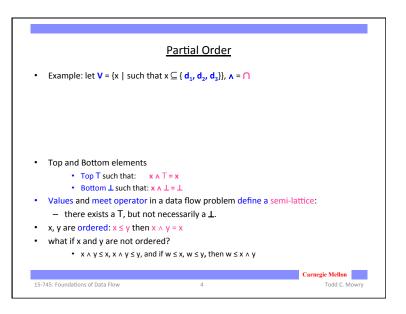
Lecture 5 Foundations of Data Flow Analysis I. Meet operator II. Transfer functions III. Correctness, Precision, Convergence IV. Efficiency *Reference: ALSU pp. 613-631 *Background: Hecht and Ullman, Kildall, Allen and Cocke[76] *Marlowe & Ryder, Properties of data flow frameworks: a unified model. Rutgers tech report, Apr. 1988 **Carnegie Mellon** **Carnegie Mellon** **Todd C. Mowry** **Lodd C. Mowry**

I. Meet Operator Properties of the meet operator commutative: x ∧ y = y ∧ x idempotent: x ∧ x = x associative: x ∧ (y ∧ z) = (x ∧ y) ∧ z there is a Top element T such that x ∧ T = x Meet operator defines a partial ordering on values x ≤ y if and only if x ∧ y = x Transitivity: if x ≤ y and y ≤ z then x ≤ z Antisymmetry: if x ≤ y and y ≤ x then x = y Reflexitivity: x ≤ x

A Unified Framework • Data flow problems are defined by • Domain of values: V • Meet operator (∨ ∧ ∨ → ∨), initial value • A set of transfer functions (∨ → ∨) • Usefulness of unified framework • To answer questions such as correctness, precision, convergence, speed of convergence for a family of problems — If meet operators and transfer functions have properties X, then we know Y about the above. • Reuse code Carnegie Mellon 15-745: Foundations of Data Flow 2 Todd C. Mowry

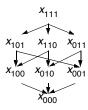


One vs. All Variables/Definitions

· Lattice for each variable: e.g. intersection



Lattice for three variables:



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II. Transfer Functions

- Basic Properties f: V → V
 - Has an identity function
 - There exists an f such that f(x) = x, for all x.
 - Closed under composition
 - if $f_1, f_2 \in F$, then $f_1 \cdot f_2 \in F$

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Descending Chain

- Definition
 - The height of a lattice is the largest number of > relations that will fit in a
 descending chain.

$$x_0 > x_1 > x_2 > ...$$

- · Height of values in reaching definitions?
- · Important property: finite descending chain
- · Can an infinite lattice have a finite descending chain?
- Example: Constant Propagation/Folding
 - · To determine if a variable is a constant
- Data values
 - undef, ... -1, 0, 1, 2, ..., not-a-constant

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Monotonicity

- A framework (F, V, A) is monotone if and only if
 - $x \le y$ implies $f(x) \le f(y)$
 - i.e. a "smaller or equal" input to the same function will always give a "smaller or equal" output
- Equivalently, a framework (F, V, Λ) is monotone if and only if
 - $f(x \wedge y) \leq f(x) \wedge f(y)$
 - i.e. merge input, then apply f is small than or equal to apply the transfer function individually and then merge the result

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Example

- Reaching definitions: f(x) = Gen U (x Kill), ∧ = U
 - Definition 1:
 - $x_1 \le x_2$, Gen U $(x_1 Kill) \le Gen U (x_2 Kill)$
 - Definition 2:
 - (Gen U (x₁ Kill)) U (Gen U (x₂ Kill))
 - = (Gen U ((x₁ U x₂) Kill))
- Note: Monotone framework does not mean that $f(x) \le x$
 - · e.g., reaching definition for two definitions in program
 - suppose: f_x : $Gen_x = \{d_1, d_2\}$; $Kill_x = \{\}$
- If input(second iteration) ≤ input(first iteration)
 - result(second iteration) ≤ result(first iteration)

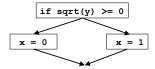
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III. Data Flow Analysis

- Definition
 - Let f_i , ..., f_m : $\subseteq F$, where f_i is the transfer function for node i
 - $f_p = f_{n_k} \cdot ... \cdot f_{n_1}$, where p is a path through nodes $n_1, ..., n_k$
 - f_p = identify function, if p is an empty path
- · Ideal data flow answer:
 - For each node n:
 - Λf_n (T), for all possibly executed paths p_i reaching n.



· Determining all possibly executed paths is undecidable

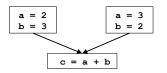
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Distributivity

- A framework (F, V, Λ) is distributive if and only if
 - $f(x \wedge y) = f(x) \wedge f(y)$
 - i.e. merge input, then apply f is **equal to** apply the transfer function individually then merge result
- Example: Constant Propagation



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Meet-Over-Paths (MOP)

- · Err in the conservative direction
- Meet-Over-Paths (MOP):
 - For each node n:

 $MOP(n) = A f_{p_i}(T)$, for all paths p_i reaching n

- a path exists as long there is an edge in the code
- · consider more paths than necessary
- MOP = Perfect-Solution ∧ Solution-to-Unexecuted-Paths
- MOP ≤ Perfect-Solution
- · Potentially more constrained, solution is small
 - hence conservative
- It is not safe to be > Perfect-Solution!
- Desirable solution: as close to MOP as possible

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Solving Data Flow Equations

- . Example: Reaching definitions
 - out[entry] = {}
 - Values = {subsets of definitions}
 - Meet operator: U
 - in[b] = ∪ out[p], for all predecessors p of b
 - Transfer functions: out[b] = gen_b ∪ (in[b] -kill_b)
- Any solution satisfying equations = Fixed Point Solution (FP)
- Iterative algorithm
 - initializes out[b] to {}
 - if converges, then it computes Maximum Fixed Point (MFP):
 - . MFP is the largest of all solutions to equations
- Properties:
 - FP ≤ MFP ≤ MOP ≤ Perfect-solution
 - FP, MFP are safe
 - in(b) ≤ MOP(b)

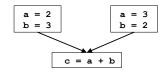
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Precision

- If data flow framework is distributive, then if the algorithm converges, IN[b] = MOP[b]
- Monotone but not distributive: behaves as if there are additional paths



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Partial Correctness of Algorithm

- If data flow framework is monotone, then if the algorithm converges, IN[b] ≤ MOP[b]
- · Proof: Induction on path lengths
 - Define IN[entry] = OUT[entry]
 and transfer function of entry = Identity function
 - Base case: path of length 0
 - Proper initialization of IN[entry]
 - If true for path of length k, $p_k = (n_1, ..., n_k)$, then true for path of length k+1: $p_{k+1} = (n_1, ..., n_{k+1})$
 - Assume: $IN[n_k] \le f_{n_{k-1}}(f_{n_{k-2}}(...f_{n_1}(IN[entry])))$
 - $IN[n_{k+1}] = OUT[n_k] \land ...$ $\leq OUT[n_k]$ $\leq f_{n_k}(IN[n_k])$ $\leq f_{n_{k+1}}(f_{n_{k+1}},...,f_{n_1}(IN[entry])))$

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Additional Property to Guarantee Convergence

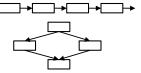
- Data flow framework (monotone) converges if there is a finite descending chain
- For each variable IN[b], OUT[b], consider the sequence of values set to each variable across iterations:
 - if sequence for in[b] is monotonically decreasing
 - sequence for out[b] is monotonically decreasing
 - (out[b] initialized to T)
 - if sequence for out[b] is monotonically decreasing
 - sequence of in[b] is monotonically decreasing

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IV. Speed of Convergence

• Speed of convergence depends on order of node visits



· Reverse "direction" for backward flow problems

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Depth-First Iterative Algorithm (forward)

```
input: control flow graph CFG = (N, E, Entry, Exit)
/* Initialize */
    out[entry] = init value
    For all nodes i
       out[i] = T
    Change = True
/* iterate */
    While Change {
       Change = False
       For each node i in rPostOrder {
          in[i] = A(out[p]), for all predecessors p of i
          oldout = out[i]
          out[i] = f, (in[i])
          if oldout # out[i]
              Change = True
    }
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```

Reverse Postorder

```
• Step 1: depth-first post order
```

```
main() {
   count = 1;
   Visit(root);
}
Visit(n) {
   for each successor s that has not been visited
      Visit(s);
   PostOrder(n) = count;
   count = count+1;
}
```

• Step 2: reverse order

```
For each node i
    rPostOrder = NumNodes - PostOrder(i)
```

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Speed of Convergence

· If cycles do not add information

- information can flow in one pass down a series of nodes of increasing order number:
 - e.g., 1 -> 4 -> 5 -> 7 -> 2 -> 4 ...
- passes determined by number of back edges in the path
 - · essentially the nesting depth of the graph
- Number of iterations = number of back edges in any acyclic path + 2
 - (2 are necessary even if there are no cycles)

What is the depth?

- corresponds to depth of intervals for "reducible" graphs
- in real programs: average of 2.75

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A Check List for Data Flow Problems

Semi-lattice

- set of values
- meet operator
- top, bottom
- finite descending chain?

Transfer functions

- function of each basic block
- monotone
- distributive?

Algorithm

- initialization step (entry/exit, other nodes)
- visit order: rPostOrder
- depth of the graph

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