15-213

"The course that gives CMU its Zip!"

Concurrent Programming April 24, 2008

Topics

- · Limitations of iterative servers
- Process-based concurrent servers
- Threads-based concurrent servers
- Event-based concurrent servers

class24.ppt

Concurrent Programming is Hard!

The human mind tends to be sequential

The notion of time is often misleading

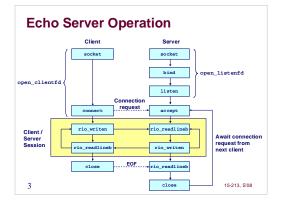
Thinking about all possible sequences of events in a computer system is at least error prone and frequently impossible

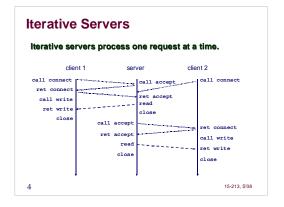
Classical problem classes of concurrent programs:

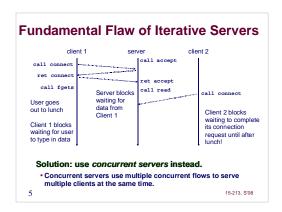
- Races: outcome depends on arbitrary scheduling decisions elsewhere in the system
 Example: who gets the last seat on the airplane?
- Deadlock: improper resource allocation prevents forward progress
 Example: traffic gridlock
 Livelock / Starvation / Fairness: external events and/or system scheduling decisions can prevent sub-task progress
 Example: people always jump in front of you in line

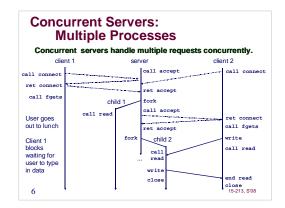
Many aspects of concurrent programming are beyond the scope of 15-213

2









Three Basic Mechanisms for Creating Concurrent Flows

1. Processes

- Kernel automatically interleaves multiple logical flows.
- Each flow has its own private address space.

2. Threads

- Kernel automatically interleaves multiple logical flows.
- All flows share the same address space.

3. I/O multiplexing with select()

- Programmer manually interleaves multiple logical flows.
- All flows share the same address space.
- Popular for high-performance server designs.

7 15-213, S'08

Review: Sequential Server

```
int main(int argo, char **argv)
{
  int listenfd, comnfd;
  int port = ato((argv[1]);
  struct sockaddr in clientaddr;
  int clientlen = siseof(clientaddr);
  int clientlen = siseof(clientaddr);
  while (1);
  value (1);
  connfd = Accept(listenfd, (SA *)&clientaddr, &clientlen);
    cho(connfd);
    close(connfd);
  }
  exit(0);
}
```

- Accept a connection request
- Handle echo requests until client terminates

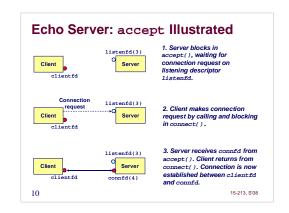
8 15-213, S'08

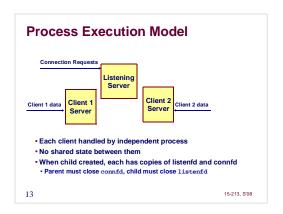
```
Inner Echo Loop

(

| size_t n; | char buf[NANLINE]; | rio_t rio]
| Rio_readinitb(ario, connfd); | while((n = Rio_readlineh(ario, buf, MAXLINE)) != 0) { | printf("server received %d bytes\n", n); | }

- Server reads lines of text
- Echos them right back
```





Implementation Issues With **Process-Based Designs**

Server must reap zombie children

to avoid fatal memory leak.

Server must close its copy of connfd.

- Kernel keeps reference count for each socket/open file.
- After fork, refcnt(connfd) = 2.
- Connection will not be closed until refcnt(connfd)==0.

14 15-213, S'08

Pros and Cons of Process-Based Designs

- + Handles multiple connections concurrently
- + Clean sharing model
- · descriptors (no)
- file tables (yes)
- global variables (no) + Simple and straightforward.
- Additional overhead for process control.
- Nontrivial to share data between processes.
- Requires IPC (interprocess communication) mechanisms
 FIFO's (named pipes), System V shared memory and semaphores

15

Traditional View of a Process

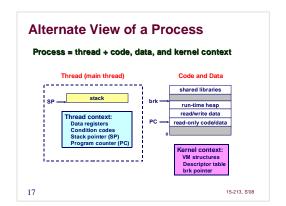
Process = process context + code, data, and stack

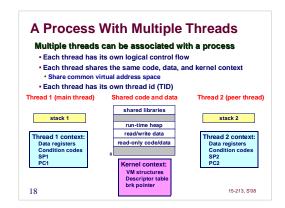
Process context

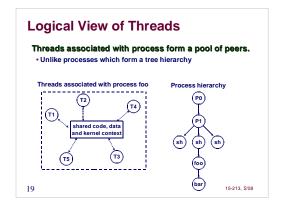
Program context:
Data registers
Condition codes
Stack pointer (SP)
Program counter (PC)
Kernel context:
VM structures
Descriptor table
brk pointer

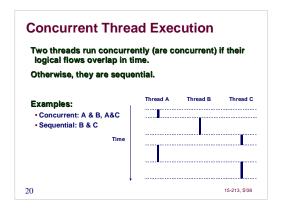
stack shared libraries run-time heap read/write data read-only code/data

15-213, S'08 16

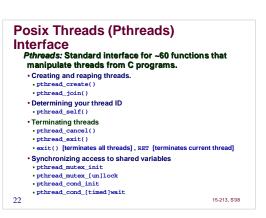


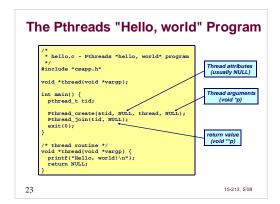


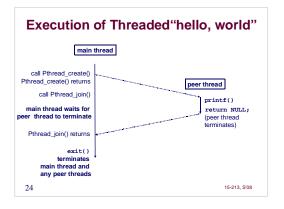




Threads vs. Processes How threads and processes are similar Each has its own logical control flow. Each can run concurrently. Each is context switched. How threads and processes are different Threads share code and data, processes (typically) do not. Threads are somewhat less expensive than processes. Process control (creating and reaping) is twice as expensive as thread control. Linux/Pentium III numbers: - ~20K cycles to create and reap a process. - 10K cycles to create and reap a thread.







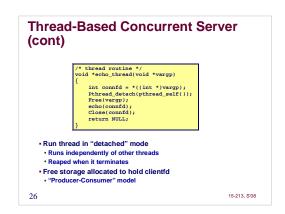
```
Thread-Based Concurrent Echo
Server

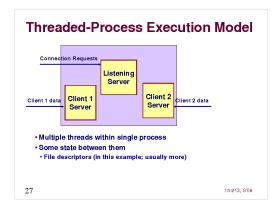
int main(int argo, char **argy)
{
    int port = atoi(argy[1]);
    struct sockaddr, in clientaddr;
    int clientlenssizeof(clientaddr);
    pthread_t tid]
    int listenfd = Open_listenfd(port);
    while (1) {
        int *connfdp = Malloo(sizeof(int));
        *connfdp = Accept(listenfd, (SA *) &clientaddr, &clientlen);
        Pthread_create(&tid, NULL, echo_thread, connfdp);
    }

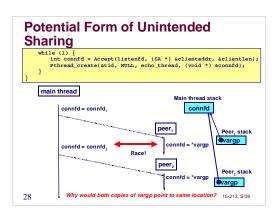
- Spawn new thread for each client
- Pass it copy of connection file descriptor
- Note use of Malloc()!

*Without corresponding Free()

15-213, SU8
```







Issues With Thread-Based Servers

Must run "detached" to avoid memory leak.

- At any point in time, a thread is either joinable or detached.
- Joinable thread can be reaped and killed by other threads.
 must be reaped (with pthread_join) to free memory resources.
- Detached thread cannot be reaped or killed by other threads. • resources are automatically reaped on termination
- Default state is joinable.
- use pthread detach(pthread self()) to make detached.

Must be careful to avoid unintended sharing.

- For example, what happens if we pass the address of connfd to the thread routine? Pthread_create(&tid, NULL, thread, (void *)&connfd);
- All functions called by a thread must be thread-safe

(next lecture)

Pros and Cons of Thread-Based Designs

- + Easy to share data structures between threads
- e.g., logging information, file cache.
- + Threads are more efficient than processes.

--- Unintentional sharing can introduce subtle and hard-to-reproduce errors!

- The ease with which data can be shared is both the greatest strength and the greatest weakness of threads.
- (next lecture)

30 15-213, S'08

Event-Based Concurrent Servers Using I/O Multiplexing

Maintain a pool of connected descriptors.

Repeat the following forever:

- Use the Unix select() function to block until:
- (a) New connection request arrives on the listening descriptor. (b) New data arrives on an existing connected descriptor.
- If (a), add the new connection to the pool of connections.
- If (b), read any available data from the connection
 Close connection on EOF and remove it from the pool.

The select() Function

 $\mathtt{select}()$ sleeps until one or more file descriptors in the set $\mathtt{readset}$ ready for reading.

#include <sys/select.h>

int select(int maxfdp1, fd_set *readset, NULL, NULL, NULL);

- Opaque bit vector (max FD_SETSIZE bits) that indicates membership in a descriptor set.

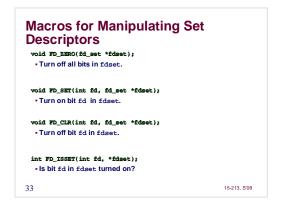
 If bit k is 1, then descriptor k is a member of the descriptor set.

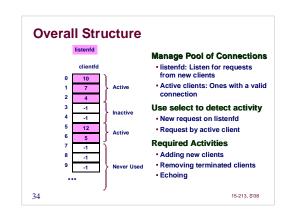
Maximum descriptor in descriptor set plus 1.
 Tests descriptors 0, 1, 2, ..., maxfdp1 - 1 for set membership.

select() returns the number of ready descriptors and sets each bit of
readset to indicate the ready status of its corresponding descriptor.

32

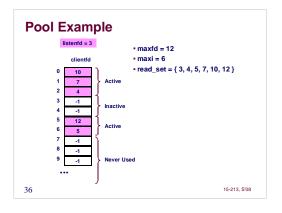
15-213, S'08 31





Representing Pool of Clients

35 15-213, S'(



```
Main Loop

int main(int argo, char **argv)
{
    int listenfd, connfd, clientlen = sizeof(struct sockaddr_in);
    struct sockaddr_in clientaddr;
    static pool pool;
    listenfd = Open_listenfd(argv[1]);
    init_pool(listenfd, spool);

while (1) {
        pool.ready_set = pool.read_set;
        pool.ready_set = pool.maxfd+1, &pool.ready_set,
        NULL, NULL, NULL);

    if (FD_ISSET(listenfd, &pool);
        counfd = Accept(listenfd, fool);
        }
        check_clients(&pool);
    }
}

15-213.508
```

```
Pool Initialization

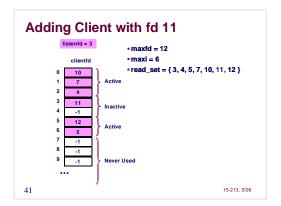
/* initialize the descriptor pool */
void init_pool(int listentd, pool *p)
{
    /* Initially, there are no connected descriptors */
    int i;
    p->maxi = -1;
    for (i=0; i < FD_SETSIZE; i++)
        p->cllentId(i] = -1;
    /* Initially, listented is only member of select read set */
    p->maxfd = listented,
    PD_SET(listented, &p->read_set);
}

38
```

Adding Client

```
void add_client(int connfd, pool *p) /* add connfd to pool p */
{
   int i;
   p->nready--;
   for (i = 0; i < FD_SETSIZE; i++) /* Find available slot */
        if (p->clientId(i) < 0) {
            p->clientId(i) = connfd;
            Rio_readintib(Ep->clientrio(i), connfd);

        FD_SET(connfd, &p->read_set); /* Add desc to read set */
        if (connfd > p->maxfd) /* Update max descriptor num */
            p->maxfd = connfd;
        if (i > p->maxi | *) Update pool high water mark */
            p->maxi = i;
        }
        if (i == FD_SETSIZE) /* Couldn't find an empty slot */
        app_error("add_client error: Too many clients");
}
```



```
Checking Clients

void check_clients(pool 'p) { /* echo line from ready descs in pool p */
int i, connid, n;
char buf(MAXLIME);
rio, t rio;

for (i = 0; (i <= p>maxi) && (p>mready > 0); i++) {
    comid = p>clientfd(1);
    rlo = p>clientfd(1);

    /* if the descriptor is ready, echo a text line from it */
    if ((connid > 0) && (PD_ISST(connid, b-p>ready_set))) {
        p>mready--;
        if ((n = Rio,readlineb(&rio, buf, MAXLIME)) != 0) {
            byte_ont += n;
            Rio_writen(connid, buf, n);
        }
        else (/* EOF detected, remove descriptor from pool */
            Close(counfd);
            p->clientfd(i] = -1;
        }
    }
}
```

Pro and Cons of Event-Based Designs + One logical control flow. + Can single-step with a debugger. + No process or thread control overhead. - Design of choice for high-performance Web servers and search engines. - Significantly more complex to code than process- or thread-based designs. - Hard to provide fine-grained concurrency - E.g., our example will hang up with partial lines.

Approaches to Concurrency

Processes
- Hard to share resources: Easy to avoid unintended sharing
- High overhead in adding/removing clients

Threads

- Easy to share resources: Perhaps too easy
 Medium overhead
 Not much control over scheduling policies
 Difficult to debug
 Event orderings not repeatable

- VO Multiplexing

 Tedious and low level

 Total control over scheduling

 Very low overhead

 Cannot create as fine grained a level of concurrency

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