

Hierarchical Radiosity with Multiresolution Meshes

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Thesis Statement

The Domain

- Radiosity on scenes with detailed models

By using face cluster hierarchies we can

- Get sub-linear or constant time complexity
- Better approximate detailed model surfaces

Route

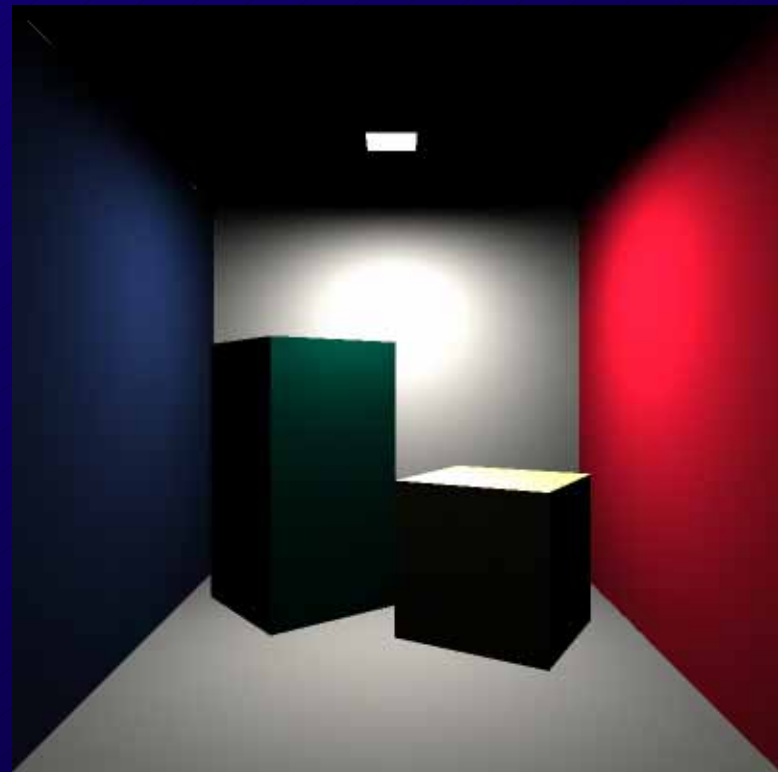


- Global illumination
- Radiosity & Hierarchical Radiosity Methods
- Problems
- Face cluster hierarchies
- Face Cluster Radiosity
- Results

Simple Illumination

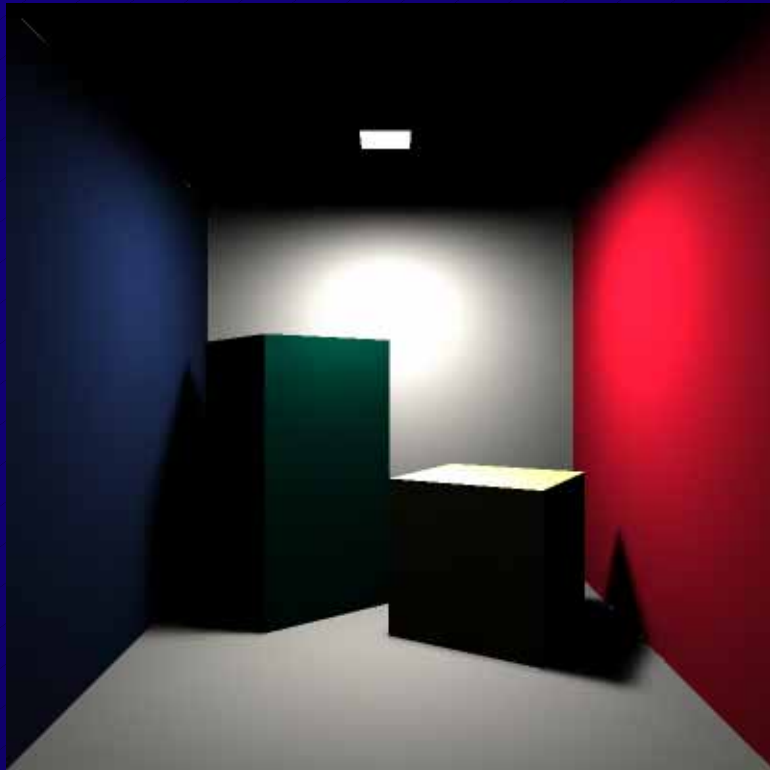


Solid Colours



Direct Illumination

Global Illumination



+ Shadows



+ Indirect Illumination

Reflection Types

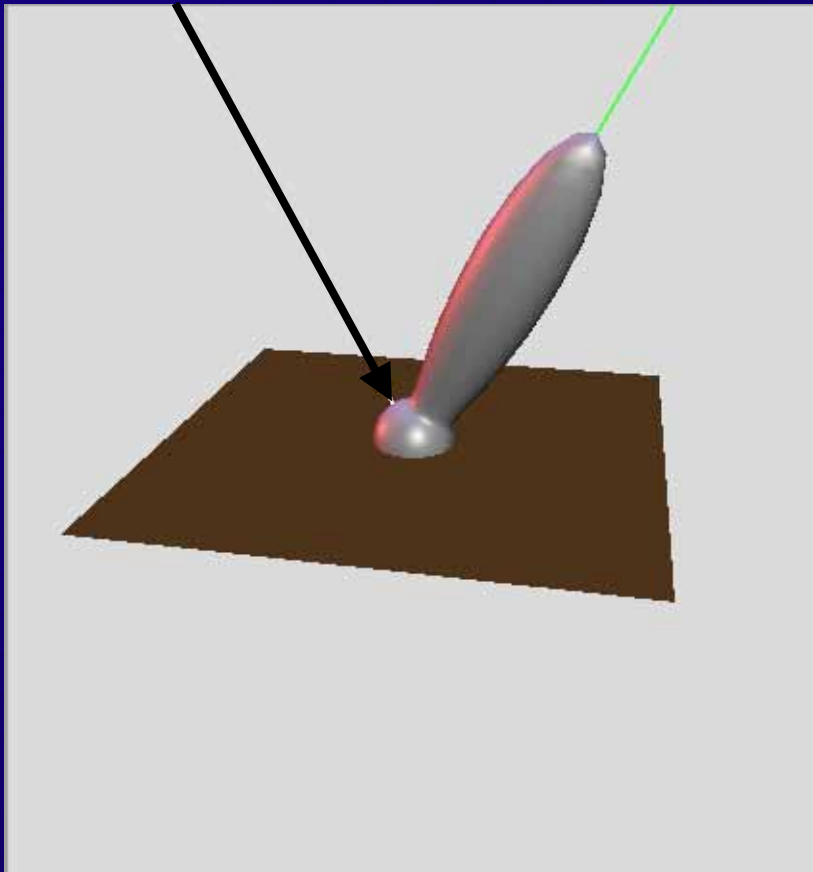


Specular

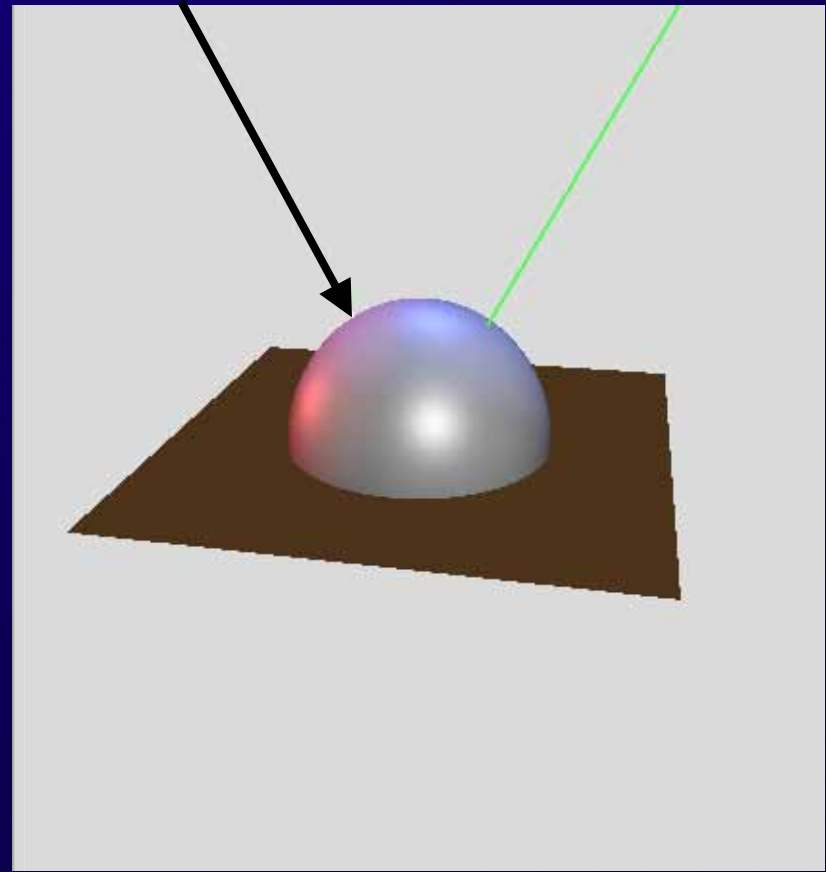


Diffuse

Reflection Types



Specular



Diffuse

Radiosity

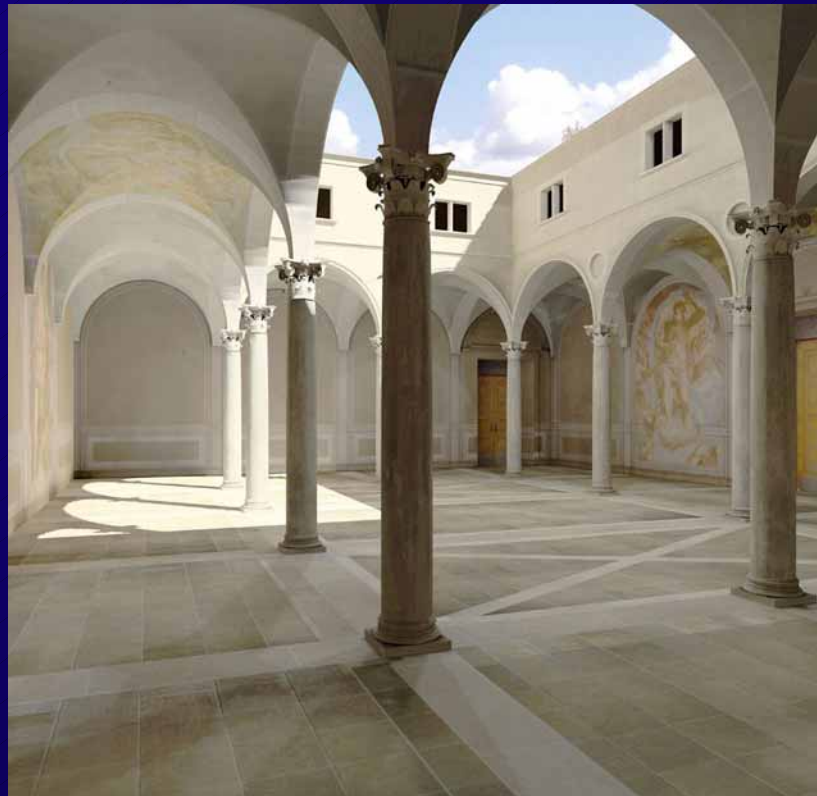
Definition

- The calculation of global illumination for scenes with only *diffuse* surfaces

Consequences

- Easier to solve than the full equation
- Suitable for finite-element methods
- The solution produced is *view-independent*

Indirect Illumination



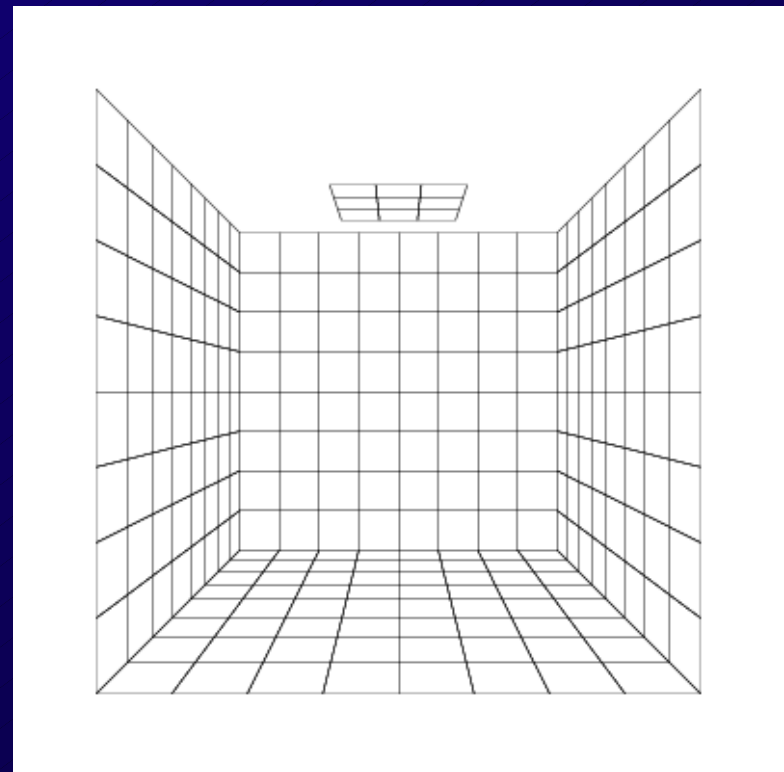
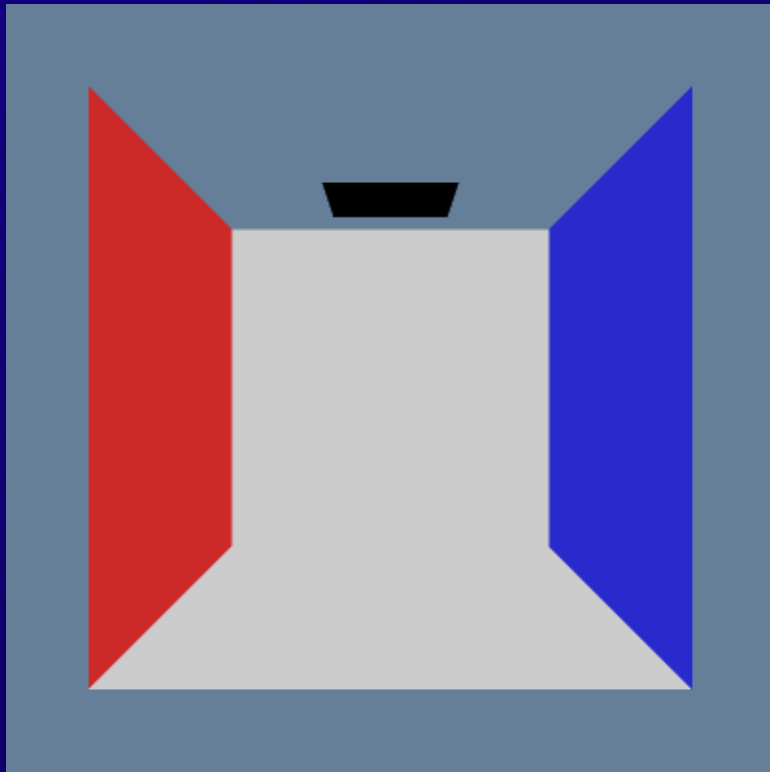
Lightscape Technologies

View-Independence



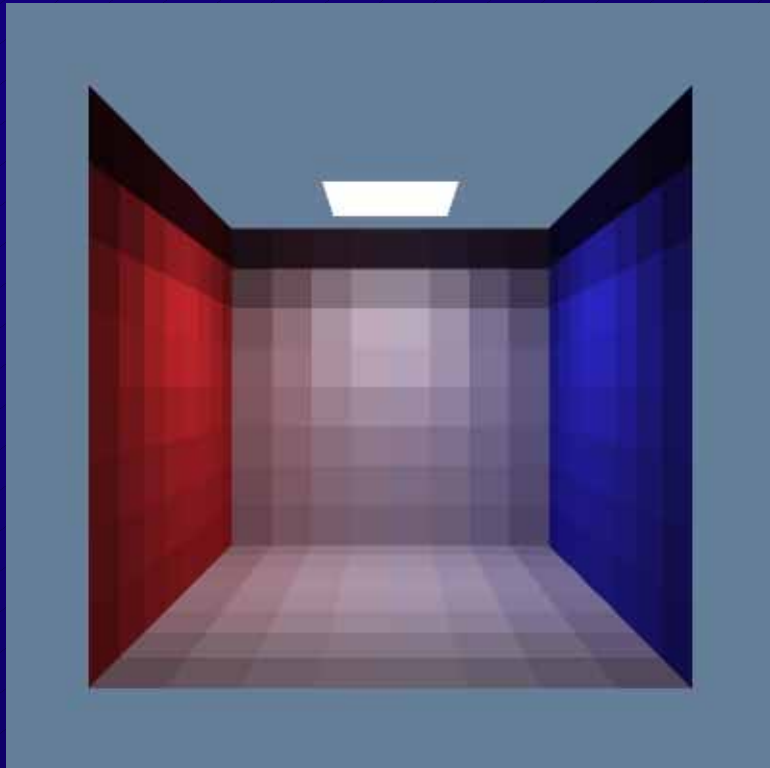
Quake: ID

Finite Elements



Discretize scene into n elements, solve for each element

Solving for Radiosity



- Each element emits **radiosity** [Watts/sr/m²]
- Can write in terms of all other elements:

$$b_i = \rho_i \sum_j F_{ij} b_j + e_i$$

- Gives system of linear equations

Early Radiosity Methods

Matrix Radiosity [Cohen '85]

- Initially used standard matrix techniques (Jacobi, Gauss-Seidel)
- **But** this is $O(n^2)$ in time and space

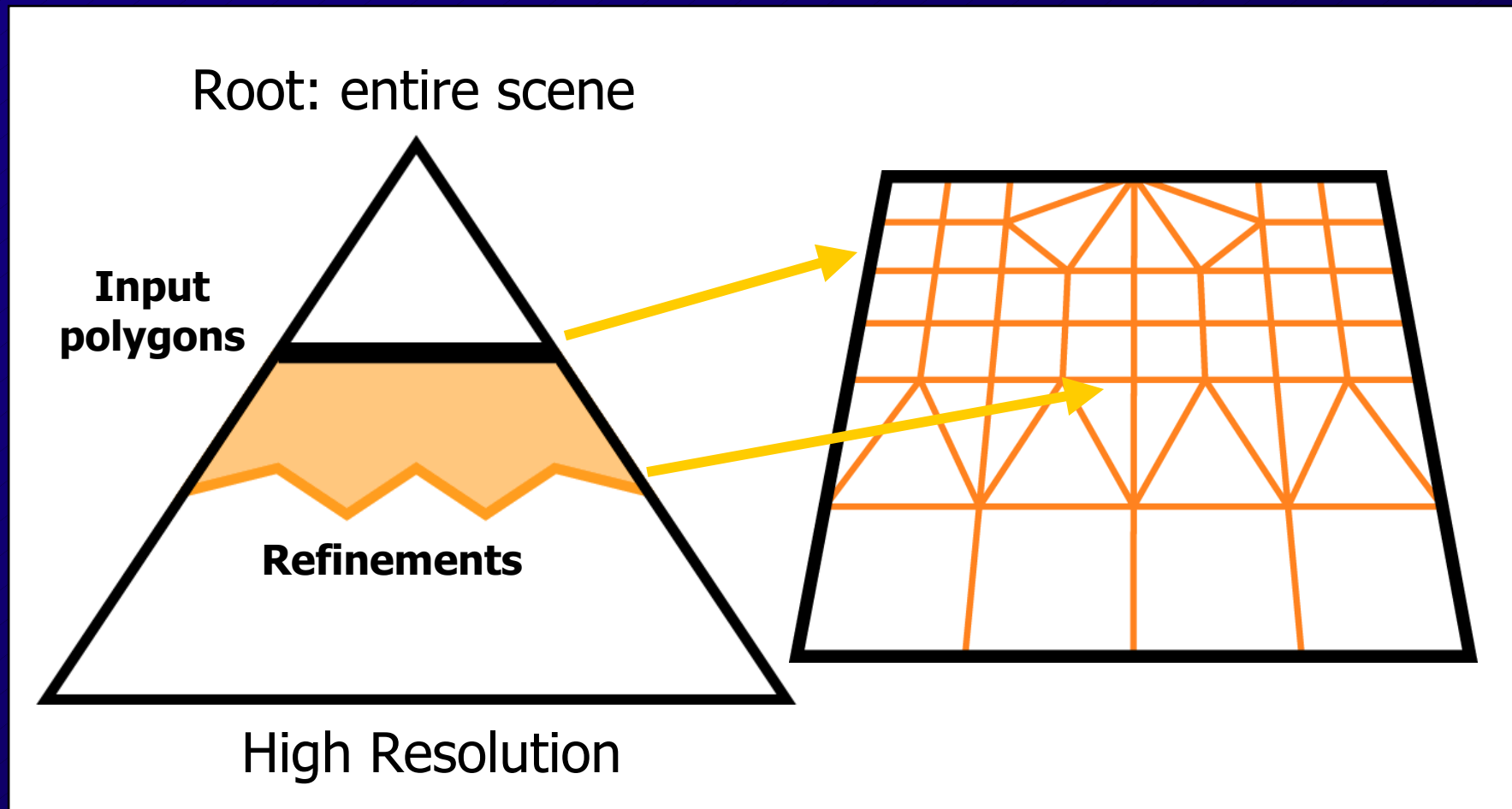
Progressive Radiosity [Cohen '88]

- Reorder computation
- Repeatedly shoot element with most unshot radiosity: can see results improving
- Still $O(n^2)$ speed, but $O(n)$ memory

Hierarchical Radiosity

- [Hanrahan '91]
- Use hierarchical mesh (quadtree)
 - **Coarse level:** unimportant interactions
 - **Fine level:** Interactions between close surfaces
- $O(k^2 + n)$ time and space complexity
 - k is the number of *input polygons*
 - n is the number of *elements* used by the solution
- k^2 is a problem for $k > 1000$ polygons

Refinement for Hier. Rad.

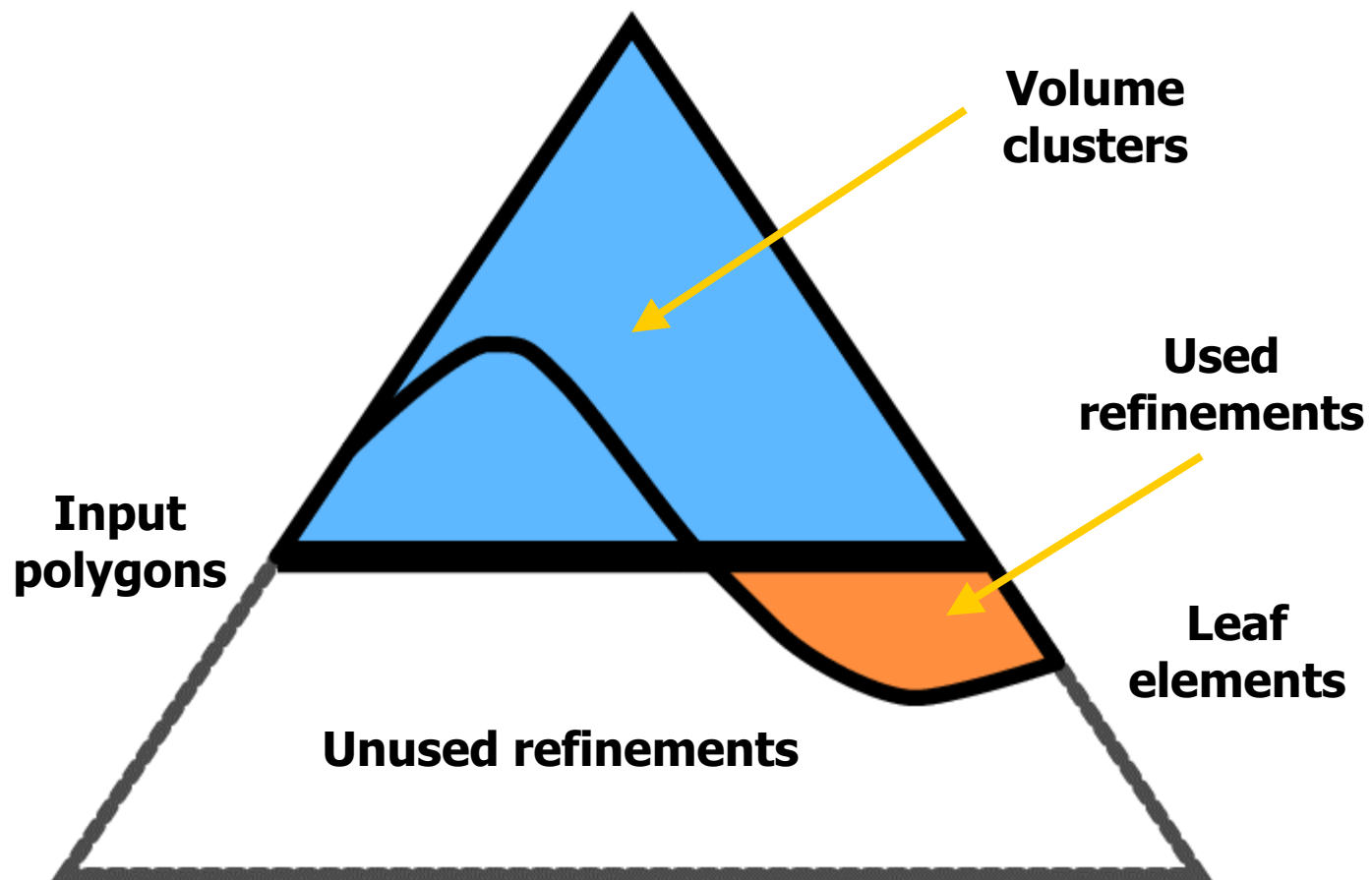


Hierarchical Radiosity with Volume Clustering

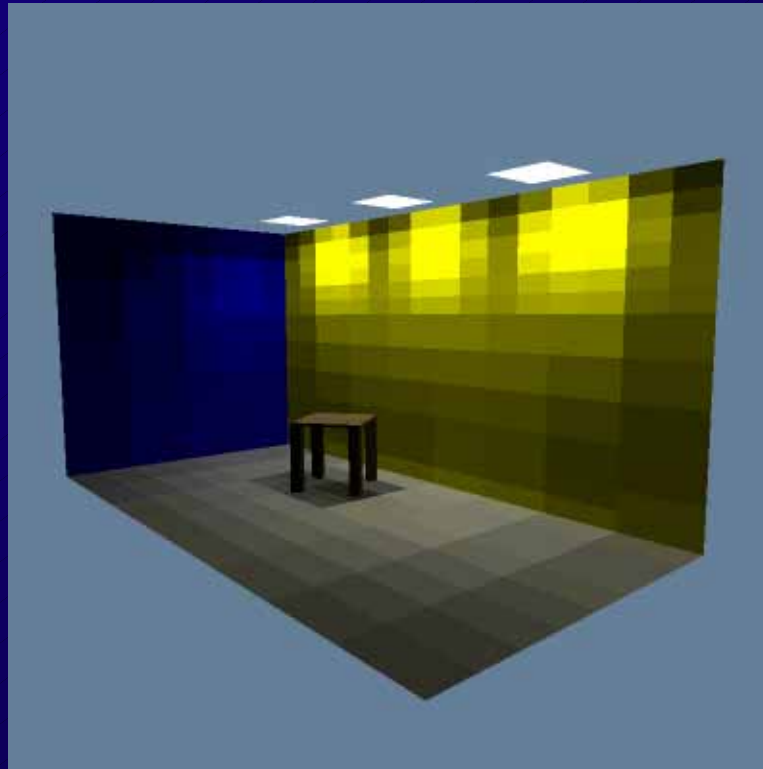
Constructs a complete scene hierarchy

- [Smits '94, Sillion '94]
- Adds volume clusters above input polygons (octree)
- Completes the hierarchy
- Algorithm is $O(k \log k + n)$
- $k \log k$ is a problem for $k > 100,000$

Volume Clustering



Hier. Radiosity Demo



Problems with HRVC

- Slow for complex scenes ($k \gg n$)
 - Must push irradiance down to leaves when gathering, pull radiosity up when shooting
 - $O(\log k)$, and **all input polygons must be touched on each iteration**
- Approximation
 - Volume clusters approximate a cloud of unconnected polygons
 - Idea: We can do better for connected, largely smooth surfaces

My Focus

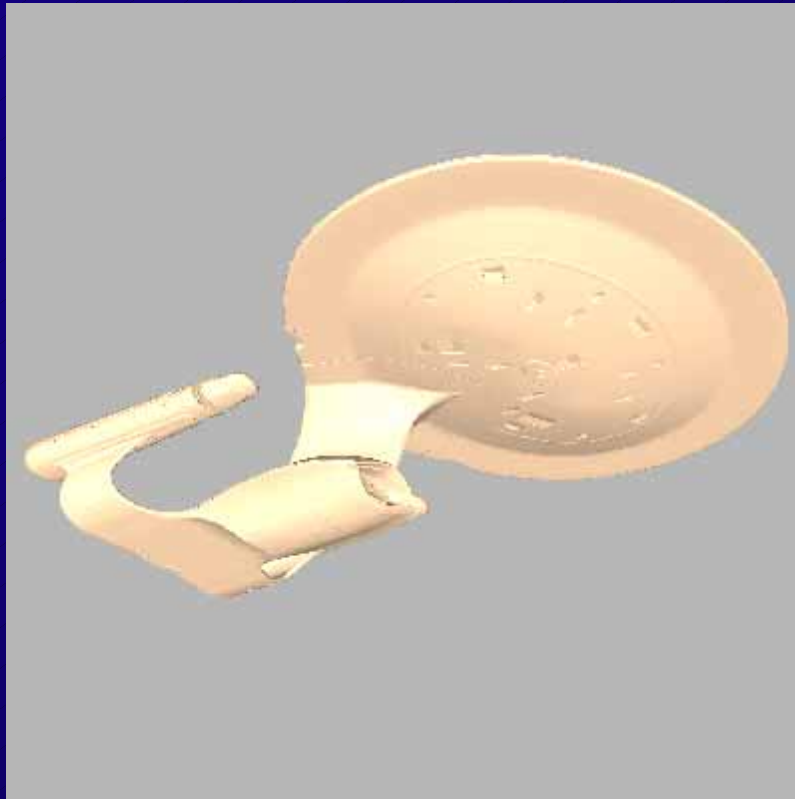
Working with large scanned models

- Large enough to make $k \log k$ a problem
- Observation
 - Most polygons are for high resolution detail
 - Don't affect radiosity computations much

and with Multiresolution Models

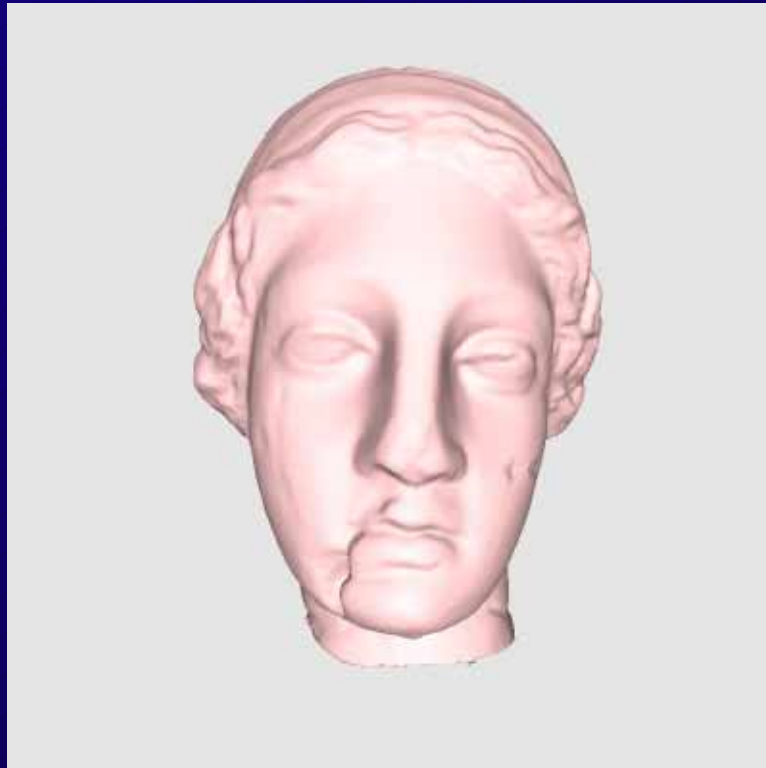
- Allow you to adjust the resolution of the model at different places on the model

Detailed Models



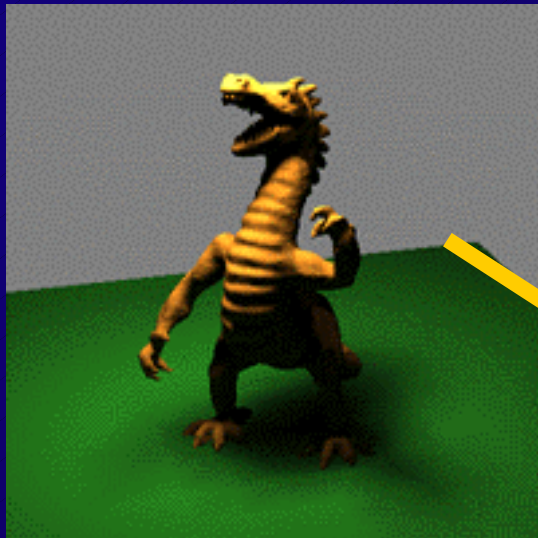
200,000 triangle model. Medium Resolution version(!)

Demo of a MR Model

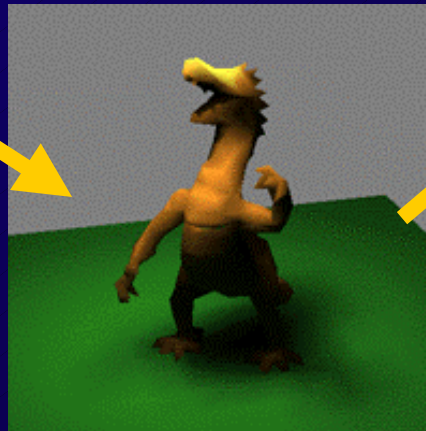


Intuition

**Instead of running
radiosity on
detailed model**

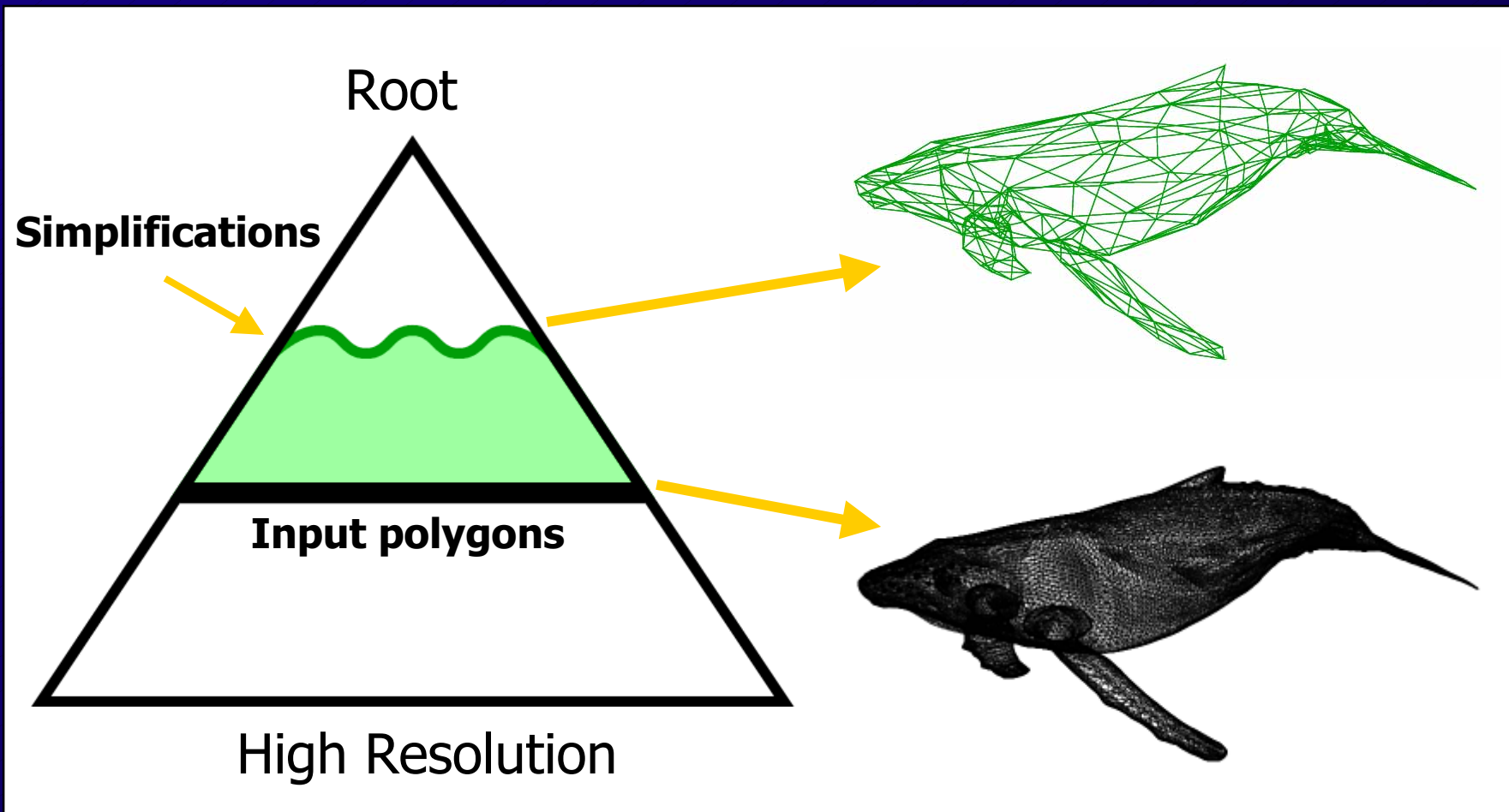


**Run radiosity
on simplified
model**



**Apply results to
original model**

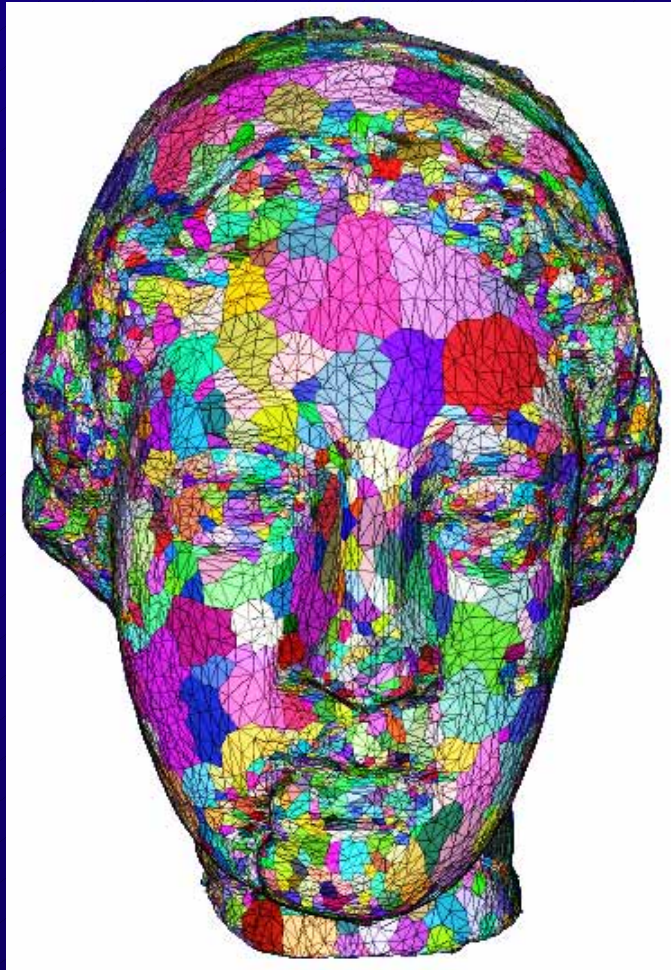
Simplification



Advantages

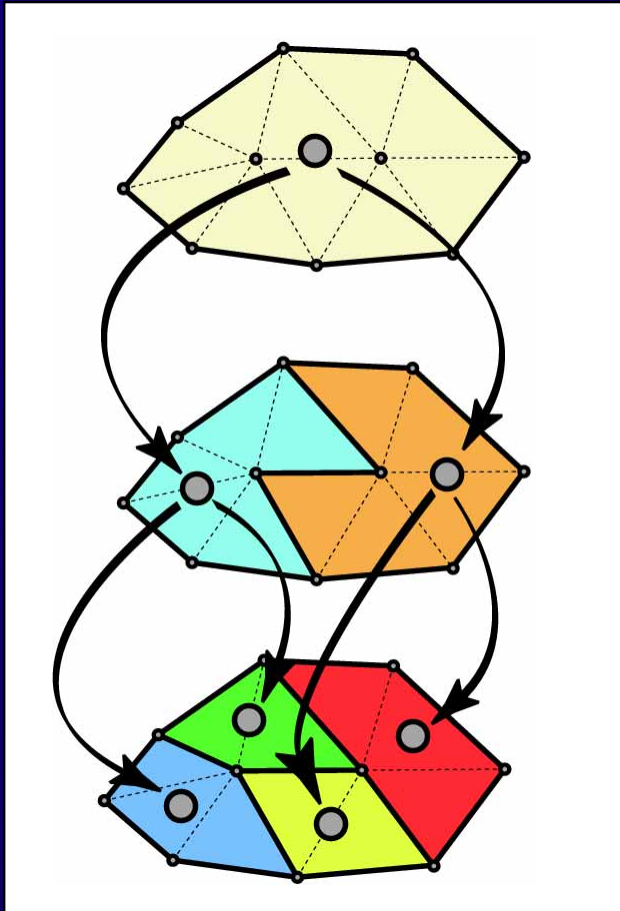
- No manual selection of simplification level
- Don't access each of the k input polygons during each iteration
- Don't store radiosity for each input polygon
- Multiresolution models are precalculated
 - Once for each new model acquired
 - Amortized over many scenes and renders

Face Clusters



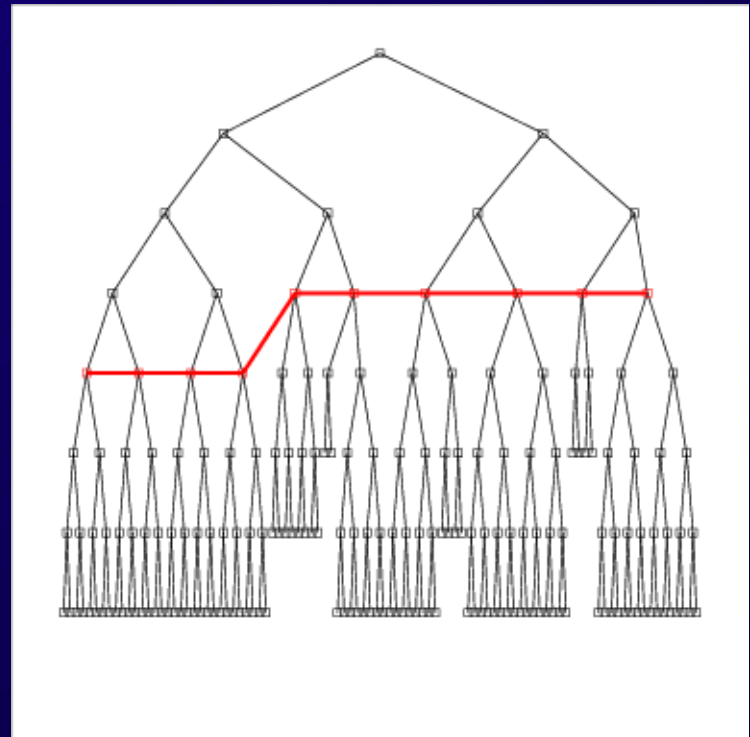
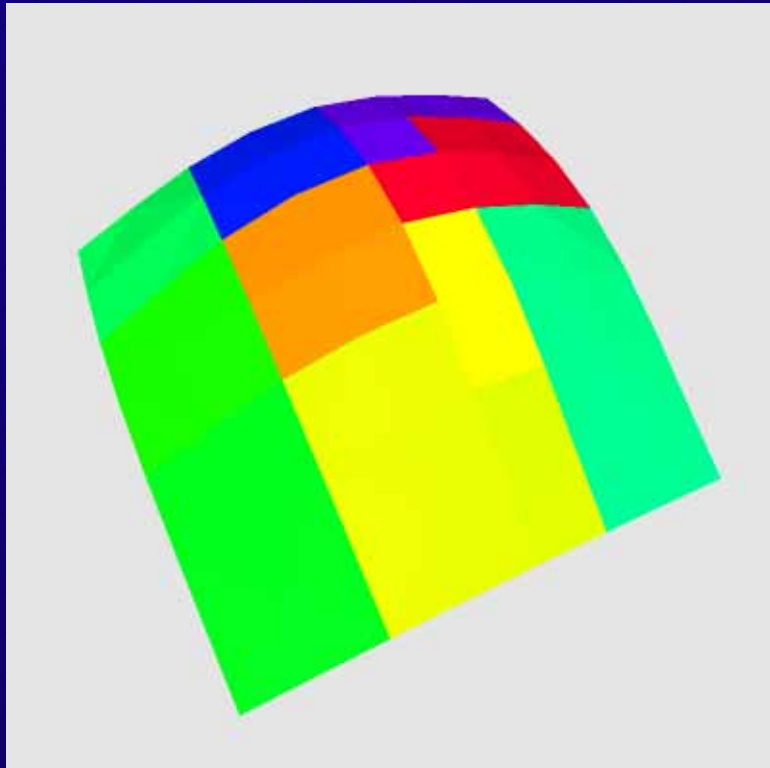
- Dual of standard multiresolution model
- Group faces rather than vertices
- Don't change geometry of the model

Face Cluster Hierarchies



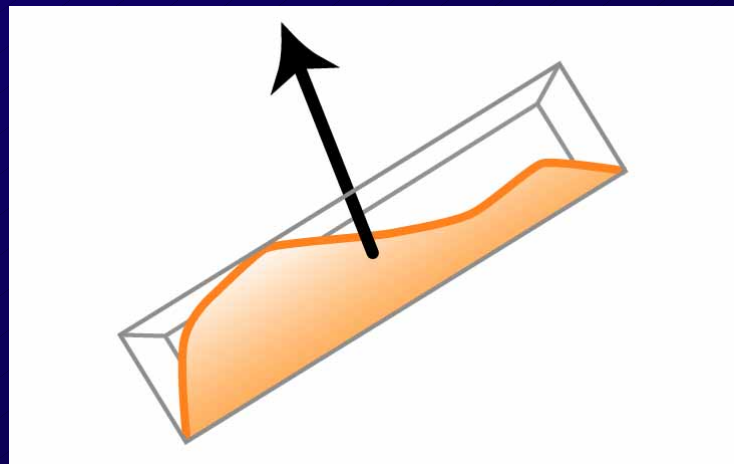
- Iteratively merge face clusters
- Initial clusters each contain a single polygon
- Create links between two child clusters and their union
- Repeat until only root cluster left

Face Cluster Demo

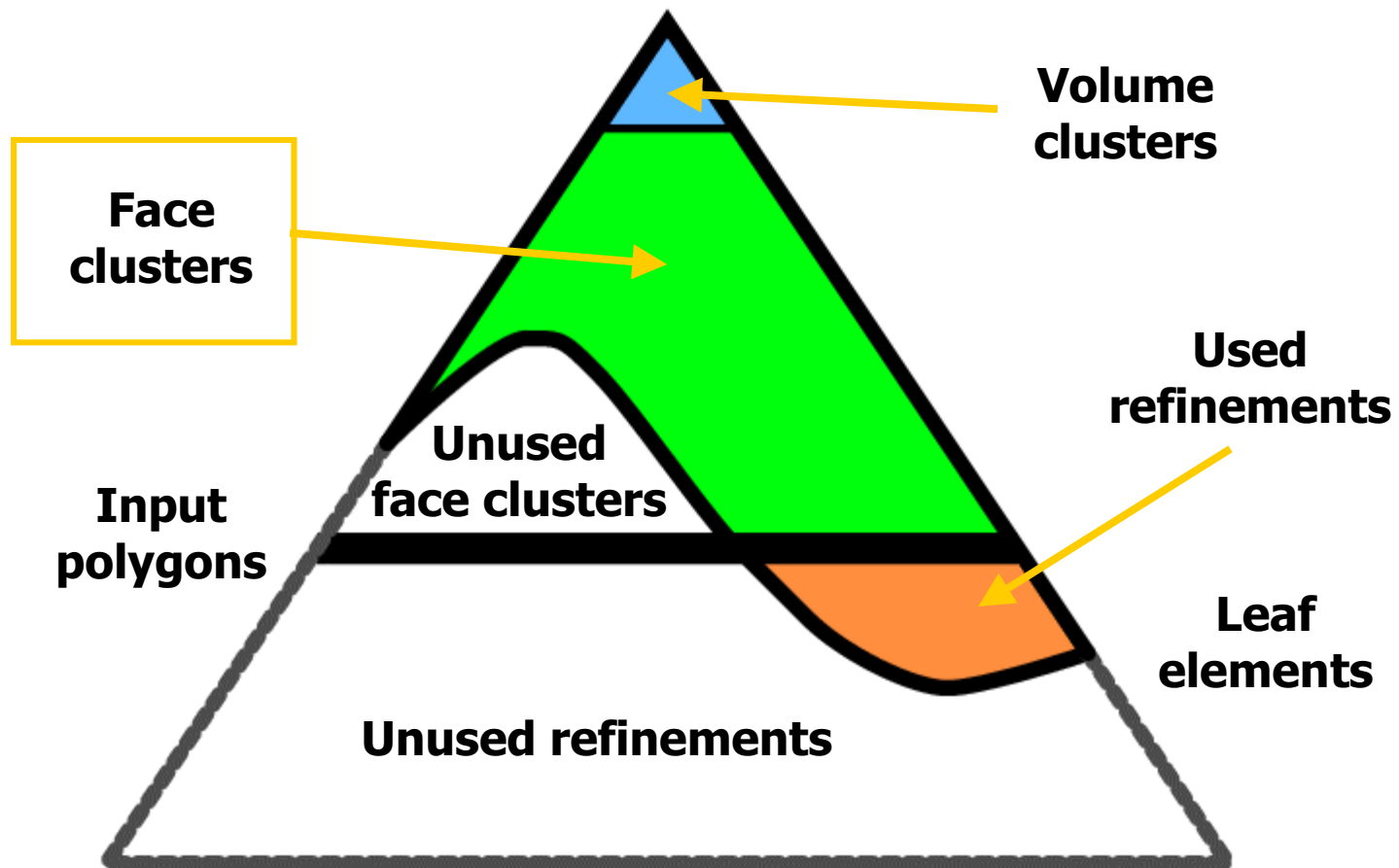


A Face Cluster

- An approximately planar region on the mesh
- Container for a set of connected faces
 - Oriented bounding box
 - Aggregate area-weighted normal
 - Pointers to the two child clusters that partition it



Radiosity with Face Clusters

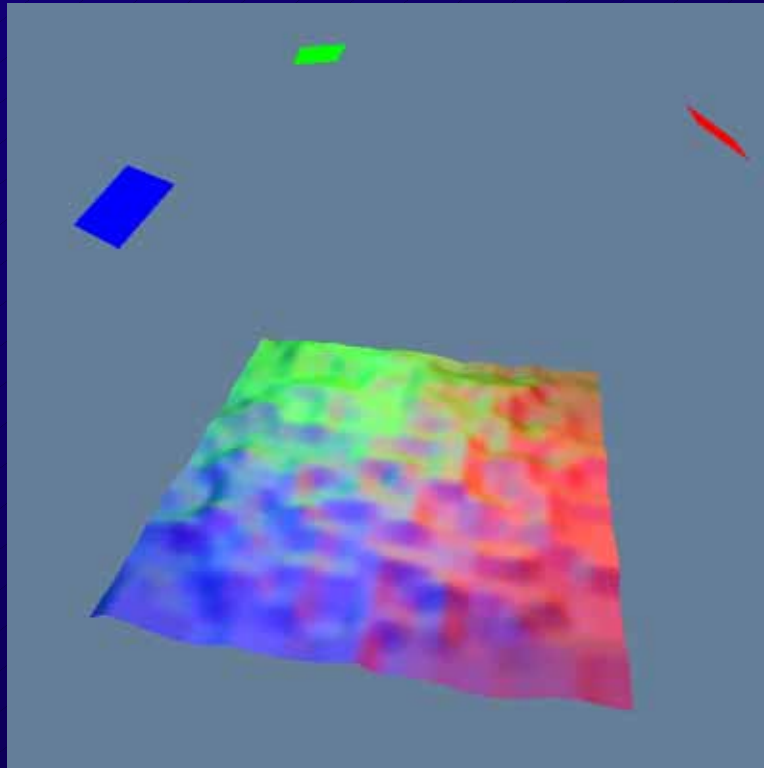


Building the Hierarchy

We use Garland's Quadric method

- Dual of edge-collapse simplification
 - Quadric error term measures distance to best-fit plane of face vertices, rather than distance to face planes of best-fit vertex.
- Most important properties
 - Produces clusters that are approximately planar
 - Tight *oriented* bounding box calculated via Principal Component Analysis
 - Add well-shaped term to get compact clusters

Radiator Demo



Vector Radiosity

Standard radiosity equation is scalar

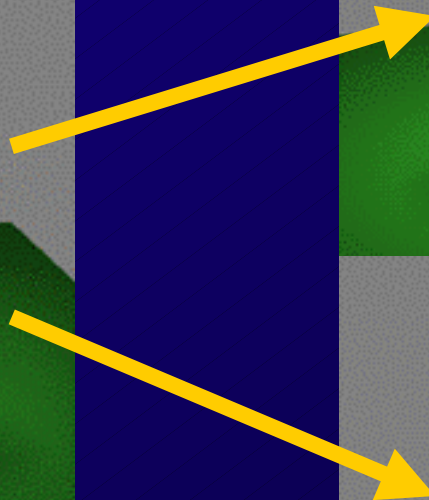
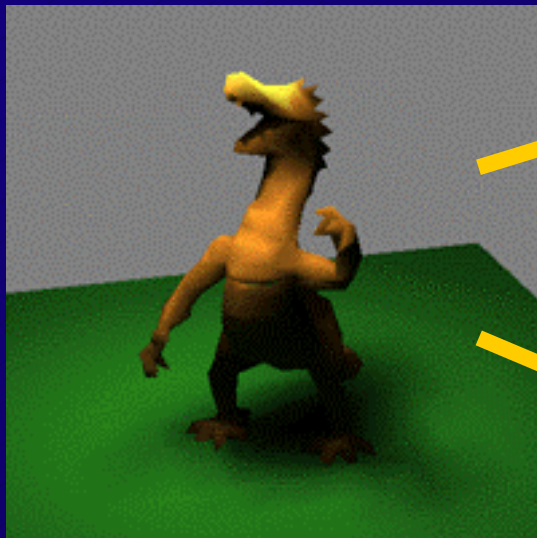
- Applied to face clusters it incorrectly ignores variation in local normals
- No obvious way of combining radiosities of two elements with different normals

Solution

- Recast radiosity equation in terms of *irradiance vector*

Why Vector Radiosity?

Leaf Elements

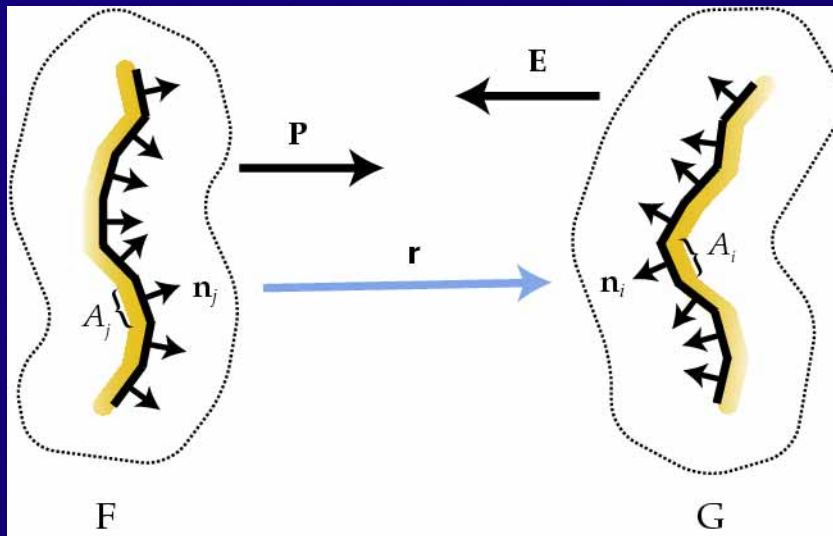


**Scalar
Radiosity**



**Vector
Radiosity**

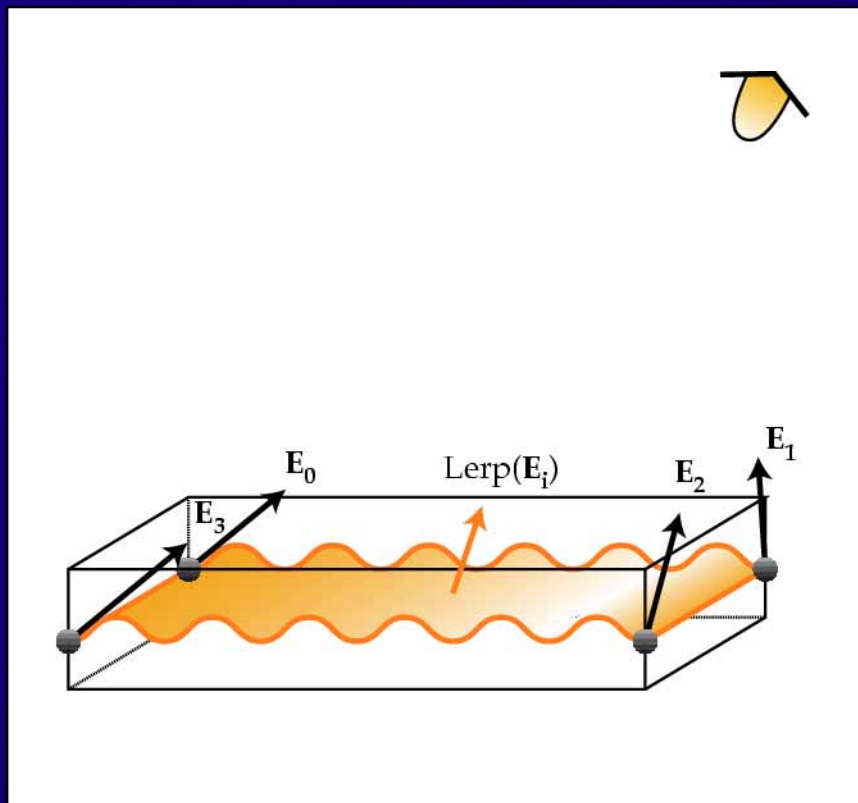
Gather in FCR



- Gather: process of transferring radiosity between elements
- Must be able to calculate *Visible Projected Area* quickly

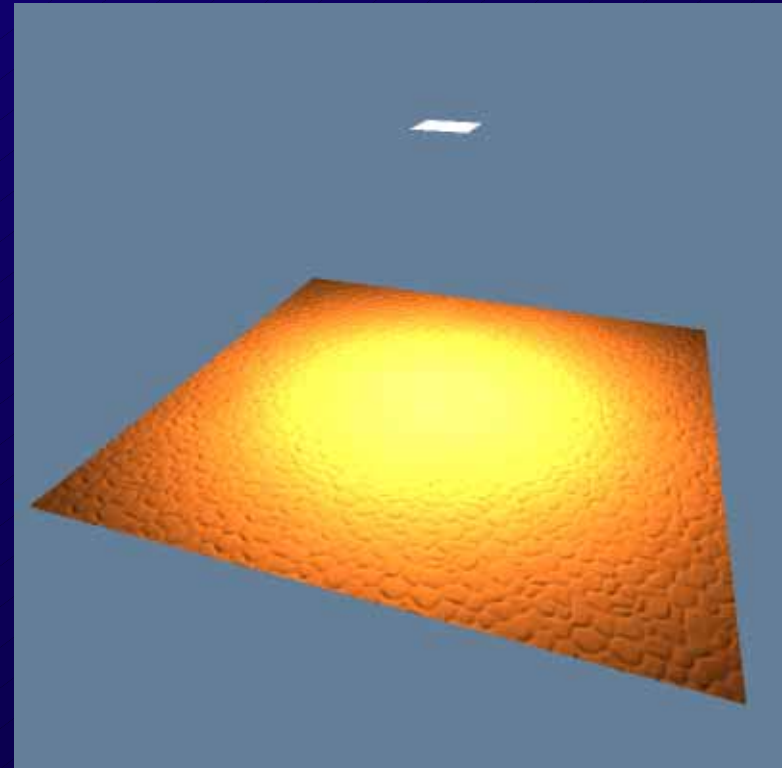
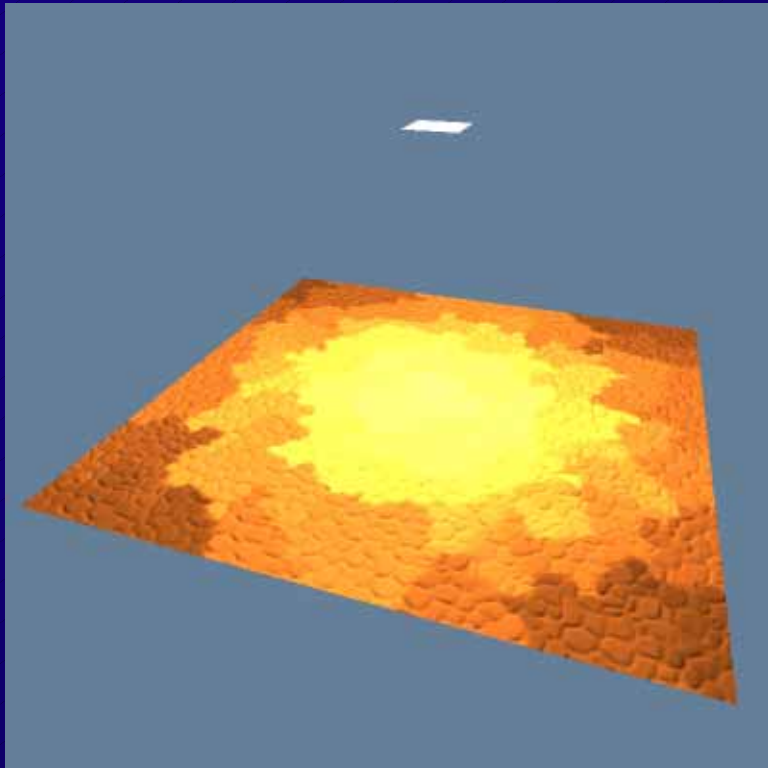
- Developed methods of bounding VPA **without sampling visibility**

Vector Interpolation



- Can get inter-cluster discontinuities, same as with constant radiosity basis function
- Can fix by resampling irradiance vector at corners of the cluster, and interpolating
- Final pass only

Vector Interpolation

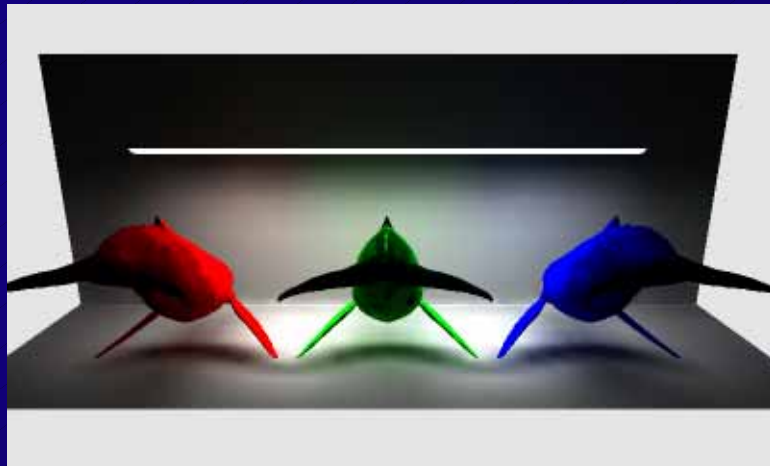


Same clusters: without & with interpolation

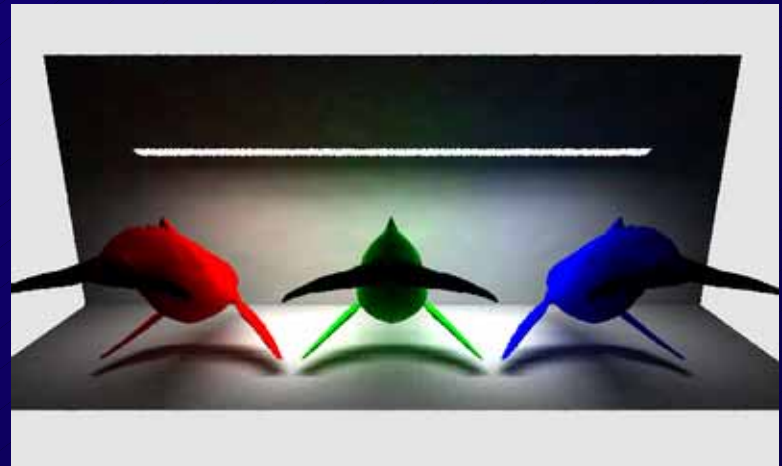
Algorithm Summary

- Construct face cluster hierarchy file for each new model. $k \log k$ (Approx. linear in k)
- Create scene from models
- Read in scene description, add root face cluster nodes to a volume cluster hierarchy
- Run gather/push-pull/refine solver. Sub-linear in k ***Dominant***
- Propagate radiosity solution to leaves of all models, write to disk. Linear in k

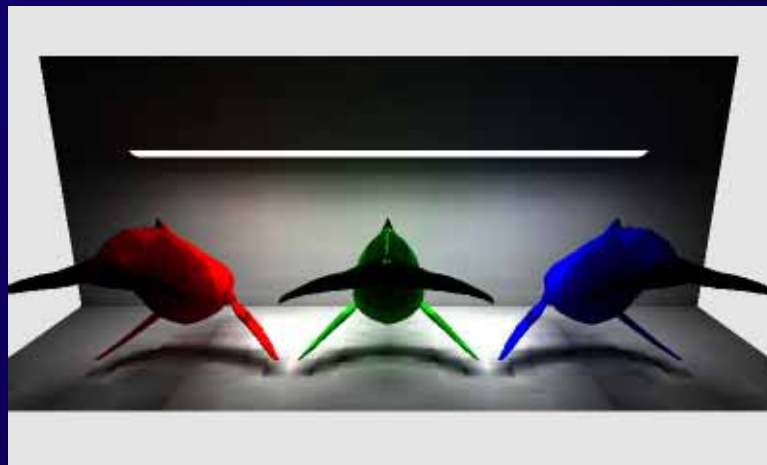
Results: Test Patch Whales



FCR, 127s



Radiance, 378s



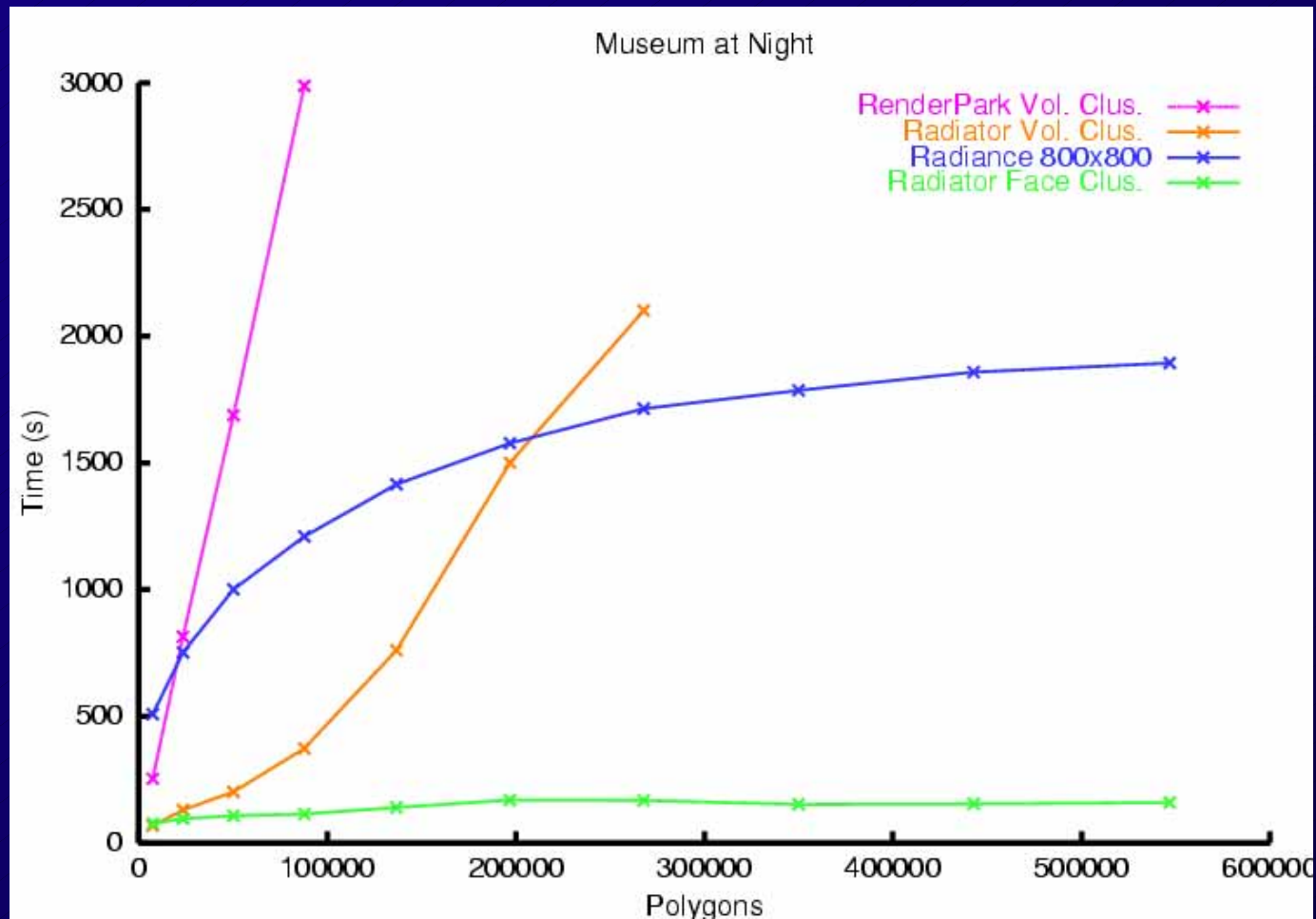
RenderPark, 2700s

Results: Complexity

Tested on several scene resolutions

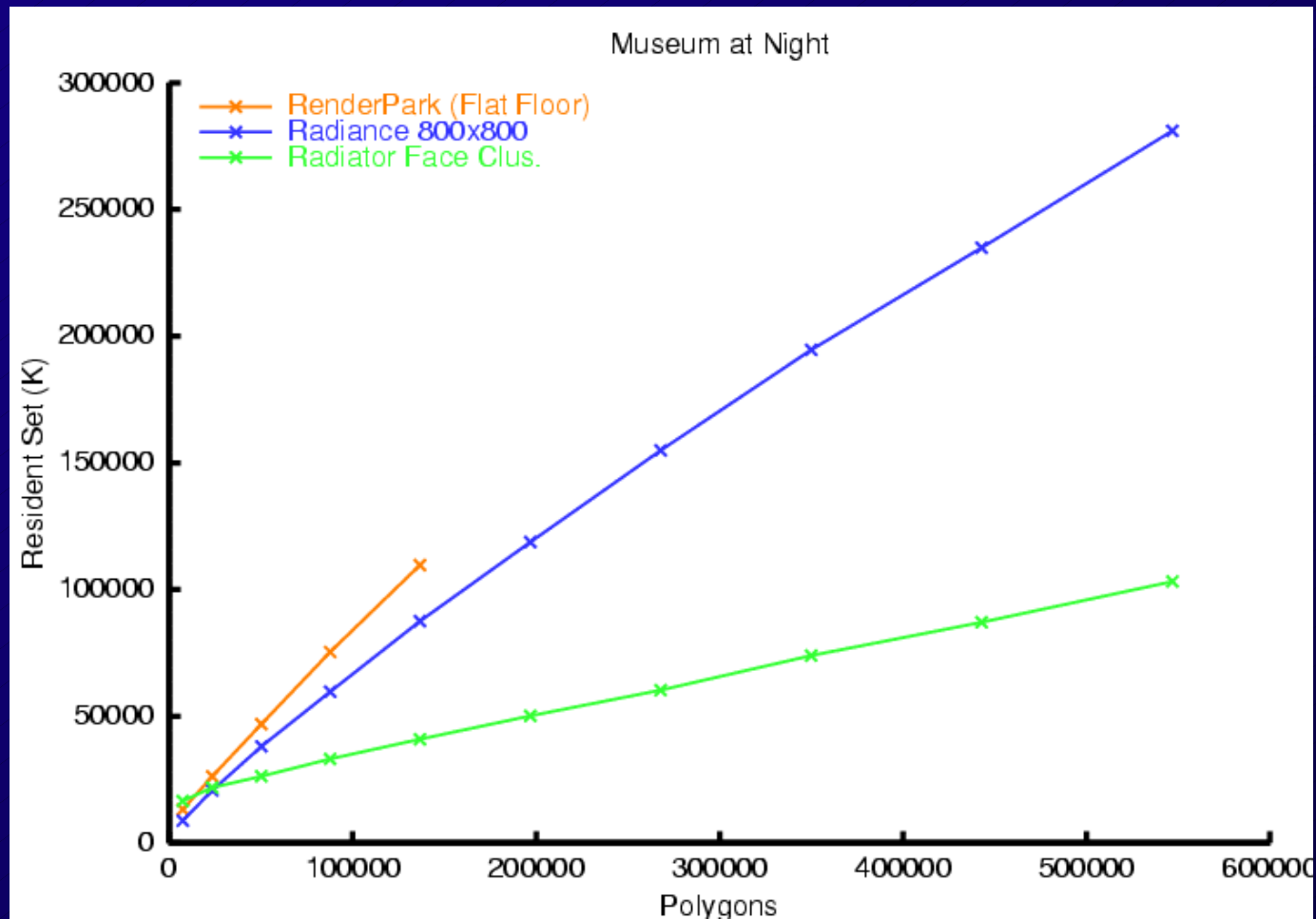
- Museum scene
- Medium-high illumination complexity (nighttime, daytime)
- 6 scanned models, implicit surface podium, displacement-mapped floor
- 550,000 polygons in maximum scene; lower-resolution ones generated by simplification

Results: Solution Time



Same scene,
progressively
more
polygons

Results: Memory Use

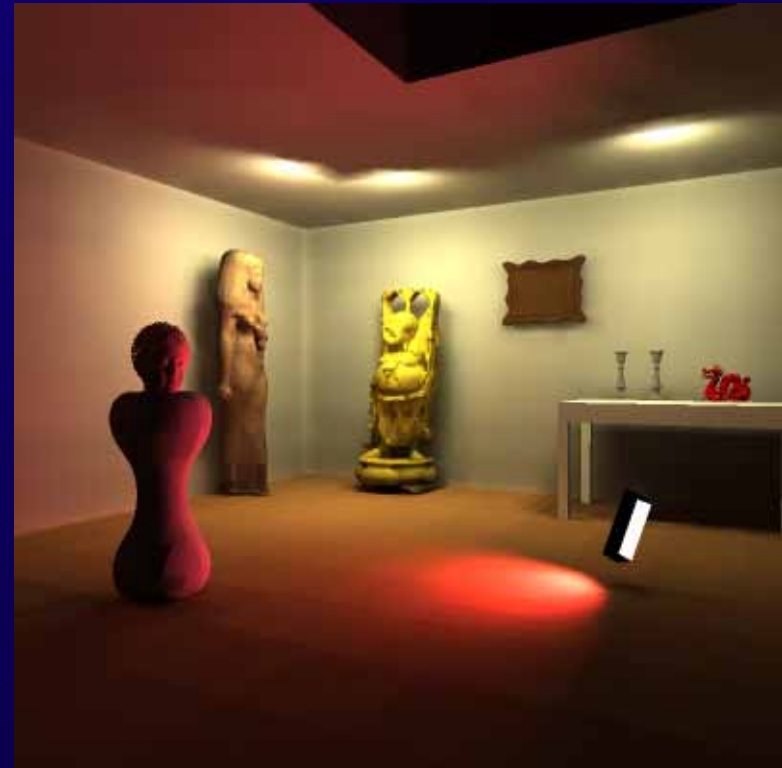


Same scene,
progressively
more
polygons

Results: Complexity



Face Cluster
Radiosity, 150s



Volume Clustering,
850s

Results: Large Scene



3,350,000
triangles

Time: 450s
secs

Radiance,
Progressive and
HRVC would
not fit in 1GB

Results: Large Scene



Conclusions

Face cluster hierarchies are highly effective for use with radiosity

- Sub-linear time in the number of input polygons, as opposed to 'previous best' of $O(k \log k)$
- After a point, solver is constant time
- Low memory usage
- Extremely detailed scenes

Contributions



- FCR helps make radiosity practical for general use
 - Runs on a laptop!
 - One of the most complex radiosity scenes simulated
- Three essential parts to making it work
 - Use of Face Clusters
 - Vector Radiosity
 - Tight visible area bounds for polygonal clusters
- Sped up Garland's cluster creation algorithm
- 80,000 lines of code available
 - <http://www.cs.cmu.edu/~ajw/thesis-code>

Future Work



- Better visibility sampling in final pass
- Extend bounded projected area to higher-order BRDFs (non-diffuse)
- Use of irradiance map to represent illumination

EXTRAS



Face Cluster Creation

Modified & Extended Garland's method

- Existing code needed lots of memory
- Showed how balance was important to clustering time
- Created new, cheaper cost terms
- Improved stability and quality of bounding boxes

Test Models



buddha



bunny



car



cow



cup



dino



dragon



dresser



egg



isis



piano



polar-bear



polar-cub



torso

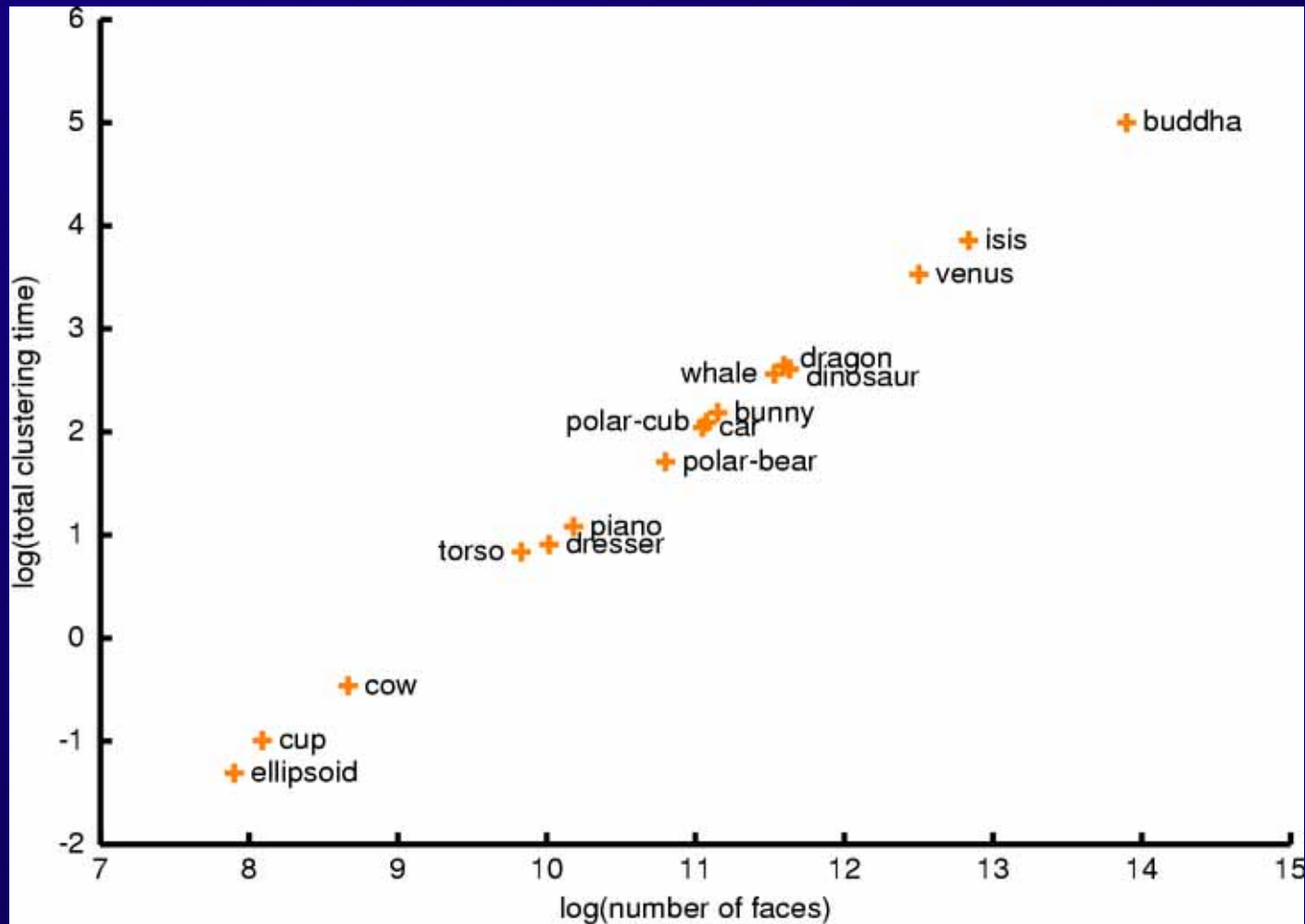


venus



whale

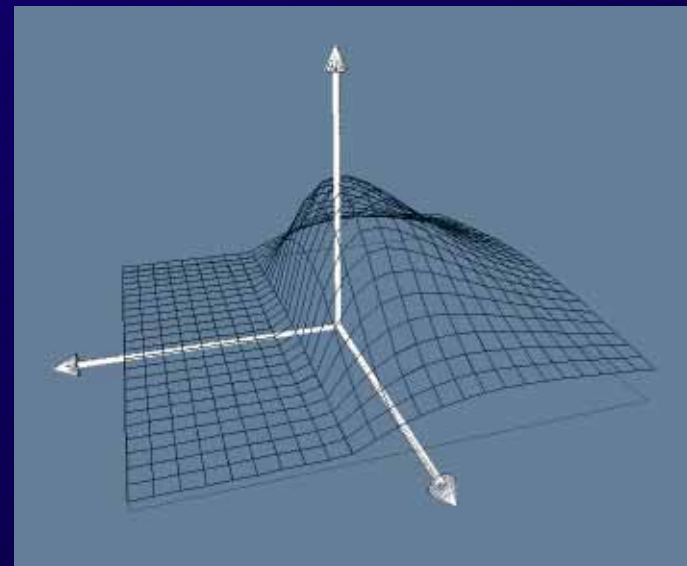
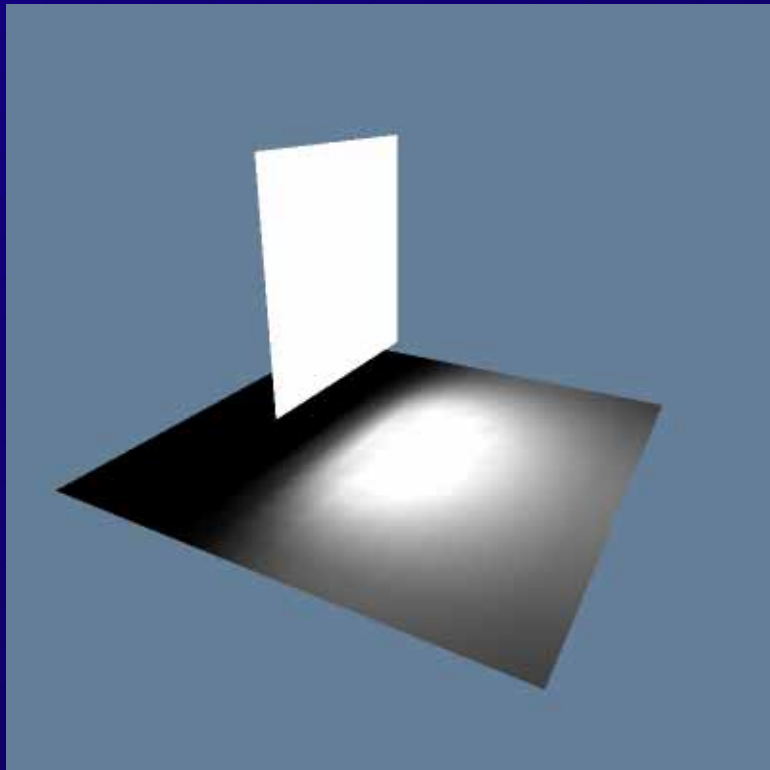
Clustering Times



150s

1s

Integration for GI



State of the Art



Research

- Hierarchical/wavelet radiosity systems

High-quality: Lightscape, Lightworks

- Progressive radiosity, 1,000-100,000 polygon scenes
- Raytracing post-pass to add specular component, 2-3 hour renders is fine.

Virtual worlds

- Progressive radiosity, 10,000 polygon scenes
- Quick previews, 10 minute final renders.

Virtual Memory



- Face cluster files are written in breadth-first order, so get good memory locality
- Usually only small first section of the face cluster file used, so it's memory mapped
- Progressive Radiosity has good total memory use, but very poor locality. Hierarchical Radiosity thrashes better.

Details



- Visibility by ray casting, nested grids
- Fractional visibility used during simulation

Complexity

- $O(s \log s)$, not $O(k \log k)$, where s is the number of face cluster hierarchies.
- $s \ll k$
- Almost always, $s \ll n$
- Each face cluster hierarchy represents a separate polygon mesh
- Corresponds to a connected part of a model surface

Vector Radiosity Equations

$$E_i = \sum_j \frac{(\hat{\mathbf{n}}_i^T \hat{\mathbf{r}}_{ij}) (\hat{\mathbf{r}}_{ji}^T \hat{\mathbf{n}}_j)}{\pi r_{ij}^2} v_{ij} A_j b_j$$



$$E_i \approx \hat{\mathbf{n}}_i^T \left[\frac{-\hat{\mathbf{r}} \hat{\mathbf{r}}^T}{\pi r^2} \sum_j \hat{\mathbf{n}}_j A_j b_j \right]$$



$$\mathbf{E} = -\mathbf{m} \mathbf{m}^T \mathbf{P}$$

The Sky as a Light Source



Colour Bleeding

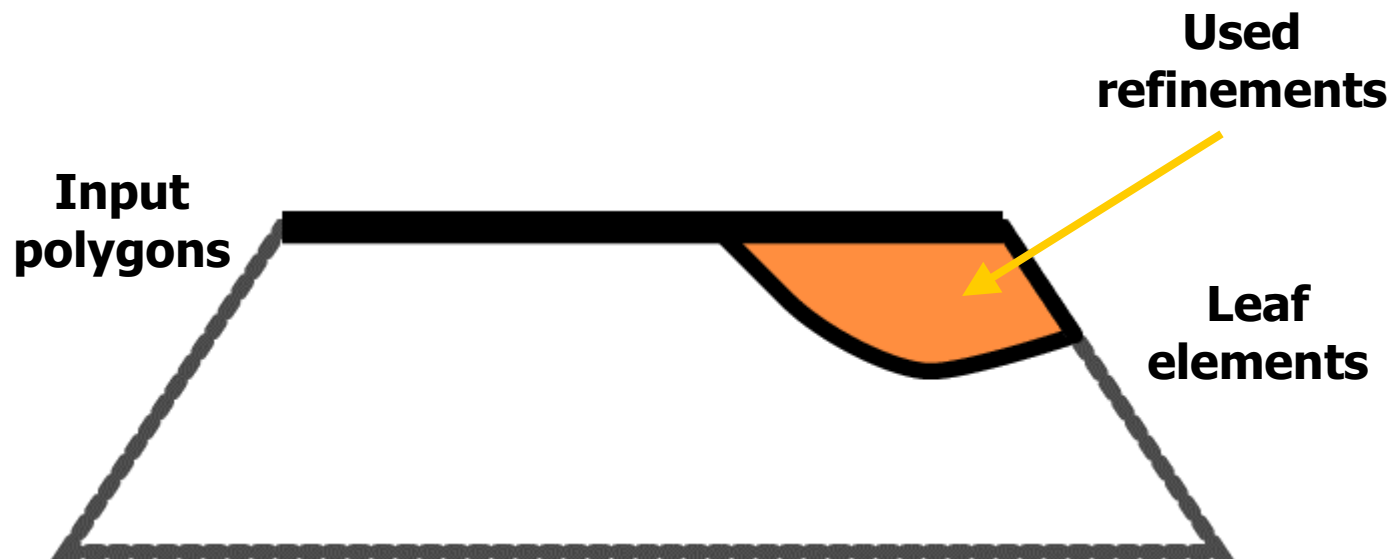


A Better Solution



- Combine simplification & radiosity algorithms
- Use multiresolution hierarchies of the models directly
- Adjust resolution on the fly to match that needed by the radiosity algorithm

Hierarchical Radiosity



Justification



- Simplest representation that captures the appropriate behaviour
- Minimises storage for each face cluster node
- We combine vectors hierarchically to represent complex radiosity distributions

Multiresolution Models



- Initially used edge-collapse models directly
 - These contain **vertex hierarchies**
- Switched to using dual of vertex hierarchy algorithm: *face cluster hierarchies*
 - It's easier to deal with **face hierarchies**