Homework 1 15-462 Computer Graphics, Spring 2012 Due 2/28 at the beginning of class

60 points Please show all of your work. Please list any references that you used to research or obtain your solution.

- 1. (5 points) Write a parametric equation for a line between points $[1 4]^T$ and $[2 1]^T$
- 2. (5 points) Write an implicit equation for the same line.
- 3. (5 points) Suppose that we wish to align a 2D coordinate frame uv to our world coordinate system xy. Let u = [2 3]^T and v=[3 -2]^T. Give a matrix that maps u to x and v to y. Show your work and demonstrate that this matrix is correct.
- 4. (5 points) Is your matrix in part 3 a rotation matrix? Why or why not?
- 5. (10 points) Derive a 2D perspective projection matrix for a camera at the origin pointed in the x-direction, with y up, an image plane at x=5. You do not have to preserve depth order. Show your derivation.
- 6. (5 points) Give several pros and cons (at least five total) of working with a mesh vs. an implicit surface
- 7. **(5 points)** what properties of a surface or material are required for the Phong Illumination Model? (Give specific parameter names and explain their meaning, referencing the equation in the first slide of lecture 9.)
- 8. **(5 points)** Surface / material properties are captured in a BRDF as a function. What is that function? (Explain any parameters you use.)
- 9. (6 points) Give three different examples of properties that can be captured in a BRDF that are not well captured in the Phong Illumination Model. Including and explaining effects in photos can be a good way to answer this question.
- 10. (5 points) Write the following quadratic spline in matrix form, as we have done for cubic splines in the class.

$$p(u) = p_1 + p_2(u - 1) u + (p_3 - p_1)u$$

- 11. (2 points) What is required for two adjacent such splines to be C0 continuous?
- 12. (2 points) What is required for two adjacent such splines to be C1 continuous?