# Data Dependence, Parallelization, and Locality Enhancement

(courtesy of Tarek Abdelrahman, University of Toronto)



$$S_{1}: A = 1.0 
S_{2}: B = A + 2.0 
S_{3}: A = C - D 
: 
S_{4}: A = B/C$$

We define four types of data dependence.

- Flow (true) dependence: a statement S<sub>i</sub> precedes a statement S<sub>j</sub> in execution and S<sub>i</sub> computes a data value that S<sub>j</sub> uses.
- Implies that  $S_i$  must execute before  $S_j$ .

$$S_i \delta^{\dagger} S_j$$
 ( $S_1 \delta^{\dagger} S_2$  and  $S_2 \delta^{\dagger} S_4$ )

**Optimizing Compilers: Parallelization** 

$$S_{1}: A = 1.0$$
  
 $S_{2}: B = A + 2.0$   
 $S_{3}: A = C - D$   
 $\vdots$   
 $S_{4}: A = B/C$ 

We define four types of data dependence.

- Anti dependence: a statement S<sub>i</sub> precedes a statement S<sub>j</sub> in execution and S<sub>i</sub> uses a data value that S<sub>j</sub> computes.
- It implies that  $S_i$  must be executed before  $S_j$ .

$$S_i \delta^{\alpha} S_j$$
  $(S_2 \delta^{\alpha} S_3)$ 

$$S_{1}: A = 1.0 
S_{2}: B = A + 2.0 
S_{3}: A = C - D 
: 
S_{4}: A = B/C$$

We define four types of data dependence.

- Output dependence: a statement S<sub>i</sub> precedes a statement S<sub>j</sub> in execution and S<sub>i</sub> computes a data value that S<sub>j</sub> also computes.
- It implies that  $S_i$  must be executed before  $S_j$ .

$$S_i \delta^{\circ} S_j$$
 ( $S_1 \delta^{\circ} S_3$  and  $S_3 \delta^{\circ} S_4$ )

**Optimizing Compilers: Parallelization** 

$$S_1: A = 1.0$$
  
 $S_2: B = A + 2.0$   
 $S_3: A = C - D$   
 $\vdots$   
 $S_4: A = B/C$ 

We define four types of data dependence.

- Input dependence: a statement  $S_i$  precedes a statement  $S_j$  in execution and  $S_i$  uses a data value that  $S_j$  also uses.
- Does this imply that S<sub>i</sub> must execute before S<sub>j</sub>?

$$S_i \delta^{I} S_j$$
  $(S_3 \delta^{I} S_4)$ 

**Optimizing Compilers: Parallelization** 

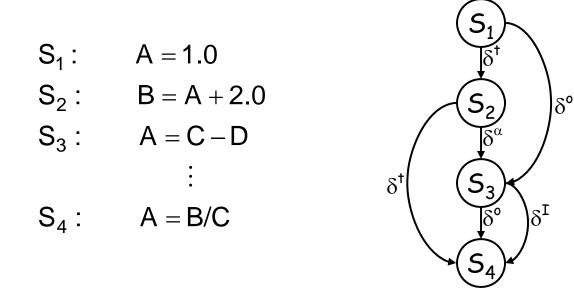
#### Data Dependence (continued)

- The dependence is said to flow from S<sub>i</sub> to S<sub>j</sub> because S<sub>i</sub> precedes S<sub>j</sub> in execution.
- $S_i$  is said to be the source of the dependence.  $S_j$  is said to be the sink of the dependence.
- The only "true" dependence is flow dependence; it represents the flow of data in the program.
- The other types of dependence are caused by programming style; they may be eliminated by re-naming.

$$S_{1}: A = 1.0 
S_{2}: B = A + 2.0 
S_{3}: A1 = C - D 
: S_{4}: A2 = B/C$$

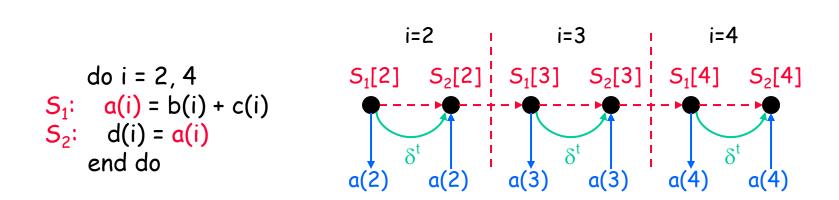
#### Data Dependence (continued)

• Data dependence in a program may be represented using a dependence graph G=(V,E), where the nodes V represent statements in the program and the directed edges E represent dependence relations.



### Value or Location?

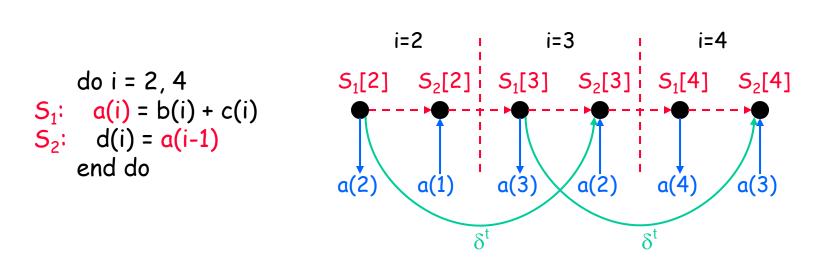
• There are two ways a dependence is defined: value-oriented or location-oriented.



- There is an instance of  $S_1$  that precedes an instance of  $S_2$  in execution and  $S_1$  produces data that  $S_2$  consumes.
- $S_1$  is the source of the dependence;  $S_2$  is the sink of the dependence.
- The dependence flows between instances of statements in the same iteration (loop-independent dependence).
- The number of iterations between source and sink (dependence distance) is 0. The dependence direction is =.

$$\mathbf{S}_{1} \, \mathbf{\delta}_{\pm}^{\dagger} \, \mathbf{S}_{2}^{\dagger}$$
 or  $\mathbf{S}_{1} \, \mathbf{\delta}_{0}^{\dagger} \, \mathbf{S}_{2}^{\dagger}$ 

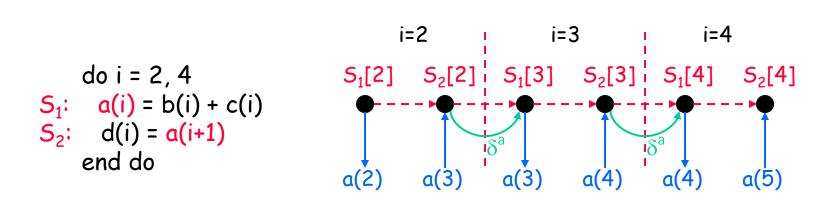
**Optimizing Compilers: Parallelization** 



- There is an instance of  $S_1$  that precedes an instance of  $S_2$  in execution and  $S_1$  produces data that  $S_2$  consumes.
- $S_1$  is the source of the dependence;  $S_2$  is the sink of the dependence.
- The dependence flows between instances of statements in different iterations (loop-carried dependence).
- The dependence distance is 1. The direction is positive (<).

$$\mathbf{S}_{1} \, \mathbf{\delta}_{<}^{\dagger} \, \mathbf{S}_{2}^{\dagger}$$
 or  $\mathbf{S}_{1} \, \mathbf{\delta}_{1}^{\dagger} \, \mathbf{S}_{2}^{\dagger}$ 

**Optimizing Compilers: Parallelization** 



- There is an instance of S<sub>2</sub> that precedes an instance of S<sub>1</sub> in execution and S<sub>2</sub> consumes data that S<sub>1</sub> produces.
- $S_2$  is the source of the dependence;  $S_1$  is the sink of the dependence.
- The dependence is loop-carried.
- The dependence distance is 1.

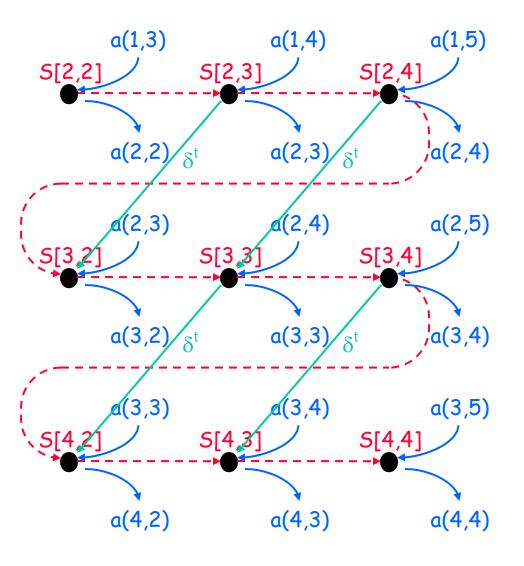
$$S_2 \delta_{<}^{\alpha} S_1$$
 or  $S_2 \delta_1^{\alpha} S_1$ 

• Are you sure you know why it is  $S_2 \delta_{<}^a S_1$  even though  $S_1$  appears before  $S_2$  in the code?

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- do i = 2, 4 do j = 2, 4 S: a(i,j) = a(i-1,j+1) end do end do
- An instance of S precedes another instance of S and S produces data that S consumes.
- S is both source and sink.
- The dependence is loopcarried.
- The dependence distance is (1,-1).

$$S\delta^{\dagger}_{(<,>)}S$$
 or  $S\delta^{\dagger}_{(1,-1)}$ 

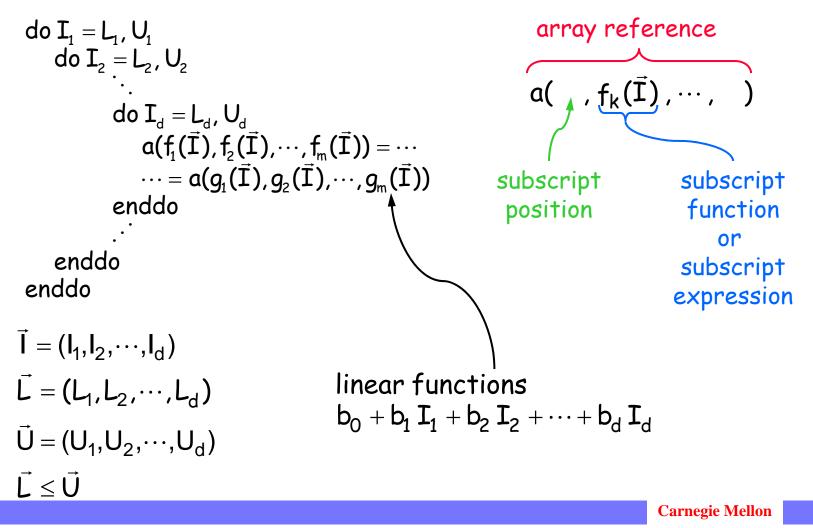


**Optimizing Compilers: Parallelization** 

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## **Problem Formulation**

• Consider the following perfect nest of depth d:



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# **Problem Formulation**

• Dependence will exist if there exists two iteration vectors  $\vec{k}$  and  $\vec{j}$  such that  $\vec{L} \le \vec{k} \le \vec{j} \le \vec{U}$  and:

and 
$$f_{1}(\vec{k}) = g_{1}(\vec{j})$$
  
and 
$$f_{2}(\vec{k}) = g_{2}(\vec{j})$$
  
i  
and 
$$\vdots$$
  
$$f_{m}(\vec{k}) = g_{m}(\vec{j})$$

• That is:

and 
$$f_{1}(\vec{k}) - g_{1}(\vec{j}) = 0$$
  
and 
$$f_{2}(\vec{k}) - g_{2}(\vec{j}) = 0$$
  
:  
and 
$$f_{m}(\vec{k}) - g_{m}(\vec{j}) = 0$$

# Problem Formulation - Example

do i = 2, 4  

$$S_1: a(i) = b(i) + c(i)$$
  
 $S_2: d(i) = a(i-1)$   
end do

• Does there exist two iteration vectors  $i_1$  and  $i_2$ , such that  $2 \le i_1 \le i_2 \le 4$  and such that:

 $i_1 = i_2 - 1?$ 

- Answer: yes;  $i_1=2 \& i_2=3$  and  $i_1=3 \& i_2=4$ .
- Hence, there is dependence!
- The dependence distance vector is  $i_2 i_1 = 1$ .
- The dependence direction vector is sign(1) = <.

# Problem Formulation - Example

```
do i = 2, 4

S_1: a(i) = b(i) + c(i)

S_2: d(i) = a(i+1)

end do
```

• Does there exist two iteration vectors  $i_1$  and  $i_2$ , such that  $2 \le i_1 \le i_2 \le 4$  and such that:

 $i_1 = i_2 + 1?$ 

- Answer: yes;  $i_1=3 \& i_2=2$  and  $i_1=4 \& i_2=3$ . (But, but!).
- Hence, there is dependence!
- The dependence distance vector is  $i_2 i_1 = -1$ .
- The dependence direction vector is sign(-1) = >.
- Is this possible?

### Problem Formulation - Example

do i = 1, 10  

$$S_1: a(2*i) = b(i) + c(i)$$
  
 $S_2: d(i) = a(2*i+1)$   
end do

• Does there exist two iteration vectors  $i_1$  and  $i_2$ , such that  $1 \le i_1 \le i_2 \le 10$  and such that:

 $2*i_1 = 2*i_2 + 1?$ 

- Answer: no;  $2*i_1$  is even &  $2*i_2+1$  is odd.
- Hence, there is no dependence!

# Problem Formulation

- Dependence testing is equivalent to an integer linear programming (ILP) problem of 2d variables & m+d constraint!
- An algorithm that determines if there exits two iteration vectors  $\vec{k}$  and  $\vec{j}$  that satisfies these constraints is called a dependence tester.
- The dependence distance vector is given by  $\vec{j} \vec{k}$ .
- The dependence direction vector is give by sign( $\vec{j} \vec{k}$ ).
- Dependence testing is NP-complete!
- A dependence test that reports dependence only when there is dependence is said to be exact. Otherwise it is in-exact.
- A dependence test must be conservative; if the existence of dependence cannot be ascertained, dependence must be assumed.

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#### Dependence Testers

- Lamport's Test.
- GCD Test.
- Banerjee's Inequalities.
- Generalized GCD Test.
- Power Test.
- I-Test.
- Omega Test.
- Delta Test.
- Stanford Test.
- etc...

# Lamport's Test

• Lamport's Test is used when there is a single index variable in the subscript expressions, and when the coefficients of the index variable in both expressions are the same.

$$A(\cdots, b^{*}i + c_{1}, \cdots) = \cdots$$
$$\cdots = A(\cdots, b^{*}i + c_{2}, \cdots)$$

• The dependence problem: does there exist  $i_1$  and  $i_2$ , such that  $L_i \le i_1 \le i_2 \le U_i$  and such that

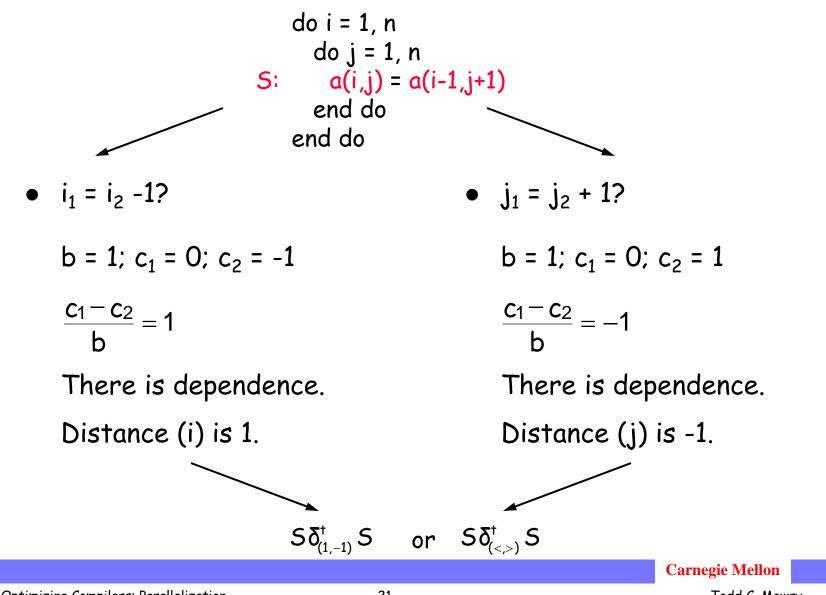
$$b*i_1 + c_1 = b*i_2 + c_2$$
? or  $i_2 - i_1 = \frac{c_1 - c_2}{b}$ ?

- There is integer solution if and only if  $\frac{c_1 c_2}{h}$  is integer.
- The dependence distance is  $d = \frac{c_1 c_2}{b}$  if  $L_i \le |d| \le U_i$ .
- d > 0 ⇒ true dependence.
   d = 0 ⇒ loop independent dependence.
   d < 0 ⇒ anti dependence.</li>

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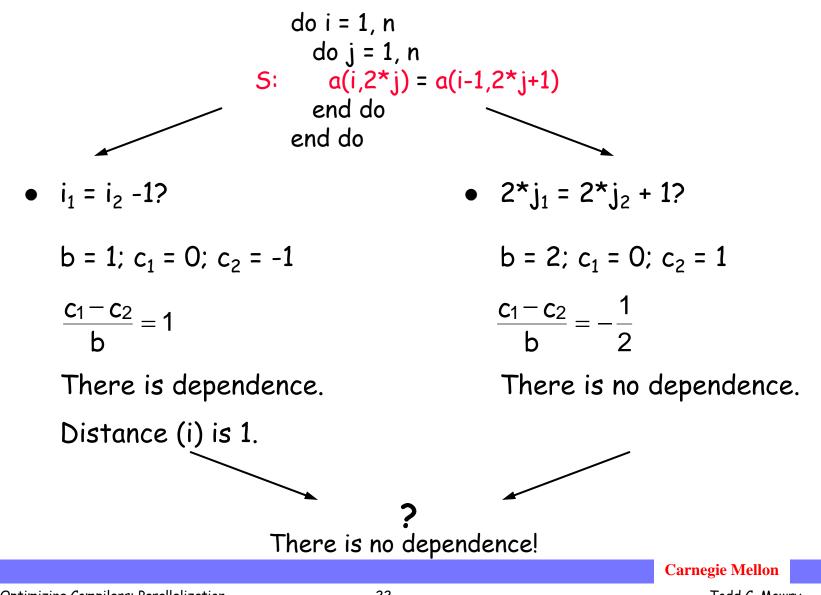
#### Lamport's Test - Example



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#### Lamport's Test - Example



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# <u>GCD Test</u>

• Given the following equation:

$$\sum_{i=1}^{n} a_i x_i = c \qquad a_i's and c are integers$$

an integer solution exists if and only if:

$$gcd(a_1, a_2, \dots, a_n)$$
 divides c

- Problems:
  - ignores loop bounds.
  - gives no information on distance or direction of dependence.
  - often gcd(.....) is 1 which always divides c, resulting in false dependences.

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### GCD Test - Example

do i = 1, 10  

$$S_1: a(2*i) = b(i) + c(i)$$
  
 $S_2: d(i) = a(2*i-1)$   
end do

• Does there exist two iteration vectors  $i_1$  and  $i_2$ , such that  $1 \le i_1 \le i_2 \le 10$  and such that:

$$2*i_1 = 2*i_2 - 1?$$

or

- There will be an integer solution if and only if gcd(2,-2) divides 1.
- This is not the case, and hence, there is no dependence!

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# GCD Test Example

do i = 1, 10  

$$S_1: a(i) = b(i) + c(i)$$
  
 $S_2: d(i) = a(i-100)$   
end do

• Does there exist two iteration vectors  $i_1$  and  $i_2$ , such that  $1 \le i_1 \le i_2 \le 10$  and such that:

```
i_1 = i_2 -100?
or
i_2 - i_1 = 100?
```

- There will be an integer solution if and only if gcd(1,-1) divides 100.
- This is the case, and hence, there is dependence! Or is there?

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### **Dependence Testing Complications**

• Unknown loop bounds.

do i = 1, N S<sub>1</sub>: a(i) = a(i+10) end do

What is the relationship between N and 10?

• Triangular loops.

Must impose j < i as an additional constraint.

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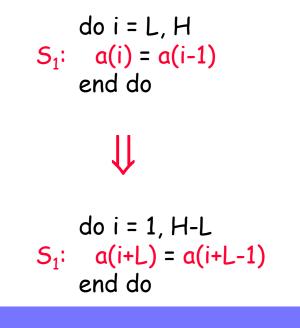
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# More Complications

• User variables.

do i = 1, 10 S<sub>1</sub>: a(i) = a(i+k) end do

Same problem as unknown loop bounds, but occur due to some loop transformations (e.g., normalization).



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### More Complications

• Scalars.

|                         | do i = 1, N           |
|-------------------------|-----------------------|
| <b>S</b> <sub>1</sub> : | <mark>×</mark> = a(i) |
| <b>S</b> <sub>2</sub> : | b(i) = 🗙              |
| _                       | end do                |

do i = 1, N S<sub>1</sub>: x(i) = a(i) S<sub>2</sub>: b(i) = x(i) end do

do i = 1, N  $S_1: a(i) = a(N-i)$ 

end do

sum = 0 do i = 1, N S<sub>1</sub>: sum = sum + a(i) end do do i = 1, N S<sub>1</sub>: sum(i) = a(i) end do sum += sum(i) i = 1, N

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### Serious Complications

- Aliases.
  - Equivalence Statements in Fortran:

real a(10,10), b(10)

makes b the same as the first column of a.

common /shared/x,y,z

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 A dependence is said to be carried by a loop if the loop is the outmost loop whose removal eliminates the dependence. If a dependence is not carried by the loop, it is loopindependent.

do i = 2, n-1  
do j = 2, m-1  

$$a(i, j) = ...$$
  
 $... = a(i, j)$   
 $b(i, j) = ...$   
 $... = b(i, j-1)$   
 $c(i, j) = ...$   
 $... = c(i-1, j)$   
end do  
end do

 A dependence is said to be carried by a loop if the loop is the outmost loop whose removal eliminates the dependence. If a dependence is not carried by the loop, it is loopindependent.

do i = 2, n-1  
do j = 2, m-1  

$$a(i, j) = ...$$
  
 $b(i, j) = ...$   
 $b(i, j) = ...$   
 $c(i, j)$ 

 A dependence is said to be carried by a loop if the loop is the outmost loop whose removal eliminates the dependence. If a dependence is not carried by the loop, it is loopindependent.

do i = 2, n-1  
do j = 2, m-1  

$$a(i, j) = ...$$
  
 $... = a(i, j)$   
 $\delta^{\dagger}_{=,<}$ 
 $b(i, j) = ...$   
 $... = b(i, j-1)$   
 $c(i, j) = ...$   
 $... = c(i-1, j)$   
end do  
end do

 A dependence is said to be carried by a loop if the loop is the outmost loop whose removal eliminates the dependence. If a dependence is not carried by the loop, it is loopindependent.

do i = 2, n-1  
do j = 2, m-1  

$$a(i, j) = ...$$
  
 $... = a(i, j)$   
 $b(i, j) = ...$   
 $... = b(i, j-1)$   
 $\delta^{\dagger}_{<,=} = c(i-1, j)$   
end do  
end do

 A dependence is said to be carried by a loop if the loop is the outmost loop whose removal eliminates the dependence. If a dependence is not carried by the loop, it is loopindependent.

do i = 2, n-1  
do j = 2, m-1  

$$a(i, j) = ...$$
  
 $\delta^{\dagger}_{=,=}$  ... = a(i, j)  
 $\delta^{\dagger}_{=,<}$   $b(i, j) = ...$   
 $... = b(i, j-1)$   
 $\delta^{\dagger}_{<,=}$   $c(i, j) = ...$   
 $... = c(i-1, j)$   
end do  
end do

• Outermost loop with a non "=" direction carries dependence!

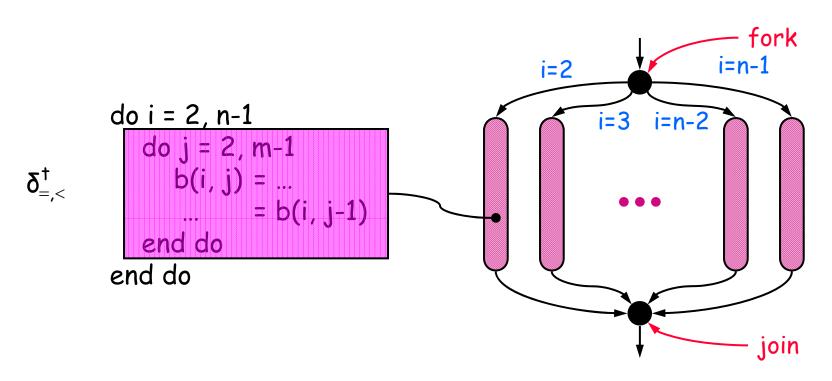
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The iterations of a loop may be executed in parallel with one another if and only if no dependences are carried by the loop!

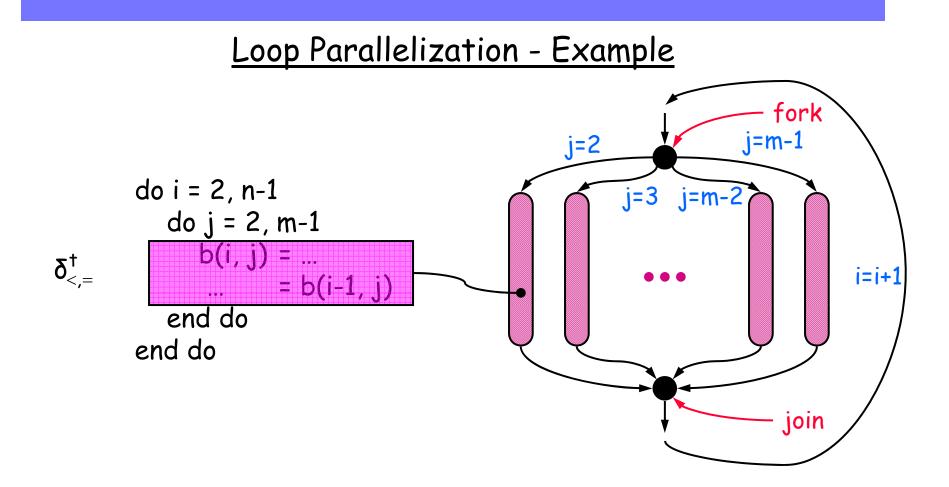
### Loop Parallelization - Example



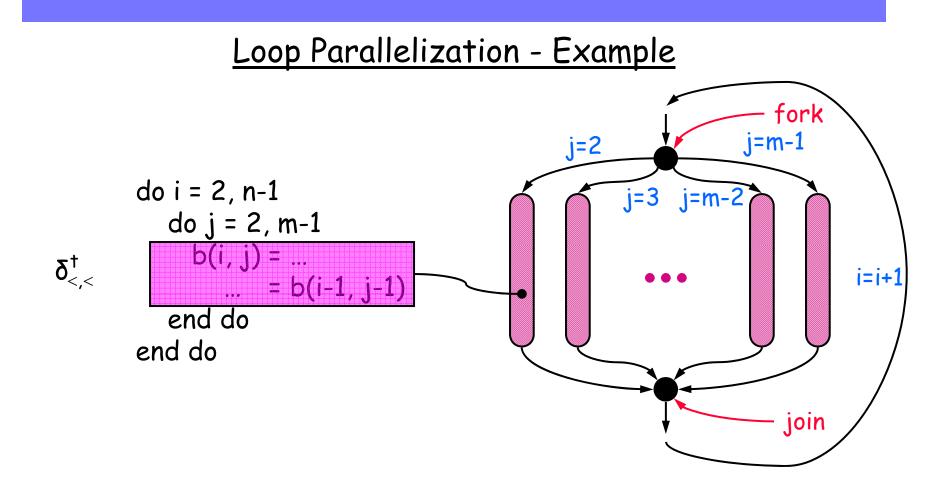
- Iterations of loop j must be executed sequentially, but the iterations of loop i may be executed in parallel.
- Outer loop parallelism.

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- Iterations of loop i must be executed sequentially, but the iterations of loop j may be executed in parallel.
- Inner loop parallelism.

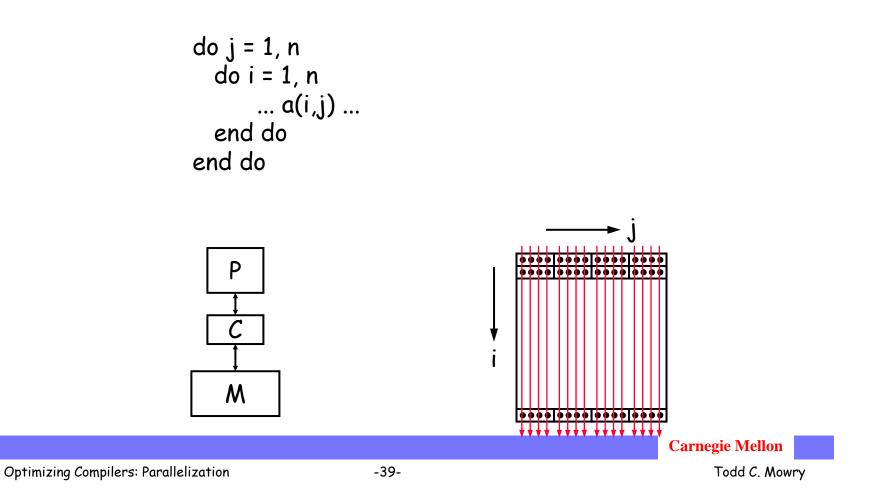


- Iterations of loop i must be executed sequentially, but the iterations of loop j may be executed in parallel. Why?
- Inner loop parallelism.

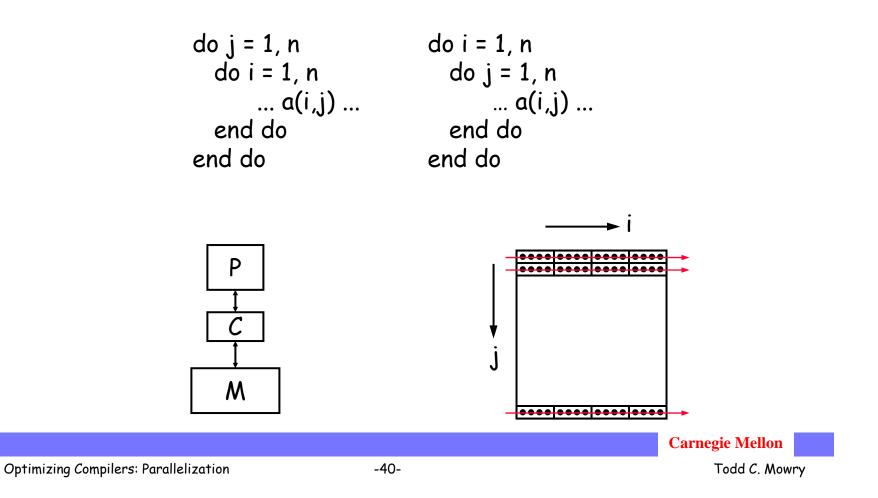
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Loop interchange changes the order of the loops to improve the spatial locality of a program.



Loop interchange changes the order of the loops to improve the spatial locality of a program.



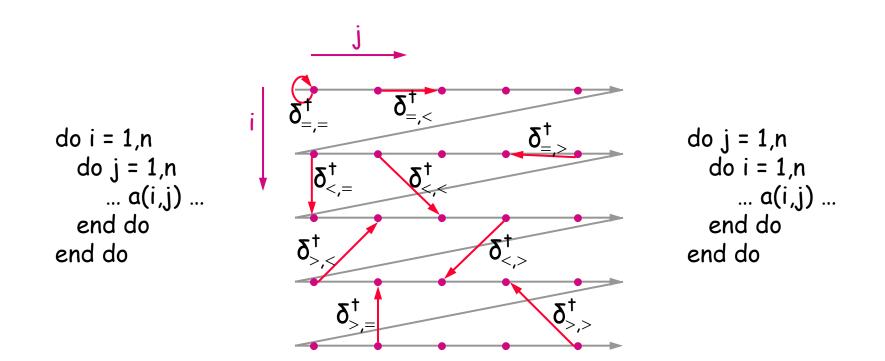
• Loop interchange can improve the granularity of parallelism!

 $\delta^{\dagger}_{=,<}$ 

.



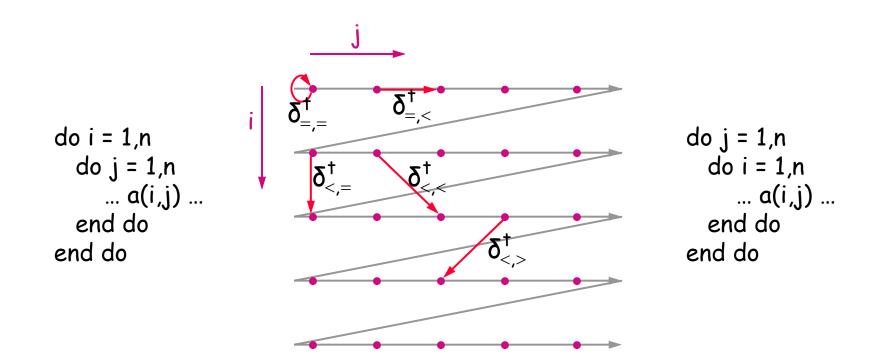
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• When is loop interchange legal?

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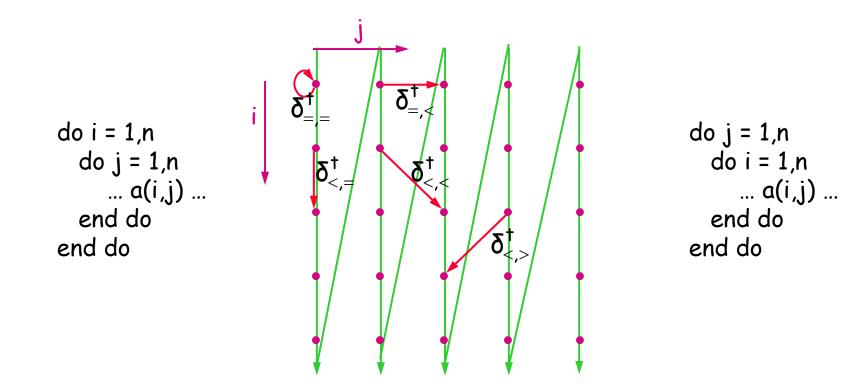
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• When is loop interchange legal?

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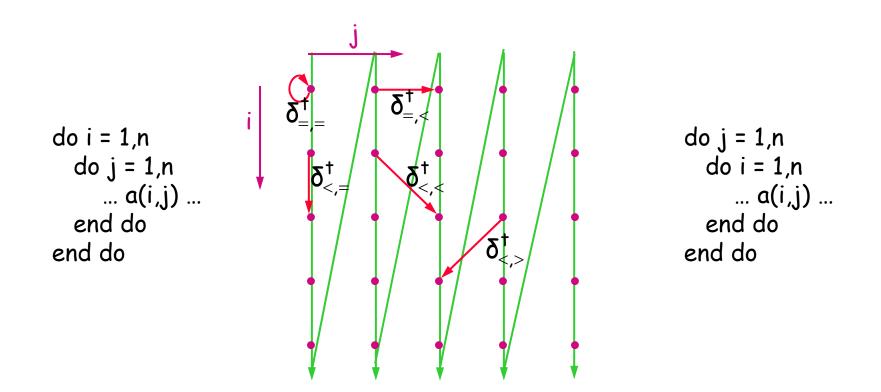


• When is loop interchange legal?

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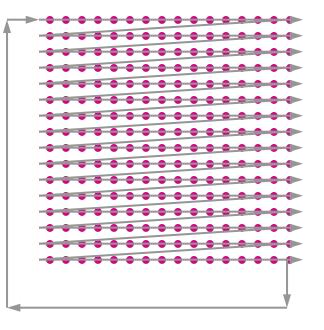
• When is loop interchange legal? when the "interchanged" dependences remain lexiographically positive!

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Exploits temporal locality in a loop nest.

```
do t = 1,T
do i = 1,n
do j = 1,n
... a(i,j) ...
end do
end do
end do
end do
```

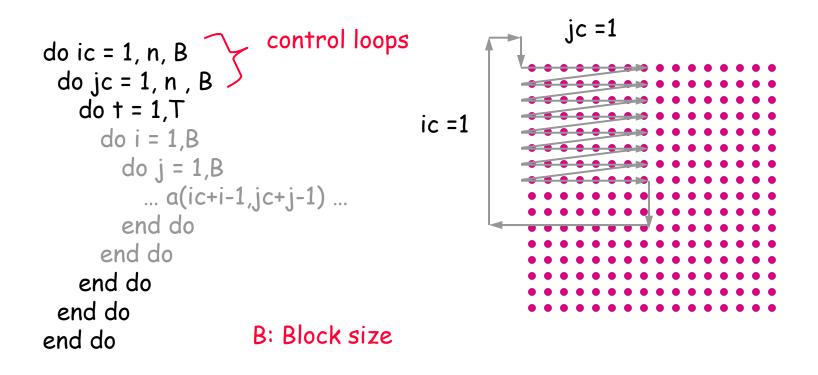


Exploits temporal locality in a loop nest.

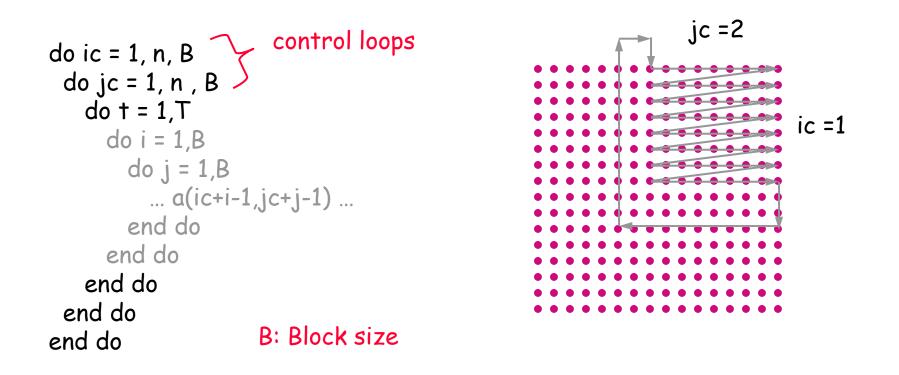
do ic = 1, n, B do jc = 1, n, B do t = 1,T do i = 1,B do j = 1,B ... a(ic+i-1,jc+j-1) ... end do end do end do end do B: Block size

| • | • | • | • | • | • | • | • | • | • | • | • | • | • | • | • |
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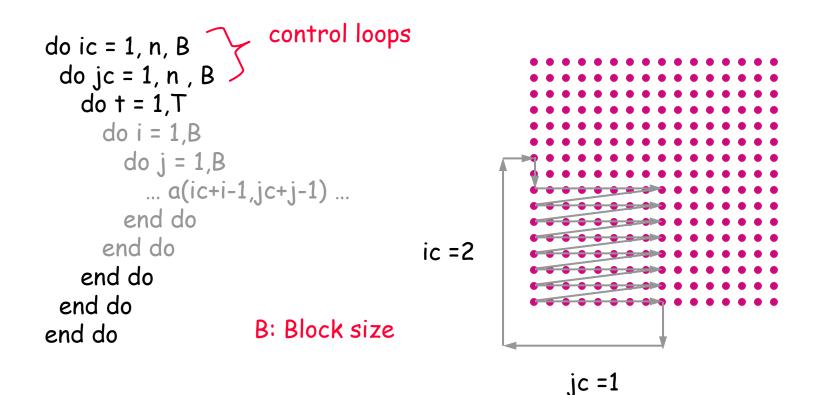
Exploits temporal locality in a loop nest.



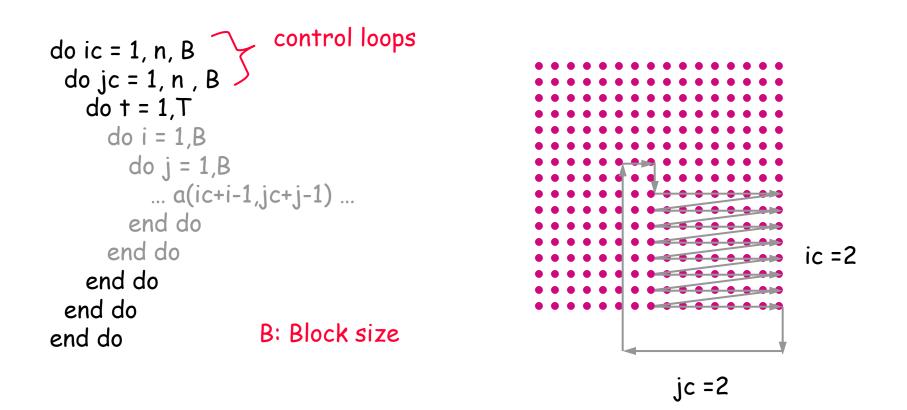
Exploits temporal locality in a loop nest.



Exploits temporal locality in a loop nest.



Exploits temporal locality in a loop nest.



# Loop Blocking (Tiling)

do t = 1,T do i = 1,n do j = 1,n ... a(i,j) ... end do end do end do

- do t = 1,T do ic = 1, n, B do i = 1,B do jc = 1, n, B do j = 1,B ... a(ic+i-1,jc+j-1) ... end do end do end do
- do ic = 1, n, B do jc = 1, n, B do t = 1,T do i = 1,B do j = 1,B ... a(ic+i-1,jc+j-1) ... end do end do end do end do end do end do

• When is loop blocking legal?