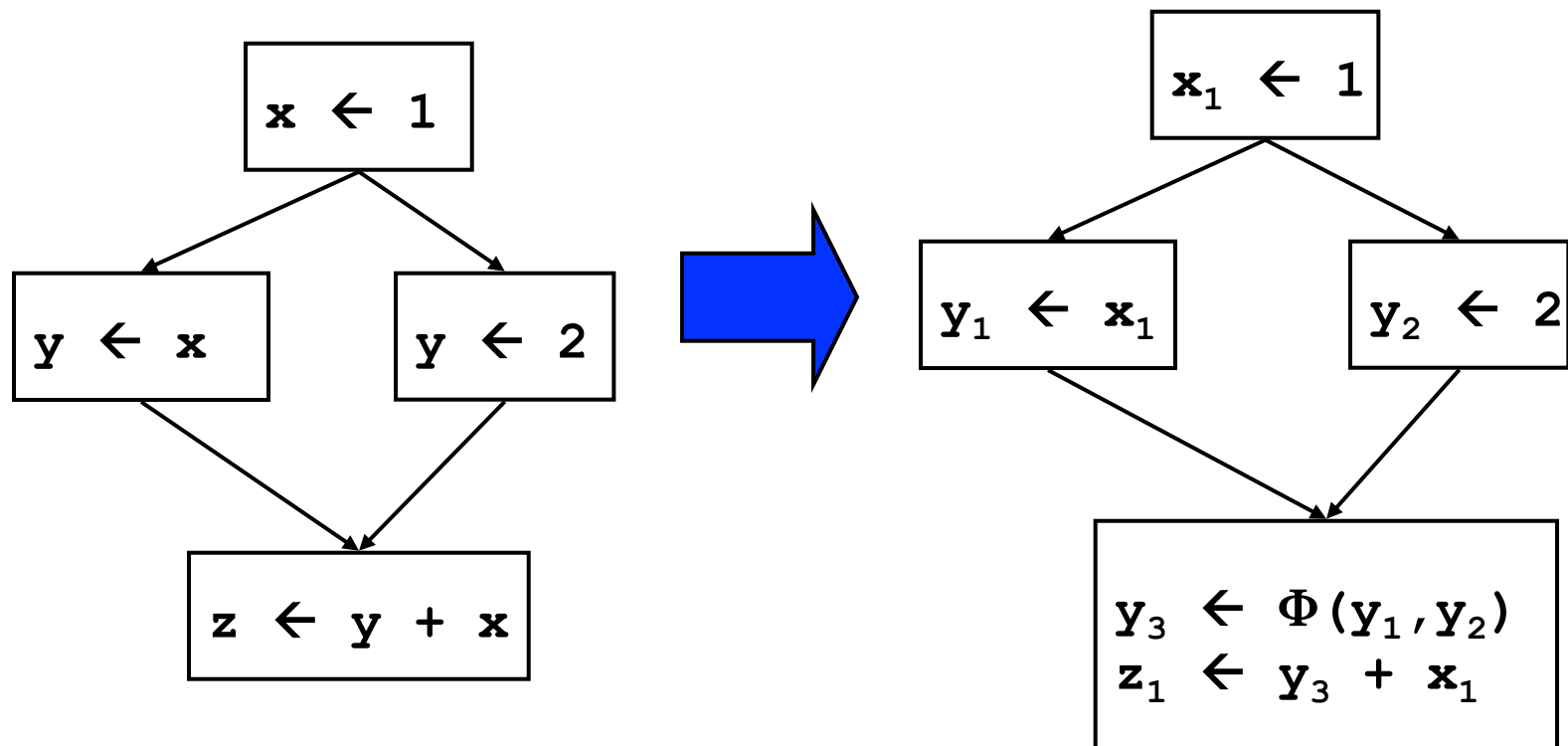


SSA-Style Optimizations

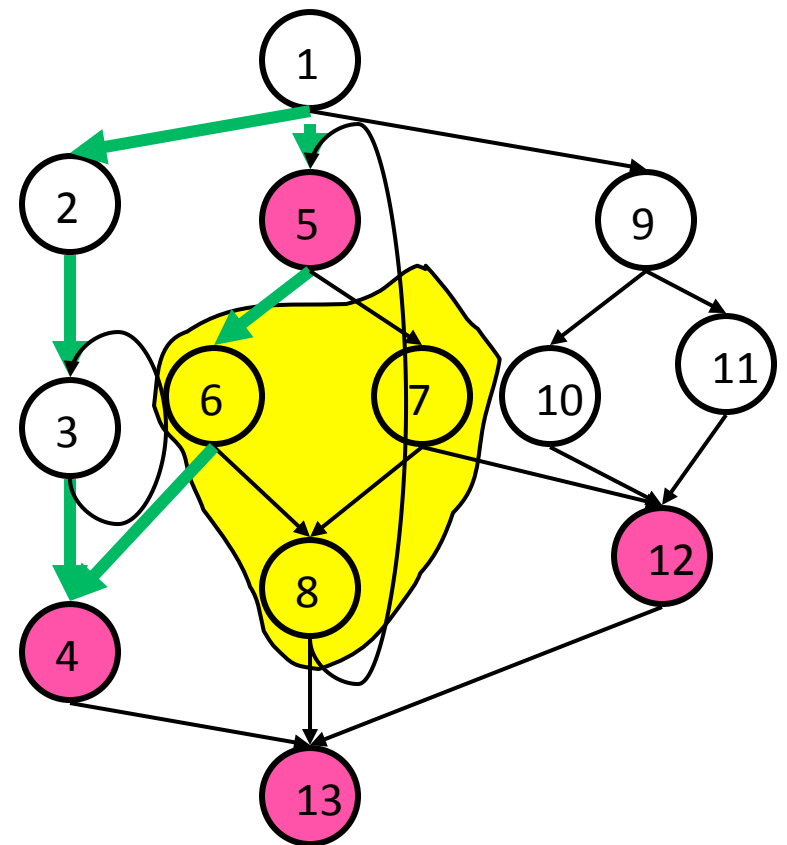
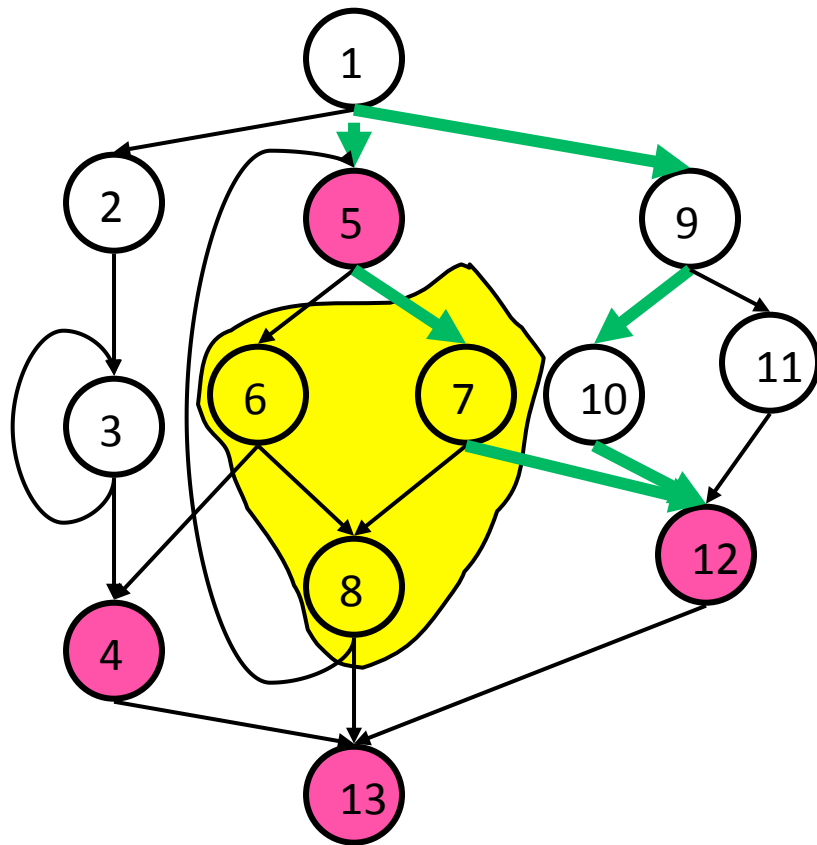
(Slide content courtesy of Seth Goldstein.)

Review: Minimal SSA

- Each assignment generates a fresh variable.
- At each join point insert Φ functions for all **live variables** with **multiple outstanding defs**.



Review: Dominance Frontier and Path Convergence



Constant Propagation

- If “ $v \leftarrow c$ ”, replace all uses of v with c
- If “ $v \leftarrow \Phi(c, c, c)$ ” (each input is the same constant), replace all uses of v with c

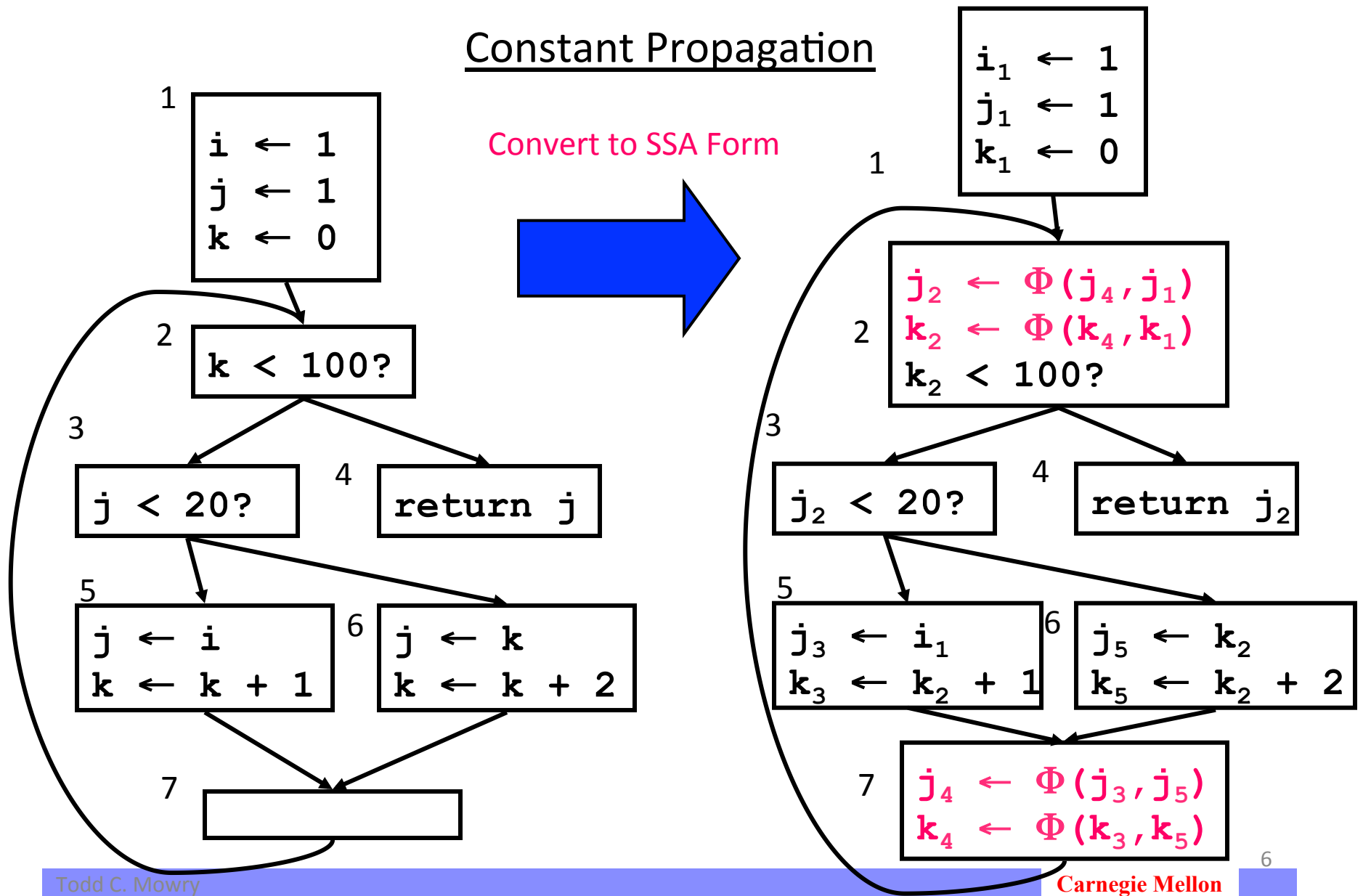
```
W ← list of all defs
while !W.isEmpty {
    Stmt S ← W.removeOne
    if ((S has form " $v \leftarrow c$ ") ||
        (S has form " $v \leftarrow \Phi(c, \dots, c)$ ")) then {
        delete S
        foreach stmt U that uses  $v$  {
            replace  $v$  with  $c$  in U
        }
        W.add(U)
    }
}
```

Other Optimizations with SSA

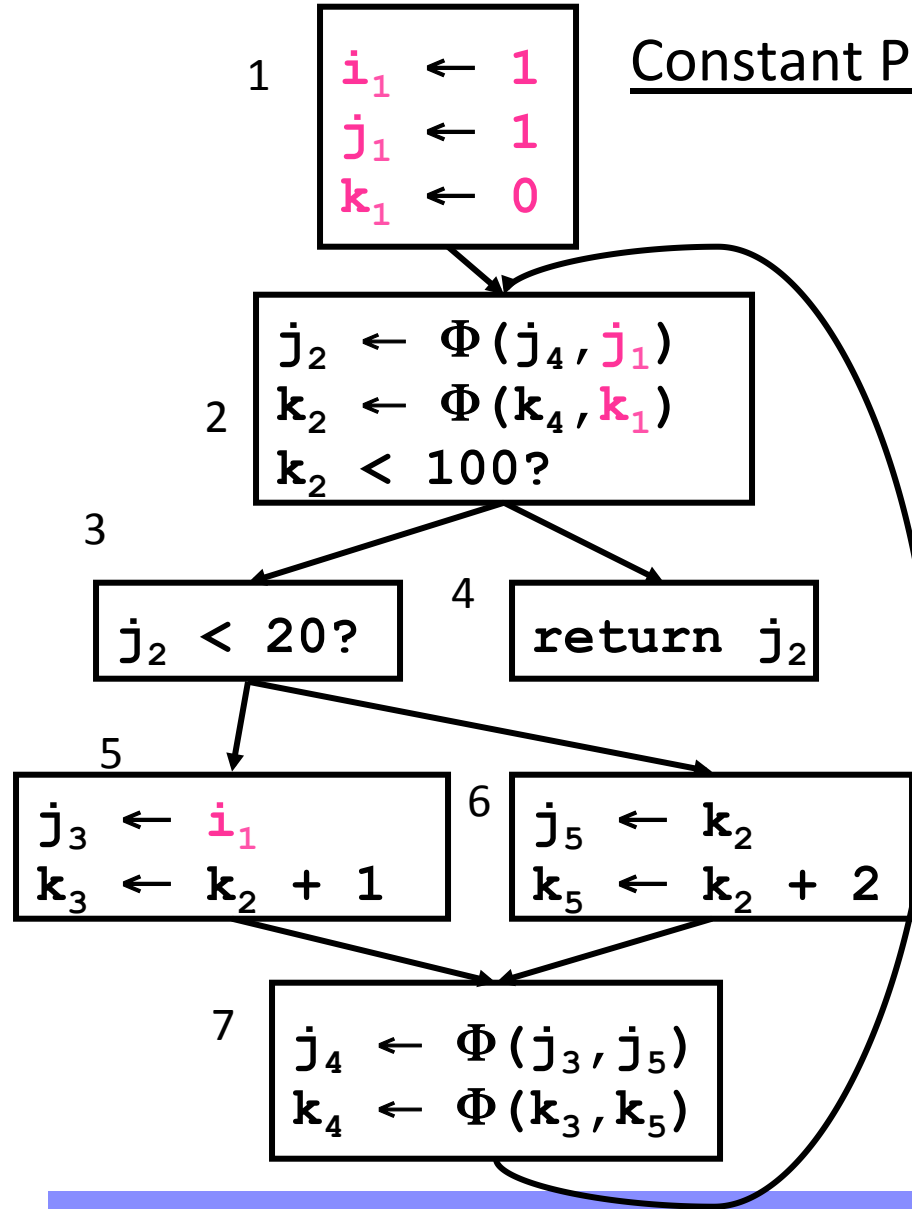
- Copy propagation
 - delete “ $x \leftarrow \Phi(y,y,y)$ ” and replace all x with y
 - delete “ $x \leftarrow y$ ” and replace all x with y
- Constant Folding
 - (Also, constant conditions too!)

Constant Propagation

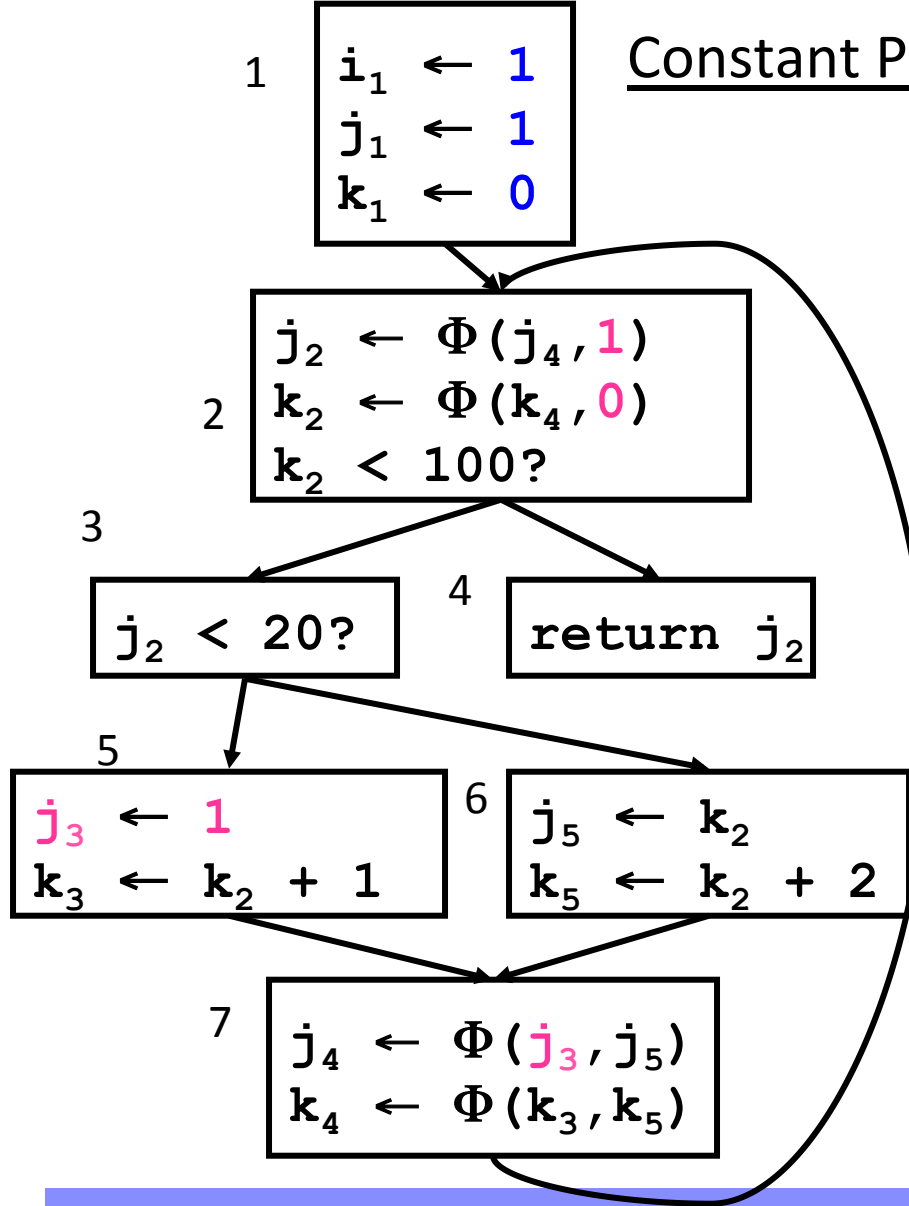
Convert to SSA Form



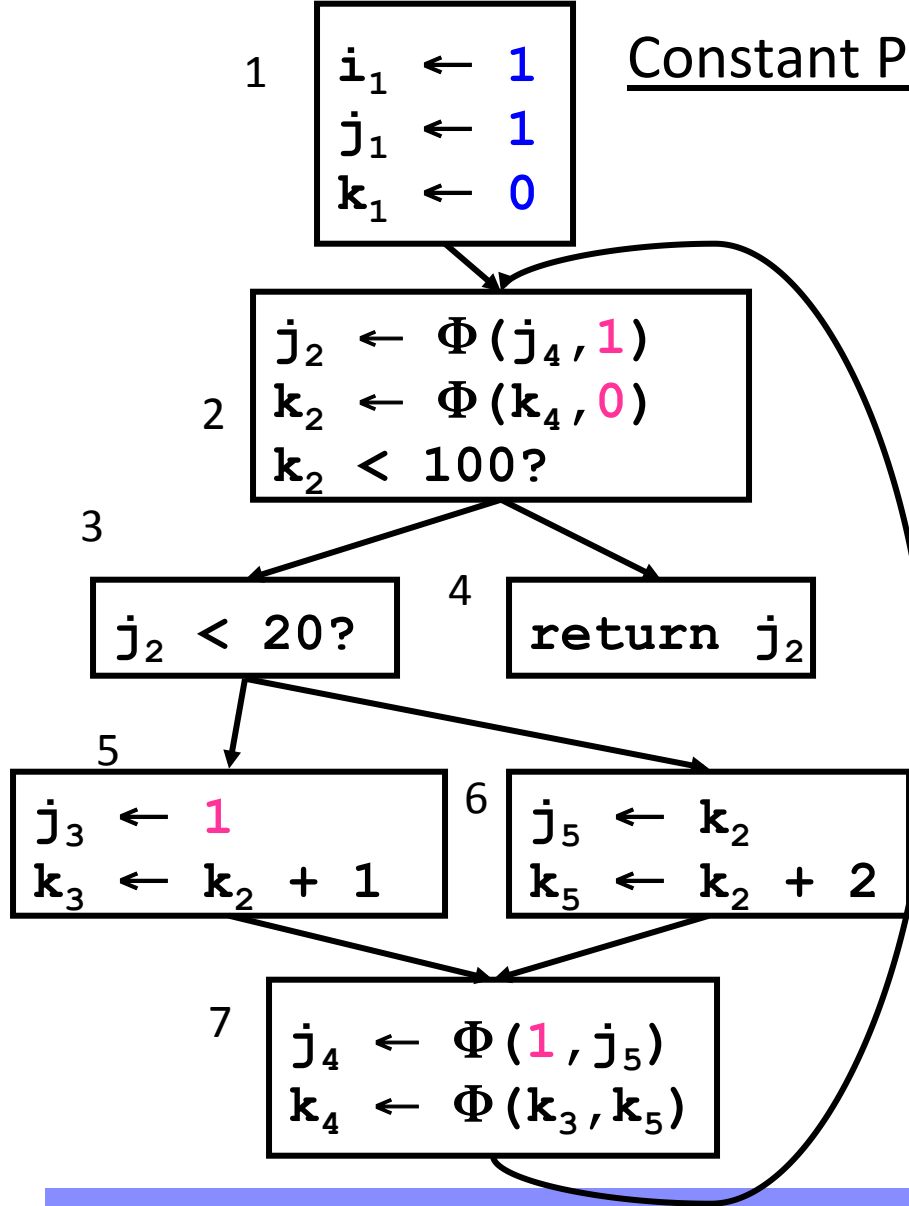
Constant Propagation



Constant Propagation

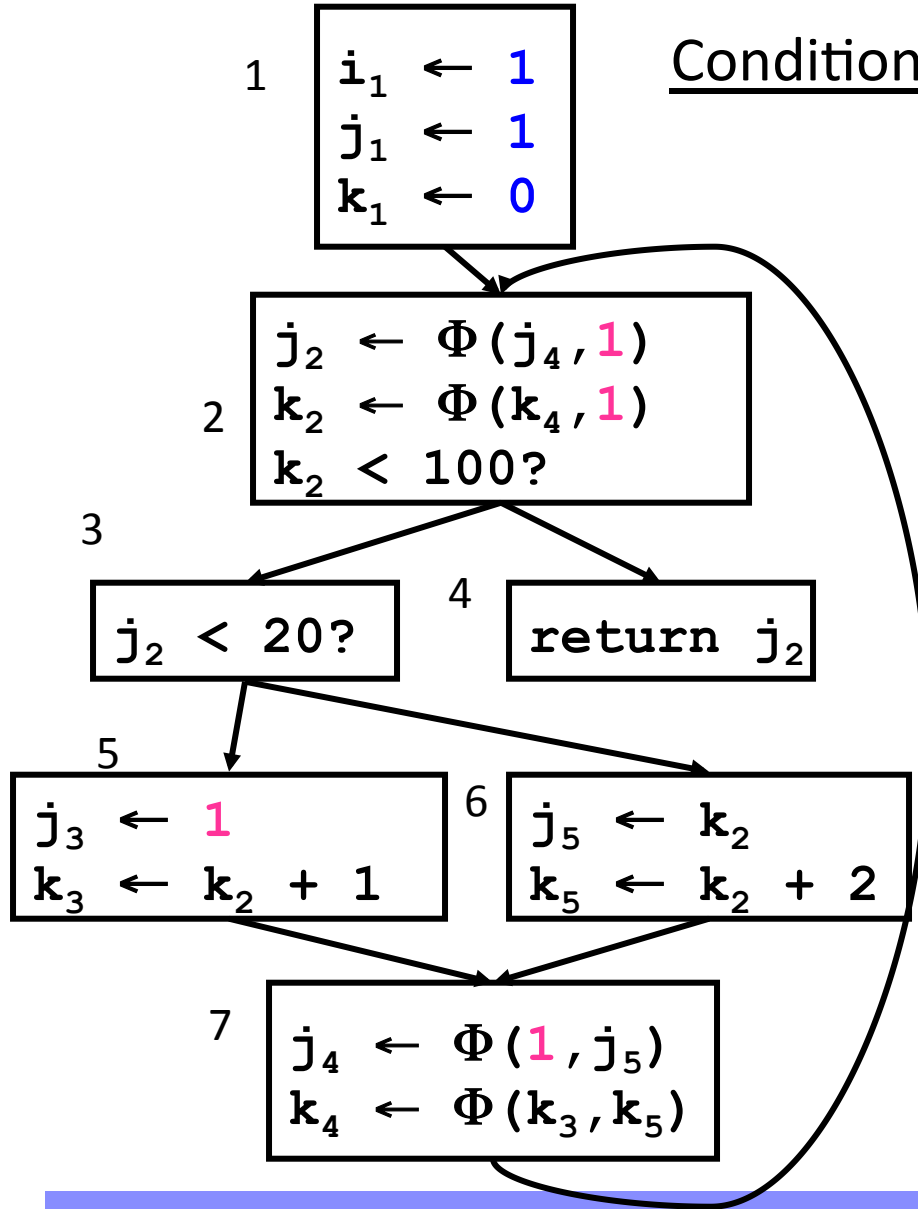


Constant Propagation



Not a very exciting result (yet)...

Conditional Constant Propagation



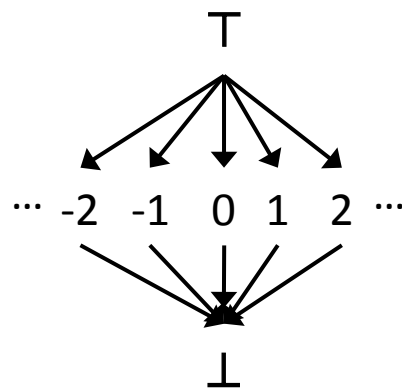
- Does block 6 ever execute?
- Simple Constant Propagation can't tell
- But "Conditional Const. Prop." *can* tell:
 - Assumes **blocks don't execute** until proven otherwise
 - Assumes **values are constants** until proven otherwise

Conditional Constant Propagation Algorithm

Keeps track of:

- **Blocks**
 - assume unexecuted until proven otherwise
- **Variables**
 - assume not executed (only with proof of assignments of a non-constant value do we assume not constant)

Lattice for representing variables:

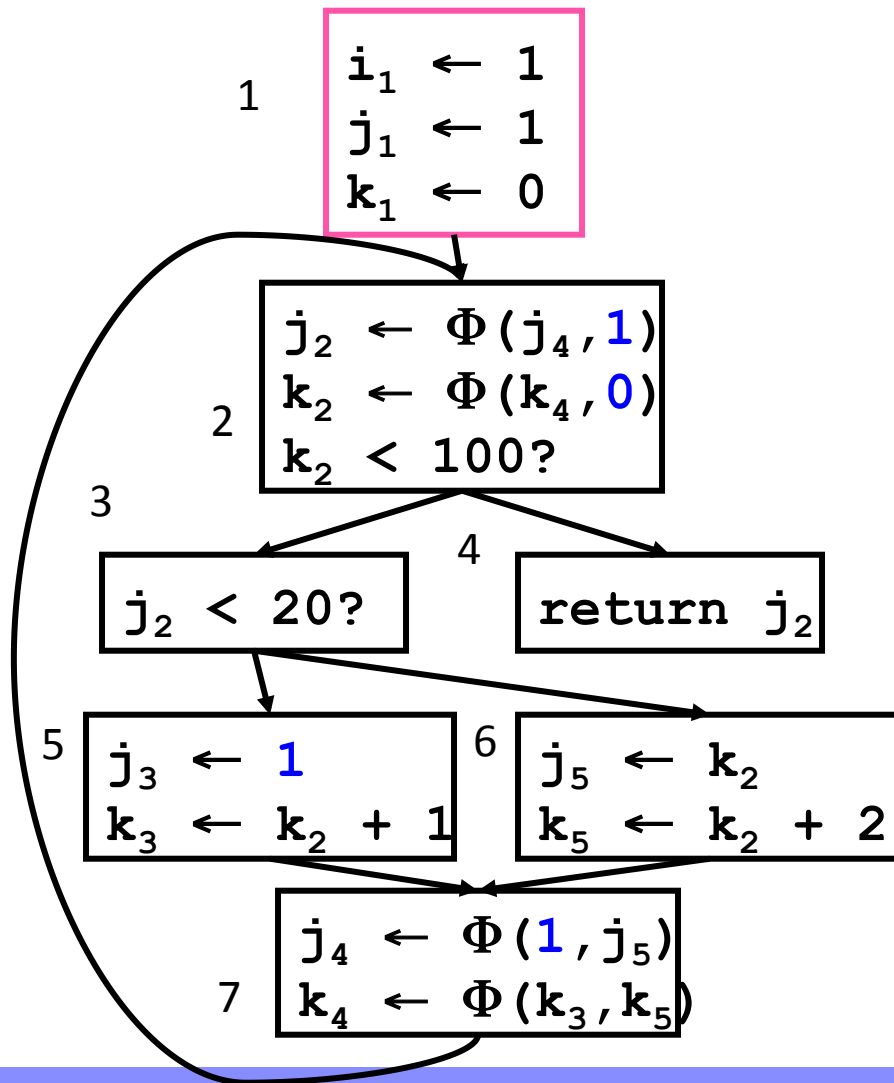


not executed

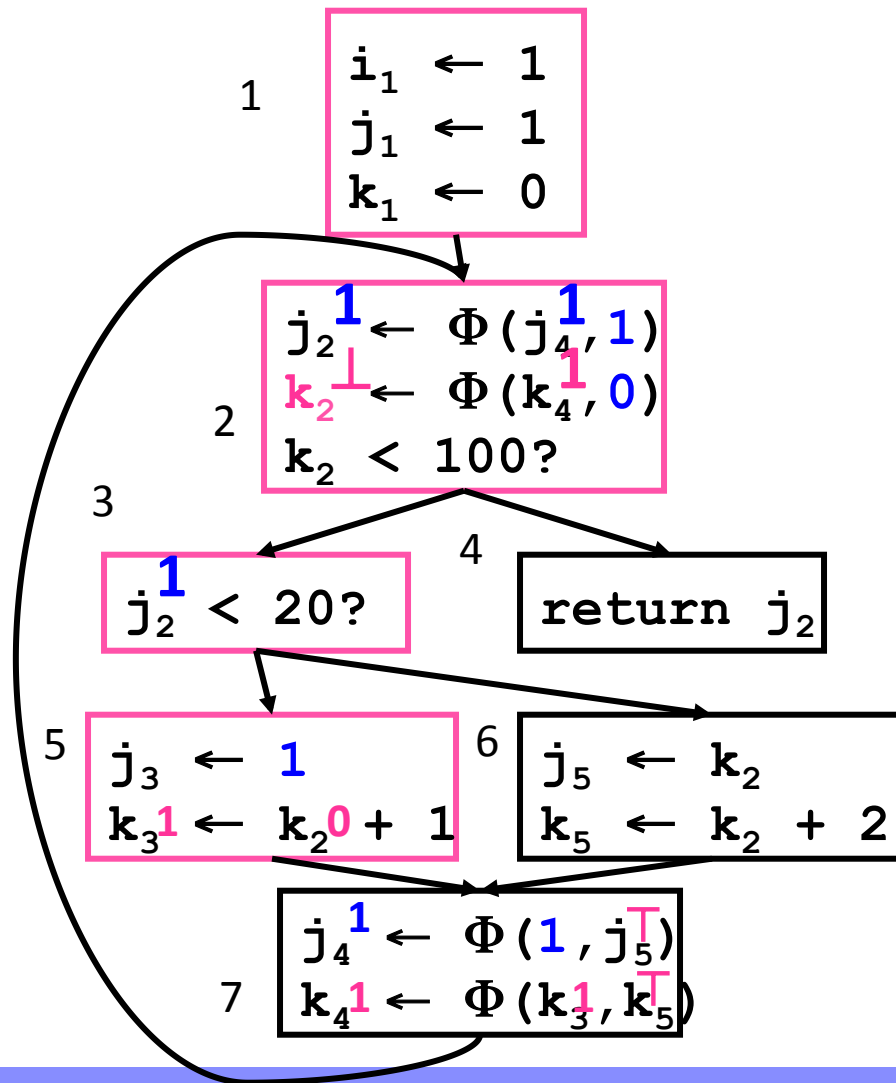
we have seen **evidence** that the variable has been **assigned a constant** with the value

we have seen **evidence** that the variable **can hold different values** at different times

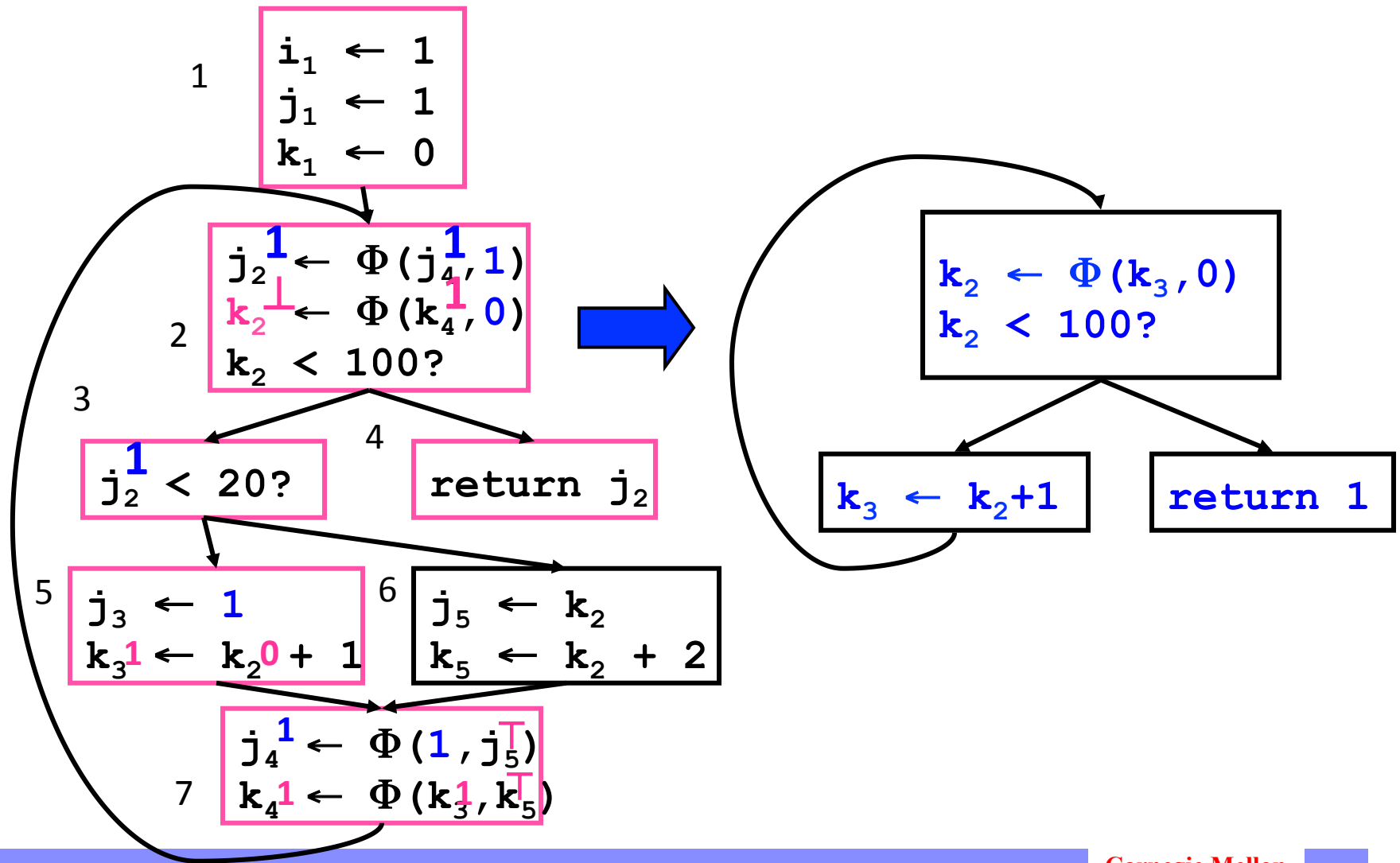
Conditional Constant Propagation



Conditional Constant Propagation



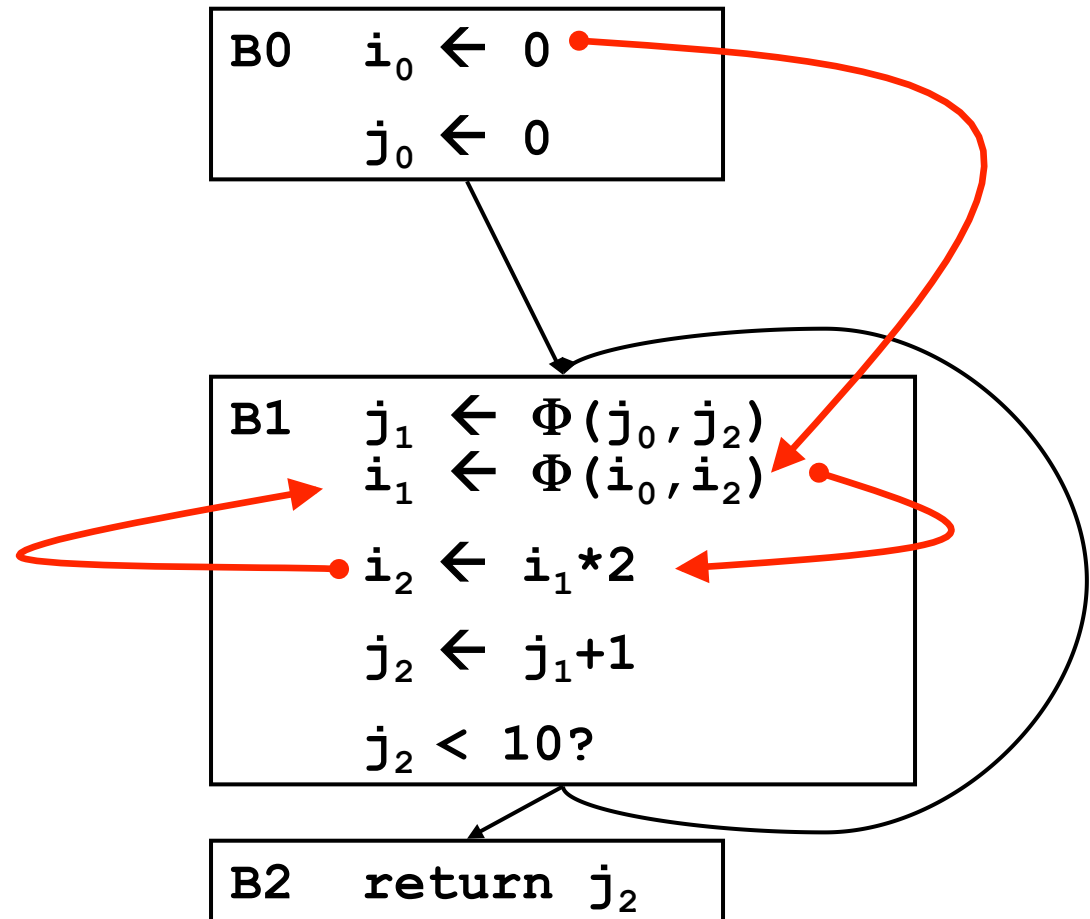
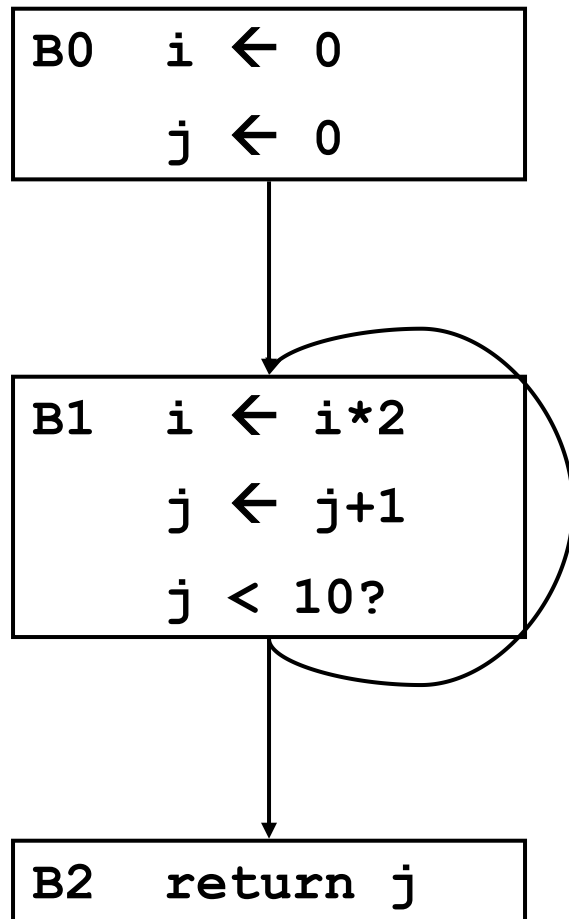
Conditional Constant Propagation



Dead Code Elimination

```
W ← list of all defs
while !W.isEmpty {
    Stmt S ← W.removeOne
    if |S.users| != 0 then continue
    if S.hasSideEffects() then continue
    foreach def in S.operands.definers {
        def.users ← def.users - {S}
        if |def.users| == 0 then
            W ← W UNION {def}
    }
    delete S
}
```

Example DCE



Standard DCE leaves Zombies!

Aggressive Dead Code Elimination

Assume a statement is dead until proven otherwise.

init:

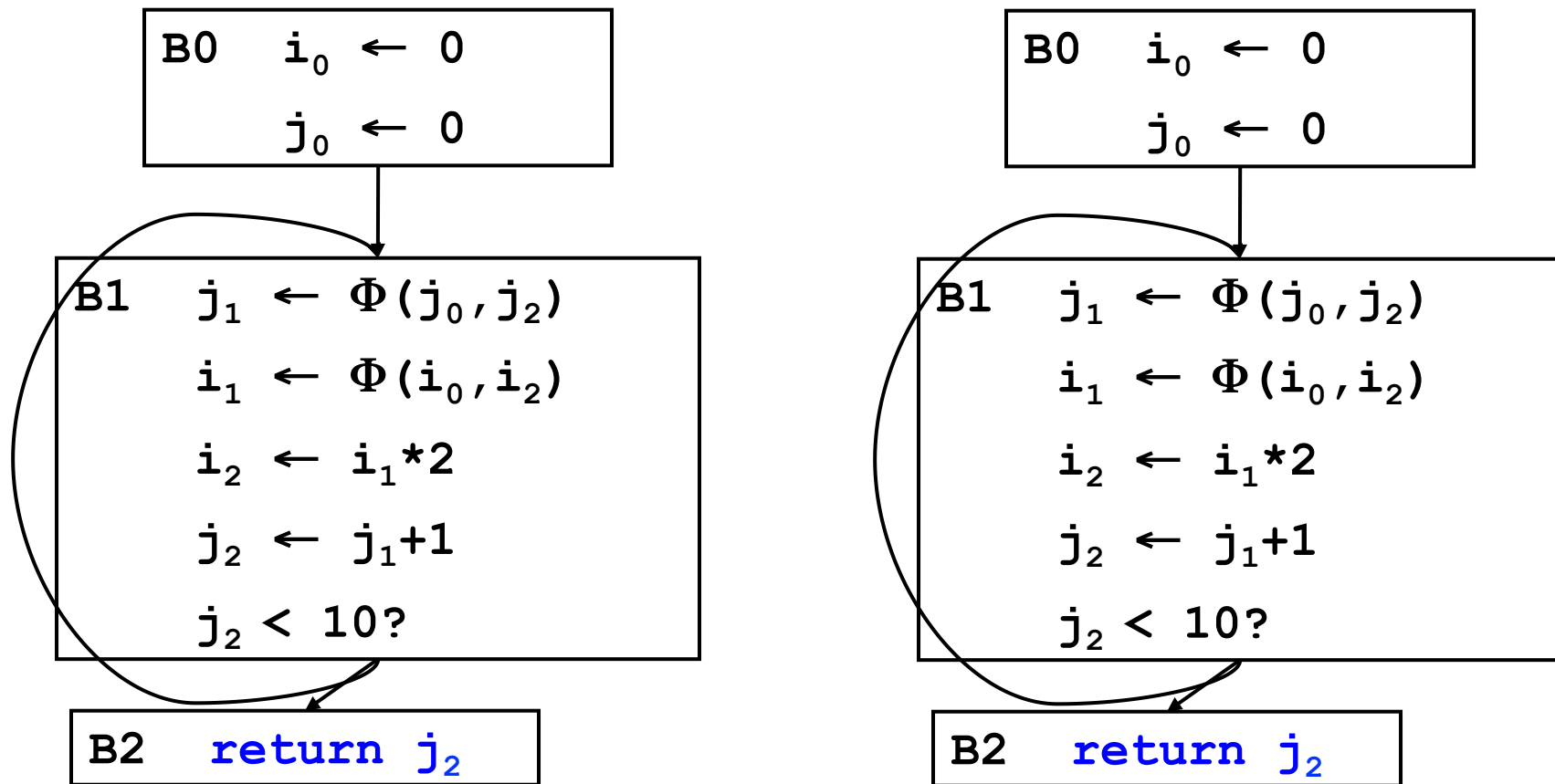
mark as **live** all stmts that have **side-effects**:

- I/O
- stores into memory
- returns
- calls a function that MIGHT have side-effects

As we mark S live, **insert S.operands.definers into W**

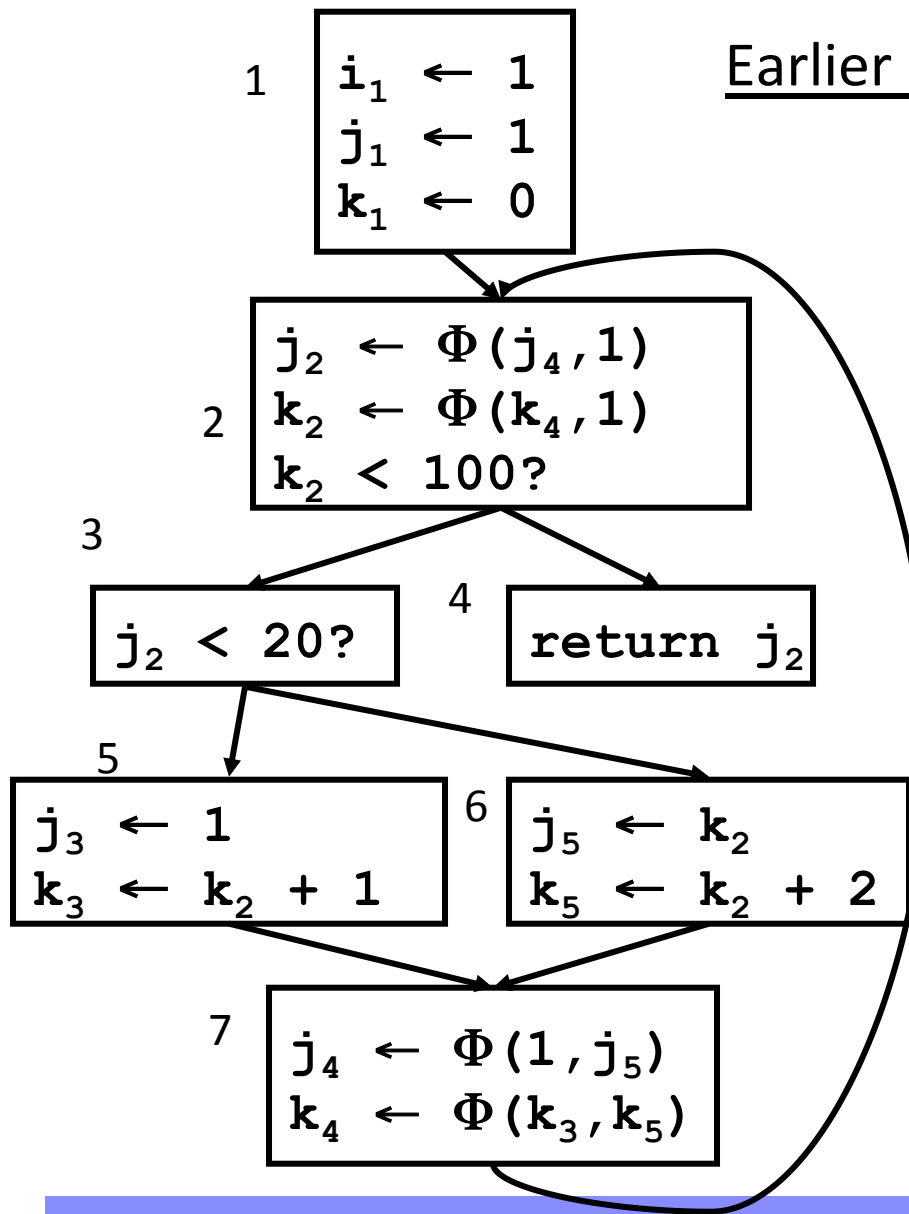
```
while (|W| > 0) {  
  S <- W.removeOne()  
  if (S is live) continue;  
  mark S live, insert S.operands.definers into W  
}
```

Example DCE



Problem!

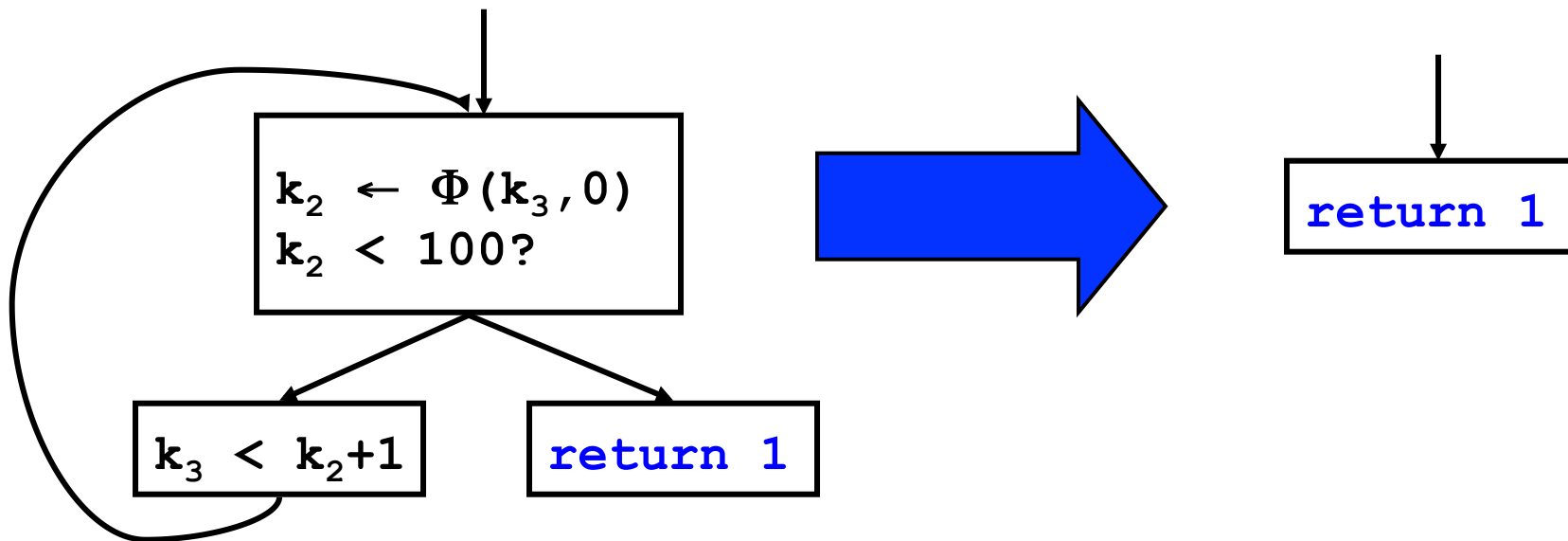
Earlier CCP Example Revisited



Applying Dead Code Elimination to the Result of CCP

After CCP

After DCE

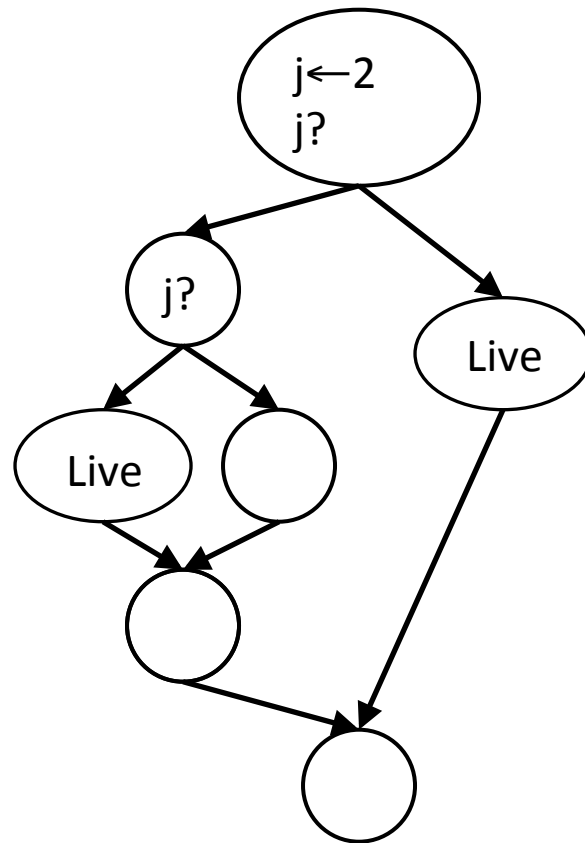


Small problem.

Fixing DCE

if S is live, then

if T determines if S can execute, T should be live

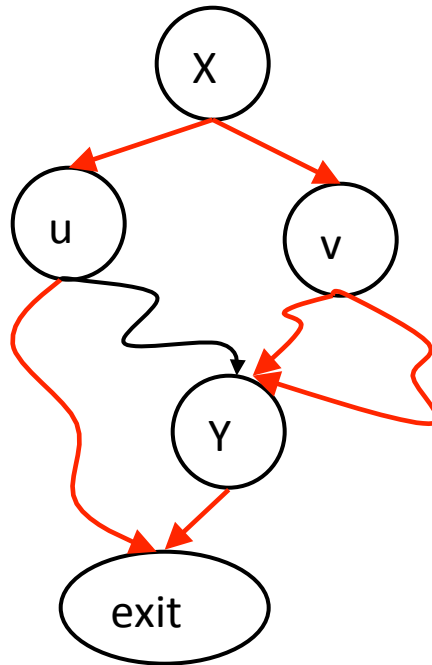


Control Dependence

Y is control-dependent on X if

- X branches to u and v
- $\exists$ a path $u \rightarrow \text{exit}$ which does not go through Y
- $\forall$ paths $v \rightarrow \text{exit}$ go through Y

i.e. X can determine whether or not Y is executed.



Aggressive Dead Code Elimination (Fixed Version)

Assume a statement is dead until proven otherwise.

init:

mark as live all stmts that have side-effects:

- I/O
- stores into memory
- returns
- calls a function that MIGHT have side-effects

As we mark S live, insert:

- S.operands.definers into W
- $S.CD^{-1}$ into W

while ($|W| > 0$) {

S ← W.removeOne()

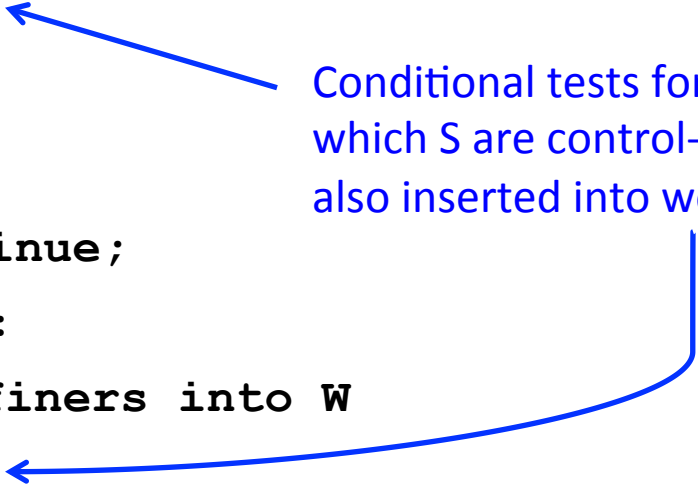
if (S is live) continue;

mark S live, insert:

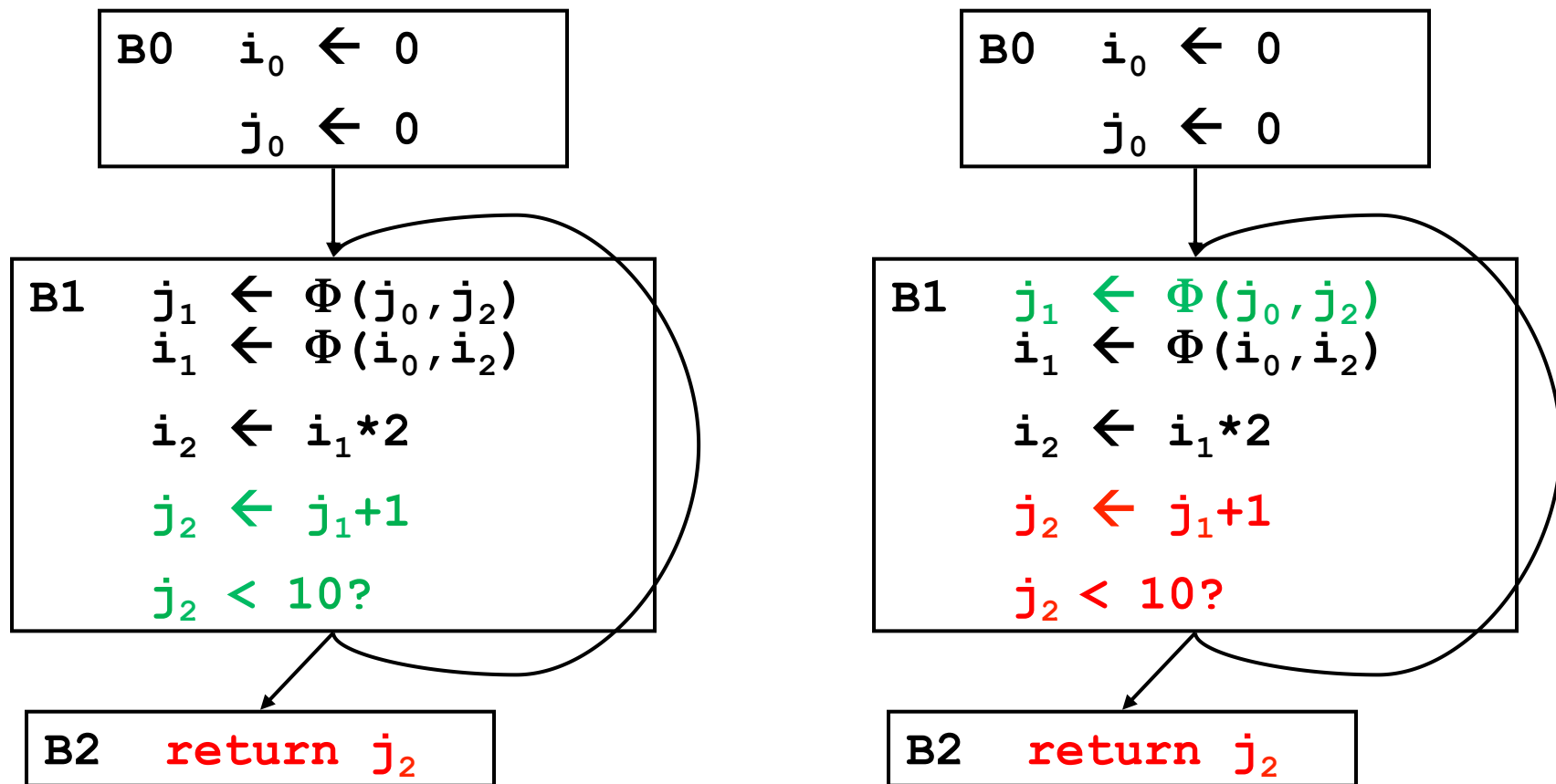
- S.operands.definers into W
- $S.CD^{-1}$ into W

}

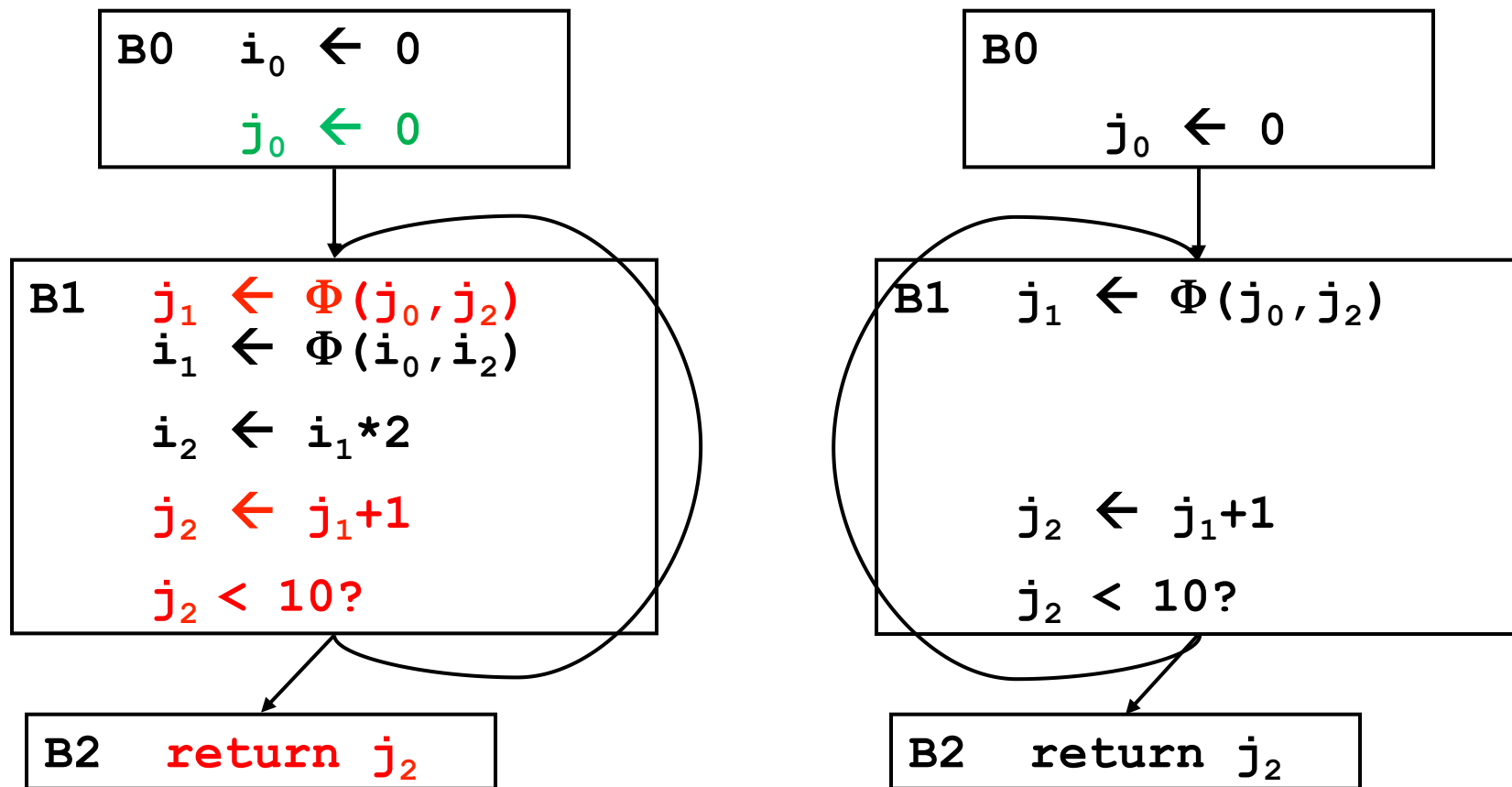
Conditional tests for blocks upon which S are control-dependent are also inserted into work-list.



Example DCE



Example DCE

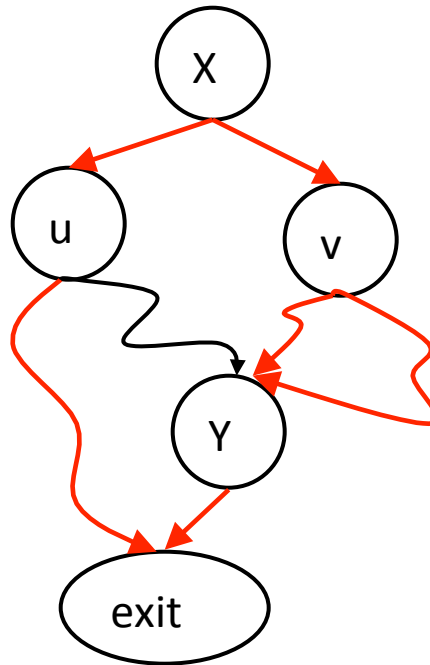


Finding the Control Dependence Graph

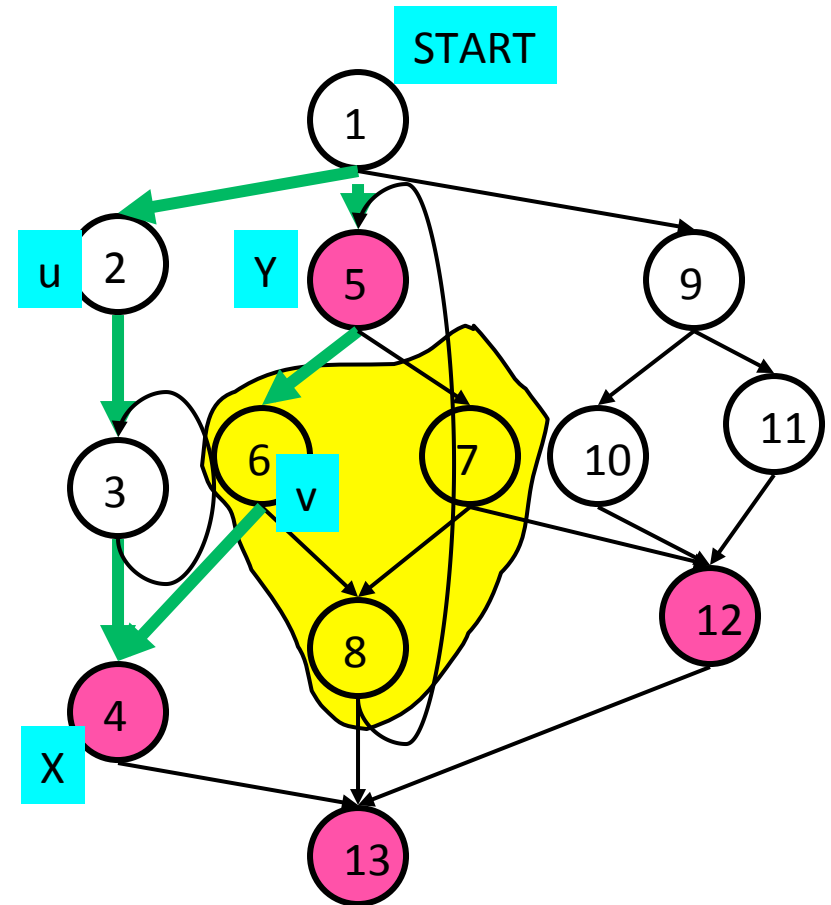
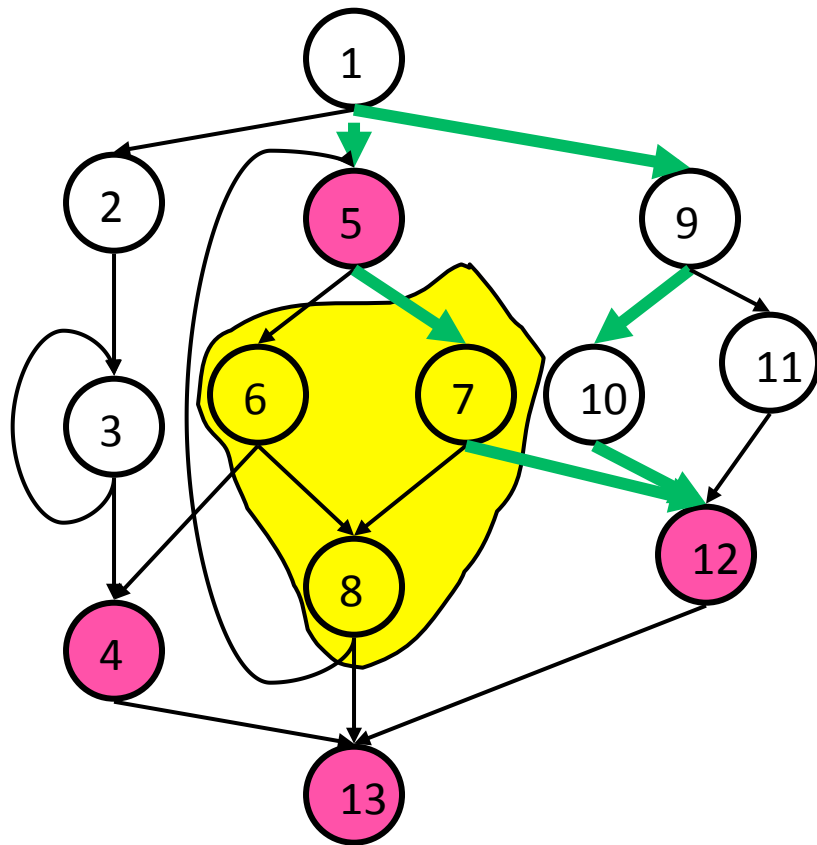
Y is control-dependent on X if

- X branches to u and v
- $\exists$ a path $u \rightarrow \text{exit}$ which does not go through Y
- $\forall$ paths $v \rightarrow \text{exit}$ go through Y

i.e. X can determine whether or not Y is executed.



Dominance Frontier and Path Convergence



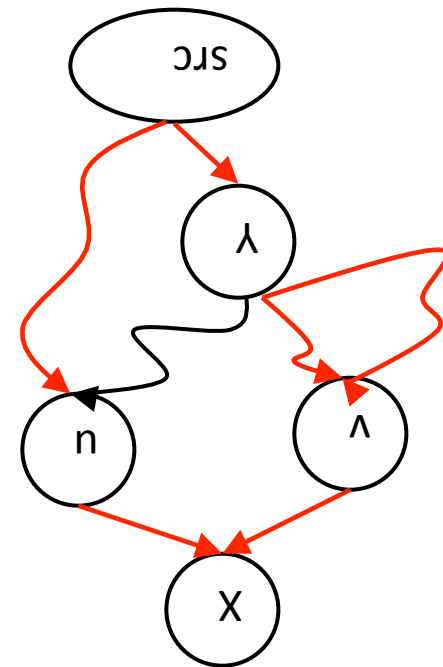
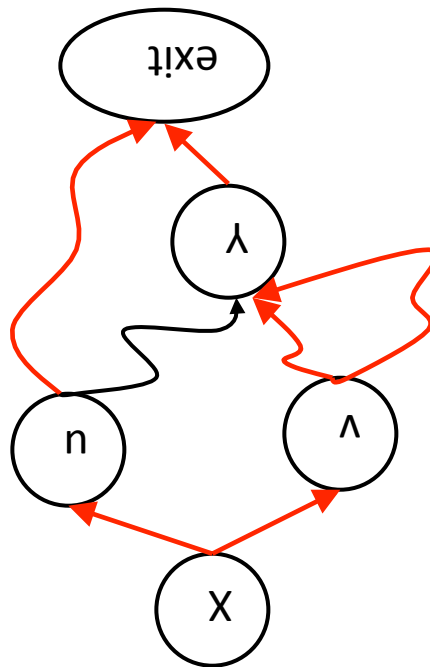
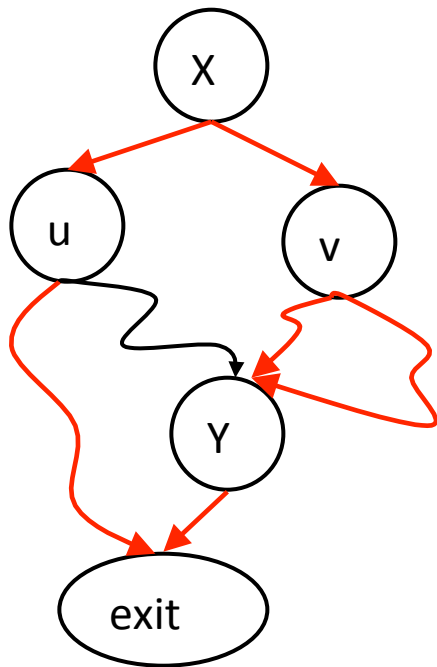
Any ideas?

Finding the Control Dependence Graph

Y is control-dependent on X if

- X branches to u and v
- $\exists$ a path $u \rightarrow \text{exit}$ which does not go through Y
- $\forall$ paths $v \rightarrow \text{exit}$ go through Y

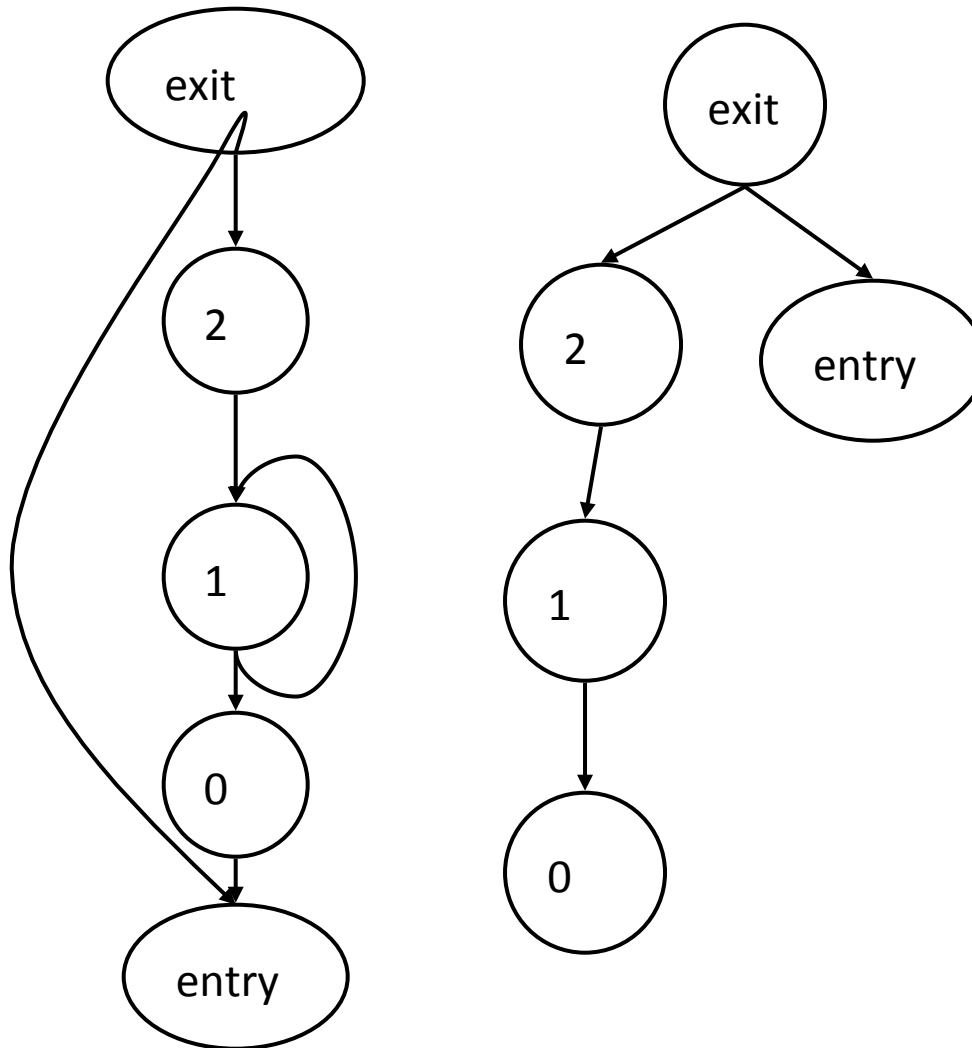
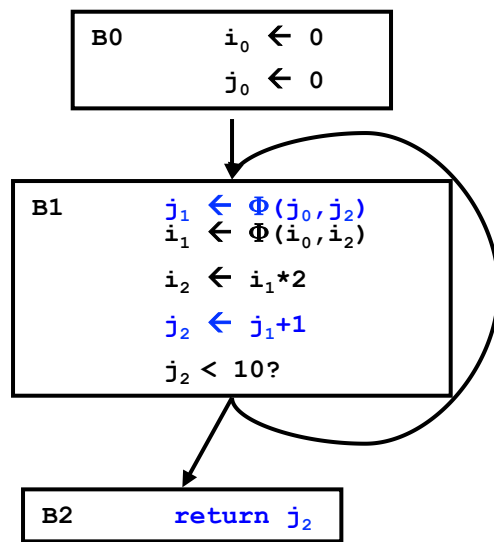
i.e. X can determine whether or not Y is executed.



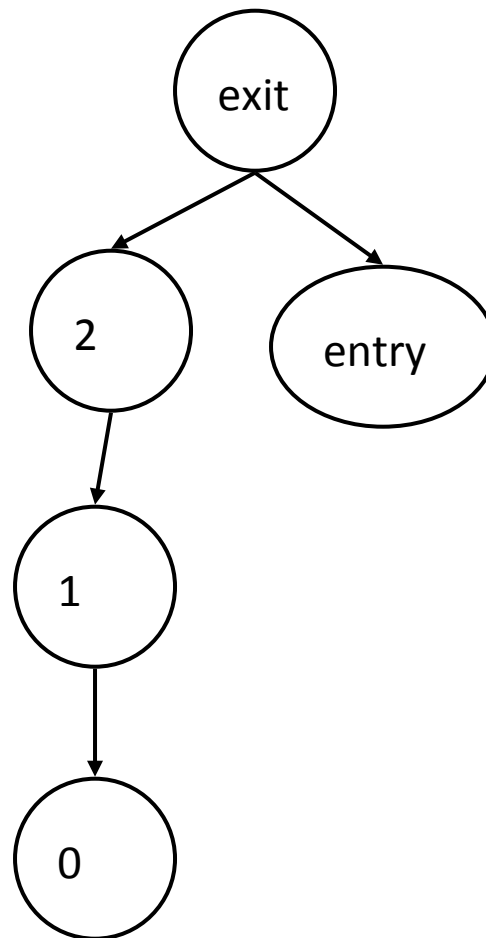
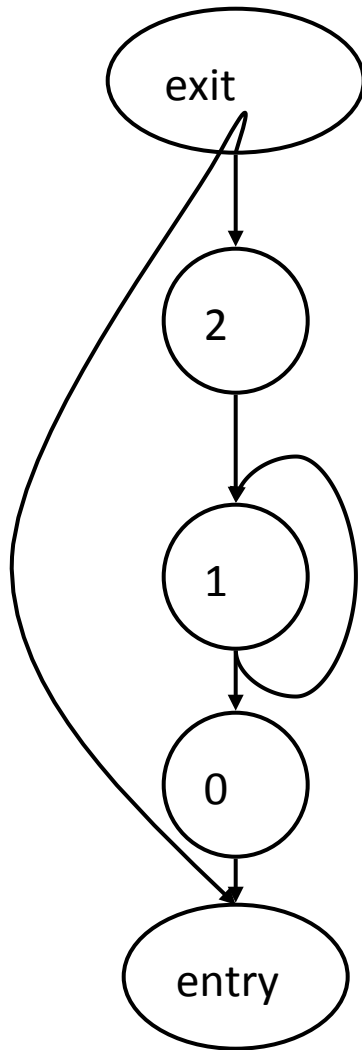
Finding the CDG

- Construct CFG
- Add entry node and exit node
- Add (entry,exit)
- Create G' , the reverse CFG
- Compute D-tree in G' (post-dominators of G)
- Compute $DF_{G'}(y)$ for all $y \in G'$ (post-DF of G)
- Add $(x,y) \in G$ to CDG if $x \in DF_{G'}(y)$

CDG of example



CDG of example



exit:	{}
2:	{entry}
1:	{1,entry}
0:	{entry}
entry:	{}