

# **15-213**

## **Dynamic Memory Allocation**

### **April 9, 2002**

#### **Topics**

- **Simple explicit allocators**
- **Data structures**
- **Mechanisms**
- **Policies**
- **Reading: 10.9**
- **Problems: 10.15 and 10.16**

# Harsh Reality #3

## *Memory Matters*

### **Memory is not unbounded**

- It must be allocated and managed
- Many applications are memory dominated
  - Especially those based on complex, graph algorithms

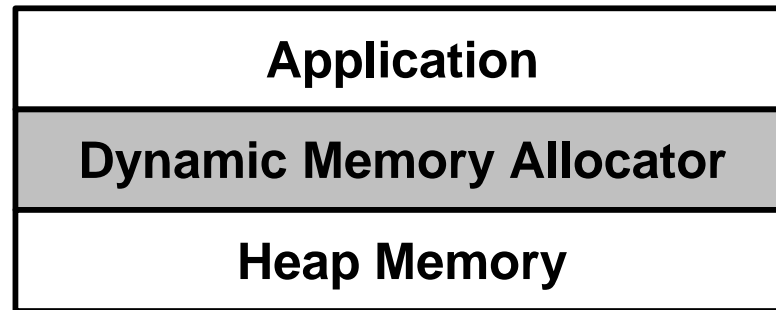
### **Memory referencing bugs especially pernicious**

- Effects are distant in both time and space

### **Memory performance is not uniform**

- Cache and virtual memory effects can greatly affect program performance
- Adapting program to characteristics of memory system can lead to major speed improvements

# Dynamic Memory Allocation



## Explicit vs. Implicit Memory Allocator

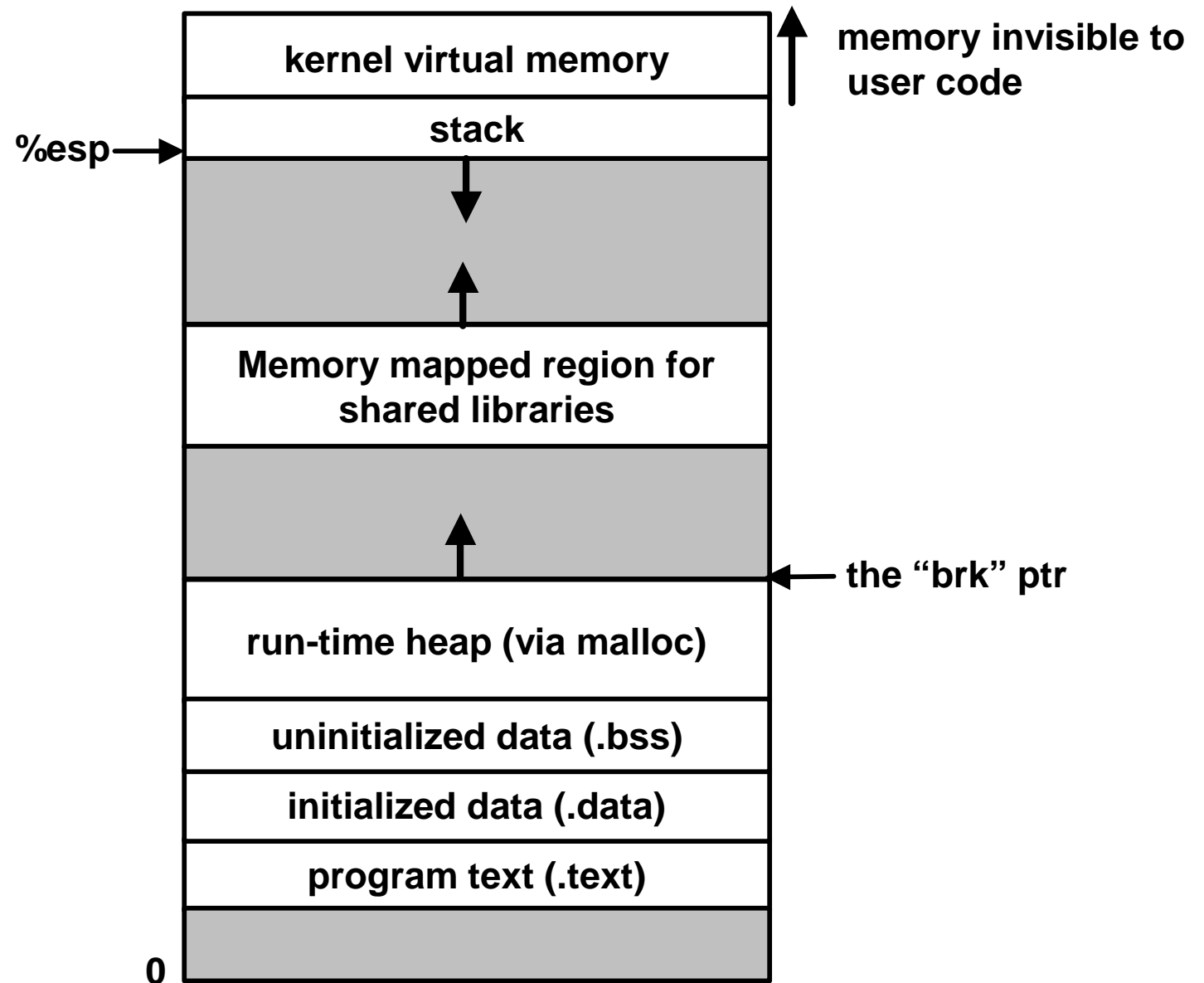
- **Explicit:** application allocates and frees space
  - E.g., `malloc` and `free` in C
- **Implicit:** application allocates, but does not free space
  - E.g. garbage collection in Java, ML or Lisp

## Allocation

- In both cases the memory allocator provides an abstraction of memory as a set of blocks
- Doles out free memory blocks to application

**Will discuss simple explicit memory allocation today**

# Process memory image



Allocators request additional heap memory from the operating system using the `sbrk()` function.

# Malloc package

```
#include <stdlib.h>
```

```
void *malloc(size_t size)
```

- **if successful:**
  - returns a pointer to a memory block of at least `size` bytes, aligned to 8-byte boundary.
  - if `size==0`, returns `NULL`
- **if unsuccessful:** returns `NULL`

```
void free(void *p)
```

- returns the block pointed at by `p` to pool of available memory
- `p` must come from a previous call to `malloc` or `realloc`.

```
void *realloc(void *p, size_t size)
```

- changes size of block `p` and returns ptr to new block.
- contents of new block unchanged up to min of old and new size.

# Malloc example

```
void foo(int n, int m) {
    int i, *p;

    /* allocate a block of n ints */
    if ((p = (int *) malloc(n * sizeof(int))) == NULL) {
        perror("malloc");
        exit(0);
    }
    for (i=0; i<n; i++)
        p[i] = i;

    /* add m bytes to end of p block */
    if ((p = (int *) realloc(p, (n+m) * sizeof(int))) == NULL) {
        perror("realloc");
        exit(0);
    }
    for (i=n; i < n+m; i++)
        p[i] = i;

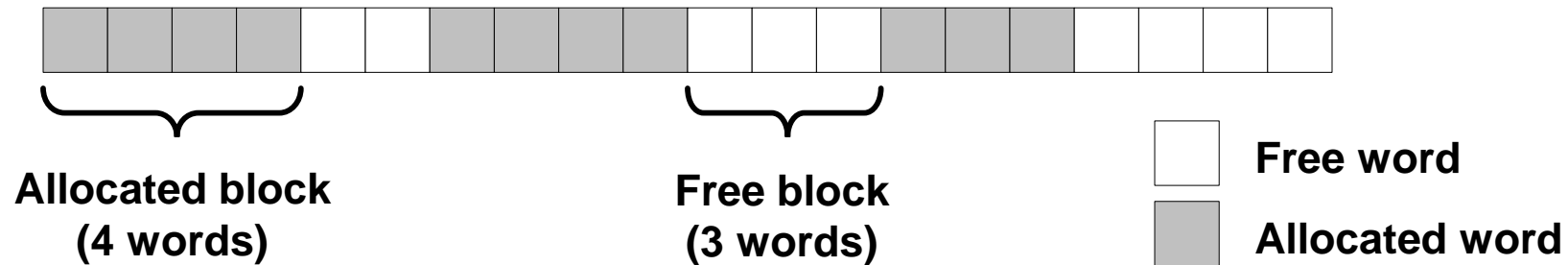
    /* print new array */
    for (i=0; i<n+m; i++)
        printf("%d\n", p[i]);

    free(p); /* return p to available memory pool */
}
```

# Assumptions

## Assumptions made in this lecture

- memory is word addressed (each word can hold a pointer)



# Allocation examples

`p1 = malloc(4)`



`p2 = malloc(5)`



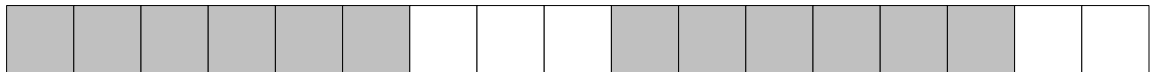
`p3 = malloc(6)`



`free(p2)`



`p4 = malloc(2)`





# Constraints

## Applications:

- Can issue arbitrary sequence of allocation and free requests
- Free requests must correspond to an allocated block

## Allocators

- Can't control number or size of allocated blocks
- Must respond immediately to all allocation requests
  - *i.e.*, can't reorder or buffer requests
- Must allocate blocks from free memory
  - *i.e.*, can only place allocated blocks in free memory
- Must align blocks so they satisfy all alignment requirements
  - usually 8 byte alignment
- Can only manipulate and modify free memory
- Can't move the allocated blocks once they are allocated
  - *i.e.*, compaction is not allowed

# Goals of good malloc/free

## Primary goals

- **Good time performance for `malloc` and `free`**
  - Ideally should take constant time (not always possible)
  - Should certainly not take linear time in the number of blocks
- **Good space utilization**
  - User allocated structures should be large fraction of the heap.
  - want to minimize “fragmentation”.

## Some other goals

- **Good locality properties**
  - structures allocated close in time should be close in space
  - “similar” objects should be allocated close in space
- **Robust**
  - can check that `free(p1)` is on a valid allocated object `p1`
  - can check that memory references are to allocated space

# Performance goals: throughput

**Given some sequence of malloc and free requests:**

- $R_0, R_1, \dots, R_k, \dots, R_{n-1}$

**Want to maximize throughput and peak memory utilization.**

- These goals are often conflicting

**Throughput:**

- Number of completed requests per unit time
- Example:
  - 5,000 malloc calls and 5,000 free calls in 10 seconds
  - throughput is 1,000 operations/second.

# Performance goals: peak memory utilization

Given some sequence of malloc and free requests:

- $R_0, R_1, \dots, R_k, \dots, R_{n-1}$

**Def: aggregate payload  $P_k$ :**

- `malloc(p)` results in a block with a *payload* of p bytes..
- After request  $R_k$  has completed, the *aggregate payload*  $P_k$  is the sum of currently allocated payloads.

**Def: current heap size is denoted by  $H_k$**

- Note that  $H_k$  is monotonically nondecreasing

**Def: peak memory utilization:**

- After  $k$  requests, *peak memory utilization* is:
  - $U_k = (\max_{i \leq k} P_i) / H_k$

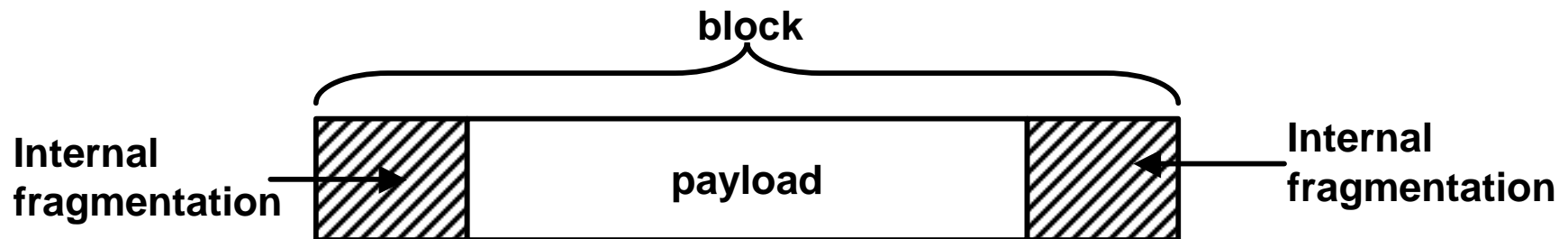
# Internal Fragmentation

**Poor memory utilization caused by *fragmentation*.**

- Comes in two forms: internal and external fragmentation

## Internal fragmentation

- For some block, internal fragmentation is the difference between the block size and the payload size.

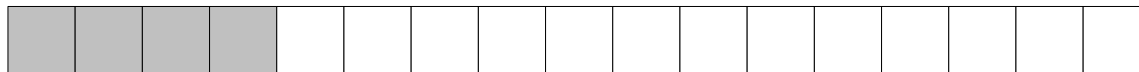


- Caused by overhead of maintaining heap data structures, padding for alignment purposes, or explicit policy decisions (e.g., not to split the block).
- Depends only on the pattern of previous requests, and thus is easy to measure.

# External fragmentation

Occurs when there is enough aggregate heap memory, but no single free block is large enough

```
p1 = malloc(4)
```



```
p2 = malloc(5)
```



```
p3 = malloc(6)
```



```
free(p2)
```

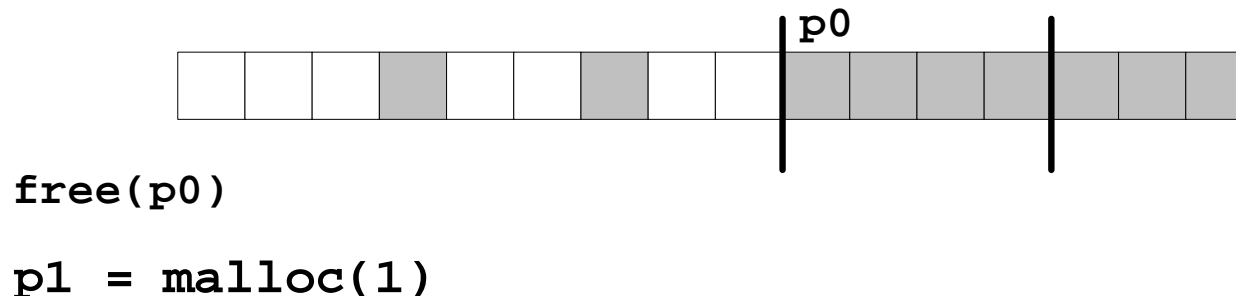


```
p4 = malloc(6)  oops!
```

External fragmentation depends on the pattern of future requests, and thus is difficult to measure.

# Implementation issues

- How do we know how much memory to free just given a pointer?
- How do we keep track of the free blocks?
- What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in?
- How do we pick a block to use for allocation -- many might fit?
- How do we reinsert freed block?



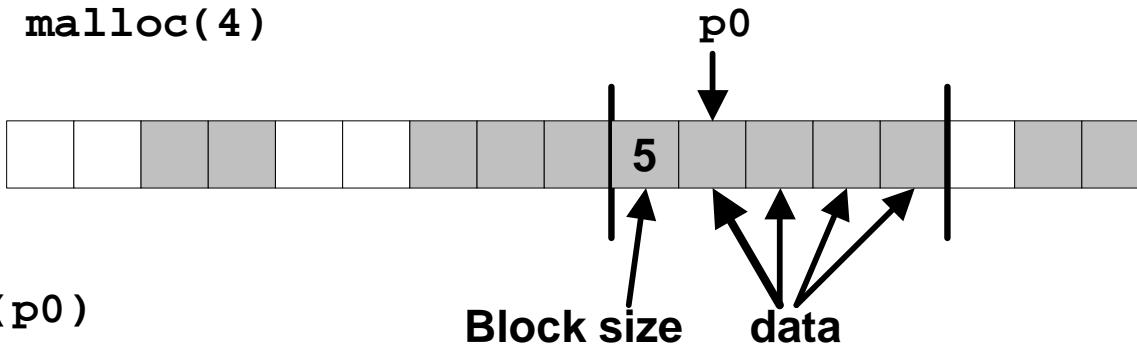
# Knowing how much to free

## Standard method

- keep the length of a structure in the word preceding the structure
  - This word is often called the *header field* or *header*
- requires an extra word for every allocated structure



`p0 = malloc(4)`



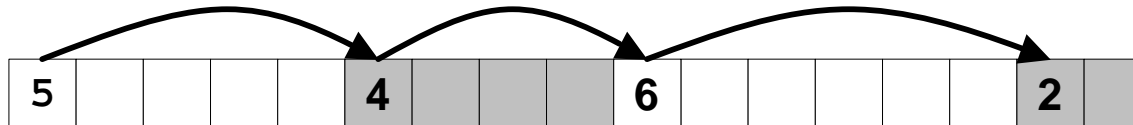
`free(p0)`



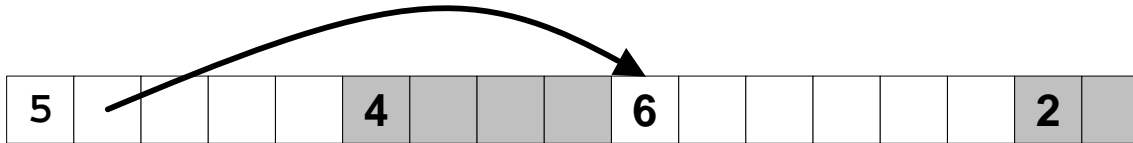


# Keeping track of free blocks

- **Method 1**: implicit list using lengths -- links all blocks



- **Method 2**: explicit list among the free blocks using pointers within the free blocks



- **Method 3**: segregated free lists

- Different free lists for different size classes

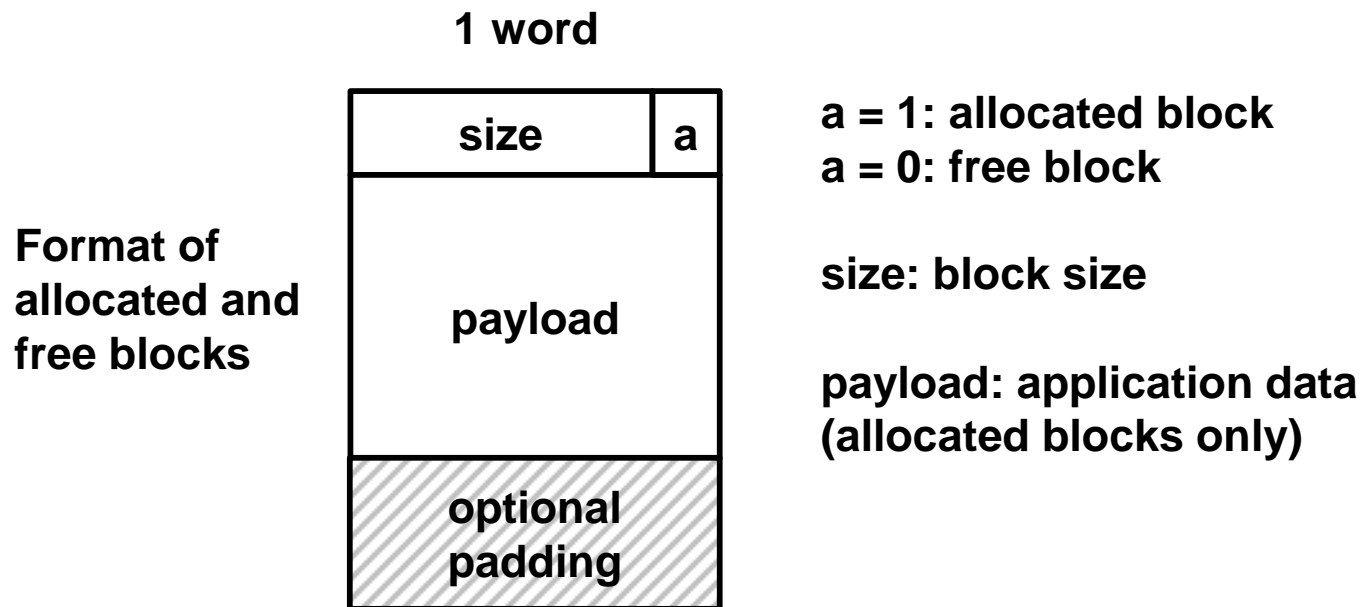
- **Method 4**: blocks sorted by size

- Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

# Method 1: implicit list

**Need to identify whether each block is free or allocated**

- Can use extra bit
- Bit can be put in the same word as the size if block sizes are always multiples of two (mask out low order bit when reading size).



# Implicit list: finding a free block

## First fit:

- Search list from beginning, choose first free block that fits

```
p = start;
while ((p < end) ||      \\ not passed end
      (*p & 1) ||      \\ already allocated
      (*p <= len));    \\ too small
```

- Can take linear time in total number of blocks (allocated and free)
- In practice it can cause “splinters” at beginning of list

## Next fit:

- Like first-fit, but search list from location of end of previous search
- Research suggests that fragmentation is worse

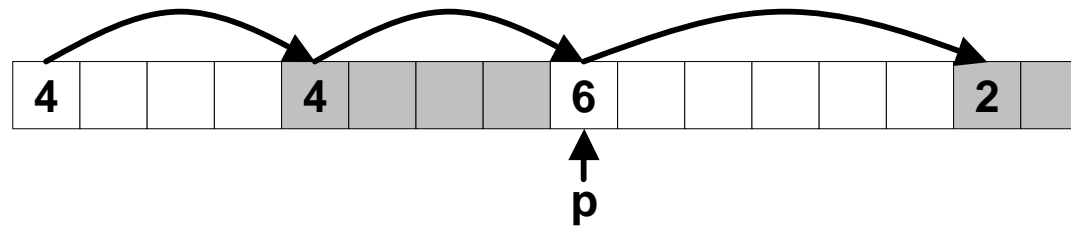
## Best fit:

- Search the list, choose the free block with the closest size that fits
- Keeps fragments small --- usually helps fragmentation
- Will typically run slower than first-fit

# Implicit list: allocating in a free block

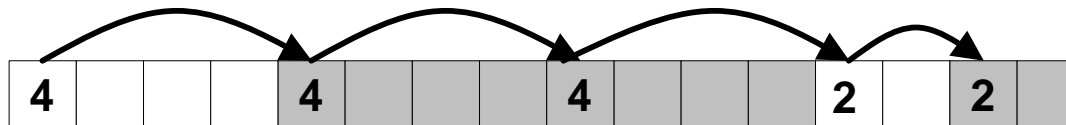
## Allocating in a free block - *splitting*

- Since allocated space might be smaller than free space, we might want to split the block



```
void addblock(ptr p, int len) {  
    int newsize = ((len + 1) >> 1) << 1;    // add 1 and round up  
    int oldsize = *p & -2;                    // mask out low bit  
    *p = newsize | 1;                         // set new length  
    if (newsize < oldsize)  
        *(p+newsize) = oldsize - newsize;    // set length in remaining  
}
```

```
addblock(p, 2);
```



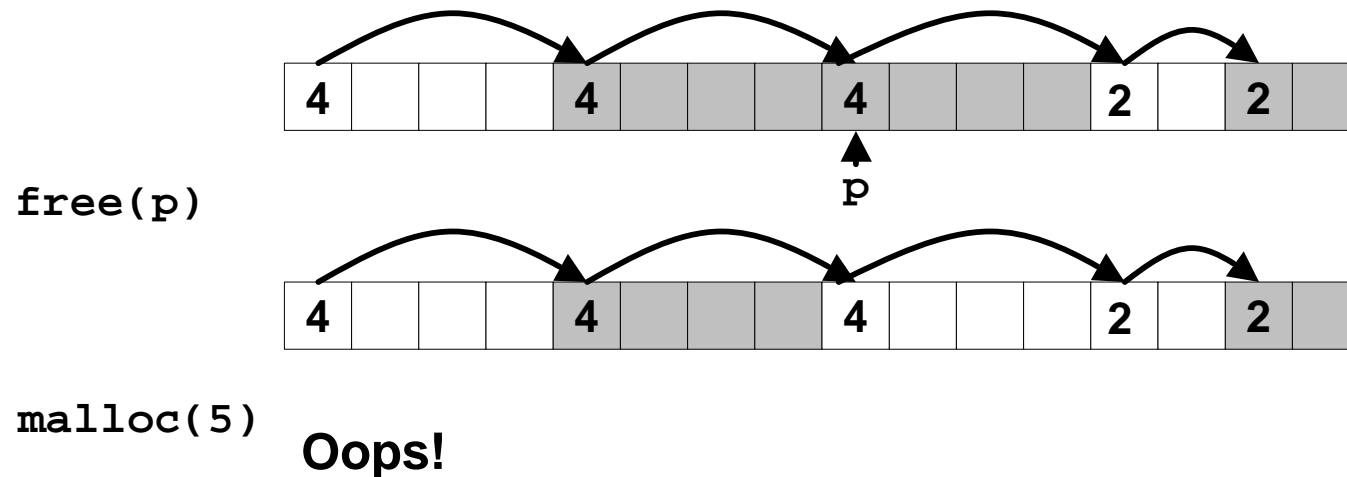
# Implicit list: freeing a block

## Simplest implementation:

- Only need to clear allocated flag

```
void free_block(ptr p) { *p = *p & -2 }
```

- But can lead to “false fragmentation”



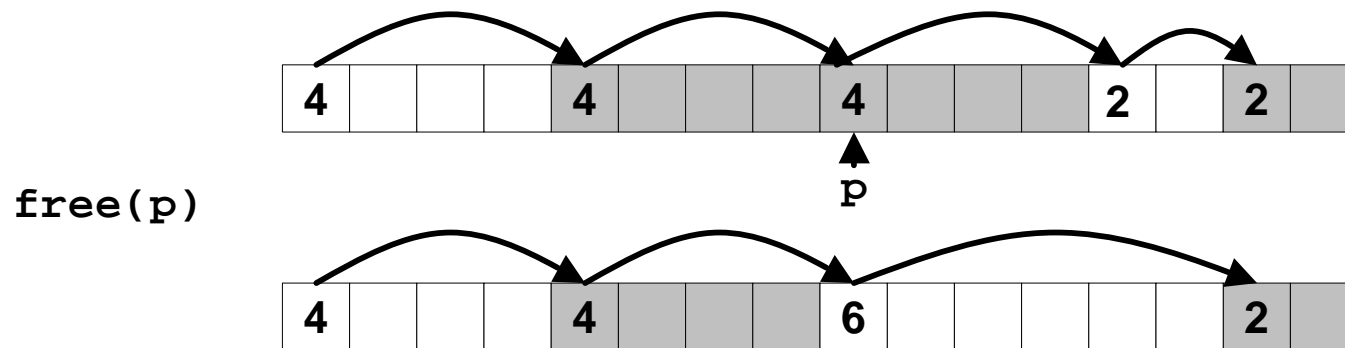
There is enough free space, but the allocator won't be able to find it

# Implicit list: coalescing

Join with next and/or previous block if they are free

- Coalescing with next block

```
void free_block(ptr p) {  
    *p = *p & -2;           // clear allocated flag  
    next = p + *p;           // find next block  
    if ((*next & 1) == 0)  
        *p = *p + *next;     // add to this block if  
    }                        // not allocated
```

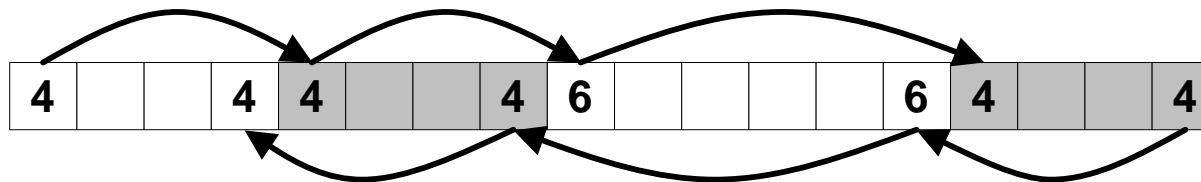
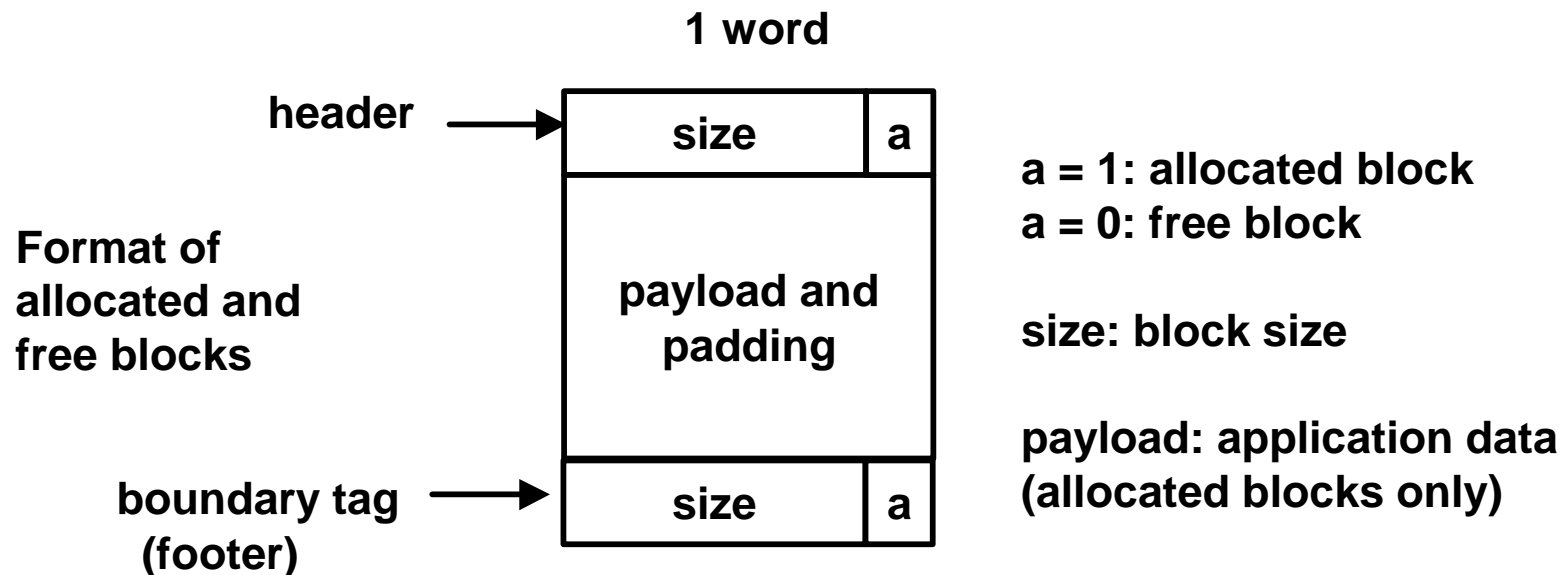


- But how do we coalesce with previous block?

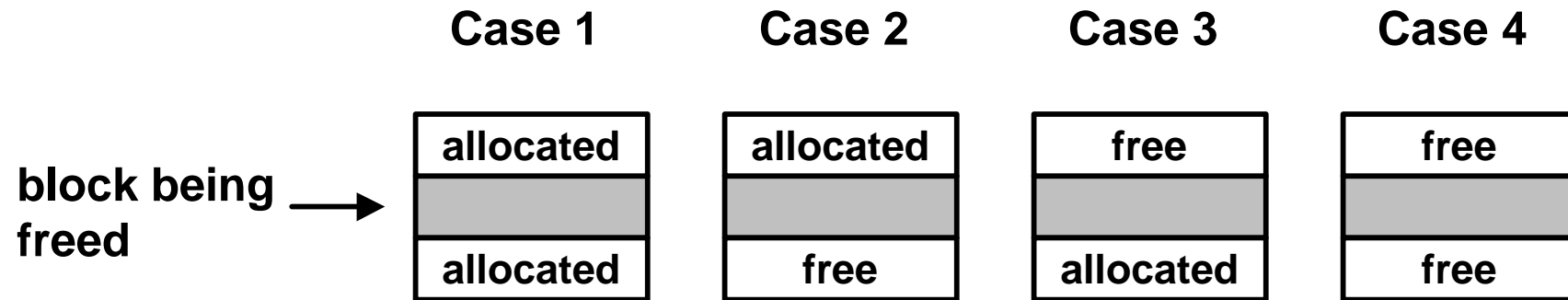
# Implicit list: bidirectional

## Boundary tags [Knuth73]

- replicate size/allocated word at bottom of free blocks
- Allows us to traverse the “list” backwards, but requires extra space
- Important and general technique!

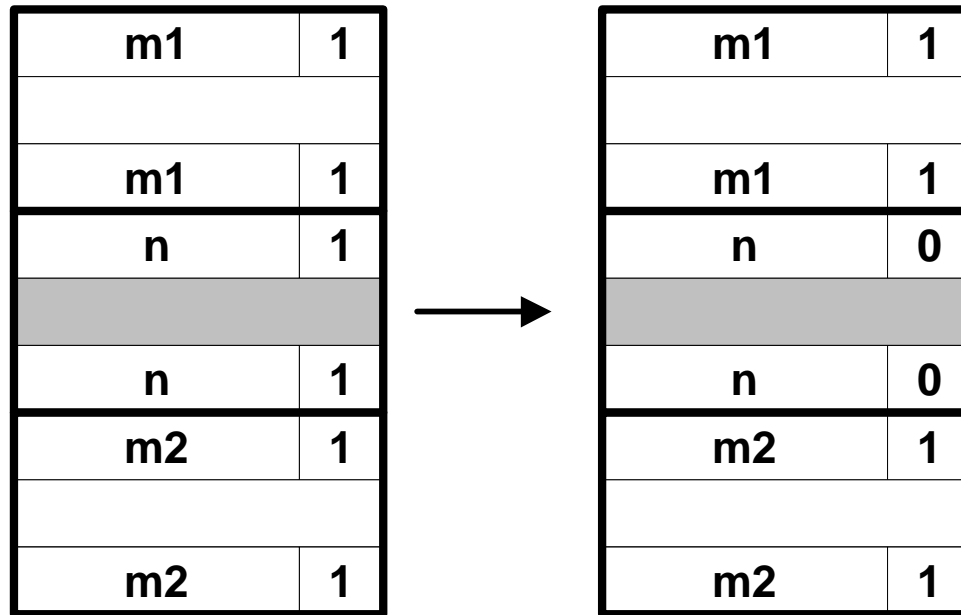


# Constant time coalescing

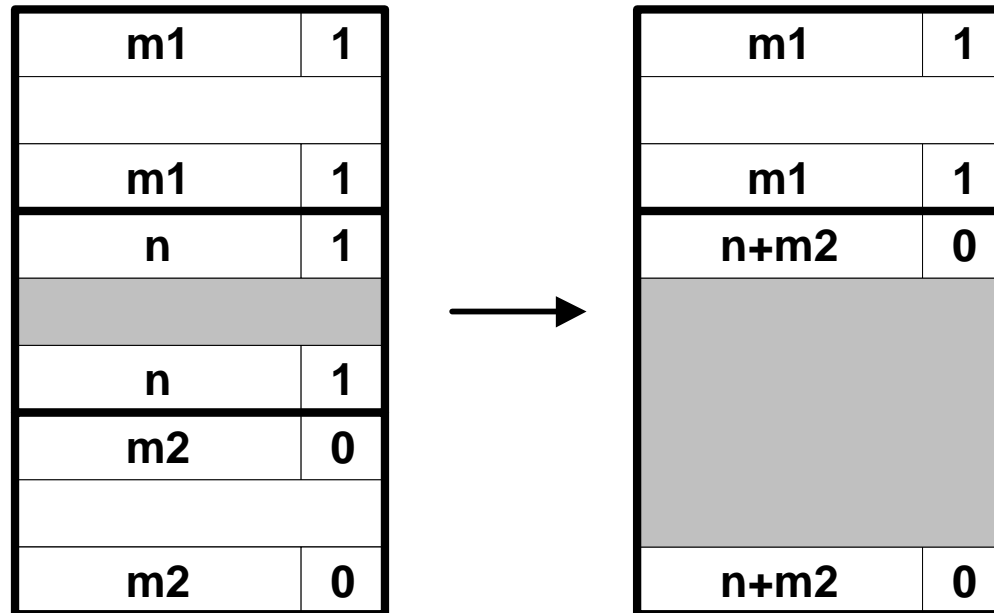




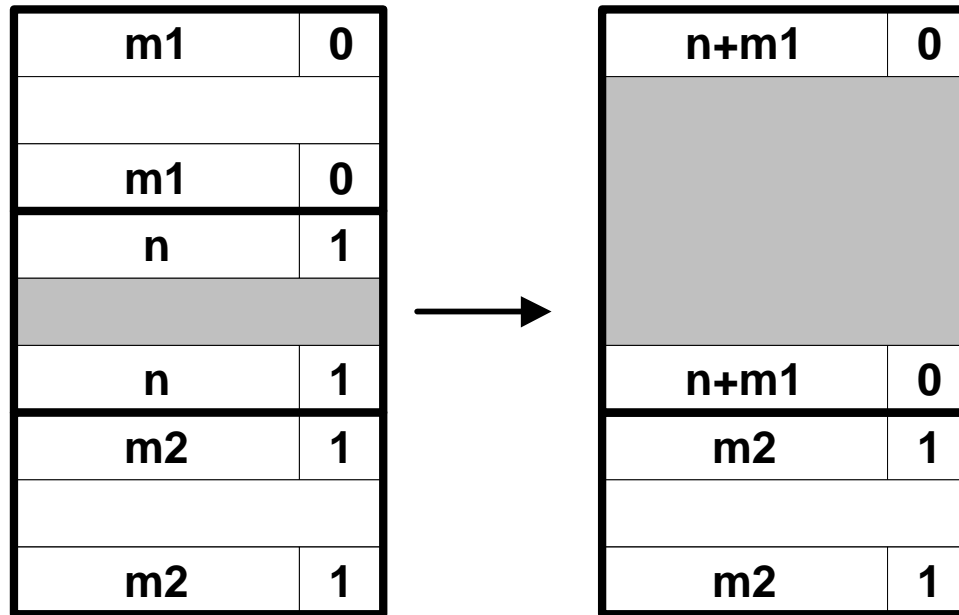
# Constant time coalescing (case 1)



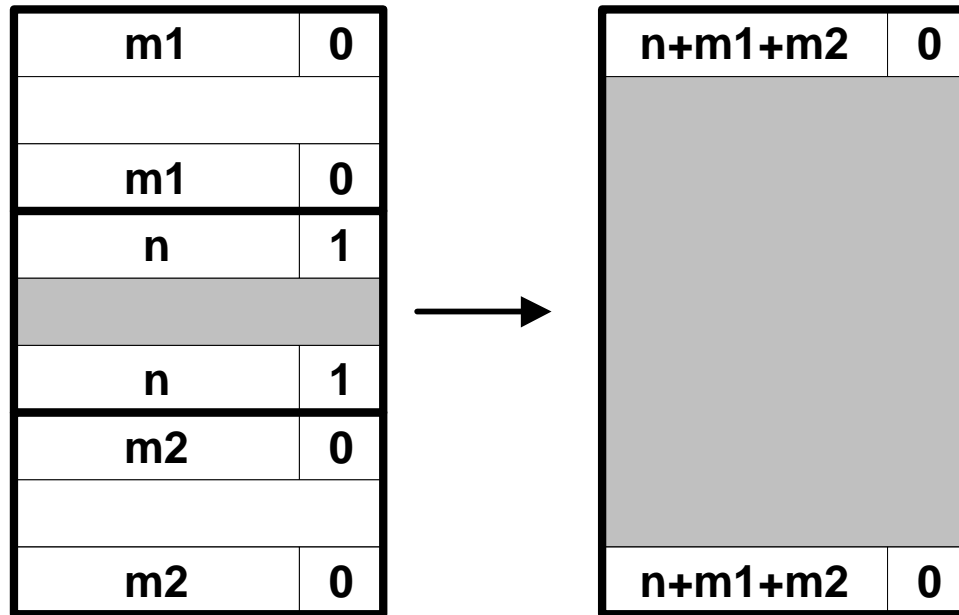
# Constant time coalescing (case 2)



# Constant time coalescing (case 3)



# Constant time coalescing (case 4)



# Summary of key allocator policies

## Placement policy:

- first fit, next fit, best fit, etc.
- trades off lower throughput for less fragmentation
  - Interesting observation: segregated free lists (next lecture) approximate a best fit placement policy without having the search entire free list.

## Splitting policy:

- When do we go ahead and split free blocks?
- How much internal fragmentation are we willing to tolerate?

## Coalescing policy:

- immediate coalescing: coalesce adjacent blocks each time free is called
- Deferred coalescing: try to improve performance of free by deferring coalescing until needed. e.g.,
  - coalesce as you scan the free list for malloc.
  - coalesce when the amount of external fragmentation reaches some threshold.

# Implicit lists: Summary

- **Implementation:** very simple
- **Allocate:** linear time worst case
- **Free:** constant time worst case -- even with coalescing
- **Memory usage:** will depend on placement policy
  - First fit, next fit or best fit

**Not used in practice for malloc/free because of linear time allocate. Used in many special purpose applications.**

**However, the concepts of splitting and boundary tag coalescing are general to *all* allocators.**