ is well-approximated by the solution to the (smaller) sketched problem $\min _{y}\|S A y-S b\|_{2}$. We make the following claim:

Theorem 2 (Linear regression from subspace embeddings). Let $A \in \mathbb{R}^{n \times d}$ and $b \in \mathbb{R}^{d}$. Let $A^{\prime}$ denote the $n \times(d+1)$ matrix adjoining $b$ (as a column vector) to the right of $A$. If $S \in \mathbb{R}^{k \times n}$ is a $\epsilon$-subspace embedding for $A^{\prime}$, then $y^{*}=\arg \min _{y}\|S A y-S b\|_{2}$ satisfies $\left\|A y^{*}-b\right\|_{2} \leq(1+\epsilon)\|A y-b\|_{2}$.

Proof. Let $\widehat{y}=\arg \min _{y}\|A y-b\|_{2}$. We claim that

$$
\begin{equation*}
(1-\epsilon)\left\|A y^{*}-b\right\|_{2}^{2} \leq\left\|S A y^{*}-S b\right\|_{2}^{2} \tag{1}
\end{equation*}
$$

and

$$
\begin{equation*}
\|S A \widehat{y}-S b\|_{2}^{2} \leq(1+\epsilon)\|A \widehat{y}-b\|_{2}^{2} \tag{2}
\end{equation*}
$$

Given these, we deduce:

$$
\begin{array}{rlr}
\left\|A y^{*}-b\right\|_{2}^{2} & \leq \frac{\left\|S A y^{*}-S b\right\|_{2}^{2}}{1-\epsilon} \\
& \leq \frac{\|S A \widehat{y}-S b\|_{2}^{2}}{1-\epsilon} \\
& \leq \frac{(1+\epsilon)\|A \widehat{y}-b\|_{2}^{2}}{1-\epsilon} \\
& \leq(1+3 \epsilon) \min _{y}\|A y-b\|_{2}^{2} & \left(y^{*}\right. \text { minimized sketched problem) } \\
\text { (holds for } \epsilon<1 / 3)
\end{array}
$$

as desired.
Now, let $x^{*}$ denote the vector consisting of $y^{*}$ followed by a single 1 entry. Thus, $A y^{*}-b=A^{\prime} x^{*}$ and $S A y^{*}-S b=S A^{\prime} x^{*}$. Thus 1 follows from the subspace embedding property of $S$ applied to $x^{*}$. Similarly, letting $\widehat{x}$ denote the vector consisting of $\widehat{y}$ followed by a single 1 entry, we get 2 .

The main advantage of this approach is that the solution to the sketched regression problem can be found efficiently (since it is only $k$-dimensional).

However, calculating $S A$ might still expensive as it is a matrix product - indeed, if $S$ is a random Gaussian matrix, we don't know a fast way to compute $S A$. (Note that in the proof for subspace embedding, we assumed WLOG that $A$ has orthonormal columns, and we showed that under this assumption, $S A$ has an i.i.d. Gaussian distribution. However, for general $A$ this will not be true, and putting it in orthonormal form is expensive. Conversely, if $A$ is already orthonormal, its pseudoinverse is just its transpose, meaning regression is very easy. So the key idea of subspace embedding is arguably that we can make $A$ have orthonormal columns only in the analysis and not in the algorithm itself.)

## 3 A better subspace embedding from the Hadamard transform

Can we design a subspace embedding such that calculating the sketched matrix $S A$ is inexpensive? One construction is due to Sárlos [1], called the subsampled randomized Hadamard transform (SRHT). This is another distribution over sketch matrices $S$; we will show that it is a subspace embedding and that $S A$ is efficiently calculable.

Say $n$ is a power of 2 WLOG. The SRHT matrix $S=P H D$ is a product of three matrices $P, H, D$, defined as:

- $P$ is an $s \times n$ random matrix. Its entries are all 0 except for a uniformly randomly and independently placed $\sqrt{n / s}$ entry in each row.
- $H$ is an $n \times n$ deterministic matrix, the (normalized) Hadamard matrix $H_{i, j}=(1 / \sqrt{n})(-1)^{\langle i, j\rangle}$ where $i, j$ are viewed as vectors in $\mathbb{F}_{2}^{\log n}$.
- $D$ is an $n \times n$ random diagonal matrix, where each diagonal entry is uniformly and independently sampled from $\{ \pm 1\}$.

This distribution also has the advantage that all probability distributions involved are discrete.

### 3.1 Efficient calculation of the embedding

First, we claim that given $P, H, D, A$, we can output the product $S A=P H D A$ in $O(n d \log n)$ time ${ }^{1}$ This is almost optimal if $A$ is dense, since $A$ is $n \times d$ and it takes $\Theta(n d)$ time to even examine all its entries!

To prove this, we look at each of the $d$ columns of $A$ individually; that is, for $P, H, D, a$, we can calculate the matrix-vector product $S a$ in $O(n \log n)$ time. This is because:

- For any $a$, computing $D a$ takes $O(n)$ time. (Indeed, $D$ 's diagonal entries are just $\pm 1$, so $D$ is just re-signing the entries of $a$.)
- The fast Hadamard transform (a.k.a. the fast Fourier transform over $\mathbb{F}_{2}$ ) means that you compute any matrix-vector product with $H$ in $O(n \log n)$ time. (This is a divide-and-conquer algorithm using the recursive structure over $H$ : If $H^{\prime}$ is the $n / 2 \times n / 2$ Hadamard matrix, then $H=\left(\begin{array}{cc}H^{\prime} & H^{\prime} \\ H^{\prime} & -H^{\prime}\end{array}\right)$. So, to compute $H a$, we can recursively compute $H^{\prime} a^{\prime}$ and $H^{\prime} a^{\prime \prime}$ where $a^{\prime}$ and $a^{\prime \prime}$ denote the first and last $n / 2$ entries of $a$, respectively.)
- For any $a$, computing $S a$ takes $O(d)$ time. This is because the $i$-th entry of the product $S a$ is just the product between $S$ 's $i$-th row and $a ; S$ 's $i$-th row only has one nonzero entry, and so the $i$-th entry of $S a$ is just an (appropriately scaled) entry of $a$.

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### 3.2 Proof of subspace embedding

Now, we prove the result that the SRHT process gives a subspace embedding.
Theorem 3 (SRHT matrices are subspace embeddings). Let $\epsilon>0, s=O\left(d / \epsilon^{2}\right)$. Let $S \in \mathbb{R}^{s \times n}$ be sampled according to the SRHT process described at the beginning of this section. Then for any fixed $A \in \mathbb{R}^{n \times d}, S$ is an $\epsilon$-subspace embedding w.h.p. over the choice of $S$.

In the proof, we will need the following concentration inequality:
Lemma 1 (Azuma-Hoeffding). Let $\left\{Z_{j}\right\}_{j \in[n]}$ be a set of independent random variables such that for all $j \in[n], \mathbb{E}\left[Z_{j}\right]=0$ and $\left|Z_{j}\right| \leq \beta_{j}$ (w.p. 1). Then

$$
\mathbb{P}\left[\left|\sum_{j=1}^{n} Z_{j}\right| \geq t\right] \leq 2 \exp \left(\frac{-t^{2}}{\sum_{j=1}^{n} \beta_{j}^{2}}\right)
$$

To prove that $S$ is a subspace embedding, we can again assume WLOG that $A$ has orthonormal columns and $x$ is a unit vector. Let $y=A x ; y \in \mathbb{R}^{n}$ is a unit vector since $A$ has orthonormal columns. In this setting, we WTS that $\|P H D y\|_{2}^{2} \in 1 \pm \epsilon$ (i.e., w.h.p. this holds for all unit $y$ in the column space of $A$ ). Note that $D, H$ are orthogonal: $D$ since it is diagonal with $\pm 1$ entries; and $H$ by definition of the Hadamard matrix (the inner product between two columns in $H$ is $\left\langle H_{* i}, H_{* j}\right\rangle=(1 / n) \sum_{k=1}^{n}(-1)^{\langle k, i\rangle+\langle k, j\rangle}=(1 / n) \sum_{k=1}^{n}(-1)^{\langle k, i+j\rangle}$, and $i+j$ is a nonzero vector since $i \neq j$, and one can setup a bijection based on toggling some coordinate on which $i$ and $j$ disagree).

So why do we need $H$ and $D$ ? If they weren't there, and our sketch was just $S=P$, recall that each entry of $S y$ will just be a randomly selected (appropriately scaled) entry of $y$. But it's quite possible that $y$ is a very sparse vector, in which case $S y$ would have decent probability of being all-0's - this is bad, because then the norm is not preserved. (Note that the expected norm of $S y$ is still 1 , but the variance is too high.) $H$ and $D$ somehow "spread out $y$ 's norm roughly evenly over all the coordinates" by randomly rotating $y$; this allows a better bound on the concentration of $\|P H D y\|_{2}$. (Note that there will still be some vectors $z$ such that $H D z$ is sparse ( $H D$ just rotates the space, after all), but this is OK as long as they aren't A's column span.)

The fact that $H D$ "spreads out" $y$ 's mass over its coordinates is formalized in the following lemma. Recall that for a vector $z \in \mathbb{R}^{n}$, the $\infty$-norm $\|z\|_{\infty}$ denotes the magnitude of the largest entry of $z$. Then:

Lemma 2 (Flattening). There exists $C>0$ such that the following holds. Let $y \in \mathbb{R}^{n}$ be any unit vector and $H \in \mathbb{R}^{n \times n}$ any matrix where all entries are $\pm 1 / \sqrt{n}$. If $D \in \mathbb{R}^{n \times n}$ is diagonal with uniform and independent $\{ \pm 1\}$ entries, then

$$
\underset{D}{\mathbb{P}}\left[\|H d y\|_{\infty} \geq C \sqrt{\frac{\log (n d / \delta)}{n}}\right] \leq \frac{\delta}{2 d}
$$

Proof. We claim that for fixed $i \in[n]$,

$$
\underset{D}{\mathbb{P}}\left[\left|(H D y)_{i}\right| \geq C \sqrt{\frac{\log (n d / \delta)}{n}}\right] \leq \frac{\delta}{2 n d} .
$$

This gives the desired result taking a union bound over $i$.
To prove the claim, we expand the matrix-(matrix-)vector product

$$
(H D y)_{i}=\sum_{j=1}^{n} H_{i, j} D_{j, j} y_{j} .
$$

Let $Z_{j}:=H_{i, j} D_{j, j} y_{j}$, so that $(H D y)_{i}=\sum_{j=1}^{n} Z_{j}$. Here are some properties of $Z_{j}: \mathbb{E}\left[Z_{j}\right]=0$ (since $H_{i, j}$ and $y_{j}$ are fixed, and $D_{j, j}$ is uniform in $\{ \pm 1\}$ ); and $\left|Z_{j}\right| \leq\left|y_{j}\right| / \sqrt{n}$ w.p. 1 over $D$, since $\left|H_{i, j}\right|=1 / \sqrt{n}$ by assumption. Defining $\beta_{j}:=\left|y_{j}\right| / \sqrt{n}$, we have $\sum_{j=1}^{n} \beta_{j}^{2}=\frac{1}{n} \sum_{j=1}^{n} y_{j}^{2}=\frac{1}{n}$ since we assumed $y$ is a unit vector. So we can apply the Azuma-Hoeffding lemma (1) with $t=C \sqrt{\log (n d / \delta) / n}$, giving concentration of $\exp \left(-t^{2} /(1 / n)^{2}\right)=\exp \left(-C^{2} \log (n d / \delta)\right)<\frac{\delta}{2 n d}$ for sufficiently large $C$.

Note that the only fact about the Hoeffding matrix required for this lemma is that all its entries have magnitude $1 / \sqrt{n}$. Indeed, the SRHT process uses the Hadamard matrix simply because it (i) has this bounded-entry property, (ii) is orthogonal, and (iii) support efficient matrix-vector products due to the recursive structure.

Since $H D A$ has orthonormal columns, taking any particular column $a$ of $A$, by Lemma 2 we have $\|H D a\|_{\infty} \leq C \sqrt{\log (n d / \delta) / n}$ w.p. $1-\delta /(2 d)$ over the choice of $D$. Taking union bound over the $d$ columns of $A$, we have that $\|H D A\|_{\infty} \leq C \sqrt{\log (n d / \delta) / n}$ w.p $1-\delta / 2$ over the choice of $D$, where $\|Z\|_{\infty}$ denotes the largest entry in the entire matrix. So for any row $(H D A)_{i *}$ of $H D A$, we have $\left\|(H D A)_{i *}\right\|_{2}^{2} \leq C^{2} d \log (n d / \delta) / n$ (since there are $d$ entries, each of magnitude at most $C \sqrt{d \log (n d / \delta) / n})$.
Recall that for a matrix $Z \in \mathbb{R}^{n \times m}$, the Frobenius norm is $\|Z\|_{F}:=\sqrt{\sum_{i=1}^{n} \sum_{j=1}^{m} Z_{i j}^{2}}$. In this case, $\|H D A\|_{F}^{2}=d$ since each of the columns are orthonormal; thus, the average value of $\left\|(H D A)_{i *}\right\|_{2}^{2}$ over $i \in[n]$ is $d / n$. So, Lemma 2 implies that no row has much larger norm than average (not much larger than a log factor).

Now, we condition on this event that the norms of rows in $H D A$ are bounded, and we want to deduce that $P H D$ is a good subspace embedding for $A$, w.h.p. over the choice of $P$. For this, we'll need another technical tool, the matrix Chernoff inequality, which bounds the spectral norm of a random matrix. Recall, the spectral norm of a matrix $Z \in \mathbb{R}^{n \times m}$ is $\|Z\|_{2}:=\sup _{\|x\|_{2}=1}\|Z x\|_{2}$ (and $\|Z\|_{2}^{2}$ also equals the largest singular value of $Z$ ). In this notation, we want to show e.g. that $\|S A\|_{2} \leq 1+\epsilon$ (so that $S A$ does not increase the norm of any unit vector by a factor more than $1+\epsilon)$.

## References

[1] Tamás Sárlos. Improved Approximation Algorithms for Large Matrices via Random Projections. In $4^{7}$ th Annual IEEE Symposium on Foundations of Computer Science, pages 143-152, October 2006. doi:10.1109/FOCS.2006.37.


[^0]:    ${ }^{1}$ This is a worst-case problem: $P$ can be any matrix with exactly one $\sqrt{n / s}$ entry in each row, and $D$ any diagonal matrix with $\pm 1$ 's on the diagonal.

