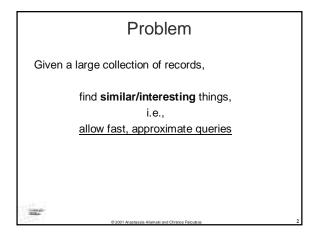
## **Indexing with B-trees**

Anastassia Ailamaki http://www.cs.cmu.edu/~natassa

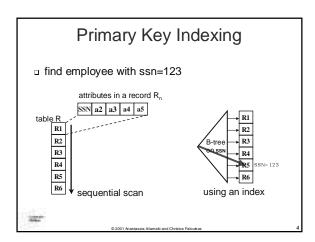


## Indexing

- primary key indexing
- □ B-trees and variants
  - □ (static) hashing
  - extendible hashing
- secondary key indexing
- spatial access methods
- □ text
- □ ...

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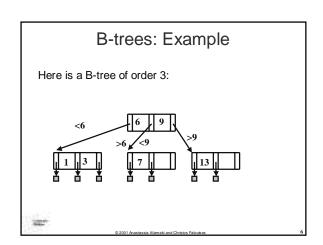


## B-trees

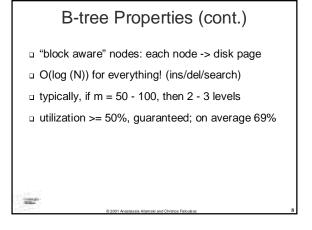
- Most successful family of index schemes
  - □ B-trees
  - □ B+-trees
  - □ B\*-trees
- Can be used for
  - □ primary/secondary, or
  - □ clustering/non-clustering index.
- □ Balanced "n-way" search trees

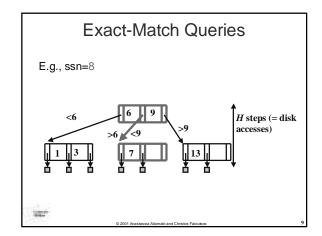
No.

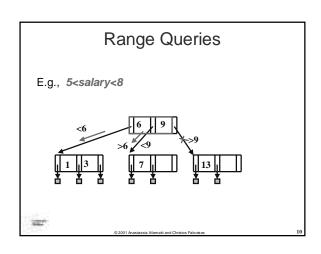
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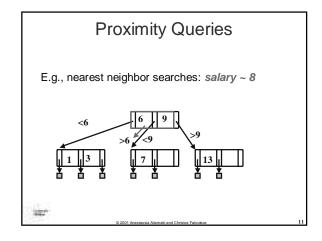


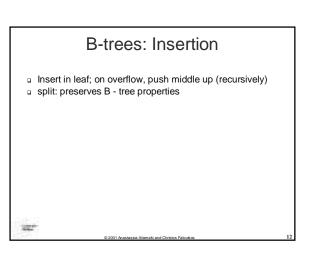
## B-tree Properties In a B-tree of order n: key order preserved at most n pointers at least n/2 pointers (except root) all leaves at the same level if number of pointers is k, node has exactly k-1 keys (leaves are empty) p1 pn pn

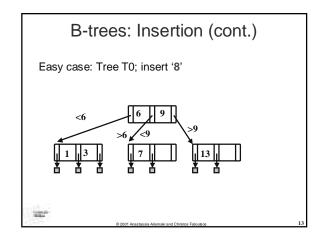


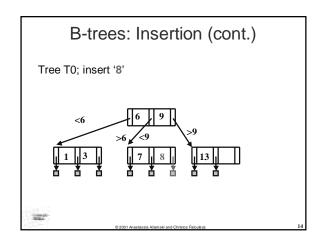


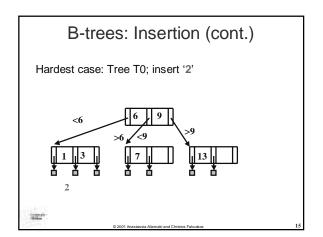


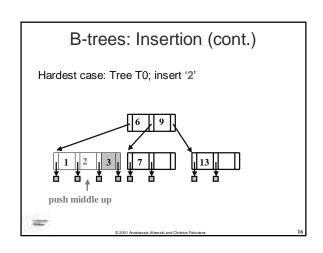


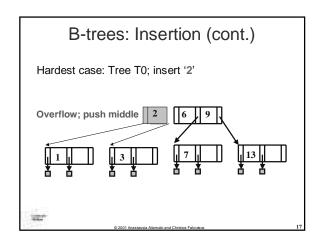


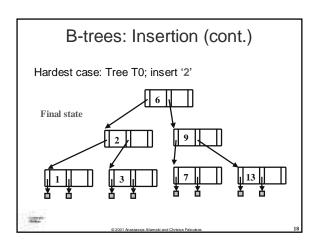












## B-trees - insertion

- □ Q: What if there are two middles? (eg, order 4)
- □ A: either one is fine

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## B-trees: Insertion Sketch

## Algorithm:

- 1. insert in leaf
- 2. on overflow:

push middle up (recursively – 'propagate split')

- □ Split preserves all B tree properties (!!)
- Notice how it grows:

height increases when root overflows & splits

Automatic, incremental re-organization

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## Algorithm: Insertion of Key 'K'

```
find the correct leaf node 'L';
```

```
if ( 'L' overflows ) {
```

split 'L' by pushing middle key up to parent 'P';

if ('P' overflows) {

repeat the split recursively;

) olco (

add key 'K' in node 'L'; // maintain key order in 'L'

}

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## B-trees: Deletion

Rough outline of algorithm:

- Delete key;
- on underflow, may need to merge

In practice, some implementors just allow underflows to happen...

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## B-trees: Deletion Cases

## □ <u>Case 1</u>

delete a key at a leaf - no underflow

### □ Case 2

 $\ \, \text{delete non-leaf key} - \text{no underflow}$ 

## □ Case 3

delete leaf-key; underflow, and 'rich sibling'

## □ Case 4

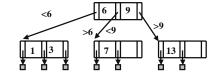
delete leaf-key; underflow, and 'poor sibling'

### 1

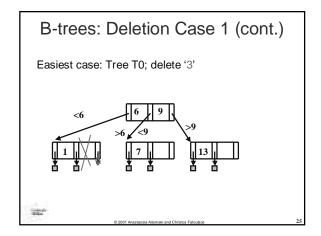
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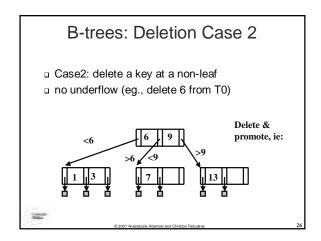
## B-trees: Deletion Case 1

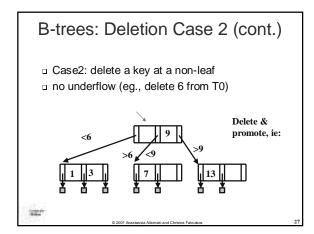
- □ Case 1: delete a key at a leaf
- □ Easiest case: no underflow (delete 3 from T0)

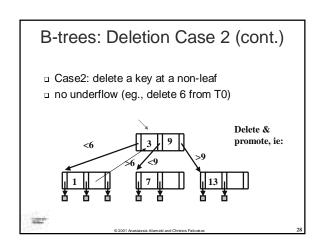


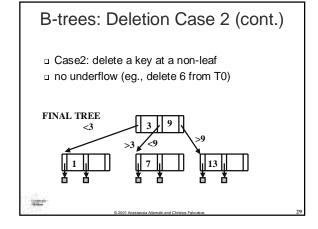
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B-trees: Deletion Case 2 (cont.)

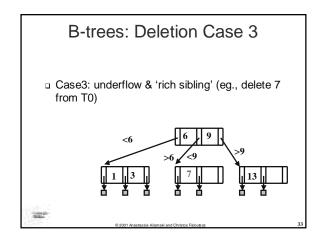
Case2: delete a key at a non-leaf – no underflow (eg., delete 6 from T0)

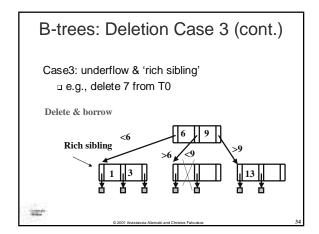
Q: How to promote?

A: pick the largest key from the left sub-tree (or the smallest from the right sub-tree)

Observation: every deletion eventually becomes a deletion of a leaf key

## B-trees: Deletion Cases (cont.) □ Case1: delete a key at a leaf – no underflow □ Case2: delete non-leaf key – no underflow □ Case3: delete leaf-key; underflow, and 'rich sibling' □ Case4: delete leaf-key; underflow, and 'poor sibling'



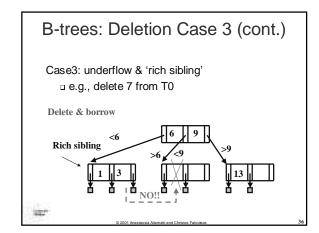


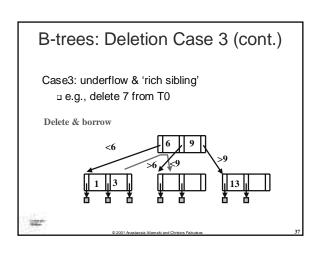
B-trees: Deletion Case 3 (cont.)

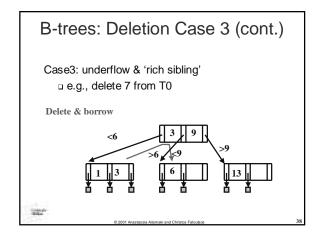
Case3: underflow & 'rich sibling'

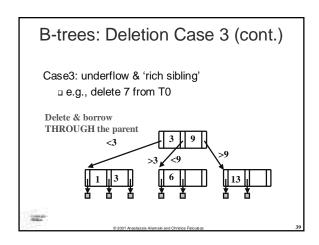
'rich' = can give a key, without underflowing

'borrowing' a key: THROUGH the PARENT!

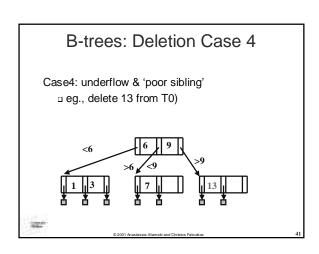


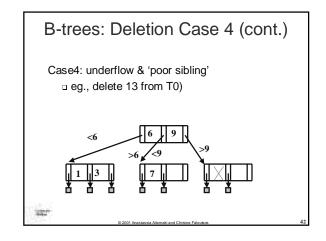


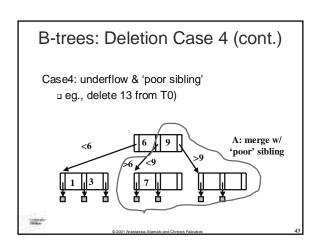




# B-trees: Deletion Cases (cont.) Case1: delete a key at a leaf – no underflow Case2: delete non-leaf key – no underflow Case3: delete leaf-key; underflow, and 'rich sibling' Case4: delete leaf-key; underflow, and 'poor sibling'

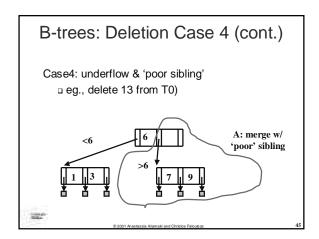




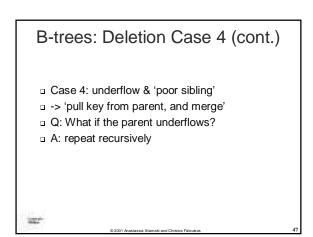


## B-trees: Deletion Case 4 (cont.) Case4: underflow & 'poor sibling' □ eg., delete 13 from T0) Merge, by pulling a key from the parent exact reversal from insertion: 'split and push

up', vs. 'merge and pull down'

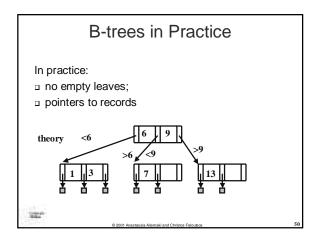


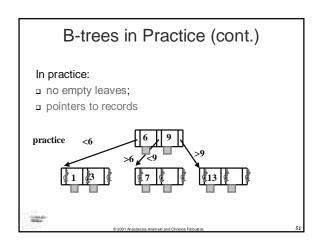
## B-trees: Deletion Case 4 (cont.) Case4: underflow & 'poor sibling' □ eg., delete 13 from T0) FINAL TREE

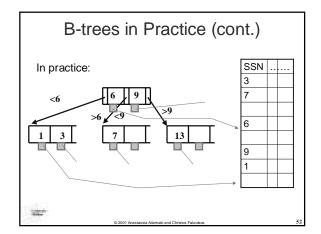


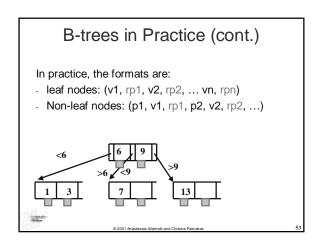
```
Algorithm: Deletion of Key 'K'
locate key 'K', in node 'N'
 if( 'N' is a non-leaf node) {
    delete 'K' from 'N';
   find the immediately largest key 'K1';
     /* which is guaranteed to be on a leaf node 'L' */
   copy 'K1' in the old position of 'K';
    invoke DELETION on 'K1' from the leaf node 'L';
  else {
/* 'N' is a leaf node */
                                         ...next slide...
```

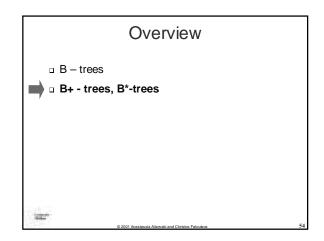
```
Deletion of Key 'K' (cont.)
if( 'N' underflows ){
     let 'N1' be the sibling of 'N';
      if( 'N1' is "rich"){ /* ie., N1 can lend us a key */
       borrow a key from 'N1' THROUGH parent node;
     } else { /* N1 is 1 key away from underflowing */
           MERGE: pull key from parent 'P', merge it
           with keys of 'N' and 'N1' into new node;
       if( 'P' underflows) { repeat recursively }
```

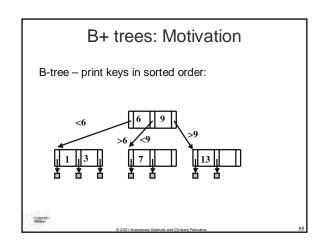


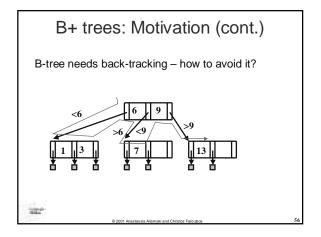


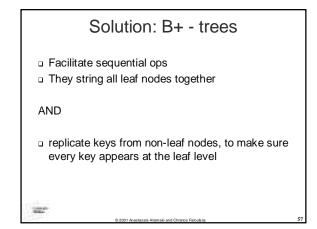


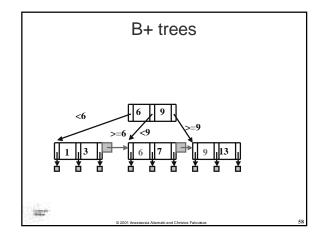


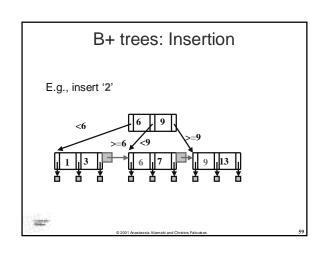


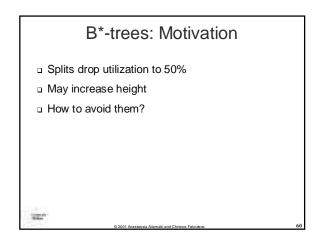


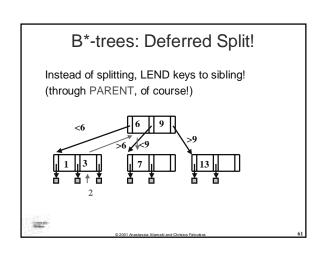


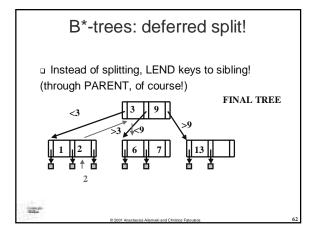












## B\*-trees: Advantages

- □ Tree becomes
  - □ Shorter,
  - More packed,
  - □ Faster
- Rare case: improve together
  - □ space utilization
  - □ speed
- BUT: What if sibling has no room for 'lending'?

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## B\*-trees: deferred split!

- BUT: What if sibling has no room for 'lending'?
- 2-to-3 split
  - 1. get the keys from the sibling
  - 2. pool them with ours (and a key from the parent)
  - split in 3
- Details: too messy (and even worse for deletion)

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## Conclusions

- Main ideas: recursive; block-aware; on overflow
   split; defer splits
- All B-tree variants have excellent, O(logN) worst-case performance for ins/del/search
- It's the prevailing indexing method

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## Performance Aspects of B-trees

Two parameters matter:

Height H (maximum search path)

$$H = 1 + \lceil \log_{\mathsf{F}^*}(\lceil N/C^* \rceil) \rceil$$

- □ N is the number of tuples
- $\hfill \square$   $C^{\star}$  is the average number of entries in a leaf node, and
- $\hfill \hfill \hfill$
- Size S (number of pages tree occupies)

$$S = \sum_{i} (F^*)^{i-1}, 1 \le i < H$$

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## Reducing the Number of Leafs

- □ Increase page size (hard)
- □ Shorten data length (values, tuples, pointers)
- Is it worthwhile to change the tuples to TIDs?
- □ No extra page accesses!

From Gray&Reuter:  $1.1 \le log_{F^*}X$  must hold i.e., average fan-out really small or tuples > 1K

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## Increasing the Fanout

- Compression
  - □ Prefix store differences (suffixes)
  - □ Suffix store prefixes
- □ Prefix compression: sequential scan
  - □ "anchor" keys

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## Lehman and Yao - CC on B-trees

- □ "safe" node: node with <2k entries
- unsafe" node: node with =2k entries
- □ Simple CC won't do. Why?

L.

## 

## Previous B-tree CC algorithms

- □ Samadi 1976
  - lock the whole subtree of affected node
- □ Bayer & Schkolnick 1977
  - parameters on degree/type of consistency required
  - u writer-exclusion locks (readers may proceed) upper
  - exclusive locks on modified nodes
- □ Miller & Snyder 1978
  - □ pioneer and follower locks
  - locked region moves up the tree
  - no modifications

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## Blink-tree

- □ Node + P2k+1 pointer to next node at the same level of tree
- □ Rightmost node's B-link is NULL
- □ IDEA:
- □ Splitting

is implemented as



□ legal to have "left twin" and no parent

## Advantages

- Allows for "temporary fix" until all pointers are added correctly
- Link pointers should be used infrequently
   because splitting a node is a "special case"
- □ "Level traversal" comes for free as a side effect

## Algorithms

- □ Search
  - No locks needed for reads
  - Just move right as well as down
- Insertions
  - Well-ordered locks
  - Use stack to remember ancestors
  - Split while preserving links
- Deletions
  - No underflows, no merging



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