

Cache Lab Implementation and Blocking

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Section J

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Welcome to the World of Pointers !



Class Schedule

■ Cache Lab

- Due Thursday.
- Start now (if you haven't already)

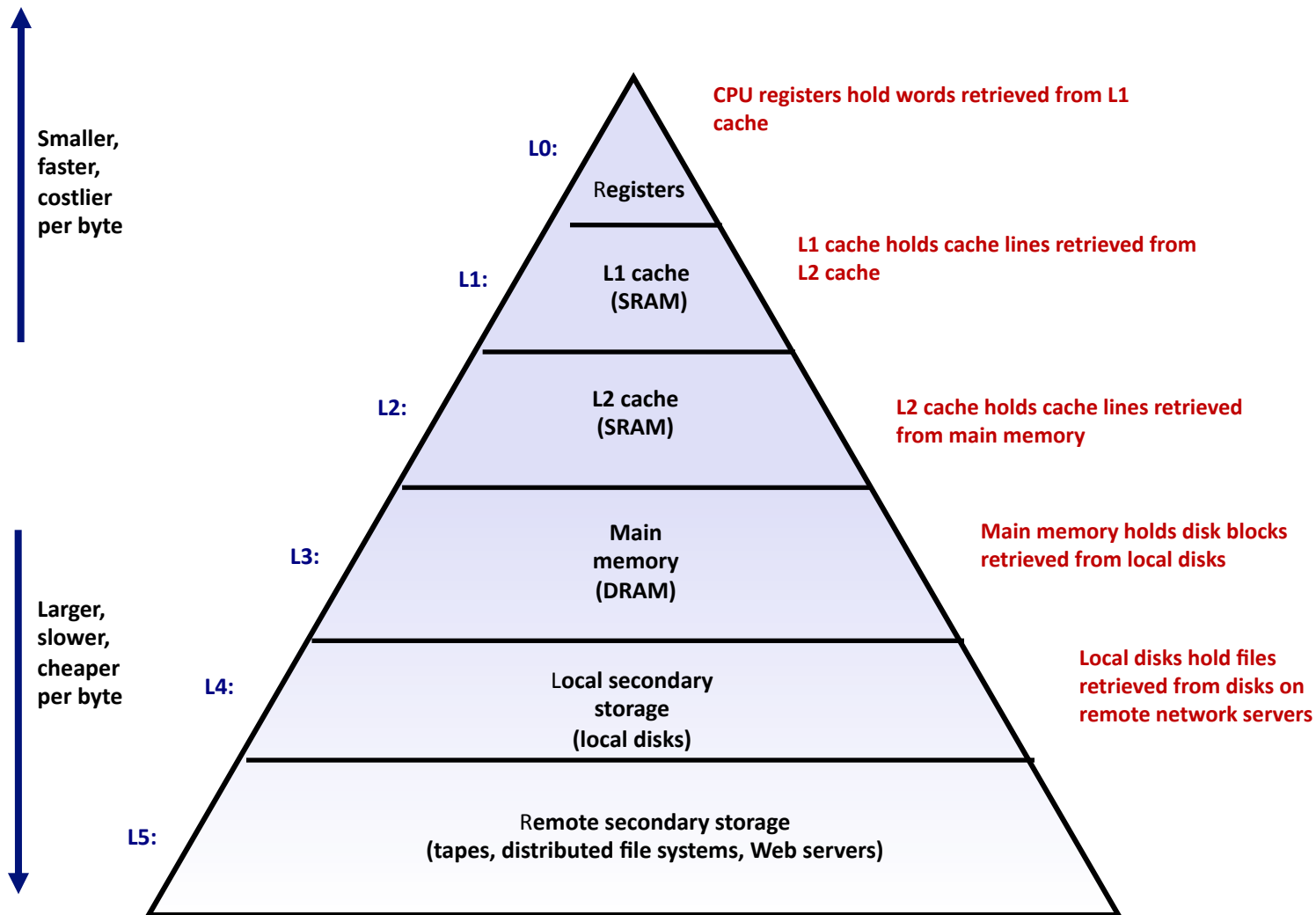
■ Exam Soon !

- Start doing practice problems.
- Wed Oct 16th – Sat Oct 19
- 10 days

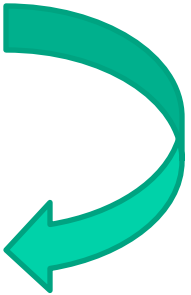
Outline

- **Schedule**
- **Memory organization**
- **Caching**
 - Different types of locality
 - Cache organization
- **Cachelab**
 - Part (a) Building Cache Simulator
 - Part (b) Efficient Matrix Transpose

Memory Hierarchy



Memory Hierarchy

- Registers
 - SRAM
 - DRAM
 - Local Secondary storage
 - Remote Secondary storage
- 
- We will discuss this interaction

SRAM vs DRAM tradeoff

■ SRAM (cache)

- Faster (L1 cache: 1 CPU cycle)
- Smaller (Kilobytes (L1) or Megabytes (L2))
- More expensive and “energy-hungry”

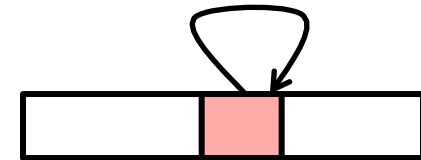
■ DRAM (main memory)

- Relatively slower (hundreds of CPU cycles)
- Larger (Gigabytes)
- Cheaper

Locality

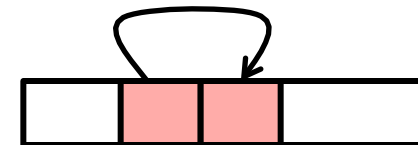
■ Temporal locality

- Recently referenced items are likely to be referenced again in the near future
- After accessing address X in memory, save the bytes in cache for future access



■ Spatial locality

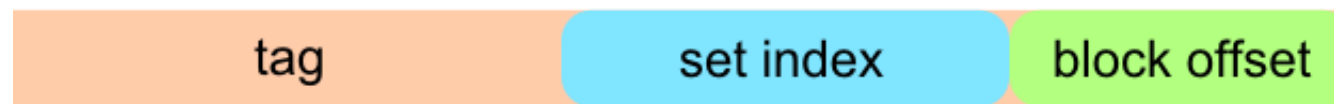
- Items with nearby addresses tend to be referenced close together in time
- After accessing address X , save the block of memory around X in cache for future access



Memory Address

- 64-bit on shark machines

memory address

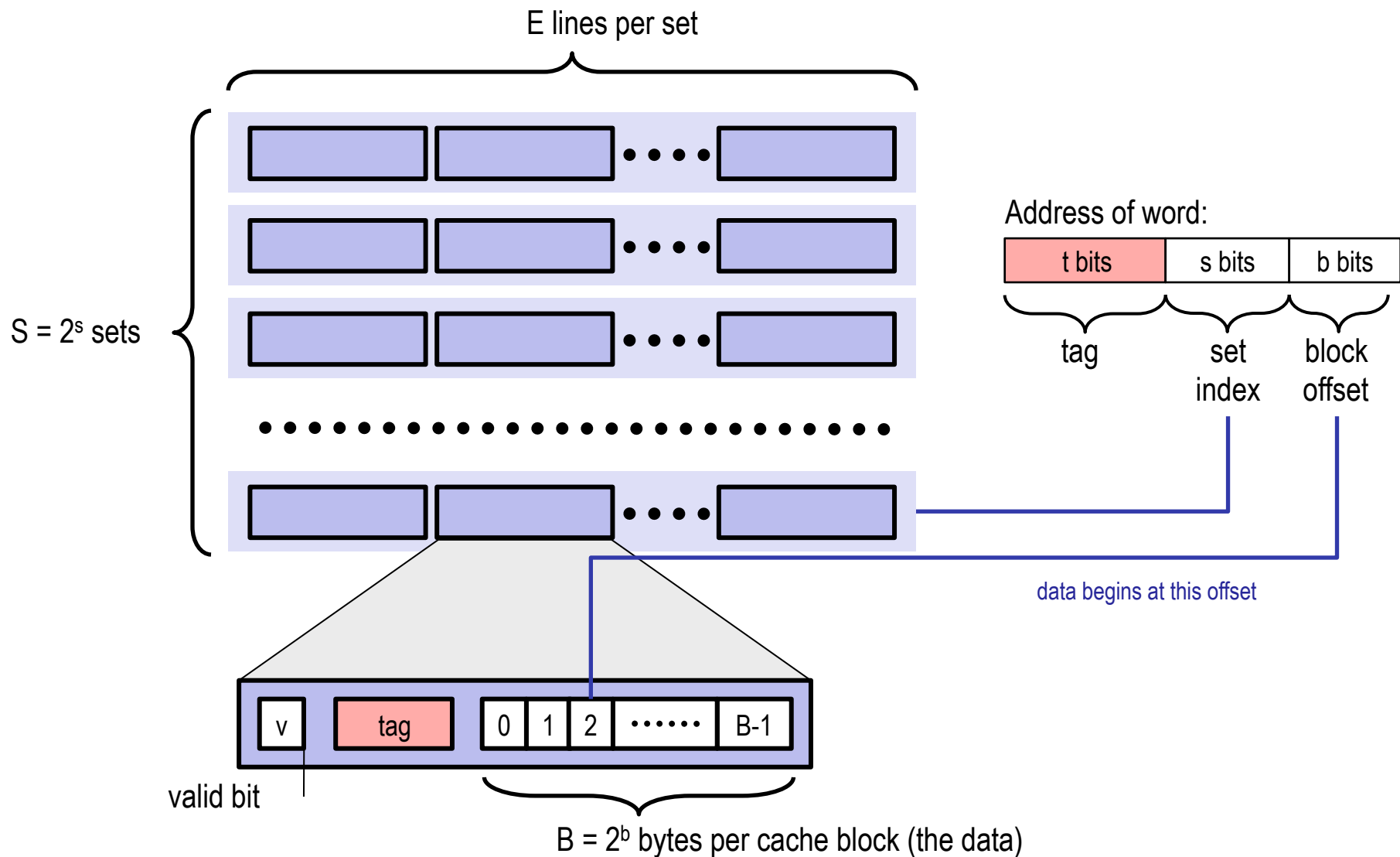


- Block offset: b bits
- Set index: s bits
- Tag Bits: Address Size $- b - s$

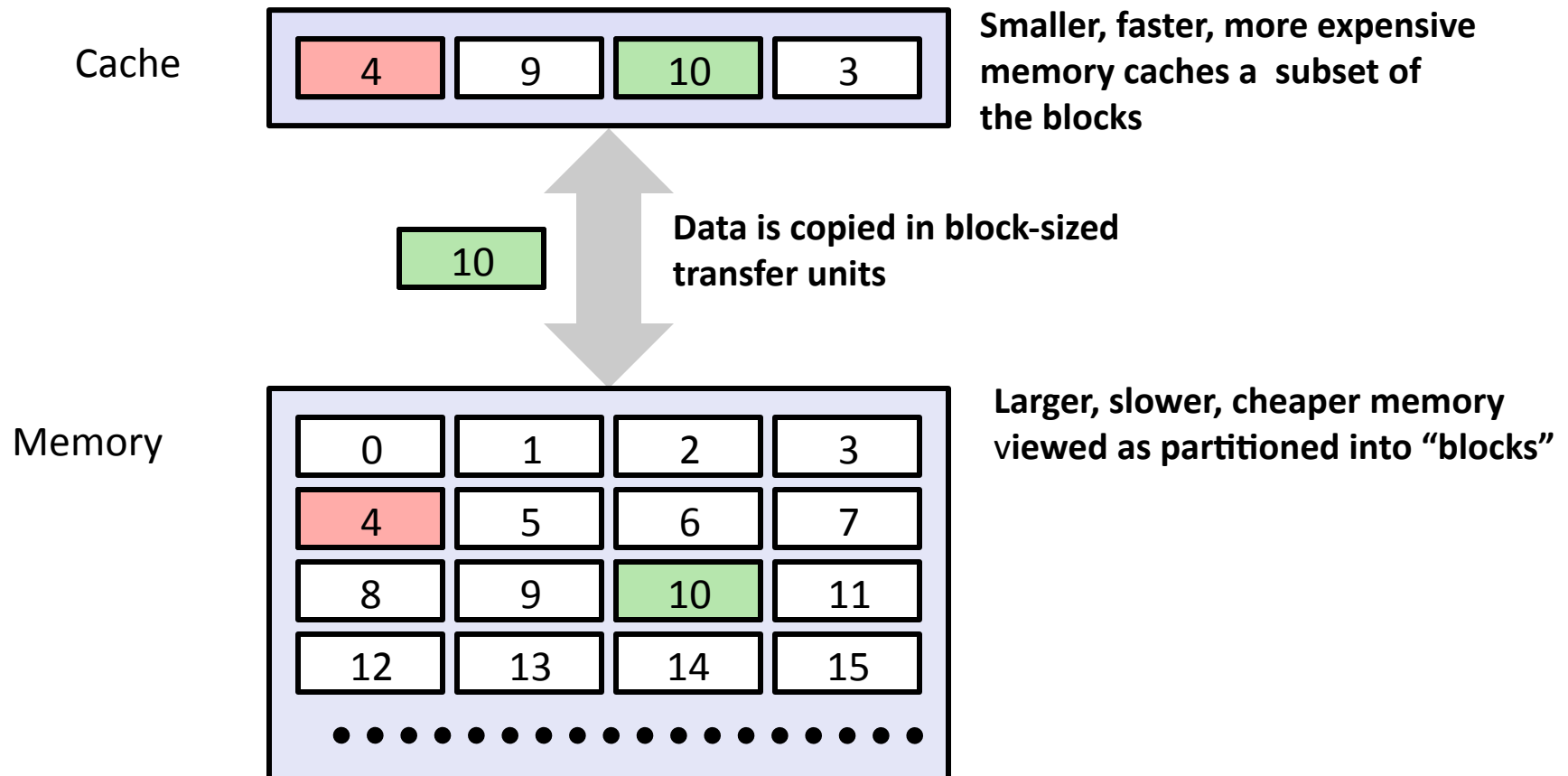
Cache

- **A cache is a set of 2^s *cache sets***
- **A *cache set* is a set of E *cache lines***
 - E is called associativity
 - If $E=1$, it is called “direct-mapped”
- **Each *cache line* stores a block**
 - Each block has $B = 2^b$ bytes
- **Total Capacity = $S*B*E$**

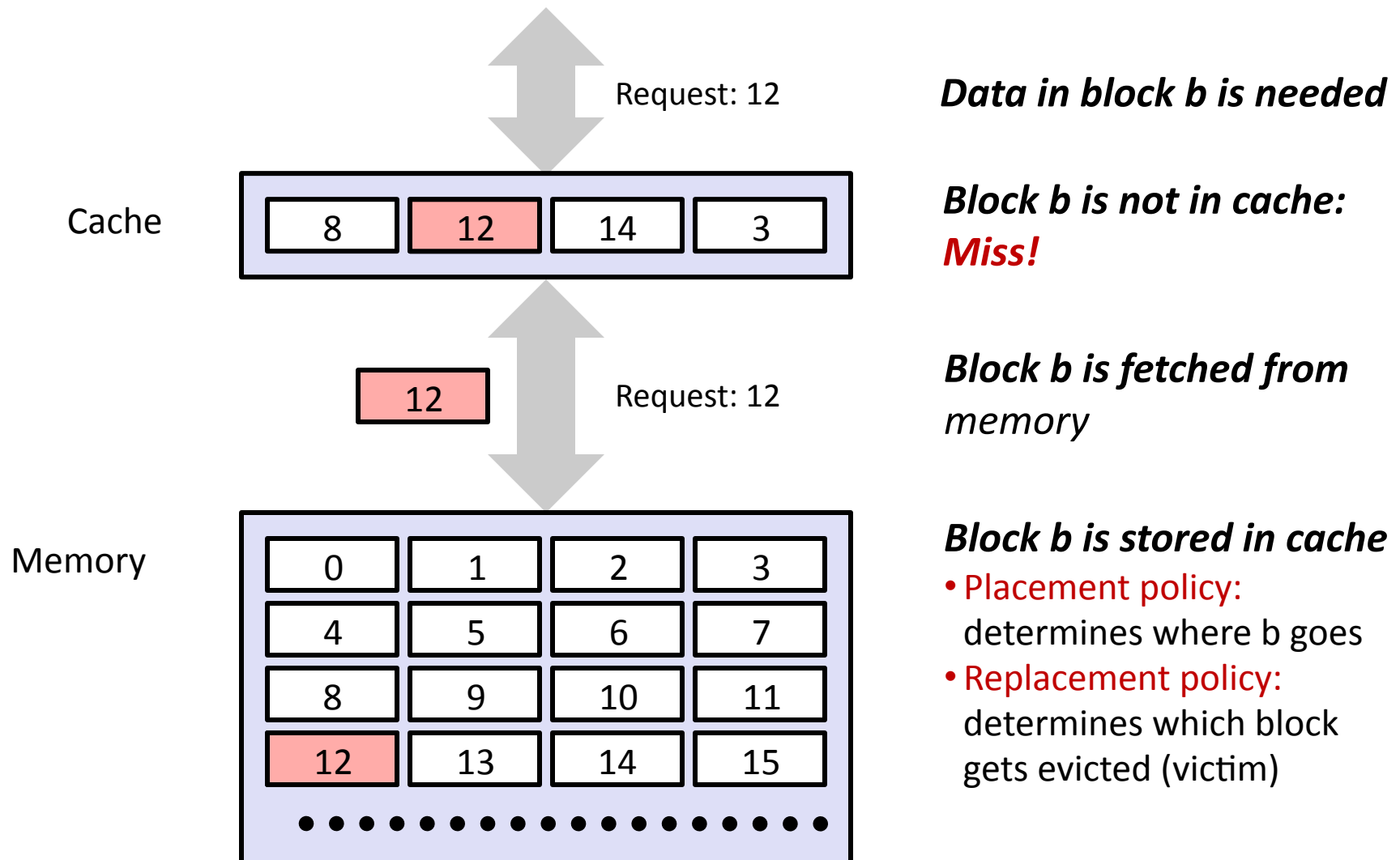
Visual Cache Terminology



General Cache Concepts



General Cache Concepts: Miss



General Caching Concepts:

Types of Cache Misses

■ Cold (compulsory) miss

- The first access to a block has to be a miss

■ Conflict miss

- Conflict misses occur when the level k cache is large enough, but multiple data objects all map to the same level k block
 - E.g., Referencing blocks 0, 8, 0, 8, 0, 8, ... would miss every time

■ Capacity miss

- Occurs when the set of active cache blocks (**working set**) is larger than the cache

Cachelab

- **Part (a) Building a cache simulator**
- **Part (b) Optimizing matrix transpose**

Part (a) Cache simulator

- **A cache simulator is NOT a cache!**
 - Memory contents NOT stored
 - Block offsets are NOT used – the b bits in your address don't matter.
 - Simply **count** hits, misses, and evictions
- **Your cache simulator need to work for different s , b , E , given at run time.**
- **Use LRU – Least Recently Used replacement policy**
 - Evict the least recently used block from the cache to make room for the next block.
 - Queues ? Time Stamps ?

Cache simulator: Hints

- **A cache is just 2D array of *cache lines*:**
 - `struct cache_line cache[S][E];`
 - $S = 2^s$, is the number of sets
 - E is associativity
- **Each `cache_line` has:**
 - Valid bit
 - Tag
 - LRU counter (only if you are not using a queue)

Cache Lab Implementation: getopt

- **getopt() automates parsing elements on the unix command line If function declaration is missing**
 - Typically called in a loop to retrieve arguments
 - Its return value is stored in a local variable
 - When getopt() returns -1, there are no more options
- **To use getopt, your program must include the header file unistd.h**
- **If not running on the shark machines then you will need #include <getopt.h>.**
 - Better Advice: Run on Shark Machines !

getopt

- **A switch statement is used on the local variable holding the return value from getopt()**
 - Each command line input case can be taken care of separately
 - “optarg” is an important variable – it will point to the value of the option argument
- **Think about how to handle invalid inputs**

getopt Example

```
int main(int argc, char** argv){
    int opt, x,y;
    /* looping over arguments */
    while(-1 != (opt = getopt(argc, argv, "x:y:"))){
        /* determine which argument it's processing */
        switch(opt) {
            case 'x':
                x = atoi(optarg);
                break;
            case 'y':
                y = atoi(optarg);
                break;
            default:
                printf("wrong argument\n");
                break;
        }
    }
}
```

- Suppose the program executable was called “foo”. Then we would call “./foo -x 1 -y 3” to pass the value 1 to variable x and 3 to y.

fscanf

- **The fscanf() function is just like scanf() except it can specify a stream to read from (scanf always reads from stdin)**
 - parameters:
 - file pointer,
 - format string with information on how to read file,
 - the rest are pointers to variables to storing data from file
 - Typically want to use this function in a loop until it hits the end of file
- **fscanf will be useful in reading lines from the trace files.**
 - L 10,1
 - M 20,1

Example

```
FILE * pFile; //pointer to FILE object

pFile = fopen ("tracefile.txt","r"); //open file for reading

char identifier;
unsigned address;
int size;
// Reading lines like " M 20,1" or "L 19,3"

while(fscanf(pFile," %c %x,%d", &identifier, &address, &size)>0)
{
    // Do stuff
}

fclose(pFile); //remember to close file when done
```

Malloc/free

- **Use malloc to allocate memory on the heap**
- **Always free what you malloc, otherwise may get memory leak**
 - `Some_pointer_you_malloced = malloc(sizeof(int));`
 - `Free(some_pointer_you_malloced);`
- **Don't free memory you didn't allocate**

Part (b) Efficient Matrix Transpose

- Matrix Transpose (A \rightarrow B)

Matrix A

1	2	3	4
5	6	7	8
9	10	11	12
13	14	15	16

Matrix B

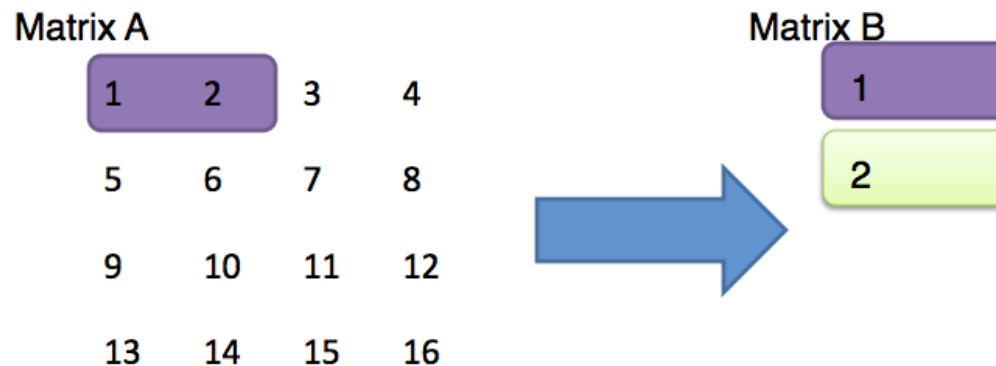
1	5	9	13
2	6	10	14
3	7	11	15
4	8	12	16



- How do we optimize this operation using the cache?

Part (b) Efficient Matrix Transpose

- Suppose Block size is 8 bytes ?



- Access $A[0][0]$ cache miss
- Access $B[0][0]$ cache miss
- Access $A[0][1]$ cache hit
- Access $B[1][0]$ cache miss

Should we handle 3 & 4
next or 5 & 6 ?

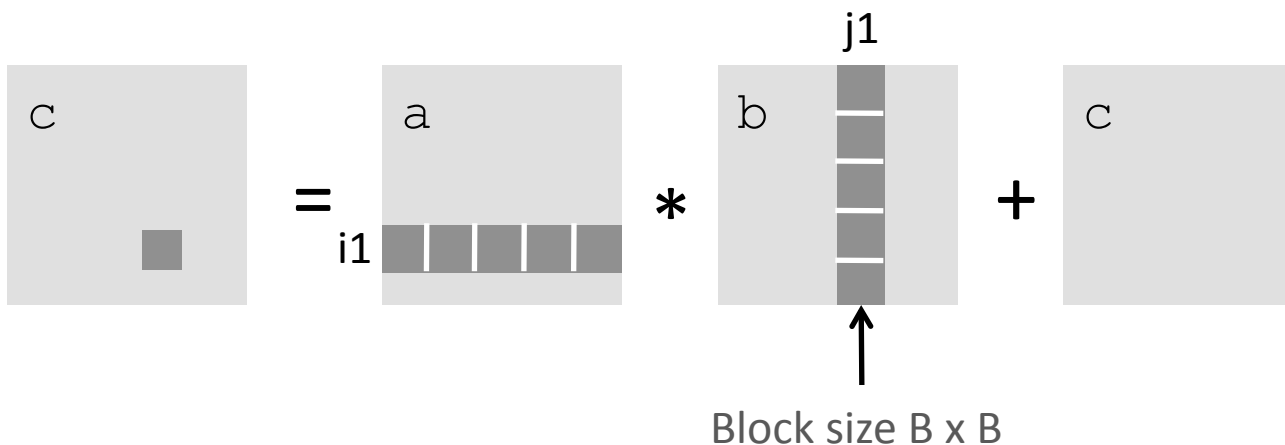
Blocked Matrix Multiplication

```

c = (double *) calloc(sizeof(double), n*n);

/* Multiply n x n matrices a and b */
void mmm(double *a, double *b, double *c, int n) {
    int i, j, k;
    for (i = 0; i < n; i+=B)
        for (j = 0; j < n; j+=B)
            for (k = 0; k < n; k+=B)
                /* B x B mini matrix multiplications */
                for (i1 = i; i1 < i+B; i++)
                    for (j1 = j; j1 < j+B; j++)
                        for (k1 = k; k1 < k+B; k++)
                            c[i1*n+j1] += a[i1*n + k1]*b[k1*n + j1];
}

```



Blocking

- **Divide matrix into sub-matrices**
This is called blocking.
- **Size of sub-matrix depends on cache block size, cache size, input matrix size.**
- **Try different sub-matrix sizes.**

Part (b)

■ Cache:

- You get 1 kilobytes of cache
- Directly mapped ($E=1$)
- Block size is 32 bytes ($b=5$)
- There are 32 sets ($s=5$)

■ Test Matrices:

- 32 by 32, 64 by 64, 61 by 67

Part (b)

- **Things you'll need to know:**
 - Warnings are errors
 - Header files
 - Useful functions

Warnings are Errors

- **Strict compilation flags**
- **Reasons:**
 - Avoid potential errors that are hard to debug
 - Learn good habits from the beginning
- **Add “-Werror” to your compilation flags**

Missing Header Files

- Remember to include files that we will be
- using functions from
- If function declaration is missing
 - Find corresponding header files
 - Use: `man <function-name>`

- Live example
 - `man 3 getopt`

Tutorials

■ **getopt:**

- http://www.gnu.org/software/libc/manual/html_node/Getopt.html

■ **fscanf :**

- <http://crasseux.com/books/tutorial/fscanf.html>

■ **Google is your friend**

Style

- **Read the style guideline**
 - But I already read it!
 - Good, read it again.

- **Pay special attention to failure and error checking**
 - Functions don't always work
 - What happens when a syscall fails??

- **Start forming good habits now!**

Questions?

