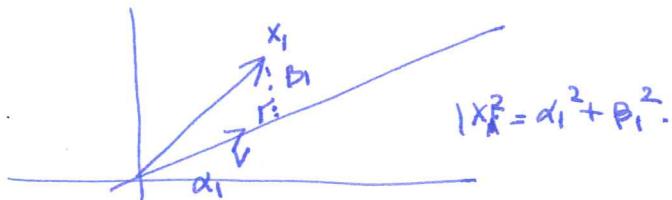


Singular Value Decomposition

We're given a set of points $X = \{x_1, x_2, \dots, x_n\}$ in \mathbb{R}^D . They're placed as rows of a matrix $A = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$. We want to represent them using a small #A dimensions, but now not to preserve distances but preserve the "energy".

The 1-dimensional problem : find a 1-dimensional subspace such that the sum of projections (squared) is maximized - or the sum of distances squared is minimized.

These are equivalent (by pythagoras).



So want v st. $\sum_i (x_i \cdot v)^2$ is maximized st $\|v\|=1$. but $\sum_i (x_i \cdot v)^2 = \|Av\|^2$.

first (right) singular vector $v_1 := \arg \max_v \frac{\|Av\|^2}{\|v\|^2} = \arg \max_{\|v\|=1} \|Av\|^2$.

first singular value $\sigma_1(A) := \max_{\|v\|=1} \|Av\| = \|Av_1\|$.

$\sigma_1^2 = \text{sum of squared projections of points on } v_1$.

Suppose want 2-d subspace in some greedy fashion :- let's find

$$v_2 = \arg \max_{\|v\|=1, v \perp v_1} \|Av\| . \quad \text{and} \quad \sigma_2(A) = \max_{\|v\|=1, v \perp v_1} \|Av\| .$$

Similarly:

$$\bullet v_i = \arg \max_{\|v\|=1, v \perp v_1, v_2, \dots, v_{i-1}} \|Av\| \quad \text{and} \quad \sigma_i(A) = \max_{\|v\|=1, v \perp v_1, \dots, v_{i-1}} \|Av\| .$$

Observe: we've just defined things greedily. Find v_1 , then v_2 , then v_3, \dots , then v_k .

What if the best 2-dim subspace did some global optimization non-greedily?

(2).

Thankfully, things are pretty good for us!

Claim: Suppose $A \in \mathbb{R}^{n \times d}$ with singular vectors v_1, v_2, \dots, v_r . means $\max_{v \in V} \|Av\| = 0$.

Let $V_k = \text{span}(v_1, \dots, v_k)$. $\forall k \leq r$.

then V_k is best-fit k -dimensional subspace first.

(i.e. sgs S is another k -dim subspace spanned by w_1, \dots, w_k (orthonormal basis))
 $\Rightarrow \sum_{i=1}^k \|Aw_i\|^2 \leq \sum_{i=1}^r \|Av_i\|^2.$)

Pf: . Base case $k=1$ (trivially true)

• $k=2$: v_1, v_2 are sig vectors. say S is another subspace. Let w_1, w_2 span S .
 Choose $w_2 \perp v_1$ in the subspace, and then w_1 accordingly.

$$\cdot \|Aw_2\|^2 \leq \|Av_2\|^2. \quad \text{by choice of } V_L. \quad \checkmark.$$

$$\cdot \|Aw_1\|^2 \leq \|Av_1\|^2 \quad \text{by choice of } V_1.$$

• k general. By induction V_{k+1} is best fit k -dim subspace.

Choose w_1, \dots, w_k to span S such that $w_k \perp v_1, \dots, v_{k-1}$.

Again same argument.



Fact: $\sum_i \sigma_i^2 = \|A\|_F^2 = \sum_{ij} a_{ij}^2$.

$$\underline{\text{Pf:}} \quad \sum_i \sigma_i^2 = \sum_i \sum_j \|Av_i\|^2 = \sum_i \sum_j \langle a_j, v_i \rangle^2 = \sum_j \sum_i \langle a_j, v_i \rangle^2$$

but v_i form an orthonormal basis for the row space of A .

$$= \sum_j \|a_j\|^2 = \sum_{jk} a_{jk}^2 = \|A\|_F^2. \quad \checkmark$$

Now define: $u_i = \frac{Av_i}{\|Av_i\|} = \frac{Av_i}{\sigma_i}$. Clearly unit vectors. (also in fact orthonormal)

$u_i := i$ th left singular vector of A .

$= \arg \max_{\substack{u \perp u_1, \dots, u_{i-1} \\ \|u\|=1}} \|u\|$ much like the right singular vector.
 (by the way)

(3)

$$\text{Claim: } A = \sum_i \sigma_i u_i v_i^T$$

(BTW: if $U = \begin{pmatrix} u_1 & u_2 & \dots & u_r \\ 1 & 1 & \dots & 1 \end{pmatrix}$

$$D = \begin{pmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_r \end{pmatrix} \quad V = \begin{pmatrix} | & | & | \\ v_1 & v_2 & \dots & v_r \\ | & | & | \end{pmatrix} \text{ then } \sum_i \sigma_i u_i v_i^T = UDV^T \text{ ok.}$$

$= \begin{array}{c|c|c} \hline & \text{size } n \times r & \text{size } r \times d \\ \hline \text{size } n \times d & \text{size } r \times r & \text{size } d \times d \\ \hline \end{array}$

Pf: [SubClaim: A and B are same iff $Av = Bv \forall v \in \mathbb{R}^n$.

Pf: \Rightarrow trivial \Leftarrow sps not then choose $v = e_i$, where differ in i^{th} column.

[Subclaim: A and B are same iff $Av = Bv \forall v$ in basis. Pf write each v in this basis.]

Now: consider the basis of $v_1, v_2, \dots, v_r, \underbrace{v_{r+1}, \dots, v_d}_{\text{extend to orthonormal basis}}$

for any $j \in [r]$ ~~$\Rightarrow (\sum_i \sigma_i u_i v_i^T) \cdot v_j = \sigma_j u_j \Rightarrow$~~ $\Downarrow Av_j \text{ (by defn of } u_j)$

$\Rightarrow A \text{ and } \sum_i \sigma_i u_i v_i^T \text{ are identical.}$

for $j \notin [r]$ $Av_j = 0 = (\sum_i \sigma_i u_i v_i^T) v_j$

□

$$\boxed{A} = \boxed{U} \boxed{D} \boxed{V^T}$$

$$= \sum_{i=1}^r \sigma_i u_i v_i^T$$

the columns of U & V
are orthonormal

(haven't proved it for columns of U
yet \rightarrow do it in HW)

Claim: Suppose $A = \boxed{UDV^T}$ for matrices $\boxed{U}, \boxed{D}, \boxed{V}$ where D is diagonal,

\boxed{U}, \boxed{V} have orthonormal columns. then $\boxed{U} = U, \boxed{D} = D, \boxed{V} = V$ (apart from
degeneracies due to subspaces). say all singular values are distinct then it is indeed
unique.)

Thm: [Eckart Young]

Sps $\sum_{i=1}^r \sigma_i u_i v_i^T = A_{n \times d}$. For any $k \leq r$, define $A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$.

Then for any matrix B_A rank at most k ,

$$\|A - B\|_F \geq \|A - A_k\|_F.$$

Also: define the 2-norm or spectral norm of a matrix A to be $\|A\|_2 = \max_{\|V\|=1} \|AV\|$.
 $= \max \text{ singular value of } A$.

$$\Rightarrow \|A - B\|_2 \geq \|A - A_k\|_2$$

See MW exercises.

The top k singular values give the best k -dimensional subspace.

lem: the rows of A_k are the projections of rows of A onto $V_k = \text{span}(v_1, \dots, v_k)$.

Pf: if a is a row of A , a 's projection is given by $\sum_{i=1}^k (\alpha_i v_i) \cdot v_i^T$

$$\Rightarrow \text{All these projections are given by } \sum_{i=1}^k (Av_i) \cdot v_i^T = \sum_{i=1}^k \sigma_i u_i v_i^T = A_k.$$

$\Rightarrow \|A - A_k\|_F$ is the remaining mass/energy

Fact: for a (square) symmetric matrix B , can find a basis of eigenvalues

$$x_i \text{ st } Bx_i = \lambda_i x_i \quad \forall i=1 \dots n. \quad x_i \text{ are orthonormal.}$$

$$\Rightarrow B = X \pi X^T \quad X = \begin{pmatrix} x_1 & x_2 & \dots & x_n \end{pmatrix} \quad \pi = \begin{pmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix}.$$

$= \sum_i \lambda_i x_i x_i^T$ (again, unique upto rotation within subspaces).

Now: sps matrix is general $A_{n \times d}$. Then

$$AA^T = (UDV^T)(UDV^T)^T = UDV^T VDU^T = UD^2U^T \leftarrow \text{eigenvalues are } \sigma_i^2. \text{ eigenvectors are } u_i.$$

$$A^TA = VD^2V^T \leftarrow \text{eigenvectors are now } v_i$$

Moreover: having found (left) eigenvalues & eigenvectors (say) $AA^T = X\pi X^T$ know $U=X$.

$$\text{and set } V^T = D^{-1}U^TA.$$

$$D^2 = \pi.$$

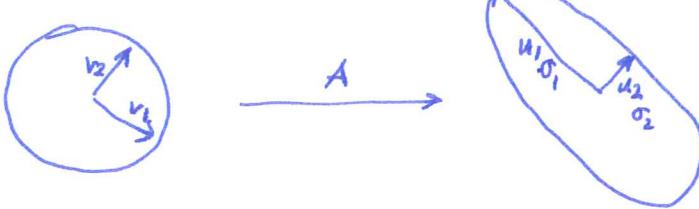
(5)

One view: v_i 's are the directions along which A has most energy.

Another view: $A = UDV^T \Rightarrow AV = UD$.

cols of both U & V are orthonormal. So A takes these orthonormal cols of V into

scaled orthonormal cols of U .



Example: handwriting recognition; face compression, etc.

~~Topic Models (naive version)~~

Topic Models (naive version)

$$A = \text{documents} \times \text{words} = UDV^T$$

$$= \underset{\text{docs}}{\left(\begin{array}{c} \\ \end{array} \right)} \underset{\substack{\text{topics} \\ \uparrow \\ \text{weights}}}{{\left(\begin{array}{c} \\ \end{array} \right)}} \underset{\substack{\text{words} \rightarrow \\ \text{topics}}}{{\left(\begin{array}{c} \\ \end{array} \right)}} \text{topics}$$

Learning Gaussian Mixtures: [Venupala Wang]

Given k gaussians, want to (a) cluster the points into k clusters, and

with weights w_i (b) find the mean, variance, weight etc of the gaussians.

(this is fine given the clustering).

Known: if \sqrt{d} distances one at least $\sqrt{2}(d^{1/4})$ then can cluster.

So: idea: find the SVD of space, with enough samples, the top k -dimensions

give us the subspace containing the k centers. Note: ~~this space~~ projecting down onto this space still gives us k Gaussians. (b/c of spherical symmetry) And hence a separation of $\sqrt{2}(k^{1/4})$ suffices

Subspace Embeddings:

Suppose $W \subseteq \mathbb{R}^n$ is a linear subspace: an ϵ -subspace embedding $\Pi : \mathbb{R}^n \rightarrow \mathbb{R}^m$ (Π is a $m \times n$ matrix) ensures that

$\| \Pi x \|_2 \leq (1+\epsilon) \| x \|_2 \quad \forall x \in W.$

$$1-\epsilon \leq \frac{\| \Pi x \|_2}{\| x \|_2} \leq 1+\epsilon \quad \forall x \in W.$$

So it maintains all ~~distances~~ vectors within subspace.

[Fact: JL applied to a fine enough net of points in W will give us such a property.]

Suppose W is given by column space of matrix $A \in \mathbb{R}^{n \times d}$. Then can use SVDs to find an embedding of W into \mathbb{R}^d . How?

write $A = UDV^T$ hence $U^T A = D V^T$

$\begin{matrix} U & \xrightarrow{n \times r} \\ \downarrow & \nearrow r \times r \\ n \times r & r \times r \\ (r \leq d) & r \times d \end{matrix}$

Any vector $x \in W$ is a linear combination of columns of A . And U^T has orthonormal columns so $U^T A$ rotates the columns of A into a r -dim subspace. $\| U^T x \| = \| x \|$ $\forall x \in \text{span}(\text{cols}(A))$

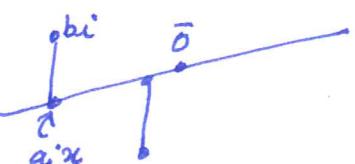
N.b. this is a exact O -subspace embedding]

Least Squares Regression:

Given $A \in \mathbb{R}^{n \times d}$, $b \in \mathbb{R}^n$ want an $x \in \mathbb{R}^d$ st $\min \| Ax - b \|$.

$$= \min \sum_i (a_i^T x - b_i)^2.$$

(useful for solving overconstrained systems.)



Observe that Ax is in column span of A . = UDV^T

so Ax^* is the projection of b onto this column span.

$$\text{Proj}(b) = UU^T b$$

↑ onto $\text{colspan}(A)$ because U is ^{orthonormal} basis for $\text{colspace}(A)$.

$$(\text{alternatively, proj onto } \text{colspace}(A)) = A(A^T A)^{-1} A^T$$

$$\text{hence } x^* = VD^{-1}U^T(UU^T b) = VD^{-1}U^T b.$$

\Rightarrow least squares regression in $SVD(n,d)$ time.

$$\begin{aligned}
 &= UDV^T (V D U^T U D V^T)^{-1} (U D V^T)^T \\
 &= UU^T
 \end{aligned}$$

BTW: If $A = UDV^T$

then $VD^{-1}U^T$ is called the pseudoinverse of A
denoted by A^+

(D^{-1} is really
 D^T , zeros stay)

and it ~~maps~~ ensures that for all vectors in the column space of A ,
 A^+ acts like an inverse! \square

Formally: Restricted to $\text{Colspace}(A^T)$ and $\text{Colspace}(A)$ respectively, the operators A and A^+ are inverses of each other.

Pf: s.p.s $x \in \text{Colspace}(A^T) \Rightarrow x = A^T y$ for some y .

$$\begin{aligned} \text{then } A^T A x - x &= A^T A(A^T y) - A^T y \\ &= V D^T U^T \cdot U D V^T (V D U^T y) - V D U^T y \\ &= V D^T D D U^T y - V D U^T y \\ &= V(D^T D - I) D U^T y = 0 \end{aligned}$$

\checkmark this multiplication gives zero. \square

(Another motivation, of course, from the least squares.)

The pseudoinverses play an important role in Laplacians.

Recall: $L(G) = \text{diag}(\text{degree vector}) - A$

but $L(G) \cdot \mathbf{1} = 0$. since the sum of all rows gives 0.

For a connected graph, the ~~eigenvalues~~ ^{values} of $L(G)$ are $0 = \lambda_0 < \lambda_1 < \dots < \lambda_n$
corresponding to eigenvector $\mathbf{1}$.

{ So can solve linear systems of the form $Lx = b$ as long as $b \perp \mathbf{1}$
(i.e. $\sum_v b_v = 0$).

by $x = L^+ b$. (gives potentials corresponding to electrical flow demands)

Fact: Also, can do calculations and show: $L^T L = LL^T = I_n - \frac{1}{n} J$.

\Rightarrow for any vector $b \perp \mathbf{1}$, $LL^T b = b$ since $bJ = 0$.