

# **Visualization and Nonphotorealistic Rendering**

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The header features a horizontal bar with a central olive-green segment containing the word 'Outline'. To the left of this segment are three vertical bars in orange, yellow-orange, and red. To the right are three vertical bars in light green, orange, and light green.

# Outline

- Visualization
- Non-photorealistic Rendering
- Cutaway Illustration
- Contour Drawing
- Good photographs.
- Map Drawing

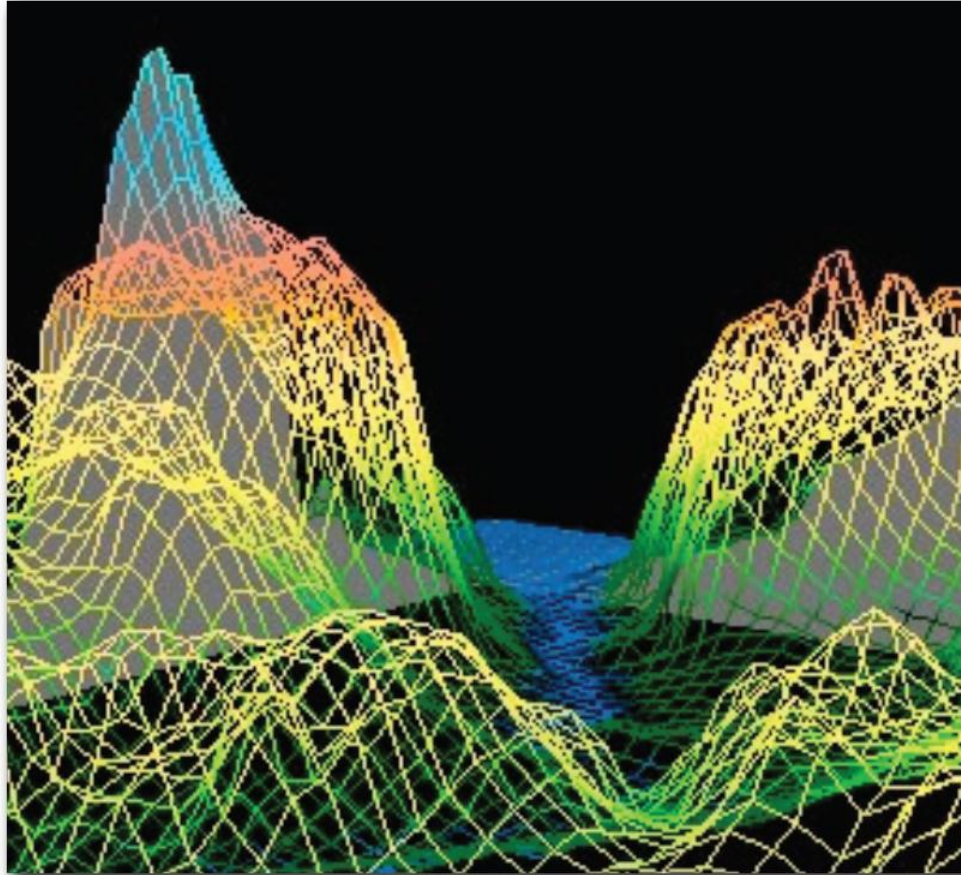
# Visualization



<http://medvis.vrvis.at/fileadmin/hvr/images/headlarge.jpg>

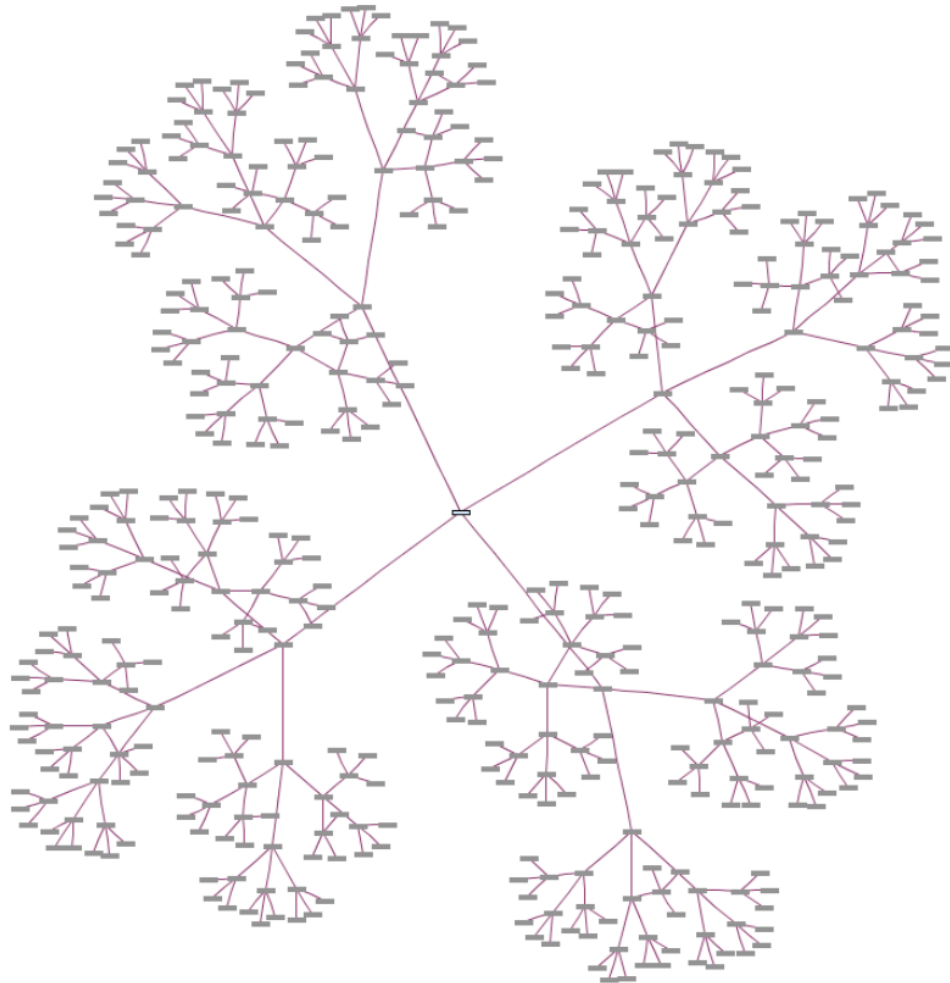
- **Goal: Use computer graphics to understand data.**
- **For virtual every data type there is a corresponding visualization.**
- **The importance of graphics!**

# Numerical Data

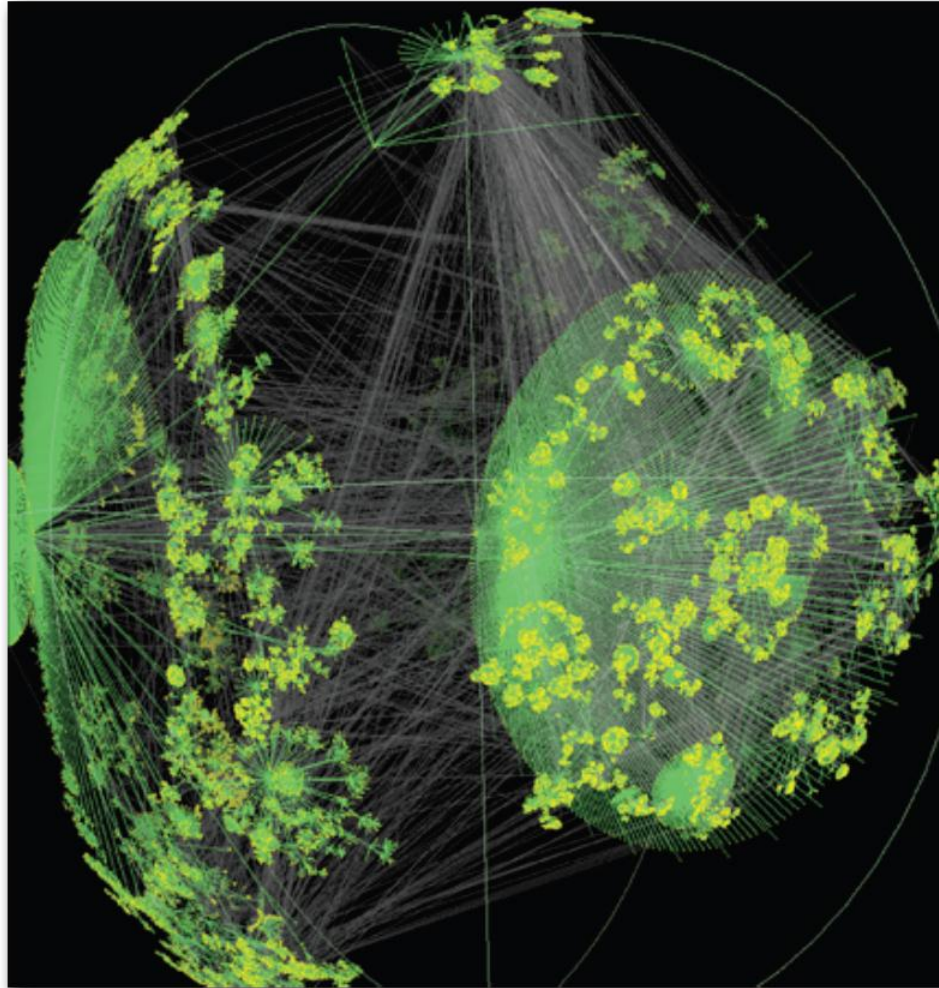


[http://www.manifold.net/news/fly\\_through.jpg](http://www.manifold.net/news/fly_through.jpg)

# Graphs



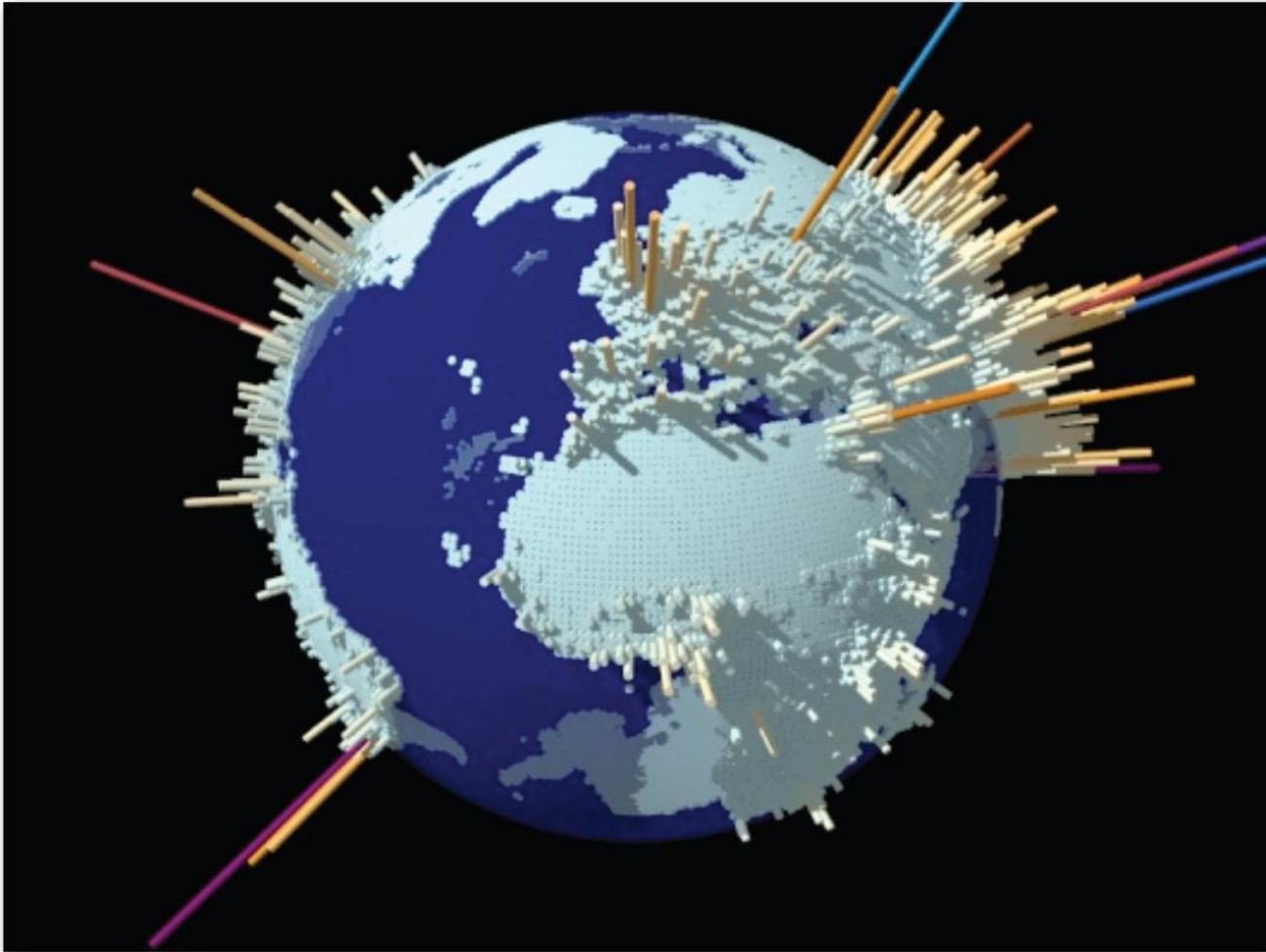
# Graphs



<http://www.designinginteractions.com/chapters/7>

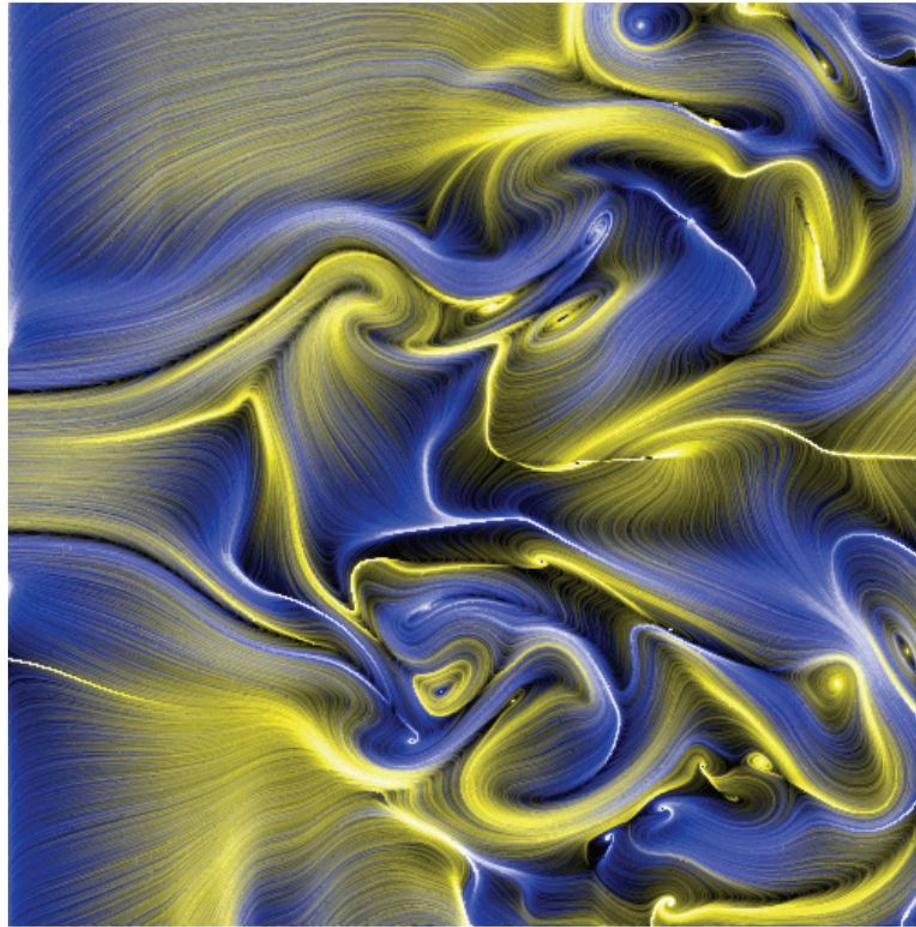


# Geographic Data



[http://flowingdata.com/wp-content/plugins/yet-another-photoblog/cache/g\\_econ.6zhzwniskpgcwwgs00okoco4s.7dm680981og04ocskgcsckco4.th.jpeg](http://flowingdata.com/wp-content/plugins/yet-another-photoblog/cache/g_econ.6zhzwniskpgcwwgs00okoco4s.7dm680981og04ocskgcsckco4.th.jpeg)

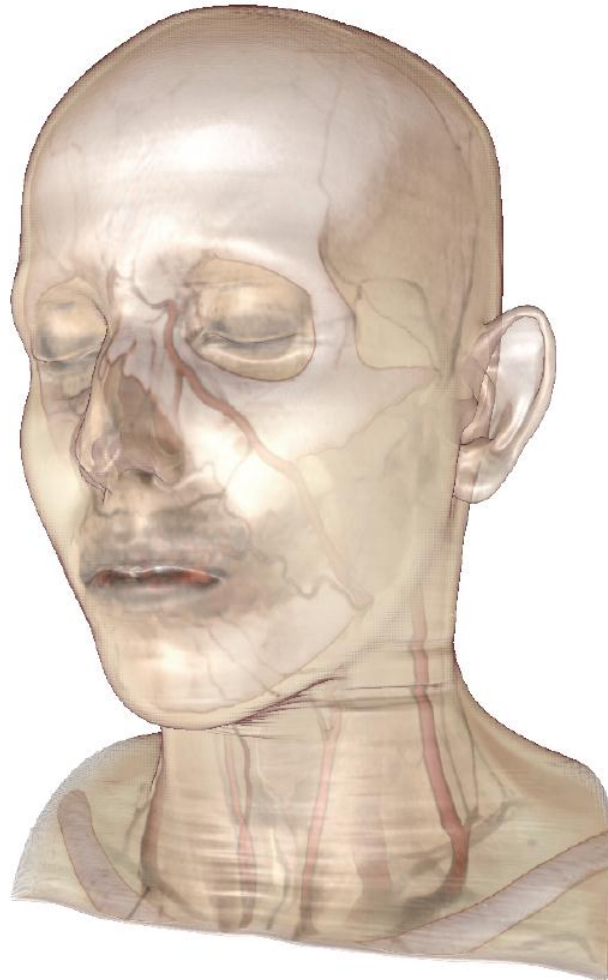
# Flow Visualization



<http://www.faculty.iu-bremen.de/linsen/publications/ParkYuHotzKreylosLinsenHamann06.jpg>



# 3D Volume Data



<http://medvis.vrvis.at/fileadmin/hvr/images/headlarge.jpg>

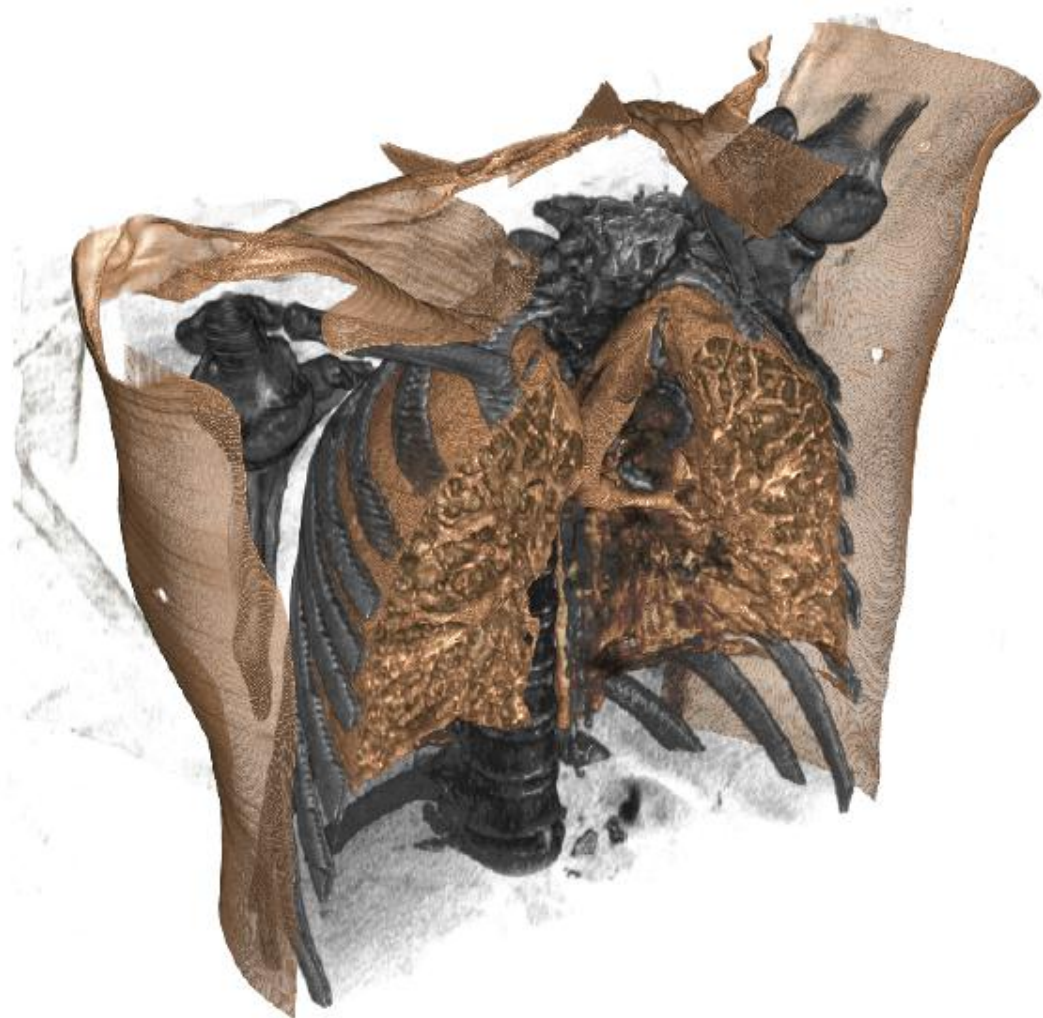
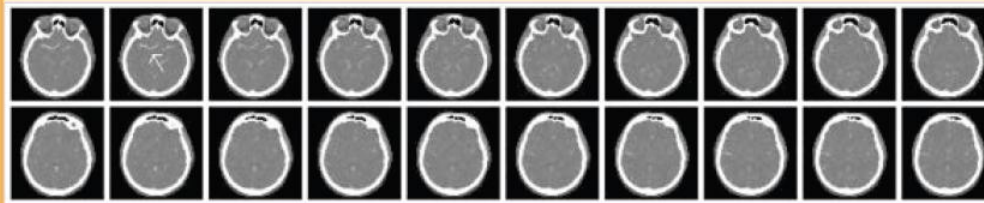


Figure 2.4: An example of a visualization of a single respiratory phase of a 4DCT visualization showing lung, bone, and skin.

# Volume Rendering

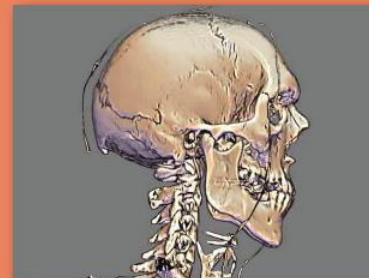
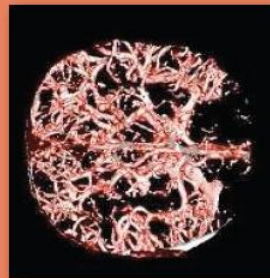
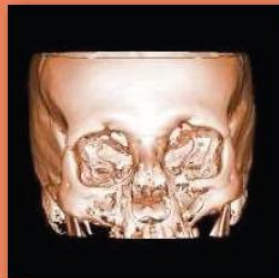
- Visualize Large dataset for scientific / medical application.
- Generally do not start with a 3D model.

INPUT



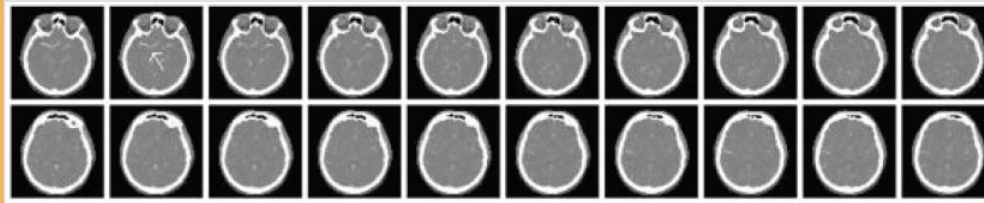
CT Scan - White means higher radiodensity.

OUTPUT



# Large Datasets

INPUT



CT Scan - White means higher radiodensity.

OUTPUT



- CT or MRI:

- e.g.  $512 \times 512 \times 200 \approx 50\text{MB}$

- Visible Human:

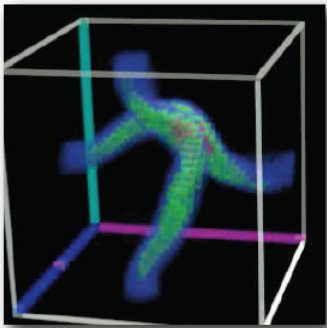
- $512 \times 512 \times 1734 \approx 433\text{MB}$



# Two Options



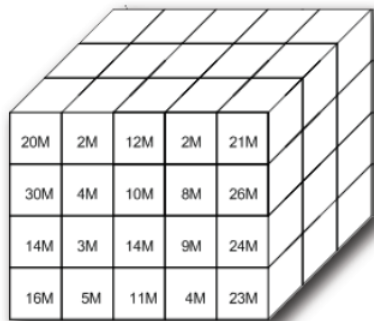
- **Surface Rendering**



- **Volume Rendering**



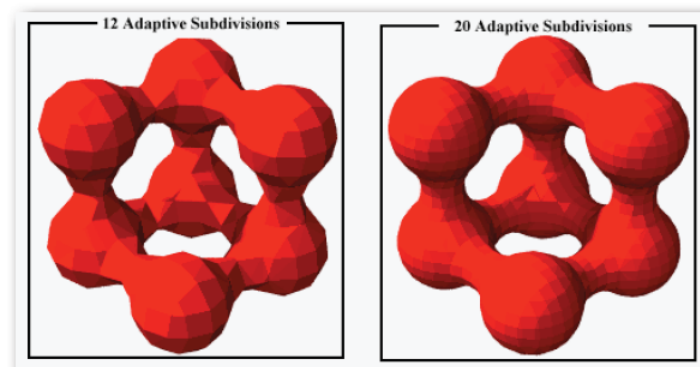
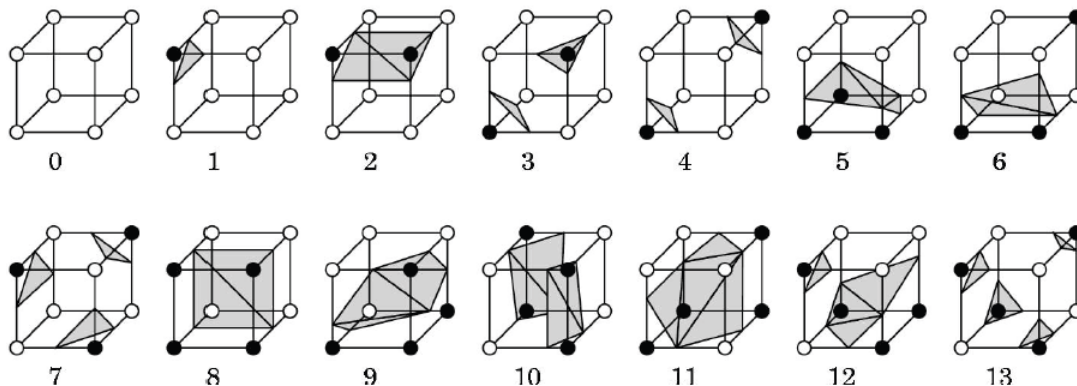
# Surface Rendering



20M	2M	12M	2M	21M
30M	4M	10M	8M	26M
14M	3M	14M	9M	24M
16M	5M	11M	4M	23M

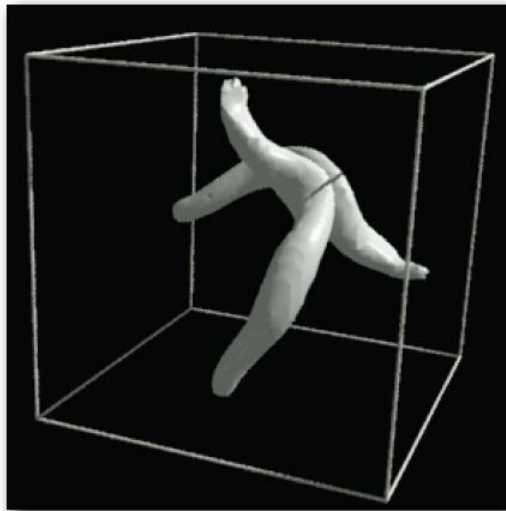
- Threshold volume data.

- Then run our favorite algorithm....
- Hint: rhymes with “starching dudes”

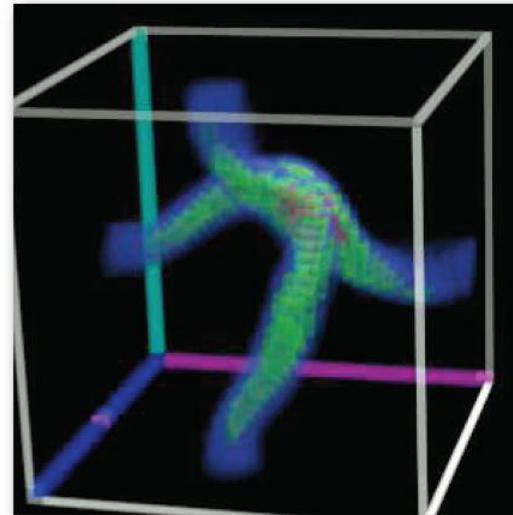


# Volume Rendering

- Some data better visualized as a volume, not a surface.
- **Idea:** Use voxels and transparency.



Raytraced  
Isosurface



Volume  
Rendering



# Outline

- Visualization
- **Non-photorealistic Rendering**
- Cutaway Illustration
- Contour Drawing
- Good photographs.
- Map Drawing

# Basic Idea

- Which best conveys “reality?”

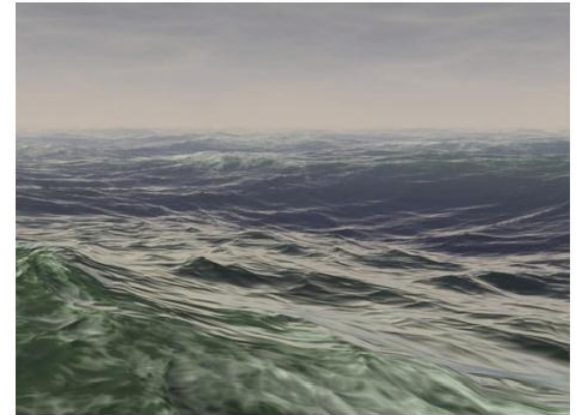


**Photograph.**



**Painting.**

A Rough Sea at a Jetty, 1650.  
Jacob van Ruysdael.



**Computer Graphics**

Duncan Brinsmead

source: Jos Stam. *Photography changes what we think “reality” looks like.*

# Reality



A Rough Sea at a Jetty, 1650. - Jacob van Ruysdael.

- This instance in time never happened!
- Perhaps a better match of “subjective reality.”
- Better illustration of “what was going on.”



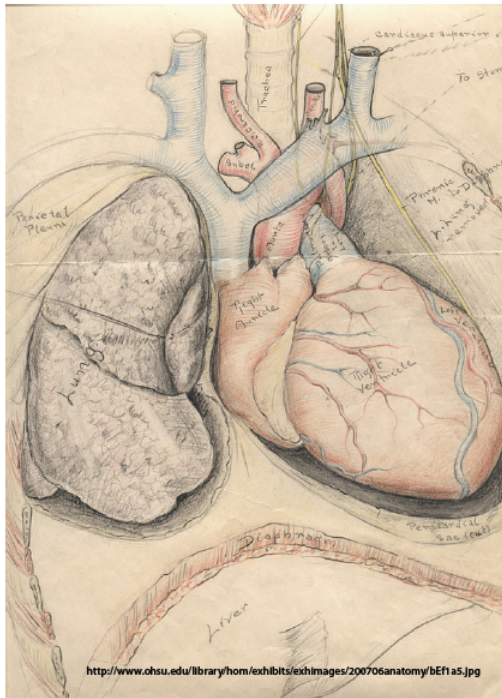
# NPR



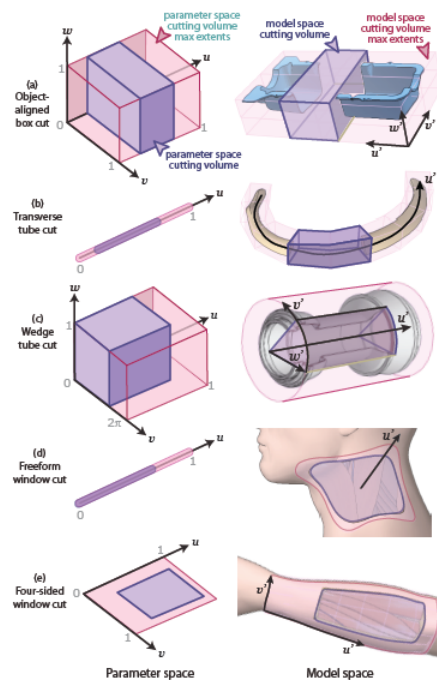
- Perhaps we can do better graphics...
  - By doing **non-photorealistic graphics!**
- ...of "subjective reality."  
...stration of "what was going on."

# NPR Pipeline

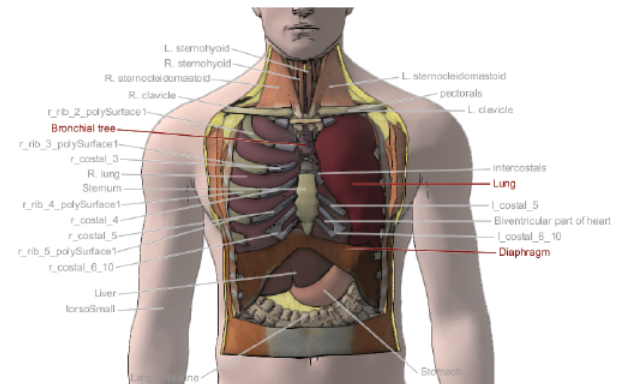
- NPR Research often follows this pipeline...



(1) Study Existing  
Rendering or  
Illustration  
Technique



(2) Extract General  
Aesthetic Rules



(b) Thorax

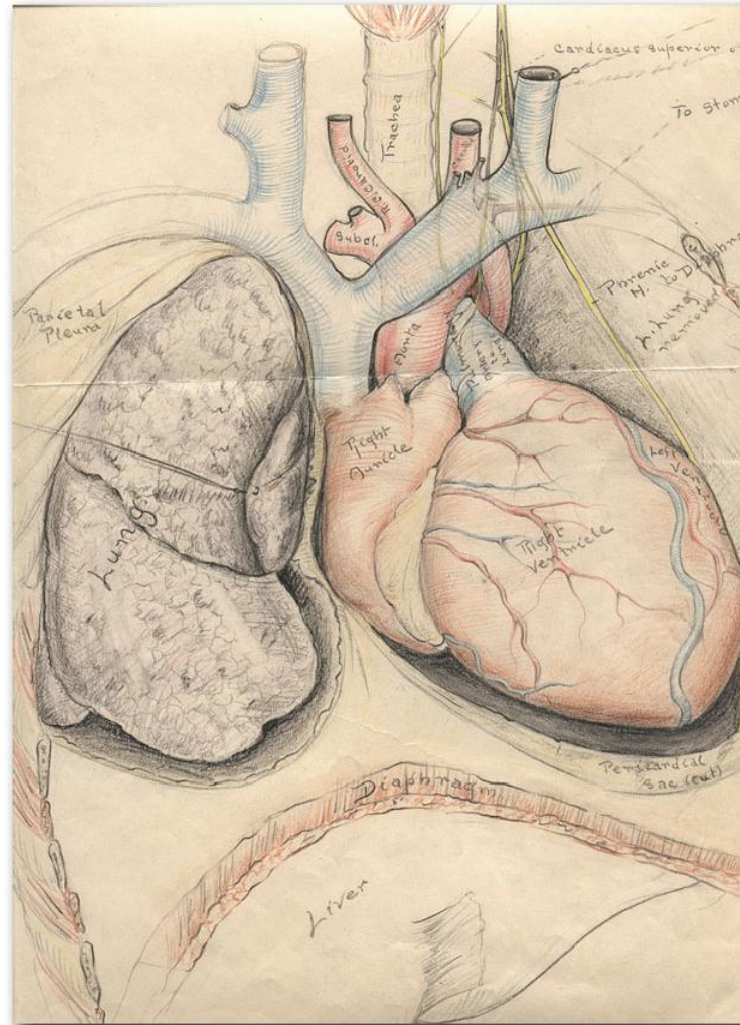
(3) "Algorithmicize"  
These Rules



# Outline

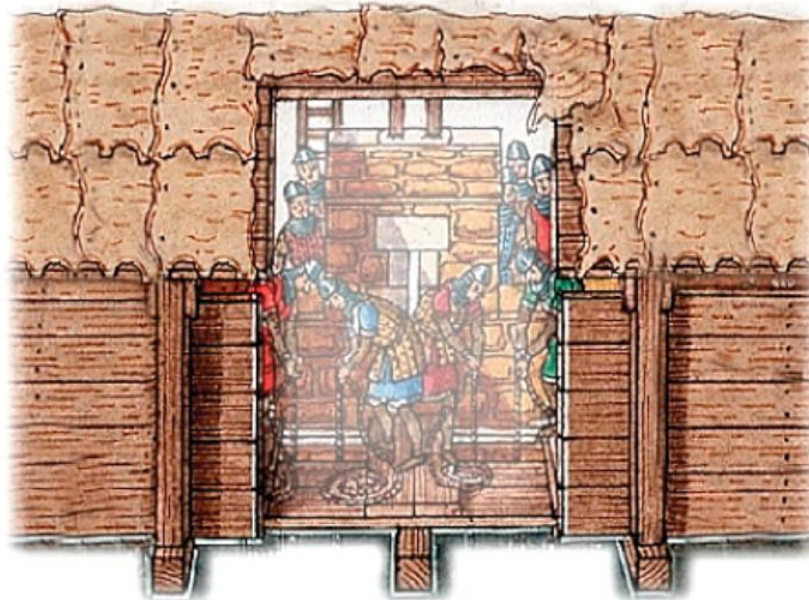
- Visualization
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- Good photographs.
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# Goal



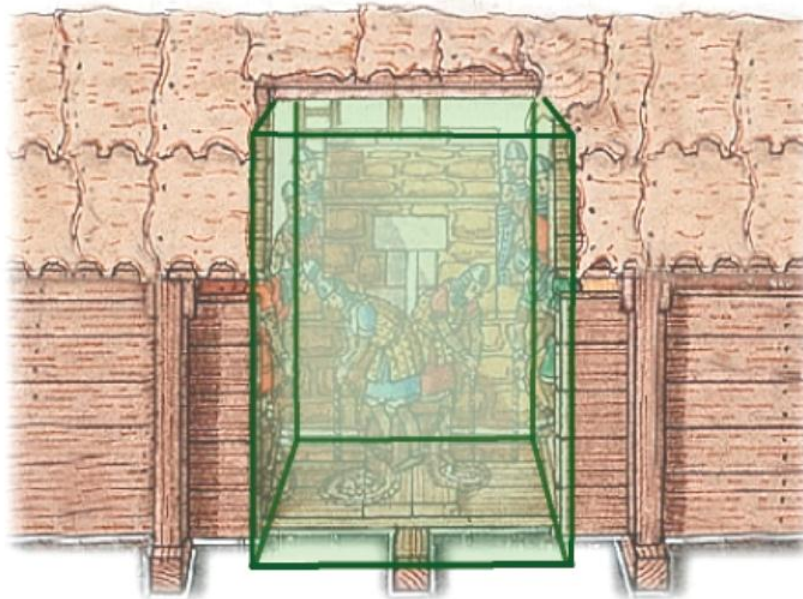


# Box Cut





# Box Cut



Object-aligned box cut

# Window Cut

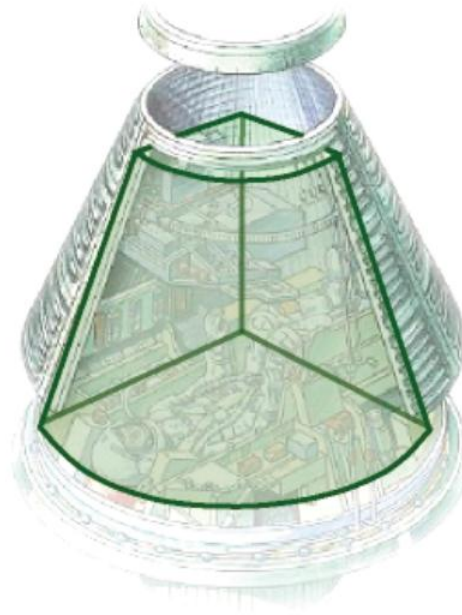


Window cut

# Wedge Cut

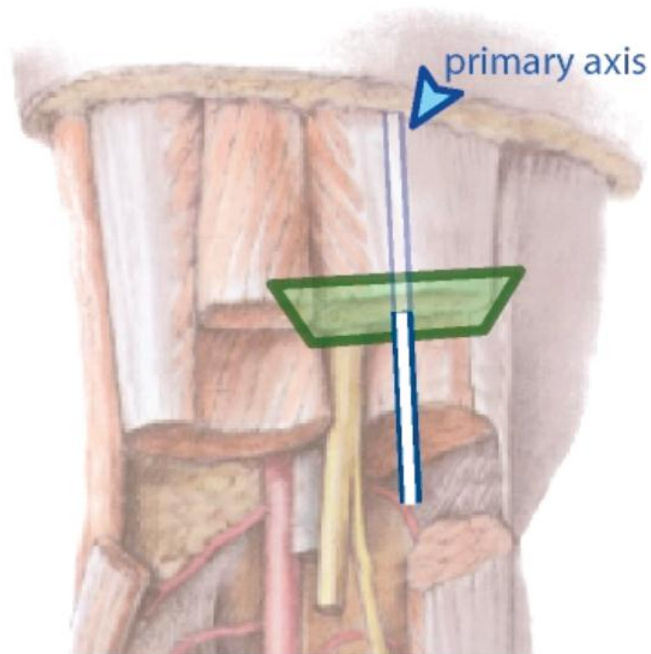


# Wedge Cut



Wedge cut

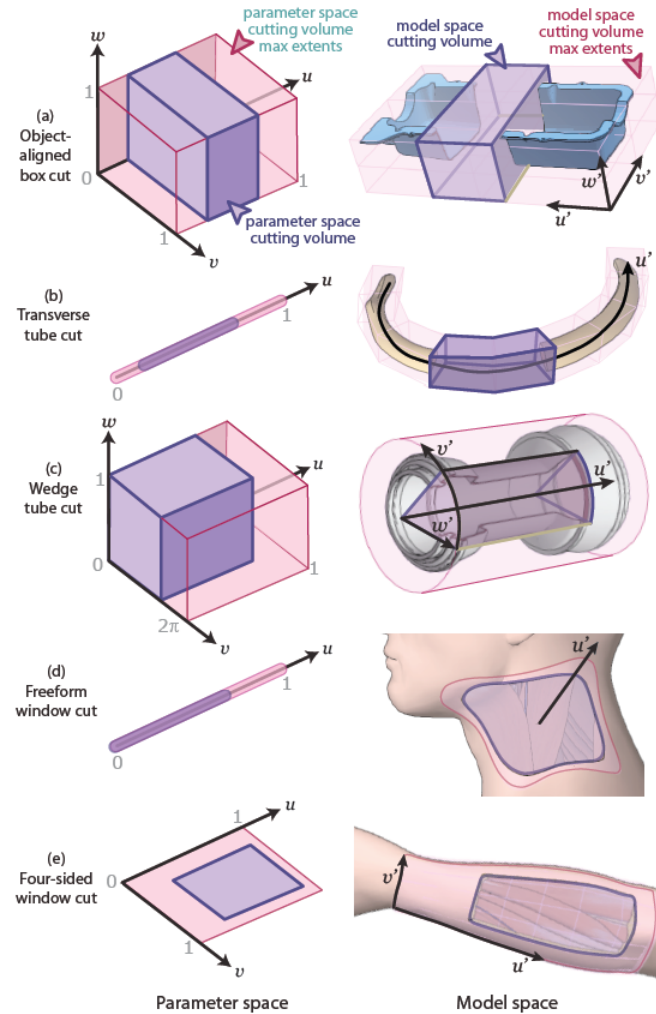
# Transverse Tube Cut



Transverse tube cut



# Cut Taxonomy





# Results

## Interactive Cutaway Illustrations of Complex 3D Models

Wilmot Li<sup>1</sup> Lincoln Ritter<sup>1</sup>

Maneesh Agrawala<sup>2</sup> Brian Curless<sup>1</sup> David Salesin<sup>1,3</sup>

<sup>1</sup>University of Washington   <sup>2</sup>University of California, Berkeley   <sup>3</sup>Adobe Systems

(Source: Li et al. InteractiveCutawayIllustrationsofComplex3DModels)



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- Good photographs.
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# Goal



[http://www.cs.princeton.edu/gfx/pubs/Cole\\_2008\\_WDP/index.php](http://www.cs.princeton.edu/gfx/pubs/Cole_2008_WDP/index.php)

# Contours



$$\mathbf{n}(\mathbf{p}) \cdot \mathbf{v}(\mathbf{p}) = 0$$

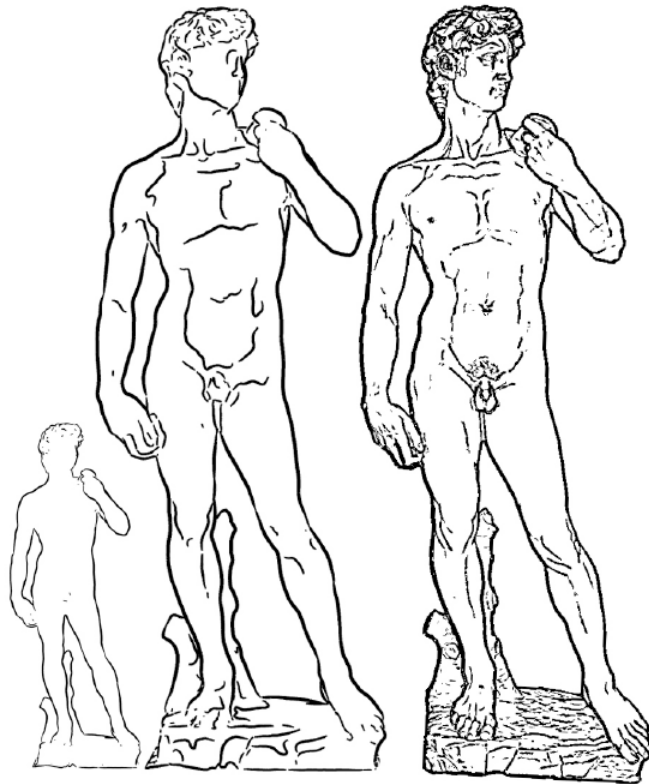


# Suggestive Contours



$$\min \mathbf{n}(\mathbf{p}) \cdot \mathbf{v}(\mathbf{p})$$

# Examples



Suggestive Contours for Conveying Shape

Doug DeCarlo<sup>1</sup>

Adam Finkelstein<sup>2</sup>

Szymon Rusinkiewicz<sup>2</sup>

Anthony Santella<sup>1</sup>

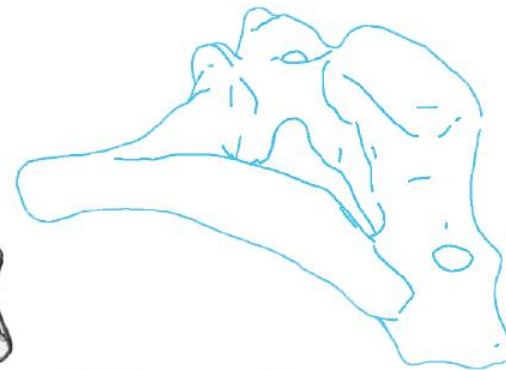
# More Examples



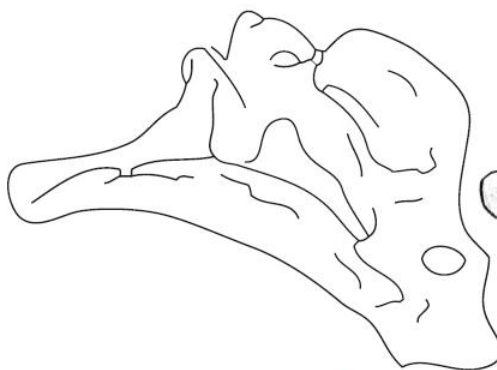
(a) Drawing likelihood



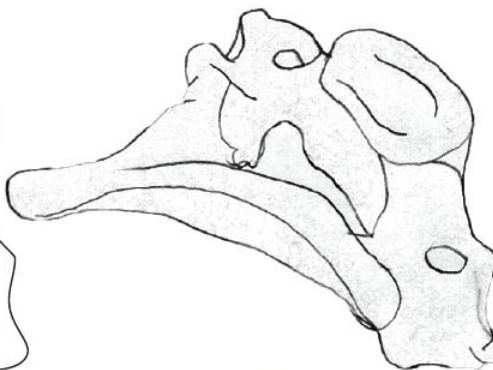
(b) User composite



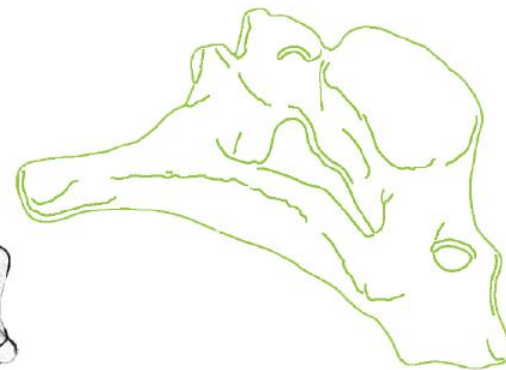
(c) Suggestive contours



(d) Extracted lines



(e) Sample drawing



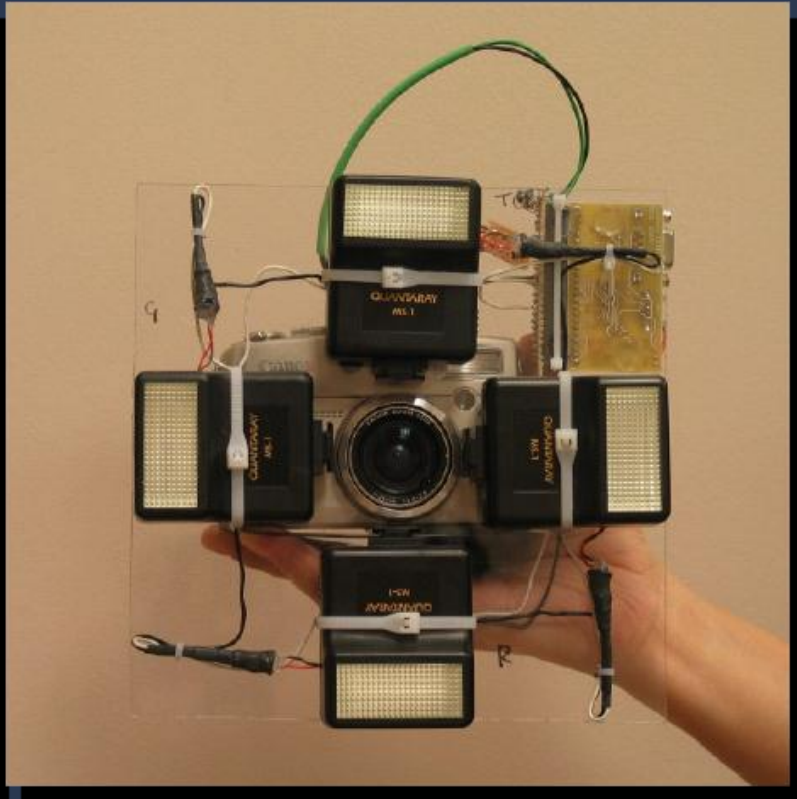
(f) Canny edges

Where Do People Draw Lines?

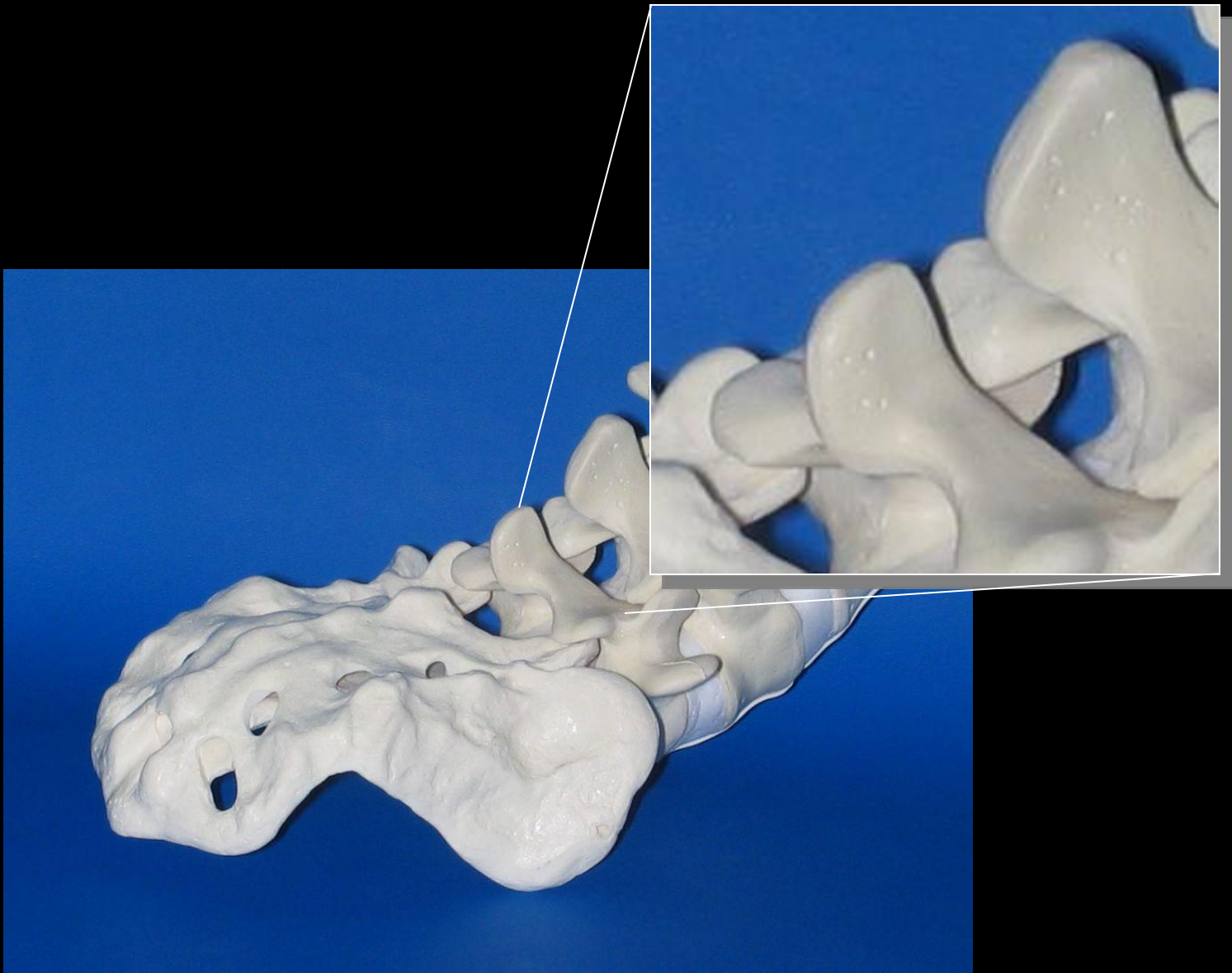
Forrester Cole, Aleksey Golovinskiy, Alex Limpaecher, Heather Stoddart Barros, Adam Finkelstein, Thomas Funkhouser, and Szymon Rusinkiewicz



# Depth Edge Camera



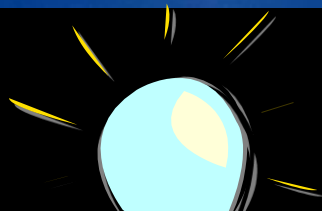














# Depth Discontinuities



Internal and external  
Shape boundaries, Occluding contour, Silhouettes





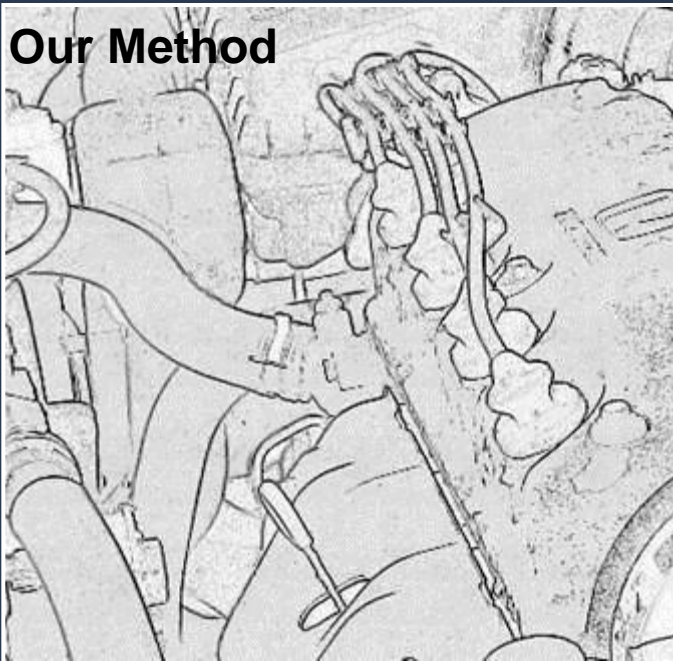
**Photo**



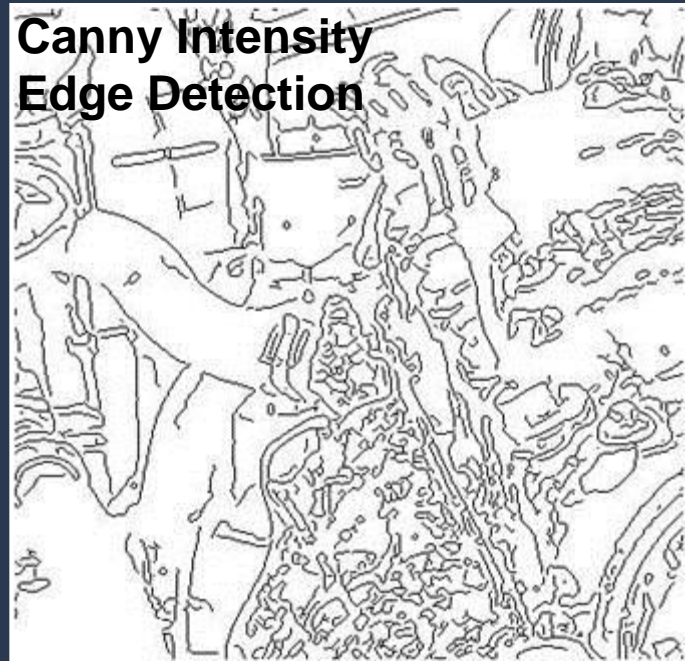
**Result**



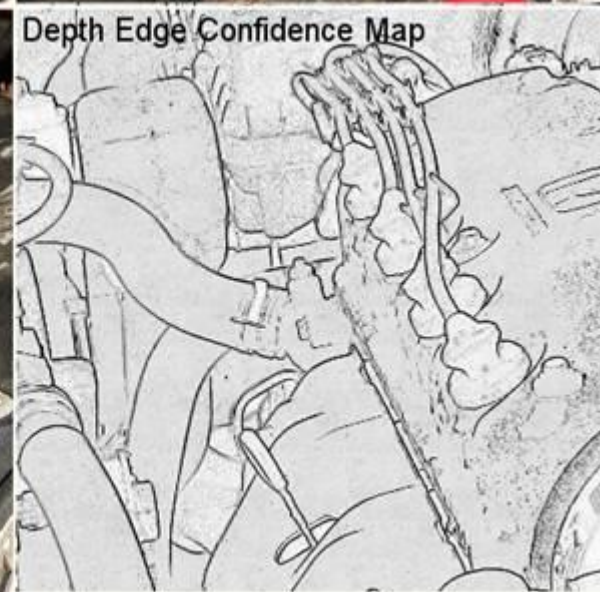
**Our Method**



**Canny Intensity  
Edge Detection**





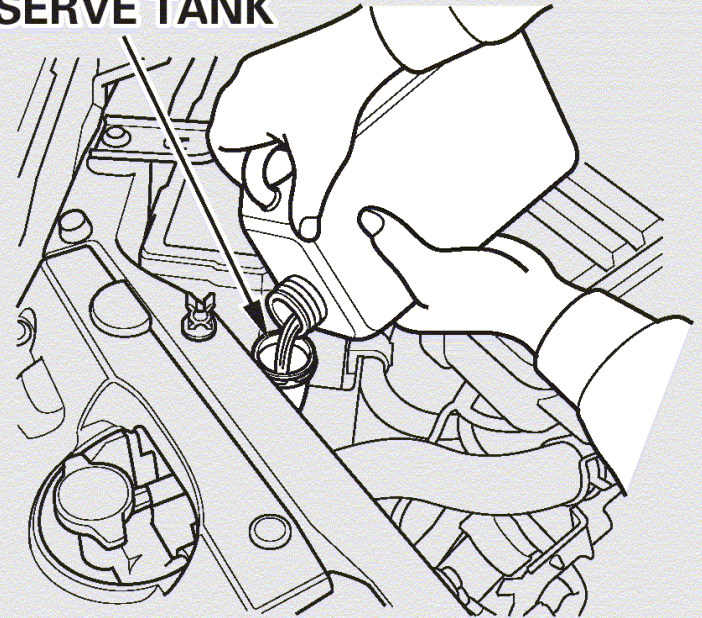






Shadows  
Clutter  
Many Colors

**RESERVE TANK**



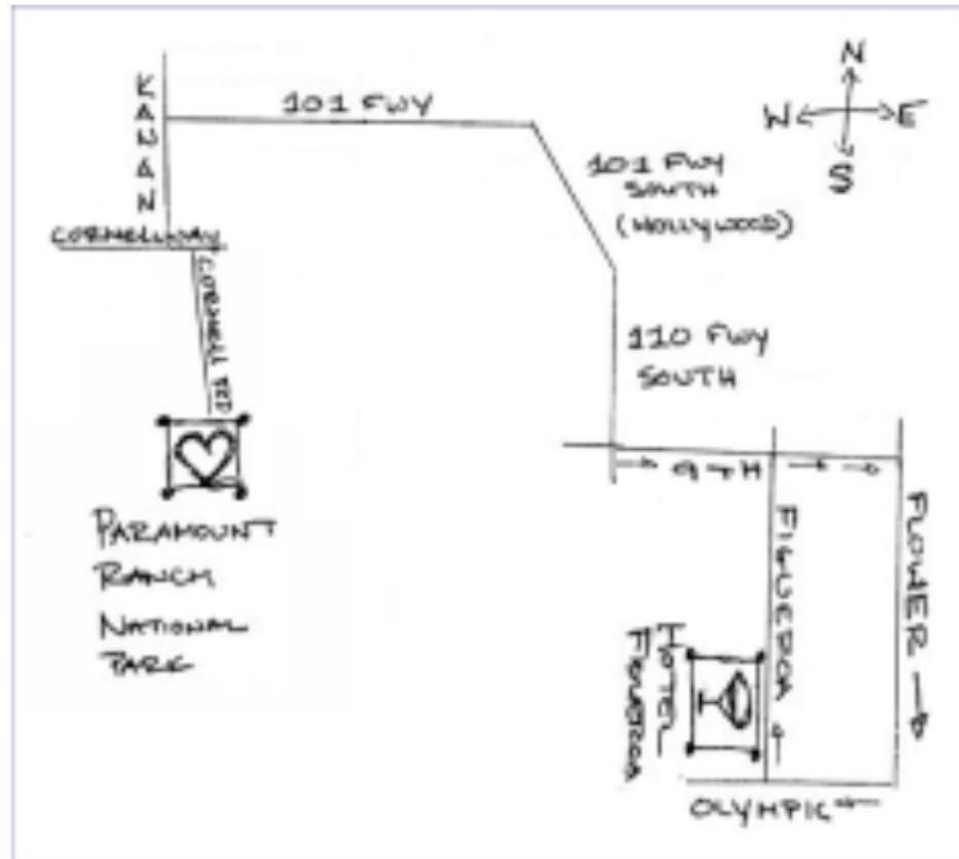
Highlight Shape Edges  
Mark moving parts  
Basic colors



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# Goal

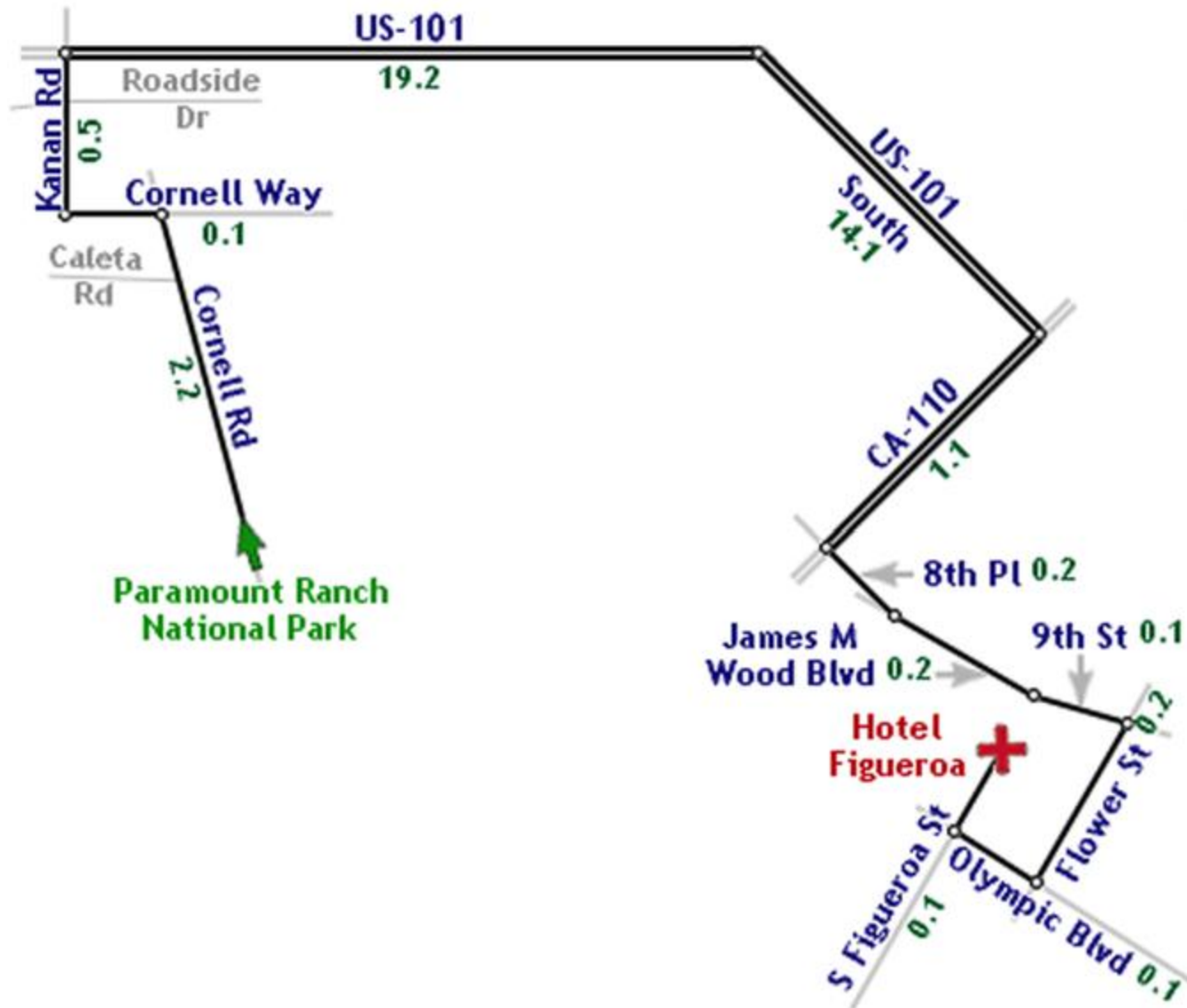




# Reality



# MapBlast / LineDrive



[Rendering effective route maps:..., Agrawala and Stolte]

# MapBlast / LineDrive

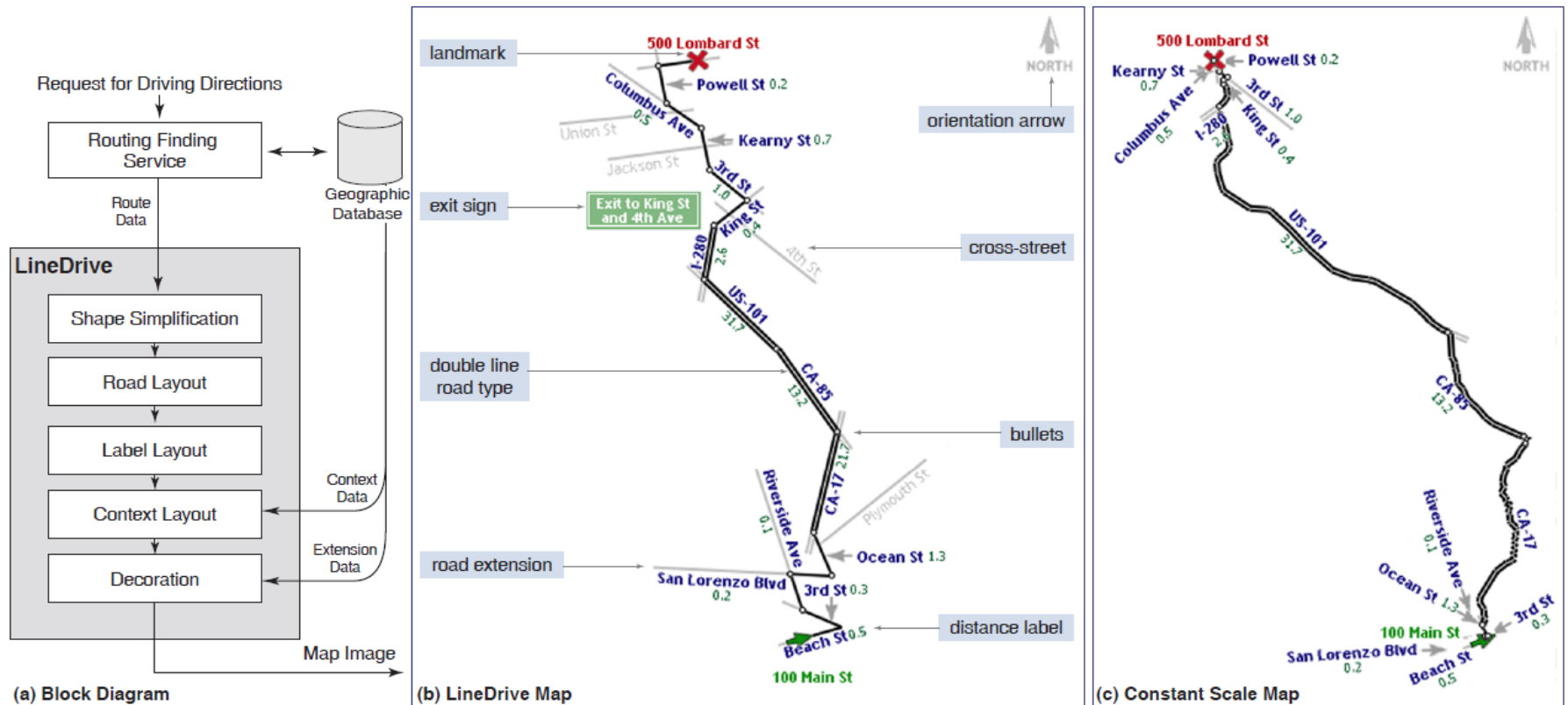
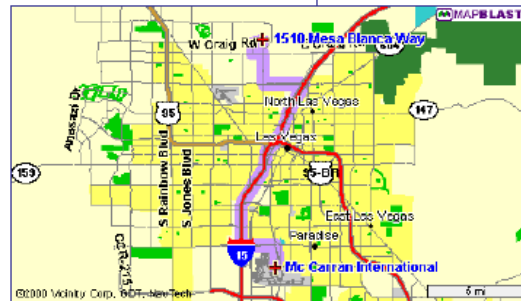
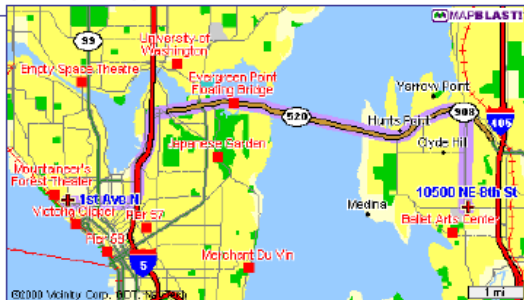
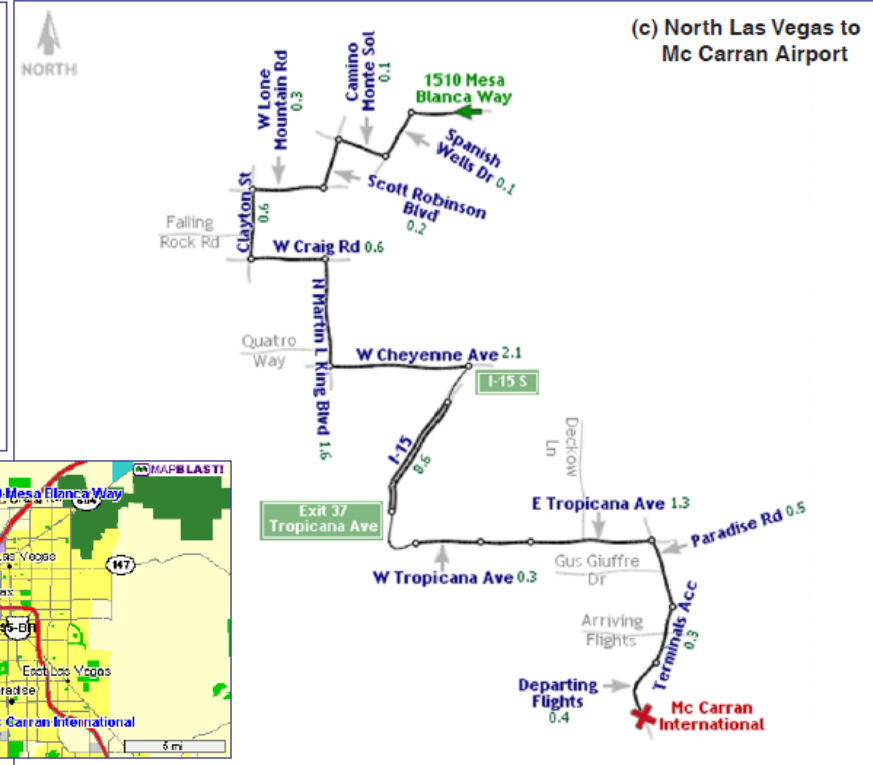
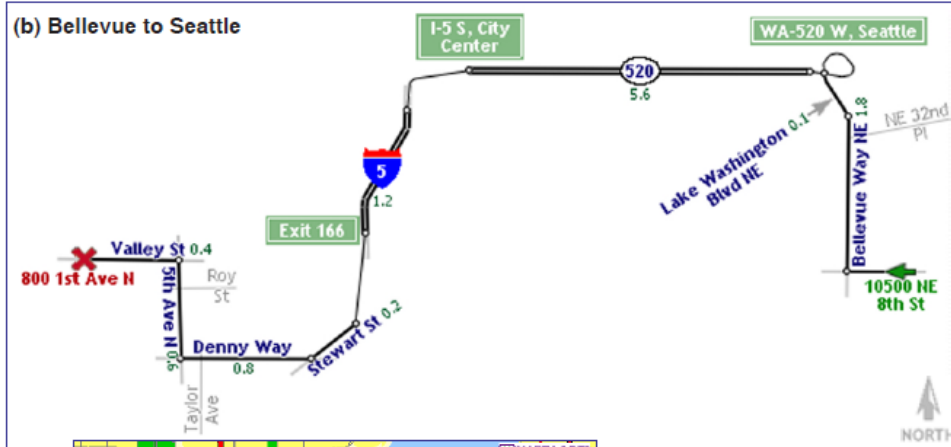
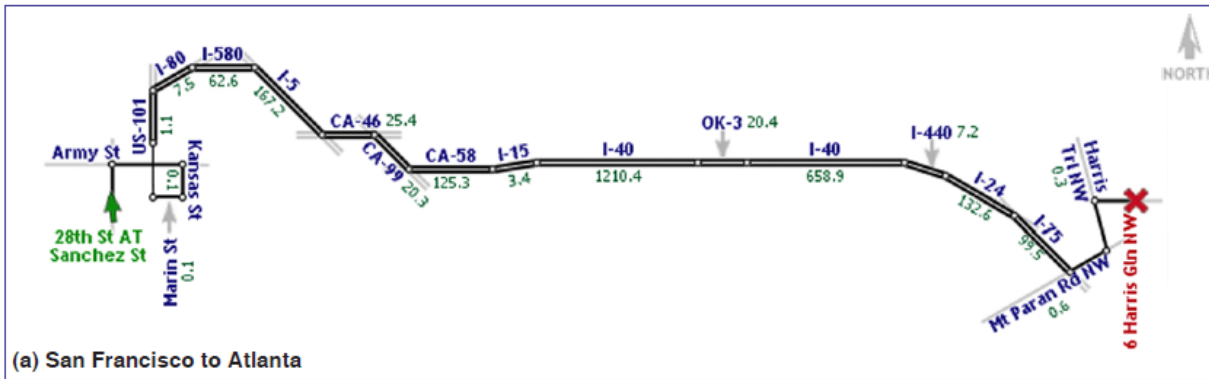


Figure 2: The LineDrive system. (a) Given a route as a sequence of roads, LineDrive designs a route map by processing the route through five consecutive stages. (b) The resulting LineDrive map. (c) The same map rendered without applying the generalization techniques performed by LineDrive. The constant scale factor and retention of detailed road shape make it difficult to identify many of the roads.

# MapBlast / LineDrive



# Practice Problem

Of all of the NPR examples you saw in class today, which did you think was most effective for what it was trying to do and why?