15-213

"The course that gives CMU its Zip!"

Time Measurement Apr. 8, 2003

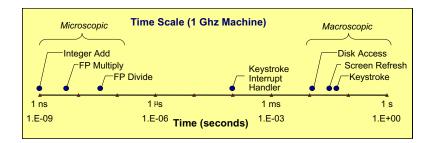
Topics

- Time scales
- Interval counting
- Cycle counters
- K-best measurement scheme

class22.ppt

Computer Time Scales

~10-9 sec.



Two Fundamental Time Scales

- Processor:
- External events: ~10⁻² sec.
 - Keyboard input
 - Disk seek
 - Screen refresh

Implication

- Can execute many instructions while waiting for external event to occur
- Can alternate among processes without anyone noticing

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Measurement Challenge

How Much Time Does Program X Require?

- CPU time
 - How many total seconds are used when executing X?
 - Measure used for most applications
 - Small dependence on other system activities
- Actual ("Wall") Time
 - How many seconds elapse between the start and the completion of X?
 - Depends on system load, I/O times, etc.

Confounding Factors

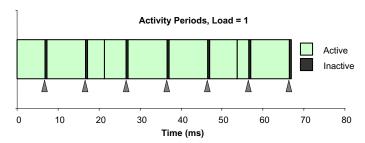
- How does time get measured?
- Many processes share computing resources
 - Transient effects when switching from one process to another
 - Suddenly, the effects of alternating among processes become noticeable

"Time" on a Computer System

real (wall clock) time
= user time (time executing instructions in the user process)
= system time (time executing instructions in kernel on behalf of user process)
= some other user's time (time executing instructions in different user's process)
+ = real (wall clock) time
We will use the word "time" to refer to user time.
cumulative user time

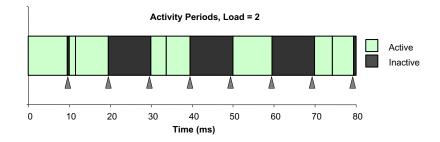
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Activity Periods: Light Load



- Most of the time spent executing one process
- Periodic interrupts every 10ms
 - Interval timer
 - Keep system from executing one process to exclusion of others
- Other interrupts
 - Due to I/O activity
- Inactivity periods
 - System time spent processing interrupts
 - ~250,000 clock cycles

Activity Periods: Heavy Load



- Sharing processor with one other active process
- From perspective of this process, system appears to be "inactive" for ~50% of the time
 - Other process is executing

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Interval Counting

OS Measures Runtimes Using Interval Timer

- Maintain 2 counts per process
 - User time
 - System time
- Each time get timer interrupt, increment counter for executing process
 - User time if running in user mode
 - System time if running in kernel mode

Interval Counting Example

(a) Interval Timings



(b) Actual Times



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Unix time Command

```
time make osevent

gcc -O2 -Wall -g -march=i486 -c clock.c

gcc -O2 -Wall -g -march=i486 -c options.c

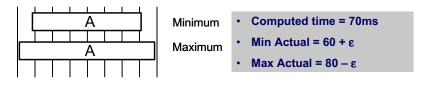
gcc -O2 -Wall -g -march=i486 -c load.c

gcc -O2 -Wall -g -march=i486 -o osevent osevent.c . . .

0.820u 0.300s 0:01.32 84.8% 0+0k 0+0io 4049pf+0w
```

- 0.82 seconds user time
 - 82 timer intervals
- 0.30 seconds system time
 - 30 timer intervals
- 1.32 seconds wall time
- 84.8% of total was used running these processes
 - \bullet (.82+0.3)/1.32 = .848

Accuracy of Interval Counting



Worst Case Analysis

■ Timer Interval = δ

0 10 20 30 40 50 60 70 80

- Single process segment measurement can be off by ±δ
- No bound on error for multiple segments
 - Could consistently underestimate, or consistently overestimate

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Accuracy of Int. Cntg. (cont.)



Average Case Analysis

- Over/underestimates tend to balance out
- As long as total run time is sufficiently large
 - Min run time ~1 second
 - 100 timer intervals
- Consistently miss 4% overhead due to timer interrupts

Cycle Counters

- Most modern systems have built in registers that are incremented every clock cycle
 - Very fine grained
 - Maintained as part of process state
 » In Linux, counts elapsed global time
- Special assembly code instruction to access
- On (recent model) Intel machines:
 - 64 bit counter.
 - RDTSC instruction sets %edx to high order 32-bits, %eax to low order 32-bits

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Cycle Counter Period

Wrap Around Times for 550 MHz machine

- Low order 32 bits wrap around every 2³² / (550 * 10⁶) = 7.8 seconds
- High order 64 bits wrap around every 2⁶⁴ / (550 * 10⁶) = 33539534679 seconds
 - 1065 years

For 2 GHz machine

- Low order 32-bits every 2.1 seconds
- High order 64 bits every 293 years

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Accessing the Cycle Cntr.

- GCC allows inline assembly code with mechanism for matching registers with program variables
- Code only works on x86 machine compiling with GCC

■ Emit assembly with rdtsc and two mov1 instructions

Measuring with Cycle Counter

Idea

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- Get current value of cycle counter
 - store as pair of unsigned's cyc hi and cyc lo
- Compute something
- Get new value of cycle counter
- Perform double precision subtraction to get elapsed cycles

```
/* Keep track of most recent reading of cycle counter */
static unsigned cyc_hi = 0;
static unsigned cyc_lo = 0;

void start_counter()
{
   /* Get current value of cycle counter */
   access_counter(&cyc_hi, &cyc_lo);
}
```

Closer Look at Extended ASM

```
void access_counter
  (unsigned *hi, unsigned *lo)
{
  /* Get cycle counter */
  asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
      : "=r" (*hi), "=r" (*lo)
      : /* No input */
      : "%edx", "%eax");
}
```

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Instruction String

- Series of assembly commands
 - Separated by ";" or "\n"
 - Use "%%" where normally would use "%"

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Closer Look at Extended ASM

```
asm("Instruction String"
      : Output List
      : Input List void access counter
      : Clobbers I
                    (unsigned *hi, unsigned *lo)
                    /* Get cycle counter */
                    asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
                         : "=r" (*hi), "=r" (*lo)
                         : /* No input */
                         : "%edx", "%eax");
 Output List
```

- Expressions indicating destinations for values %0, %1, ..., %j
 - Enclosed in parentheses
 - Must be Ivalue
 - » Value that can appear on LHS of assignment
- Tag "=r" indicates that symbolic value (%0, etc.), should be replaced by register

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Closer Look at Extended ASM

```
asm("Instruction String"
      : Output List
      : Input List void access counter
      : Clobbers I
                     (unsigned *hi, unsigned *lo)
                     /* Get cycle counter */
                     asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
                         : "=r" (*hi), "=r" (*lo)
                         : /* No input */
                         : "%edx", "%eax");
```

Input List

- Series of expressions indicating sources for values % j+1, % j+2,
- Enclosed in parentheses
- Any expression returning value
- Tag "r" indicates that symbolic value (%0, etc.) will come from register

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Closer Look at Extended ASM

```
asm("Instruction String"
      : Output List
      : Input List void access counter
      : Clobbers I
                    (unsigned *hi, unsigned *lo)
                     /* Get cycle counter */
                     asm("rdtsc; movl %%edx,%0; movl %%eax,%1"
                         : "=r" (*hi), "=r" (*lo)
                         : /* No input */
                         : "%edx", "%eax");
```

Clobbers List

- List of register names that get altered by assembly instruction
- Compiler will make sure doesn't store something in one of these registers that must be preserved across asm
 - Value set before & used after

Accessing the Cycle Cntr. (cont.)

Emitted Assembly Code

```
movl 8(%ebp),%esi
                            # hi
                            # 10
     movl 12 (%ebp), %edi
#APP
     rdtsc; movl %edx, %ecx; movl %eax, %ebx
#NO APP
     movl %ecx,(%esi)
                            # Store high bits at *hi
                            # Store low bits at *lo
     movl %ebx, (%edi)
```

- Used %ecx for *hi (replacing %0)
- Used %ebx for *1o (replacing %1)
- Does not use %eax or %edx for value that must be carried across inserted assembly code

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Completing Measurement

- Get new value of cycle counter
- Perform double precision subtraction to get elapsed cycles
- Express as double to avoid overflow problems

```
double get_counter()
{
  unsigned ncyc_hi, ncyc_lo
  unsigned hi, lo, borrow;
  /* Get cycle counter */
  access_counter(&ncyc_hi, &ncyc_lo);
  /* Do double precision subtraction */
  lo = ncyc_lo - cyc_lo;
  borrow = lo > ncyc_lo;
  hi = ncyc_hi - cyc_hi - borrow;
  return (double) hi * (1 << 30) * 4 + lo;
}</pre>
```

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Timing With Cycle Counter

Determine Clock Rate of Processor

 Count number of cycles required for some fixed number of seconds

```
double MHZ;
int sleep_time = 10;
start_counter();
sleep(sleep_time);
MHZ = get_counter()/(sleep_time * 1e6);
```

Time Function P

■ First attempt: Simply count cycles for one execution of P

```
double tsecs;
start_counter();
P();
tsecs = get_counter() / (MHZ * 1e6);
```

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Measurement Pitfalls

Overhead

- Calling get_counter() incurs small amount of overhead
- Want to measure long enough code sequence to compensate

Unexpected Cache Effects

- artificial hits or misses
- e.g., these measurements were taken with the Alpha cycle counter:

Dealing with Overhead & Cache Effects

- Always execute function once to "warm up" cache
- Keep doubling number of times execute P() until reach some threshold
 - Used CMIN = 50000

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Multitasking Effects

Cycle Counter Measures Elapsed Time

- Keeps accumulating during periods of inactivity
 - System activity
 - Running other processes

Key Observation

- Cycle counter never underestimates program run time
- Possibly overestimates by large amount

K-Best Measurement Scheme

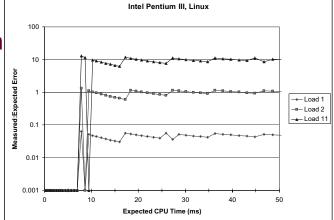
- Perform up to N (e.g., 20) measurements of function
- See if fastest K (e.g., 3) within some relative factor ε (e.g., 0.001)



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K-Best Validation

 $K = 3, \epsilon = 0.001$



0.001

Very good accuracy for < 8ms

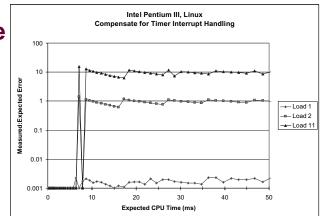
- Within one timer intervalEven when heavily loaded
- Less accurate of > 10ms
 - Light load: ~4% error
 Interval clock interrupt handling
 - Heavy load: Very high error

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Compensate For Timer

 $K = 3, \epsilon = 0.001$

Overhead

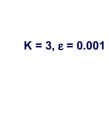


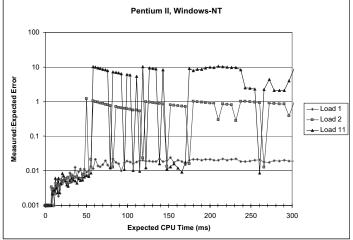
Subtract Timer Overhead

- Estimate overhead of single interrupt by measuring periods of inactivity
- Call interval timer to determine number of interrupts that have occurred

K-Best on NT

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Better Accuracy for > 10ms

- Light load: 0.2% error
- Heavy load: Still very high error

Acceptable accuracy for < 50ms

Scheduler allows process to run multiple intervals

Less accurate of > 10ms

- Light load: 2% error
- Heavy load: Generally very high error

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Time of Day Clock

- Unix gettimeofday() function
- Return elapsed time since reference time (Jan 1, 1970)
- Implementation
 - Uses interval counting on some machines
 - » Coarse grained
 - Uses cycle counter on others
 - » Fine grained, but significant overhead and only 1 microsecond resolution

```
#include <sys/time.h>
#include <unistd.h>

struct timeval tstart, tfinish;
double tsecs;
gettimeofday(&tstart, NULL);
P();
gettimeofday(&tfinish, NULL);
tsecs = (tfinish.tv_sec - tstart.tv_sec) +
    1e6 * (tfinish.tv_usec - tstart.tv_usec);
```

Measurement Summary

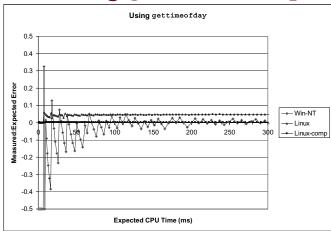
Timing is highly case and system dependent

- What is overall duration being measured?
 - > 1 second: interval counting is OK
 - << 1 second: must use cycle counters
- On what hardware / OS / OS version?
 - Accessing counters
 - » How gettimeofday is implemented
 - Timer interrupt overhead
 - Scheduling policy

Devising a Measurement Method

- Long durations: use Unix timing functions
- Short durations
 - If possible, use gettimeofday
 - Otherwise must work with cycle counters
 - K-best scheme most successful

K-Best Using gettimeofday



Linux

Windows

- As good as using cycle counter
- For times > 10 microseconds
- Implemented by interval counting
- Too coarse-grained

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