15-213

"The course that gives CMU its Zip!"

Concurrency I: Threads Nov 9, 2000

Topics

- Thread concept
- Posix threads (Pthreads) interface
- Linux Pthreads implementation
- Concurrent execution
- Sharing data

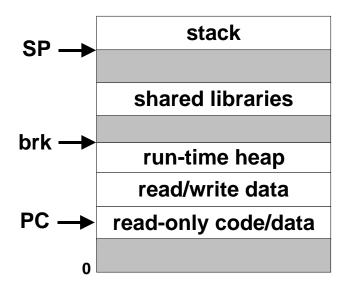
Traditional view of a process

Process = process context + code, data, and stack

Process context

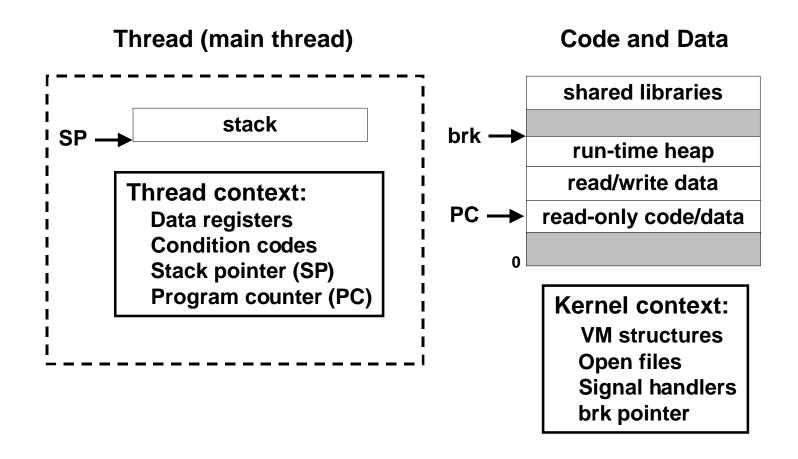
Program context:
 Data registers
 Condition codes
 Stack pointer (SP)
 Program counter (PC)
Kernel context:
 VM structures
 Open files
 Signal handlers
 brk pointer

Code, data, and stack



Modern view of a process

Process = thread + code, data, and kernel context



A process with multiple threads

Multiple threads can be associated with a process

- Each thread has its own logical control flow (sequence of PC values)
- Each thread shares the same code, data, and kernel context
- Each thread has its own thread id (tid)

Thread 1 (main thread)

stack 1

Thread 1 context:

Data registers

Condition codes

SP1
PC1

Shared code and data

shared libraries

run-time heap

read/write data

read-only code/data

Kernel context:

VM structures
Open files
Signal handlers
brk pointer

.

stack 2

Thread 2 (peer thread)

Thread 2 context:
Data registers
Condition codes

SP2

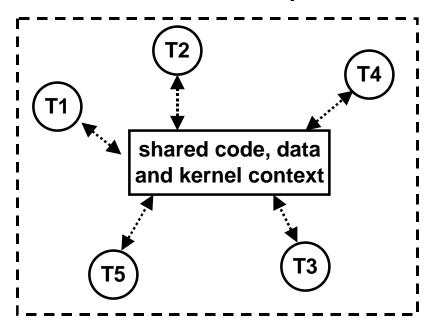
PC2

Logical view of threads

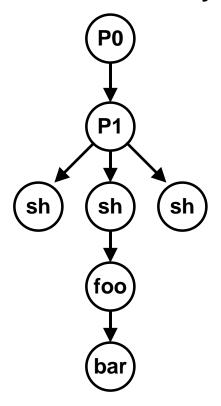
Threads associated with a process form a pool of peers.

unlike processes which form a tree hierarchy

Threads associated with process foo



Process hierarchy



Concurrent thread execution

Two threads run concurrently (are concurrent) if their logical flows overlap in time.

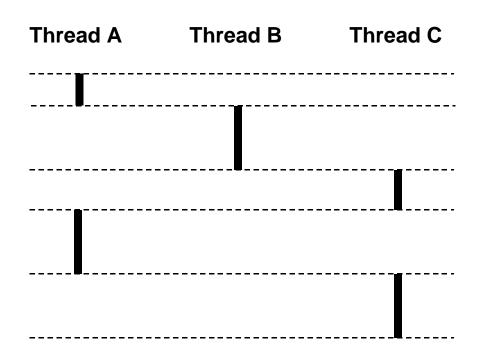
Otherwise, they are sequential.

Examples:

• Concurrent: A & B, A&C

Sequential: B & C

Time



Threads vs processes

How threads and processes are similar

- Each has its own logical control flow.
- Each can run concurrently.
- Each is context switched.

How threads and processes are different

- Threads share code and data, processes (typically) do not.
- Threads are somewhat less expensive than processes.
 - process control (creating and reaping) is twice as expensive as thread control.
 - -Linux/Pentium III numbers:
 - » 20K cycles to create and reap a process.
 - » 10K cycles to create and reap a thread.

Threads are a unifying abstraction for exceptional control flow

Exception handler

- A handler can be viewed as a thread
- Waits for a "signal" from CPU
- Upon receipt, executes some code, then waits for next "signal"

Process

A process is a thread + shared code, data, and kernel context.

Signal handler

- A signal handler can be viewed as a thread
- Waits for a signal from the kernel or another process
- Upon receipt, executes some code, then waits for next signal.

Posix threads (Pthreads) interface

Pthreads: Standard interface for ~60 functions that manipulate threads from C programs.

- Creating and reaping threads.
 - -pthread_create
 - -pthread_join
- Determining your thread ID
 - -pthread_self
- Terminating threads
 - -pthread_cancel
 - -pthread_exit
 - -exit() [terminates all threads], ret [terminates current thread]
- Synchronizing access to shared variables
 - -pthread_mutex_init
 - -pthread_mutex_[un]lock
 - -pthread cond init
 - -pthread cond [timed]wait

The Pthreads "hello, world" program

```
* hello.c - Pthreads "hello, world" program
 */
                                                     Thread attributes
#include <ics.h>
                                                      (usually NULL)
void *thread(void *vargp);
                                                     Thread arguments
int main() {
                                                        (void *p)
  pthread t tid;
  Pthread_create(&tid, NULL, thread, NULL);
  Pthread_join(tid, NULL);
  exit(0);
                                                     return value
                                                      (void **p)
/* thread routine */
void *thread(void *vargp) {
  printf("Hello, world!\n");
  return NULL;
```

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Execution of "hello, world"

main thread

peer thread

create peer thread

wait for peer thread
to terminate

exit() terminates main thread and any
peer threads

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Unix vs Posix error handling

Unix-style error handling (Unix syscalls)

- if error: return -1 and set errno variable to error code.
- if OK: return useful result as value >= 0.

```
if ((pid = wait(NULL)) < 0) {
    perror("wait");
    exit(0);
}</pre>
```

Posix-style error handling (newer Posix functions)

- if error: return nonzero error code, zero if OK
- useful results are passed back in an argument.

```
if ((rc = pthread_join(tid, &retvalp)) != 0) {
   printf("pthread_create: %s\n", strerror(rc));
   exit(0);
}
```

Suggested error handling macros

Error checking crucial, but cluttered. Use these to simplify your error checking:

```
/*
 * macro for unix-style error handling
 */
#define unix_error(msg) do {\
 printf("%s: %s\n", msg, strerror(errno));\
 exit(0);\
} while (0)
```

```
/*
 * macro for posix-style error handling
 */
#define posix_error(code,msg) do {\
 printf("%s: %s\n", msg, strerror(code));\
 exit(0);\
} while (0)
```

Pthreads wrappers

We advocate Steven's convention of providing wrappers for each system-level function call.

- wrapper is denoted by capitalizing first letter of function name.
- wrapper has identical interface as the original function.
- each wrapper does appropriate unix or posix style error checking.
- wrapper typically return nothing.
- declutters code without compromising safety.

```
/*
  * wrapper function for pthread_join
  */
void Pthread_join(pthread_t tid, void **thread_return) {
  int rc = pthread_join(tid, thread_return);
  if (rc != 0)
    posix_error(rc, "Pthread_join");
}
```

Basic thread control: create a thread

Creates a new peer thread

- tidp: thread id
- attrp: thread attributes (usually NULL)
- routine: thread routine
- argp: input parameters to routine

Akin to fork()

- but without the confusing "call once return twice" semantics.
- peer thread has local stack variables, but shares all global variables.

Basic thread control: join

int pthread_join(pthread_t tid, void **thread_return);

Waits for a specific peer thread to terminate, and then reaps it.

- tid: thread ID of thread to wait for.
- thread_return: object returned by peer thread via ret stmt

Akin to wait and wait_pid but unlike wait ...

- Any thread can reap any other thread (not just children)
- Must wait for a *specific* thread
 - no way to wait for *any* thread.
 - -perceived by some as a flaw in the Pthreads design

Linux implementation of Pthreads

Linux implements threads in an elegant way:

- Threads are just processes that share the same kernel context.
- fork(): creates a child process with a new kernel context
- clone(): creates a child process that shares some or all of the parent's kernel context.

Creates a new process and executes function fn with argument arg in that process using the stack space pointed to by child_stack. Returns pid of new process.

flags determine the degree of kernel context sharing: e.g.,

CLONE_VM: share virtual address space CLONE_FS: share file system information CLONE_FILES: share open file descriptors

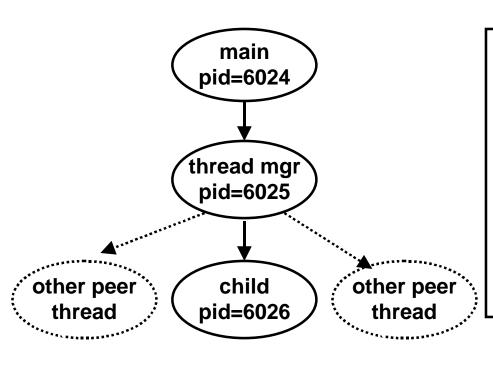
hellopid.c

The following routine will show us the process hierarchy of a Linux thread pool:

```
#include <ics.h>
void *thread(void *vargp);
int main() {
 pthread t tid;
 printf("Hello from main thread! tid:%ld pid:%d\n",
        pthread self(), getpid());
 Pthread_create(&tid, NULL, thread, NULL);
 Pthread join(tid, NULL);
  exit(0);
void *thread(void *vargp) {
 printf("Hello from child thread! tid:%ld pid:%d ppid:%d\n",
        pthread_self(), getpid(), getppid());
  return NULL;
```

Linux process hierarchy for threads

```
bass> hellopid
Hello from main thread! tid:1024 pid:6024
Hello from child thread! tid:1025 pid:6026 ppid:6025
```



Thread manager supports thread abstraction using signals:

- exit(): kills all threads, regardless where it is called from
- slow system calls such as sleep() or read() block only the calling thread.

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beep.c: Performing concurrent tasks

```
/*
 * beeps until the user hits a key
 */
#include <ics.h>
void *thread(void *vargp);
/* shared by both threads */
char shared = '\0';
int main() {
 pthread t tid;
  Pthread_create(&tid, NULL,
                 thread, NULL);
 while (shared == '\0') {
    printf("BEEP\n");
    sleep(1);
  Pthread_join(tid, NULL);
  printf("DONE\n");
  exit(0);
```

```
/* thread routine */
void *thread(void *vargp) {
   shared = getchar();
   return NULL;
}
```

badcnt.c: Sharing data between threads

```
/* bad sharing */
#include <ics.h>
#define NITERS 1000
void *count(void *arg);
struct {
  int counter;
} shared;
int main() {
  pthread t tid1, tid2;
  Pthread create(&tid1, NULL,
                 count, NULL);
  Pthread create(&tid2, NULL,
                  count, NULL);
  if (shared.counter != NITERS*2)
    printf("BOOM! counter=%d\n",
            shared.counter);
  else
   printf("OK counter=%d\n",
            shared.counter);
```

Key point:

"struct shared" is visible to all threads.

"i" and "val" are visible only to the count thread.

Running badcnt.c

Output of run 1

1025: 0 1025: 1 1025: 2 ... 1025: 997 1025: 998 1025: 999 2050: 969 2050: 970 2050: 971 ... 2050: 1966 2050: 1967 2050: 1968 BOOM! counter=1969

Output of run 2

1025:	0
1025:	1
1025:	2
• • •	
1025:	997
1025:	998
1025:	999
2050:	712
2050:	713
2050:	714
• • •	
2050:	1709
2050:	1710
2050:	1711
BOOM!	counter=1712

Output of run 3

```
1025: 0
1025: 1
1025: 2
...
1025: 997
1025: 998
1025: 999
2050: 1000
2050: 1001
2050: 1001
2050: 1997
2050: 1998
2050: 1999
OK counter=2000
```

So what's the deal?

We must synchronize concurrent accesses to shared thread data (the topic of our next lecture)