

Dynamic Graph Algorithms

Solve standard algorithmic problems in the setting where graph is changing over time.

E.g. dynamic connectivity.

- insert (u, v) . \leftarrow insert only } fully dynamic ?
- delete (u, v) . \leftarrow delete only
- connected (u, v) ? connected (G) ?

Basic question, many results, but not completely resolved yet.

~~Clearly if arbitrary updates @ each operation \rightarrow can run DFS each time.~~
~~so minimize update time vs query time.~~

Some results	Foerster et al. SICOMP '85	$O(m^{1/2})$ update	$O(1)$ query time	deterministic worst case.
	Eppstein et al.	$\overset{?}{O}(n^{1/2})$	"	HW.
	Trollin de Lichtenberg Thorup '98	$O(\text{poly}(\log))$ update	$O(\log n)$ query	Holder analyzed det. worst case de Lichtenberg Thorup
	Kapron King Monajem	$O(\text{poly}(\log))$ update	"	random // worst case !

Let's see some ideas used in these papers today.

$$\text{BTdL: LBd: Demaine Paterson: } T_{\text{update}} \times \log \left(\frac{T_{\text{query}}}{T_{\text{update}}} \right) \geq \Omega(\log n).$$

$$\text{Thorup: } T_{\text{query}} \times \log \left(\frac{T_{\text{up}}}{T_q} \right)$$

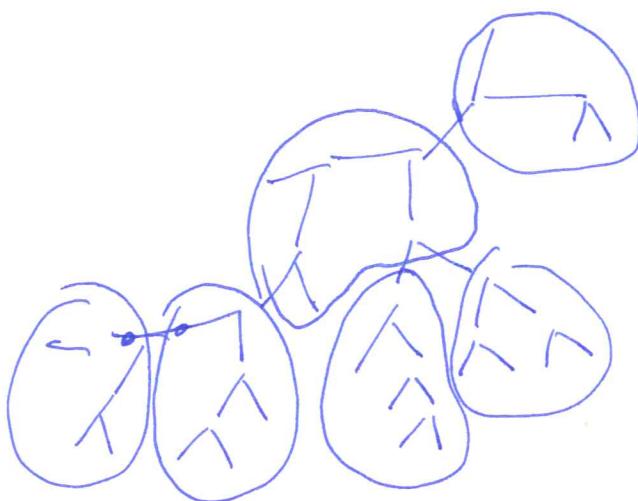
even randomized algo (Monte Carlo alg).

(2)

Fredericksen (A weaker $m^{2/3}$ result).

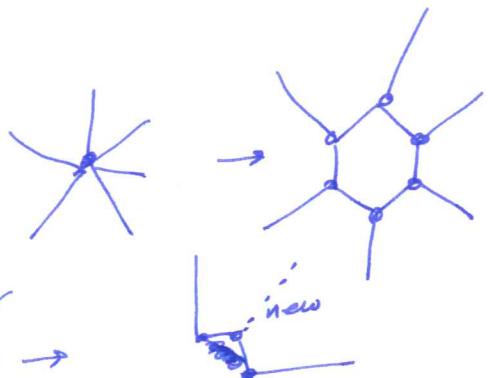
- Sps insert-only. Then union-find does the job. Insert = Union. } implicitly maintains a spanning forest.
Query = find. }
- But delete: hmm: suppose we maintain a spanning forest and delete an edge in tree.
how to find a replacement edge. (if delete off-tree edge, no worries).

Idea: Cluster the tree into ^{connected} pieces of size $\leq z$. (some parameter).

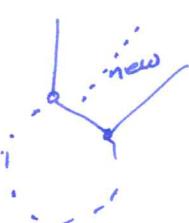


Assumption 1: G has ~~0~~ degree ≤ 3 .

} Replace high degree nodes by gadgets of cycles



now if new edge then



incorrect delete of 1 edge in original graph

\Leftrightarrow inserts delete of $O(1)$ edges in new graph.

New graph has $m = \Theta(n)$ and $\deg \leq 3$.

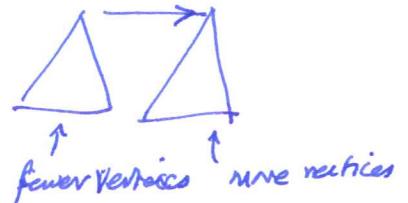
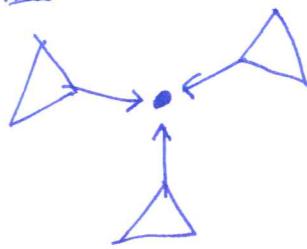
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Fact 2: Given a tree with max degree ≤ 3 , can mark set of edges so that non-marked edges form components of size $\in [z, 3z]$

assume
tree of
size $> z$
...
...
...
...
...

PF: Direct each edge from smaller subtree to larger (break ties arbitrarily).

Then ~~at most~~ one vertex is outdegree = 0.



if tree has size $\geq 3z$ then ~~deleting~~ for at least one of these in-edges, deleting it gives components of size $\geq z$ on both sides. Recurse.

Actually can do this in time linear in the tree. (How? Exercise).

Call this a z -bounded clustering of the tree. (if tree has $< z$ nodes, all vtes in the same cluster)

We maintain: . a spanning forest F of G .

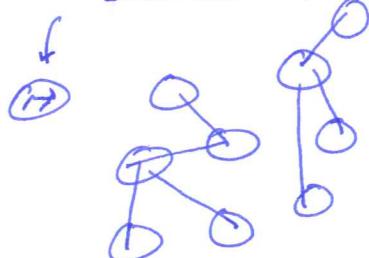
. a z -bounded clustering of each tree.

. for each pair of clusters, 1 bit for whether

of some tree

edge from C_i to C_j

not in F .



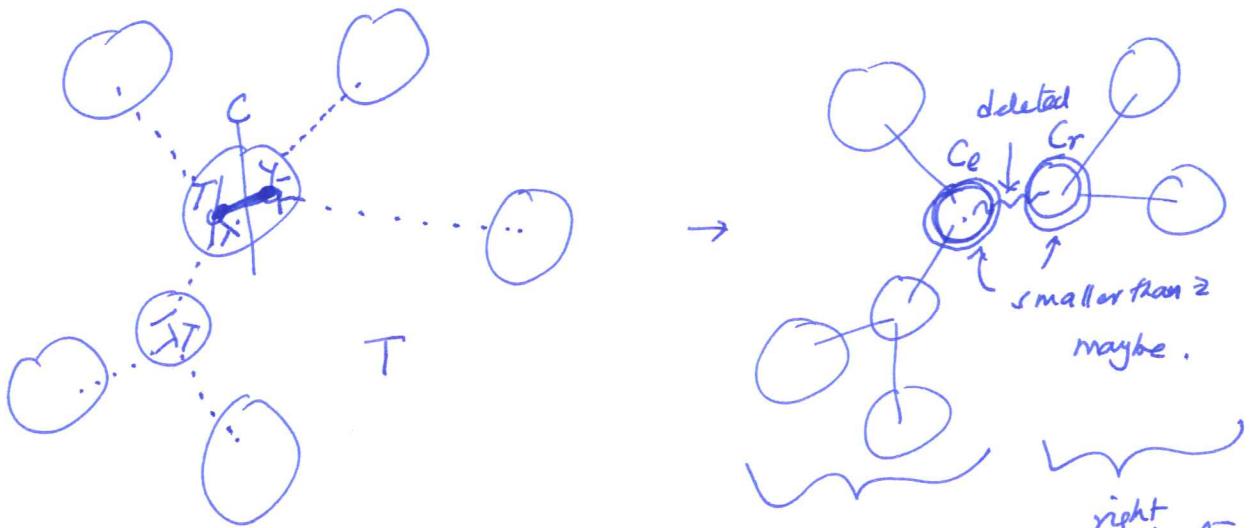
(and a list of these edges)

Inserts are easy (exercise!) so look at deletes.

If off-tree edge deleted, just update the bit for the clusters (C_i, C_j) this edge goes ~~between~~ between. (Must belong to some tree in F , since F spanning forest).

So delete $e \in F$. (say $e \in T$).

Sps e within cluster (other case similar)



Try to find a replacement edge
b/w left & right clusters.

- At most $O(m/z)$ clusters \Rightarrow for each look up bit $\Rightarrow O((m/z)^2)$ time.

But careful! No record of (C_e, C') edges

since $C_e \cup C_r = C$ was original cluster.

No prob! Only $O(z)$ edges hit $C_e \cup C_r = C$, so scan all of them in $O(z)$ time.

- Finally, either replacement edge or not. Either case C_e, C_r maybe too small.
So merge with some neighbor cluster and re-partition if too big.
Again $O(z)$ time.

Total time: $O((m/z)^2 + z)$. Balance to get $z = O(m^{2/3})$. ☺.

Using more careful data structures, get $O(m^{1/2})$. [same paper].

Eppstein et al. gave clever technique (very general) to reduce to $\tilde{O}(n^{1/2})$.
[Homework]

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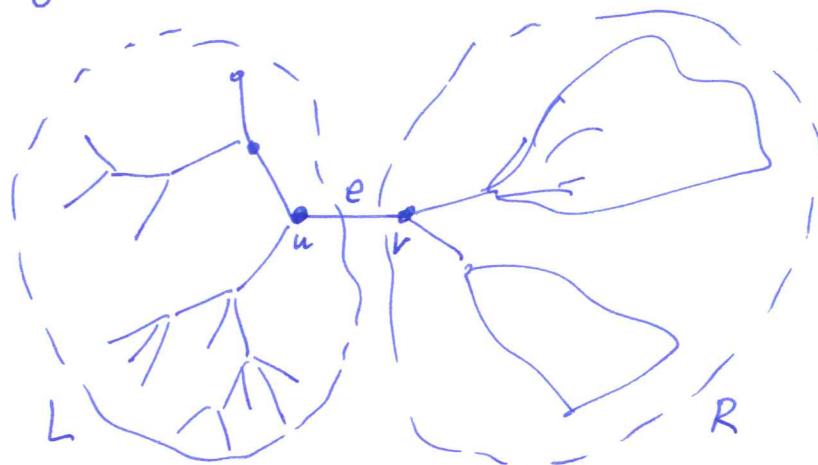
Randomized Idea (Very high level sketch)

Suppose we have just one deletion. Want fast Worst case time, only that error probability is $o(1)$.

Here's idea: each vertex name is $O(\lg n)$ bits: $\ell(x) \leftarrow \text{"label of } x\text{"}$.

edge $e = (u, v)$ represented by $\langle \ell(u), \ell(v) \rangle \stackrel{\text{def}}{=} \ell(e)$
 (assume $u < v$ according to some total order on vertex names).

Maintain spanning forest on G . Now get $\text{delete}(e = (u, v))$ operation
 (wlog assume tree T)



Need replacement edge between L & R.

Suppose: Only one edge f in $\text{Cut}(L, R) \setminus \{e\}$. Unique replacement edge.

Then:
$$\bigoplus_{x \in L}^{x \neq R} \ell(e') = \ell(f) = \bigoplus_{x \in R} \bigoplus_{e' \in \delta_G^-(x)} \ell(e')$$

$\bigoplus_{x \in L}$ all edges'
incident to x

$\bigoplus_{x \in R}$ $e' \in \delta_G^-(x)$

(smiley face)

~~What if many replacement edges?~~

How do you compute this in polylog time? ~~maintain the tree~~

Use some smart data structures (link-cut trees or Euler-tour trees).

OK: What if there are many edges crossing from L + R in $G \setminus e$?

Sample! For each j , sample $\frac{1}{2^j}$ and maintain the $\bigoplus_{e' \in \delta_G^-(x) \text{ sampled}} \ell(e')$

for each such sample. (let $\oplus_{\text{edges in sample}} \ell(e)$ be the "signature" of x .)

This will work if \exists a unique edge from $L \rightarrow R$ in the sample. So if $\exists \leq 2^i$ edges across the cut, $P_r[\text{unique edge survives}] \geq \sum_{\text{edges}} \frac{1}{2^i} \cdot \left(1 - \frac{1}{2^i}\right)^{2^i-1} \geq \Theta(1)$.

Now if repeat $\Omega(\log n)$ times, one sample succeeds w/ $1 - \frac{1}{\text{poly}(n)}$!!

Does not quite work immediately for multiple deletes. B/c. the tree after the first delete depends on the sample, and now subsequent calculation cannot use independence the same way.

But Karon King Monfay [SODA 12] find a way around it.

Won't do this in class

The Holm et.al Idea for amortized polylog (deterministic) bound

Again, how to find replacement edges? Can scan all edges of LUR but may do this repeatedly! Need some way to measure progress.

Idea: Each edge is kept @ some "level" $\in [0, \log_2 n]$. "Charge" scanning edges to raising the level of some ~~some~~ edges. ~~some~~

Insert: edge added @ level 0.

Delete: . ~~if e @ level l~~ if e @ level l \leftarrow highest level for e
 . look at tree $T \ni e$, splits into L & R. Say $|L| \leq |R|$.

(if e not in any tree, ignore.)

. raise edges of L to level $l+1$
 (those edges of level l).

// Maintains Invariant II

b/c $|L| \leq |T|/2 \leq n/2^l \cdot 1/2^l$ by induction.

Invariants: $E_0 \supseteq E_1 \supseteq E_2 \supseteq \dots \supseteq E_L$
 \downarrow
 edges @ level i in hyper

① F_i is ~~some~~ spanning forest of ~~some~~ E_i
 $F_{i-1} \supseteq F_i$
 i.e. if $x, y \in E_i$ connected $\Rightarrow x, y$ connected in F_i

② each component in F_i has $\leq \frac{n}{2^i}$ nodes

Now start scanning edges ~~incident~~^{nontree} to $V(L)$.
those of level l .

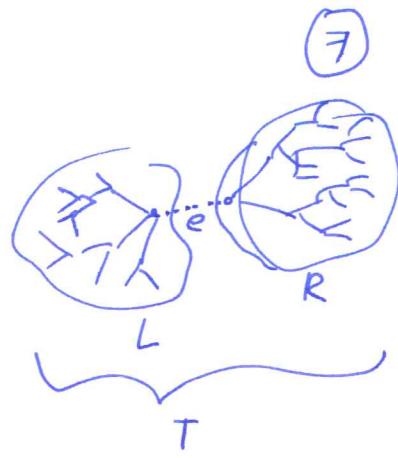
If it goes within L , raise to level $l+1$.

If it goes to R , done. Stop, and add to $F_l, F_{l-1} \dots F_0$.

Sps. run out of level- l edges, then go to level $l-1$.

Now T_l has tree T_{l-1} containing e that has split into L_{l-1} & R_{l-1} .

Again if $|L_{l-1}| \leq |R_{l-1}|$, raise edges of level $l-1$ in L_{l-1} to level l ,
and start scanning level $l-1$ edges incident to $V(L_{l-1})$.



Note we maintain Invariants.

(Raising levels of edges does not harm Inv I, may mess with Inv II, so that is why
we raise levels carefully ensuring that size of comp halves when levels rise)

Time Analysis:

We were kinda vague about how we maintain the forests. Basically each F_i is maintained by Sleator/Tarjan Link/Cut trees. When edge added, use Link.

When delete, use Cut. And then for each edge during the scan, use membership tests of LC trees to test if edge goes across (and use Link if it does).

Fact: Amortized cost of these operations $O(\lg n)$.

Each edge ~~is charged~~^{charged} $O(\lg n)$ times, ~~so~~ $\Rightarrow O(\lg^2 n)$ per update.

Query time: check if (x, y) in same component, $O(\lg n)$ time.

of subtree.
Oh, size calculation
also ok in LC trees.

Takeaway Ideas: "charge to smaller side". for Holm et al algo.

- "power of XOR" and "power of sampling" for KKM.

- clustering and tree separator for Fredriksson.