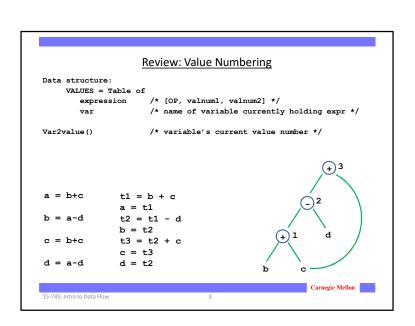
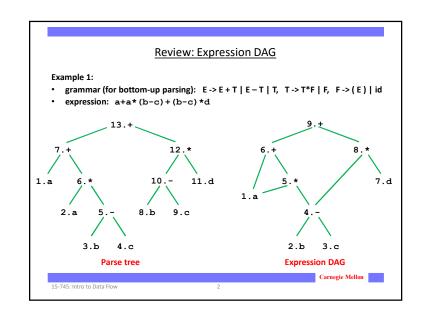
Lecture 5 Introduction to Data Flow Analysis I. Structure of data flow analysis II. Example 1: Reaching definition analysis III. Example 2: Liveness analysis IV. Framework Carnegie Mellon Phillip B. Gibbons 15-745: Intro to Data Flow 1





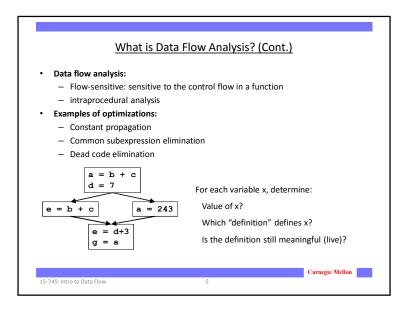
What is Data Flow Analysis?

- Local analysis (e.g. value numbering)
 - analyze effect of each instruction
 - compose effects of instructions to derive information from beginning of basic block to each instruction
- · Data flow analysis
 - analyze effect of each basic block
 - compose effects of basic blocks to derive information at basic block boundaries
 - from basic block boundaries, apply local technique to generate information on instructions

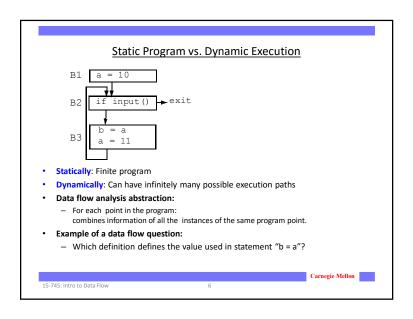
[ALSU 9.2]

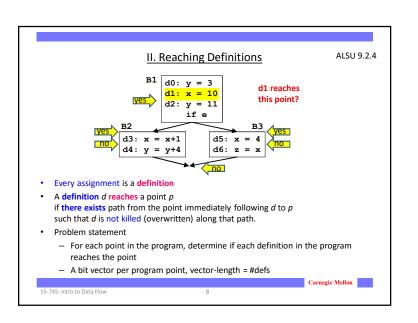
15-745: Intro to Data Flow

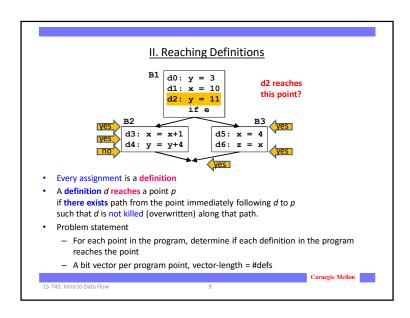
Carnegie Mellon

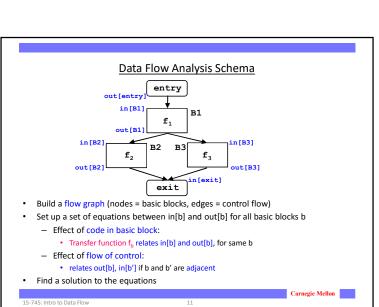


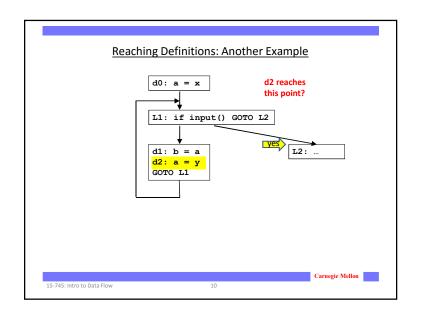
Effects of a Basic Block • Effect of a statement: a = b+c • Uses variables (b, c) · Kills an old definition (old definition of a) new definition (a) Compose effects of statements -> Effect of a basic block • A locally exposed use in a b.b. is a use of a data item which is not preceded in the b.b. by a definition of the data item • any definition of a data item in the basic block kills all definitions of the same data item reaching the basic block. • A locally available definition = last definition of data item in b.b. t1 = r1+r2r2 = t1t2 = r2+r1r1 = t2t3 = r1*r1r2 = t3if r2>100 goto L1 Carnegie Mellon 15-745: Intro to Data Flow

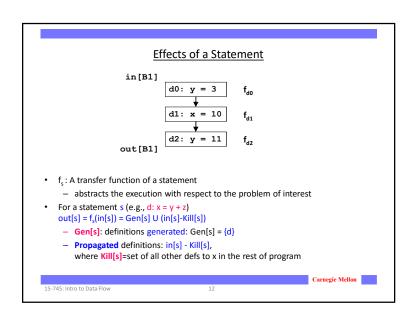


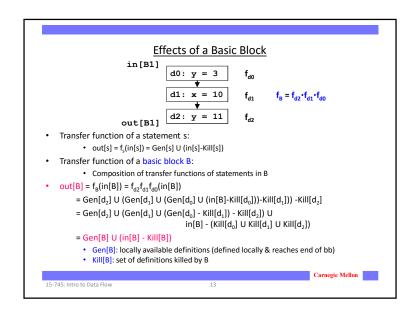


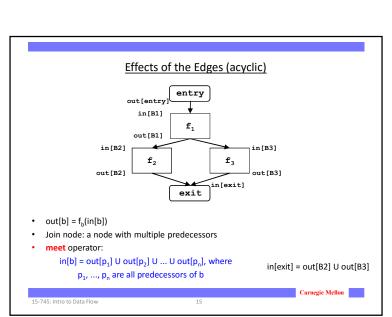


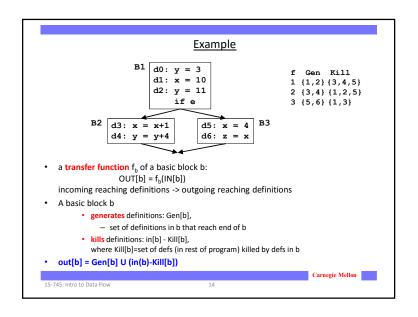


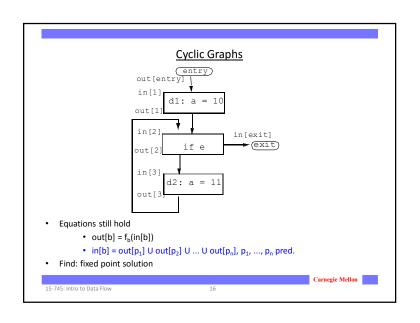












```
Reaching Definitions: Iterative Algorithm

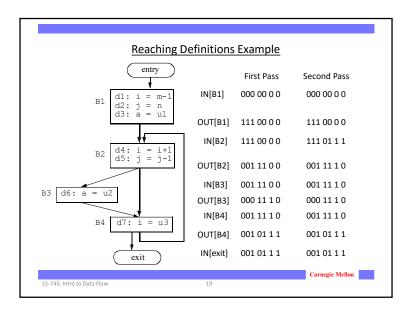
input: control flow graph CFG = (N, E, Entry, Exit)

// Boundary condition
out[Entry] = Ø

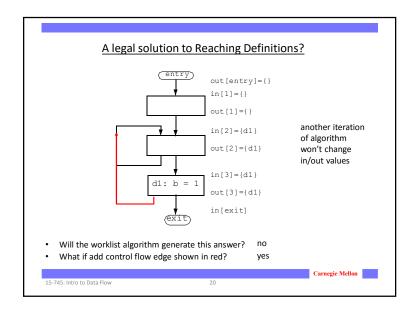
// Initialization for iterative algorithm
For each basic block B other than Entry
out[B] = Ø

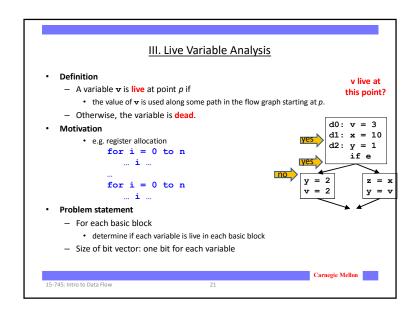
// iterate
While (Changes to any out[] occur) {
For each basic block B other than Entry {
   in[B] = U (out[p]), for all predecessors p of B
   out[B] = f_B(in[B]) // out[B]=gen[B]U(in[B]-kill[B])
}

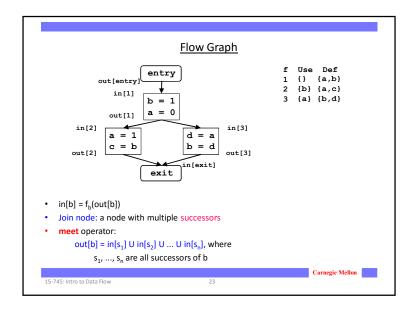
Carnegie Mellon
```



Reaching Definitions: Worklist Algorithm input: control flow graph CFG = (N, E, Entry, Exit) out[Entry] = Ø // can set out[Entry] to special def // if reaching then undefined use For all nodes i $out[i] = \emptyset$ // can optimize by out[i]=gen[i] ChangedNodes = N // iterate While ChangedNodes ≠ Ø { Remove i from ChangedNodes in[i] = U (out[p]), for all predecessors p of i oldout = out[i] out[i] = f; (in[i]) // out[i]=gen[i]U(in[i]-kill[i]) if (oldout # out[i]) { for all successors s of i add s to ChangedNodes 1 Carnegie Mellon 15-745: Intro to Data Flow







```
Effects of a Basic Block (Transfer Function)
· Insight: Trace uses backwards to the definitions
       an execution path
                                       control flow
                                                                 example
                                                                 d3: a = 1
                                                = f_b(OUT[b])
                                                                 d4: b = 1
                       def
                                                                 d5: c = a
                                     OUT[b]
                                                                 d6: a = 4
                                                          IN[b] = {a} U (OUT[b] - {a,c})
· A basic block b can
         • generate live variables: Use[b]
              - set of locally exposed uses in b
         • propagate incoming live variables: OUT[b] - Def[b],
              - where Def[b]= set of variables defined in b.b.

    transfer function for block b:

                   in[b] = Use[b] U (out(b)-Def[b])
                                                                    Carnegie Mellon
15-745: Intro to Data Flow
```

```
Liveness: Iterative Algorithm

input: control flow graph CFG = (N, E, Entry, Exit)

// Boundary condition
in[Exit] = Ø

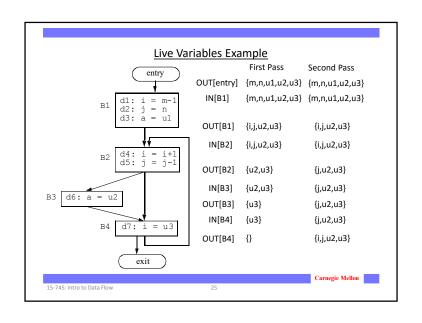
// Initialization for iterative algorithm
For each basic block B other than Exit
in[B] = Ø

// iterate

While (Changes to any in[] occur) {
For each basic block B other than Exit {
out[B] = U (in[s]), for all successors s of B
in[B] = f_B(out[B]) // in[B]=Use[B]U(out[B]-Def[B])
}

15-745: Intro to Data Flow

24
```



		Reaching Definitions	Live Variables
	Domain	Sets of definitions	Sets of variables
Meet Operation (\land) \cup \cup Boundary Condition out[entry] = \varnothing in[exit] = \varnothing in[b] = \varnothing Other Data Flow Analysis problems fit into this general framework,	Direction	$out[b] = f_b(in[b])$	$in[b] = f_b(out[b])$
Boundary Condition $\text{out}[\text{entry}] = \varnothing$ $\text{in}[\text{exit}] = \varnothing$ $\text{In}[\text{tial interior points}]$ $\text{out}[b] = \varnothing$ $\text{in}[b] = \varnothing$ Other Data Flow Analysis problems fit into this general framework,	Transfer function	$f_b(x) = Gen_b \cup (x - Kill_b)$	$f_b(x) = Use_b \cup (x - Def_b)$
Initial interior points $ out[b] = \varnothing $	Meet Operation (∧)	U	U
Other Data Flow Analysis problems fit into this general framework,	Boundary Condition	out[entry] = Ø	in[exit] = Ø
			: 0.1 0
Carnegie Mell	Initial interior points	out[b] = ∅	in[b] = Ø

• Correctness • equations are satisfied, if the program terminates. • Precision: how good is the answer? • is the answer ONLY a union of all possible executions? • Convergence: will the analysis terminate? • or, will there always be some nodes that change? • Speed: how fast is the convergence? • how many times will we visit each node? Carnegie Mellon

