

Cache Memories

15-213: Introduction to Computer Systems
12th Lecture, October 6th, 2016

Instructor:

Randy Bryant

Today

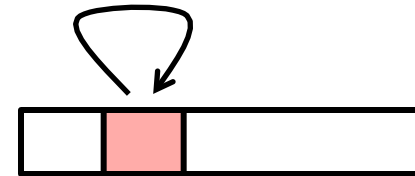
- **Cache memory organization and operation**
- **Performance impact of caches**
 - The memory mountain
 - Rearranging loops to improve spatial locality

Locality

- **Principle of Locality:** Programs tend to use data and instructions with addresses near or equal to those they have used recently

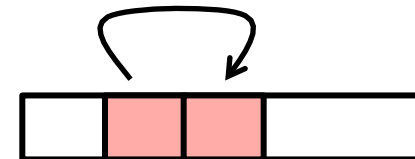
- **Temporal locality:**

- Recently referenced items are likely to be referenced again in the near future

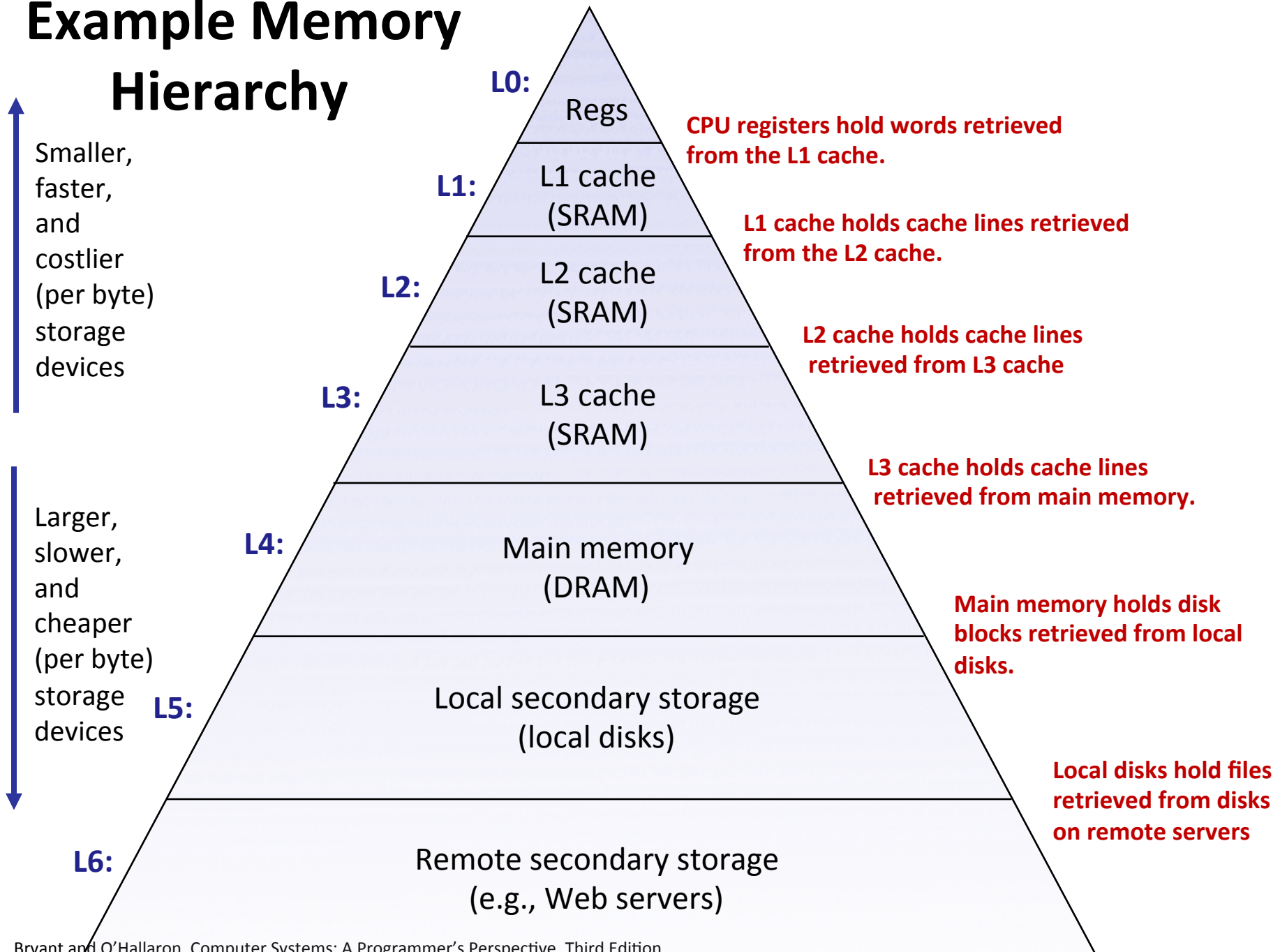


- **Spatial locality:**

- Items with nearby addresses tend to be referenced close together in time

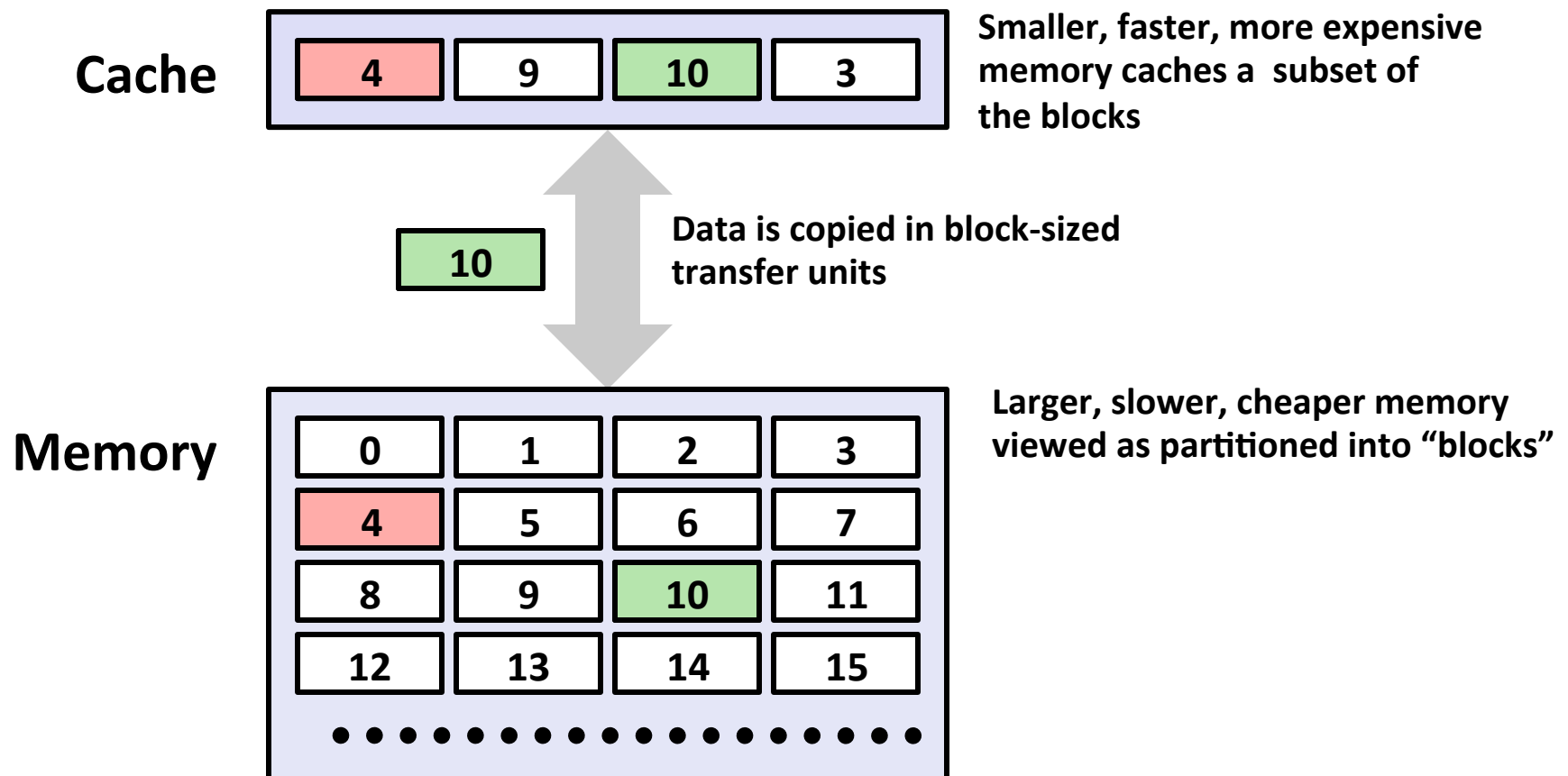


Example Memory Hierarchy

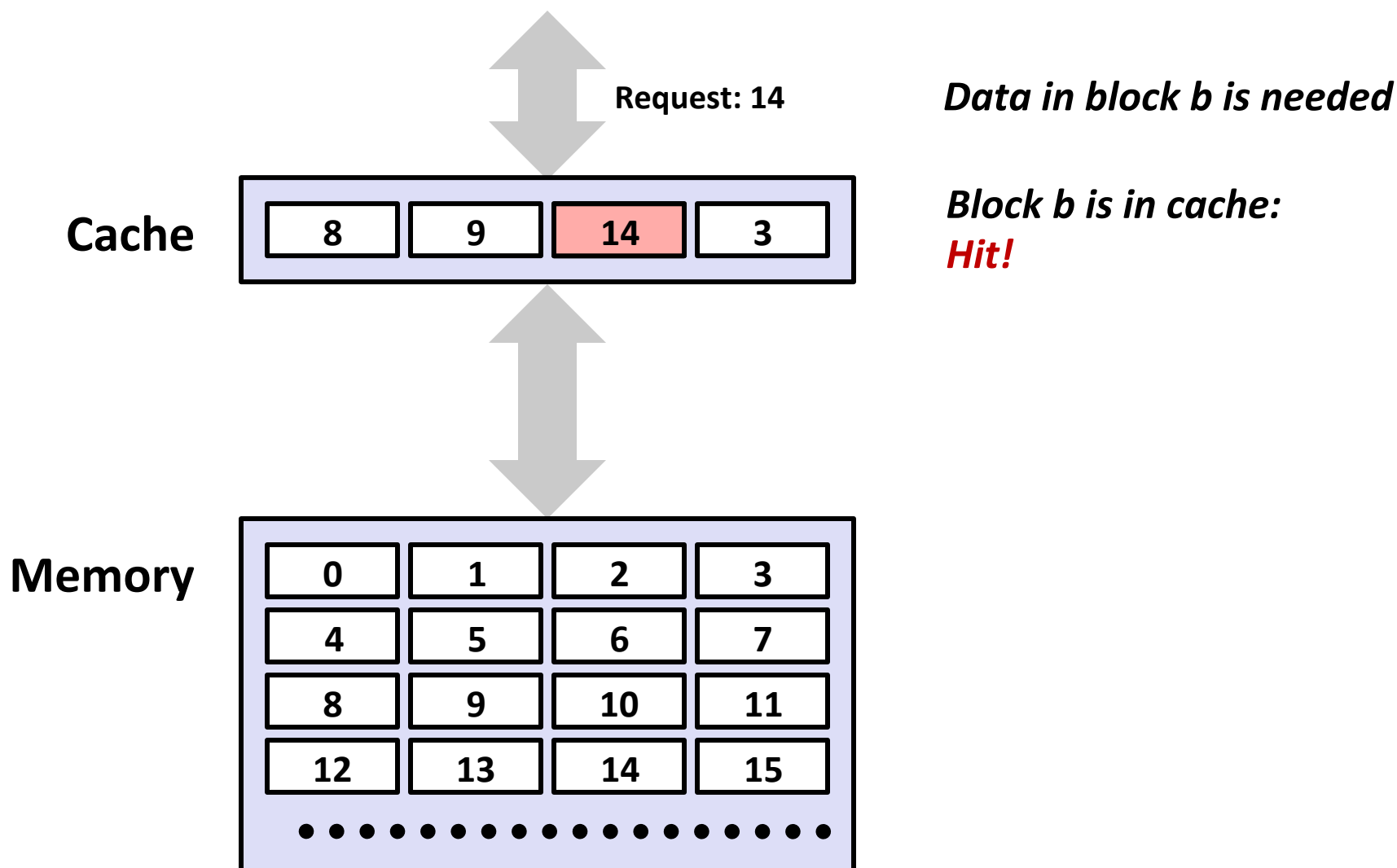


General Cache Concepts

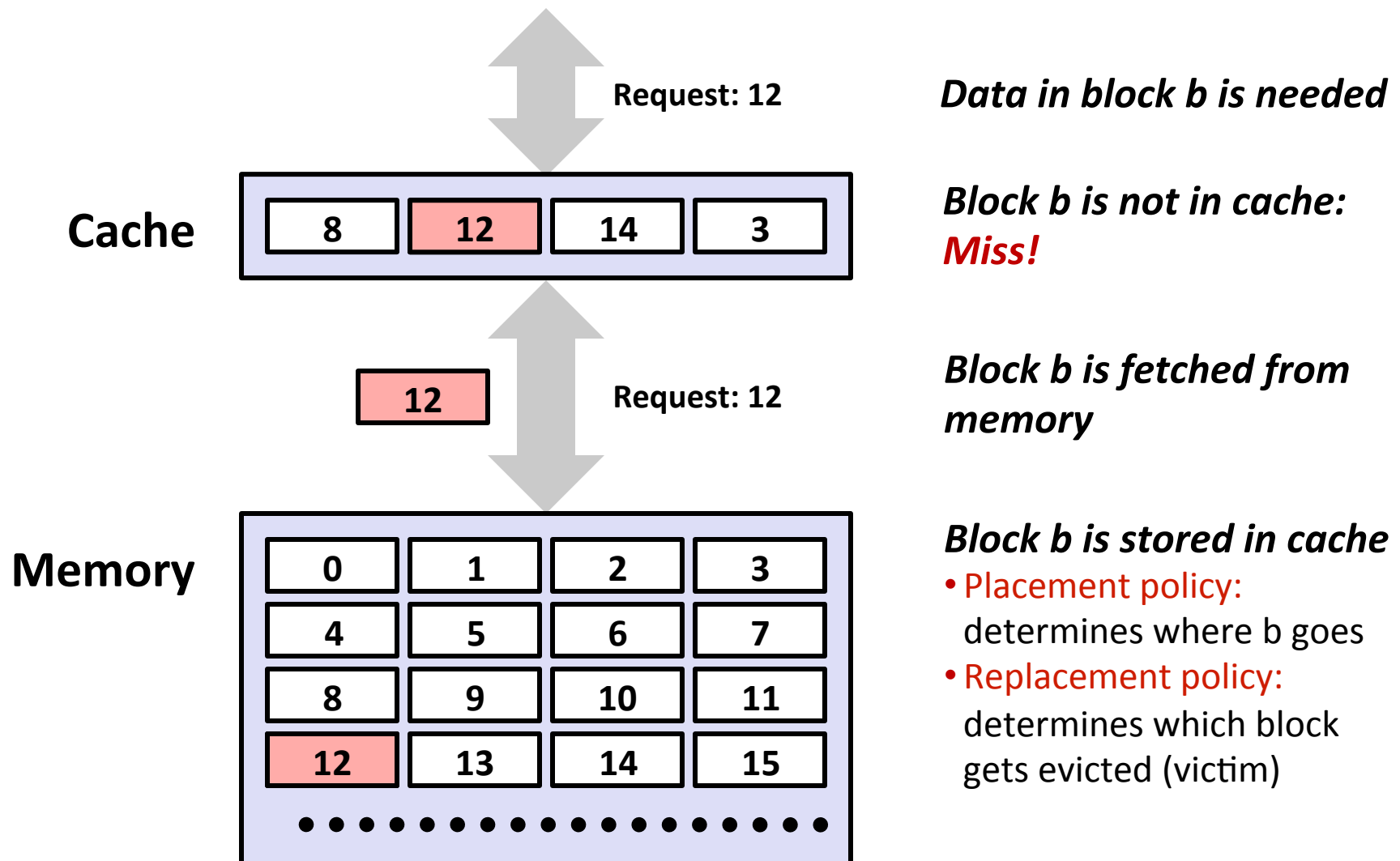
Everything handled in hardware. Invisible to programmer



General Cache Concepts: Hit



General Cache Concepts: Miss



General Caching Concepts:

Types of Cache Misses

■ Cold (compulsory) miss

- Cold misses occur because the cache is empty.

■ Conflict miss

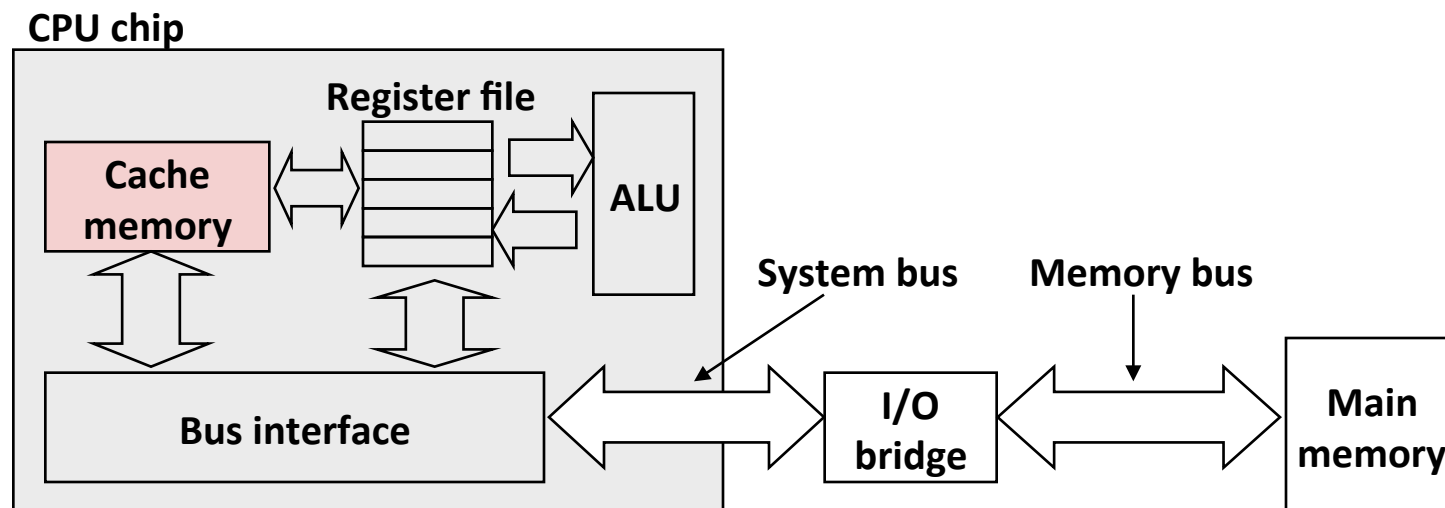
- Most caches limit blocks at level $k+1$ to a small subset (sometimes a singleton) of the block positions at level k .
 - E.g. Block i at level $k+1$ must be placed in block $(i \bmod 4)$ at level k .
- Conflict misses occur when the level k cache is large enough, but multiple data objects all map to the same level k block.
 - E.g. Referencing blocks 0, 8, 0, 8, 0, 8, ... would miss every time.

■ Capacity miss

- Occurs when the set of active cache blocks (**working set**) is larger than the cache.

Cache Memories

- **Cache memories** are small, fast SRAM-based memories managed automatically in hardware
 - Hold frequently accessed blocks of main memory
- CPU looks first for data in cache
- Typical system structure:



What it Really Looks Like

Desktop PC

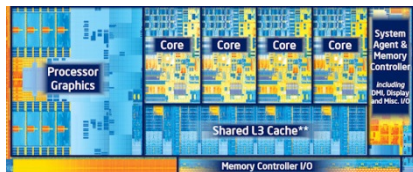


Source: Dell

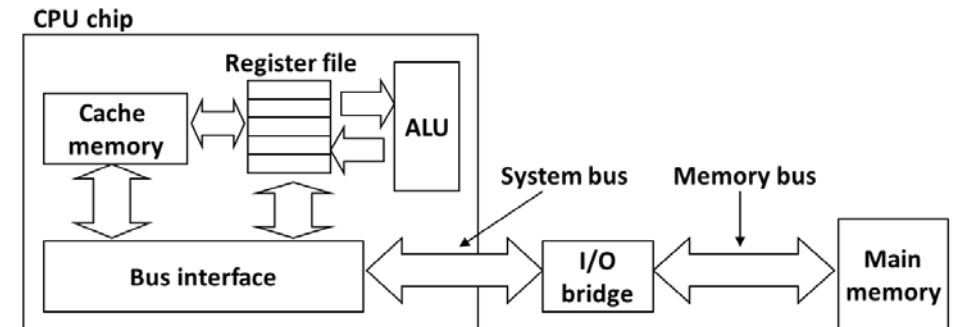
CPU (Intel Core i7)



Source: PC Magazine



Source: techreport.com

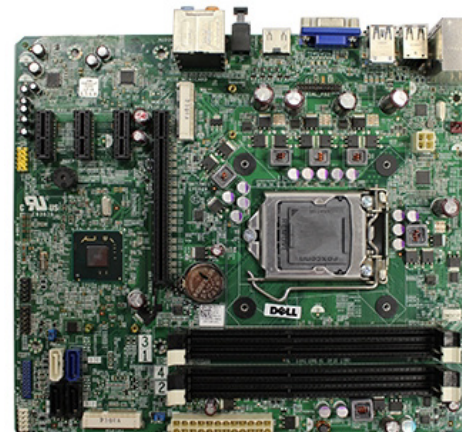


Main memory (DRAM)



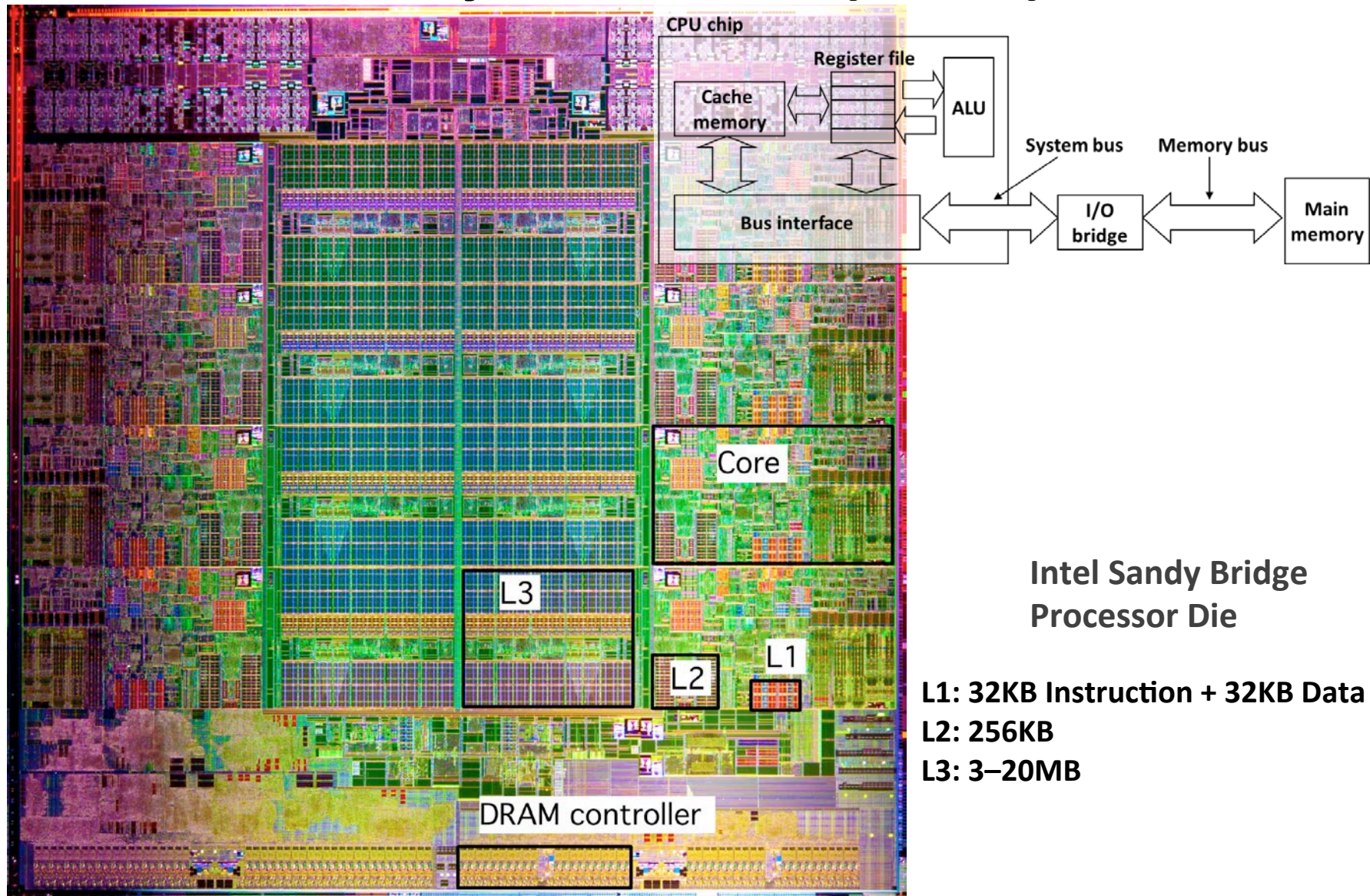
Source: Dell

Motherboard

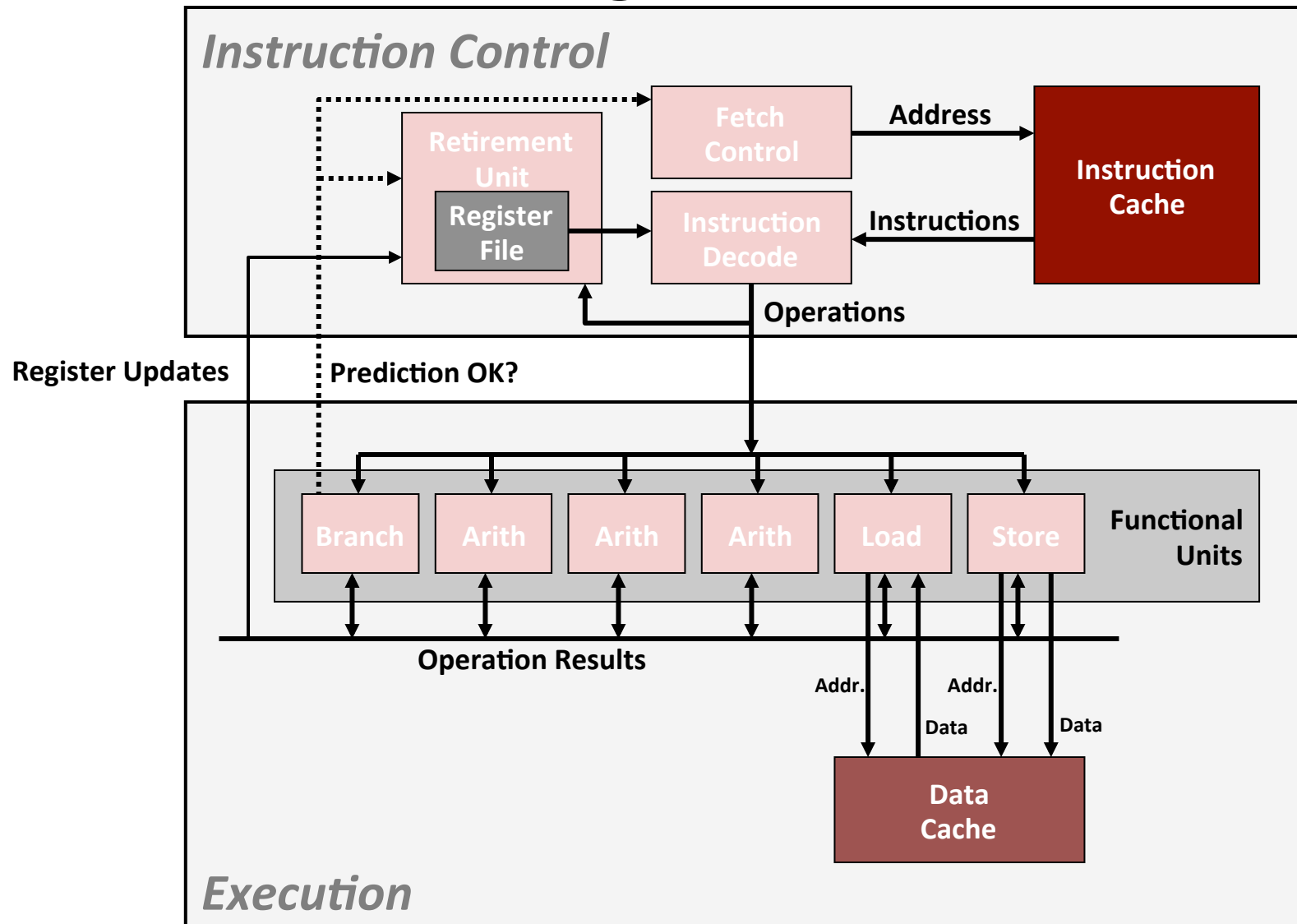


Source: Dell

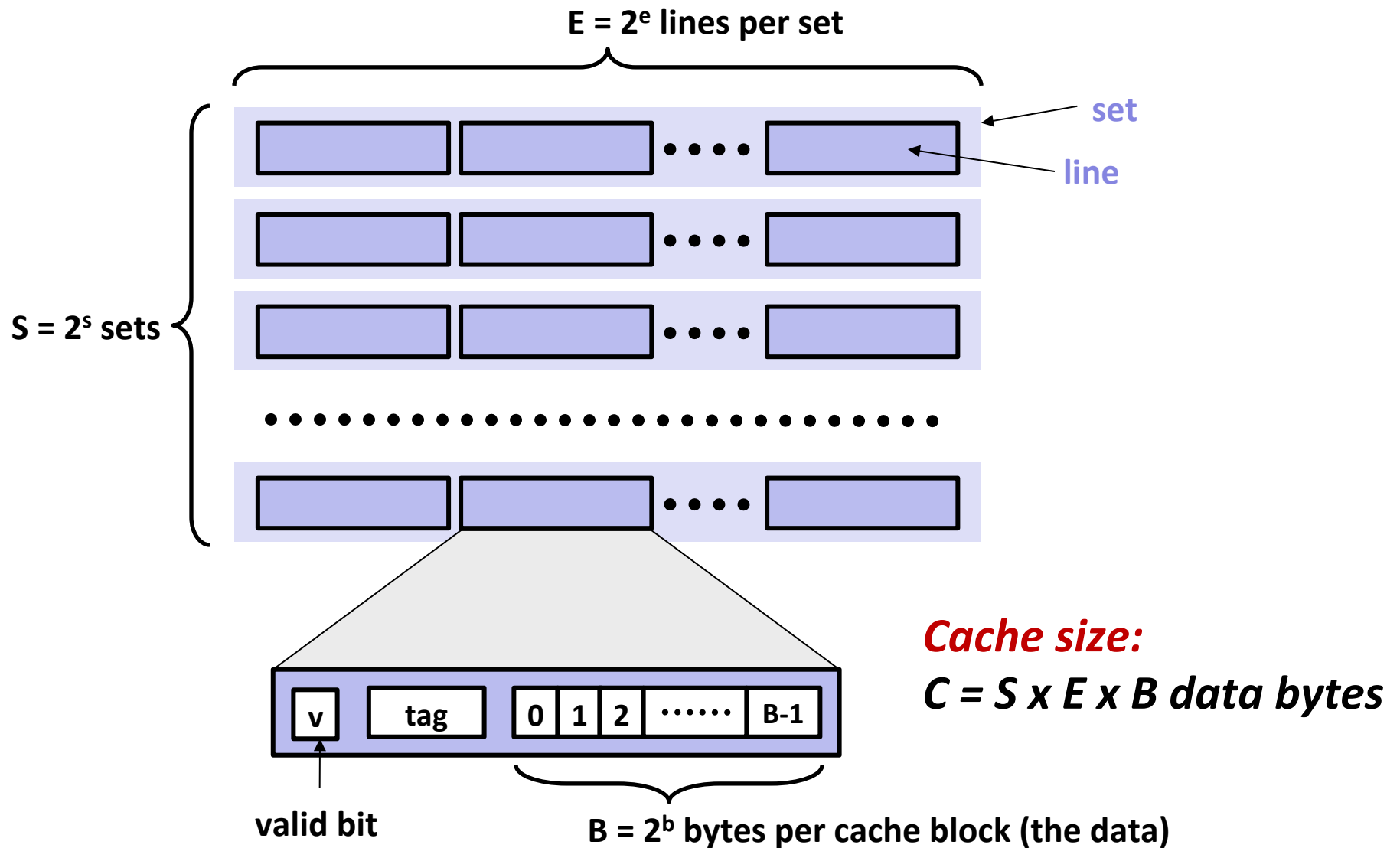
What it Really Looks Like (Cont.)



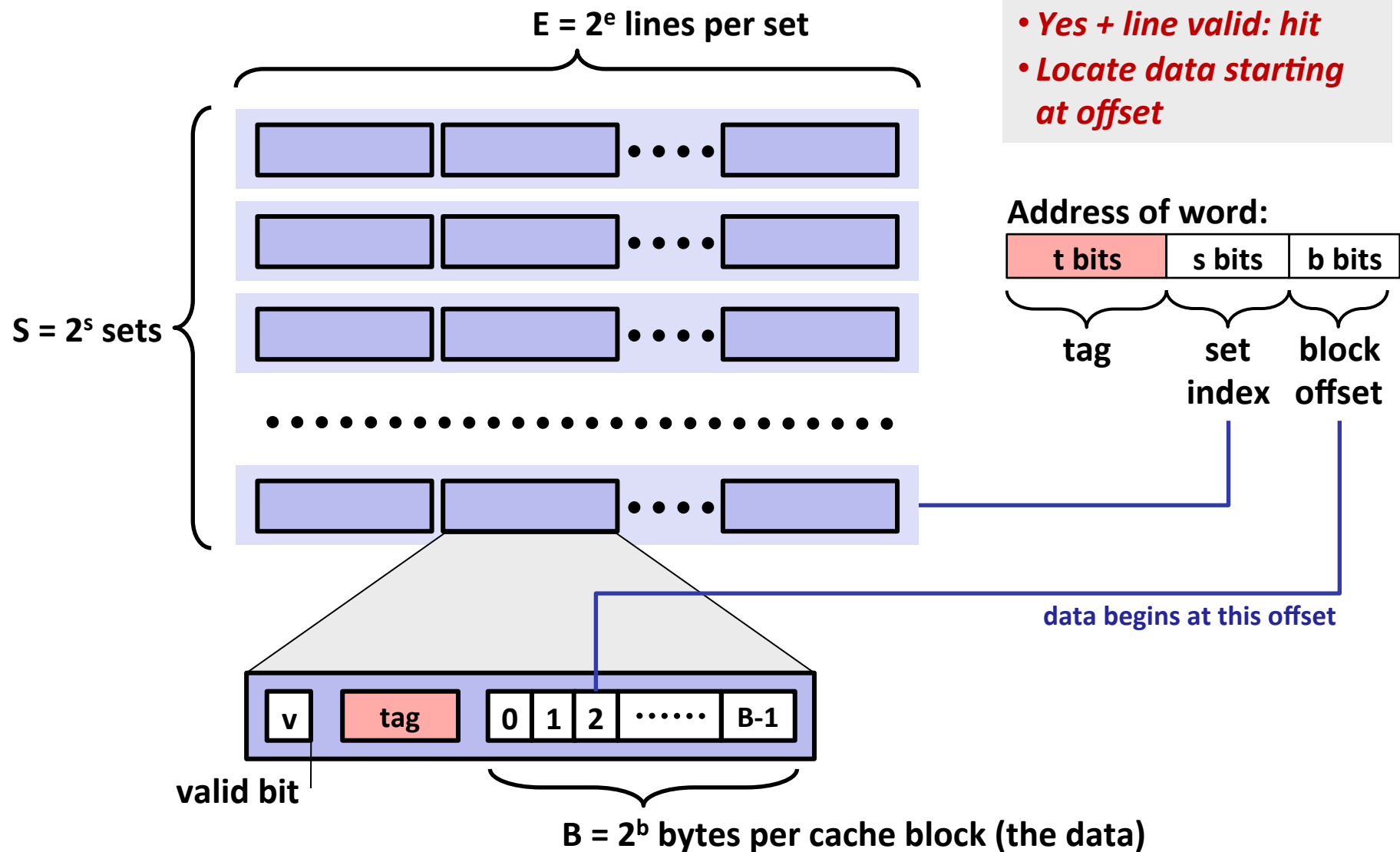
Recap from Lecture 10: Modern CPU Design



General Cache Organization (S, E, B)



Cache Read

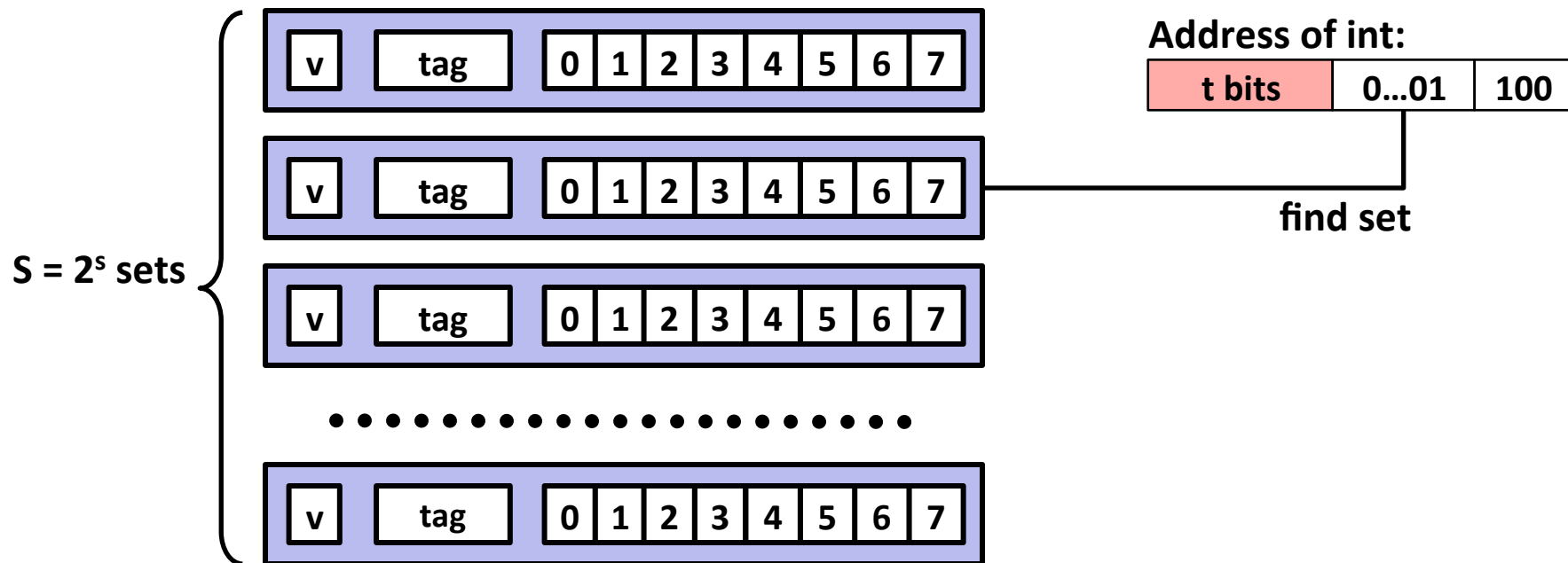


- *Locate set*
- *Check if any line in set has matching tag*
- *Yes + line valid: hit*
- *Locate data starting at offset*

Example: Direct Mapped Cache ($E = 1$)

Direct mapped: One line per set

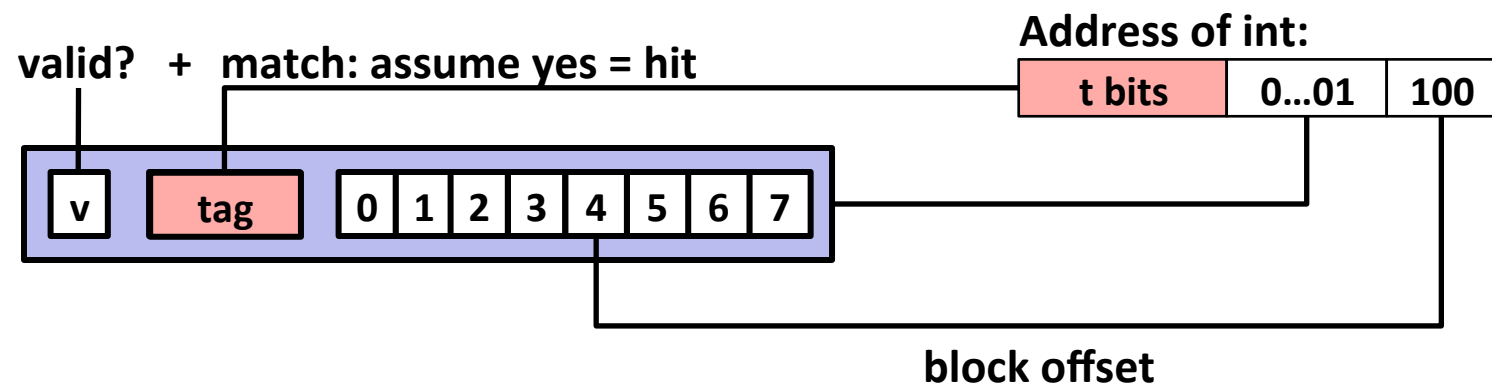
Assume: cache block size 8 bytes



Example: Direct Mapped Cache (E = 1)

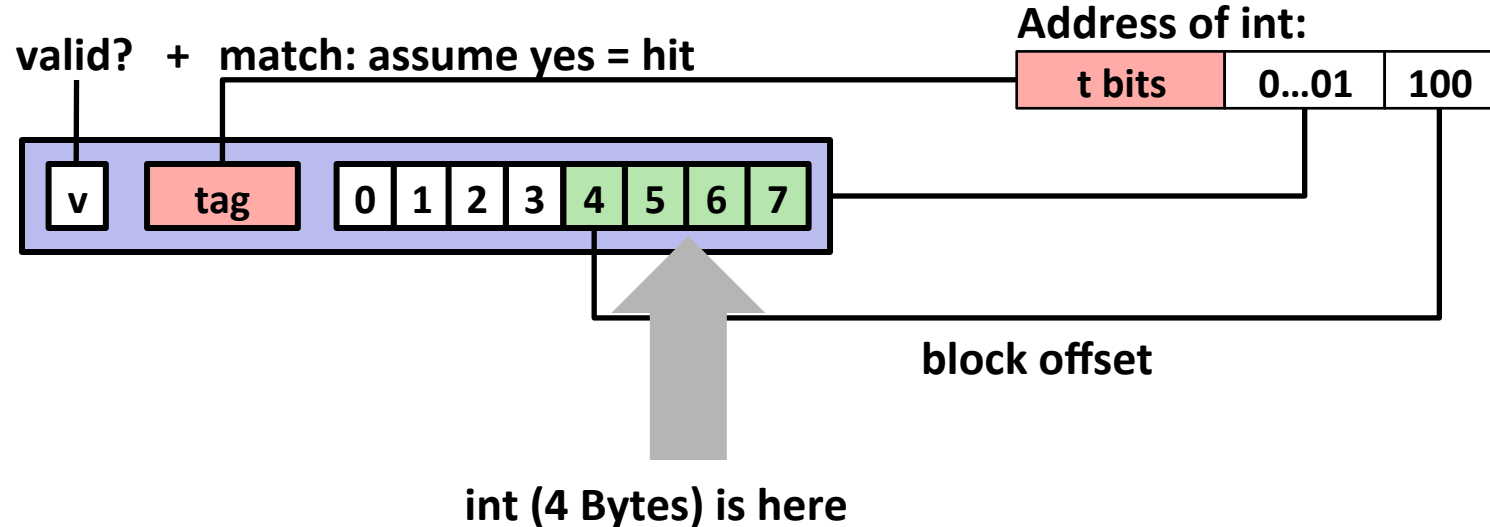
Direct mapped: One line per set

Assume: cache block size 8 bytes



Example: Direct Mapped Cache (E = 1)

Direct mapped: One line per set
Assume: cache block size 8 bytes



If tag doesn't match: old line is evicted and replaced

Direct-Mapped Cache Simulation

t=1	s=2	b=1
x	xx	x

M=16 bytes (4-bit addresses), B=2 bytes/block,
S=4 sets, E=1 Blocks/set

Address trace (reads, one byte per read):

0	[0000 ₂],	miss
1	[0001 ₂],	hit
7	[0111 ₂],	miss
8	[1000 ₂],	miss
0	[0000 ₂]	miss

	v	Tag	Block
Set 0	1	0	M[0-1]
Set 1			
Set 2			
Set 3	1	0	M[6-7]

E-way Set Associative Cache (Here: E = 2)

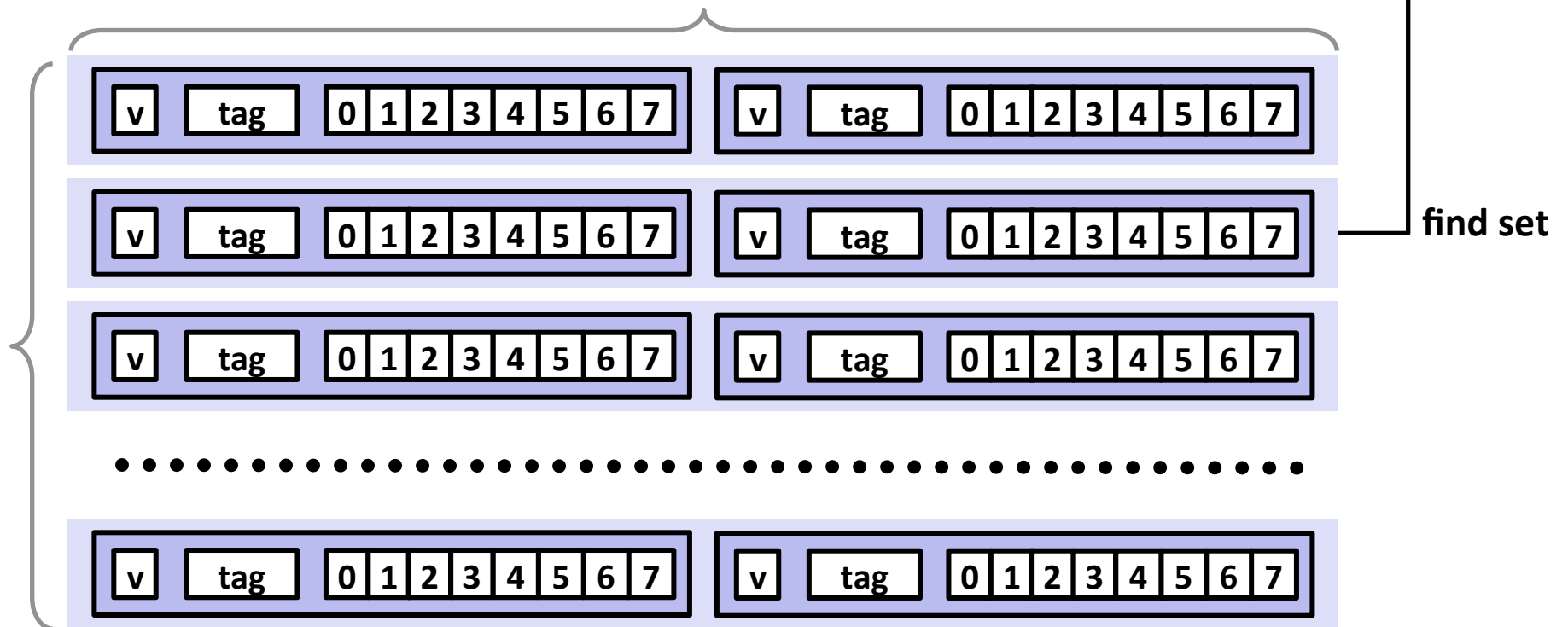
E = 2: Two lines per set

Assume: cache block size 8 bytes

Address of short int:

t bits	0...01	100
--------	--------	-----

2 lines per set

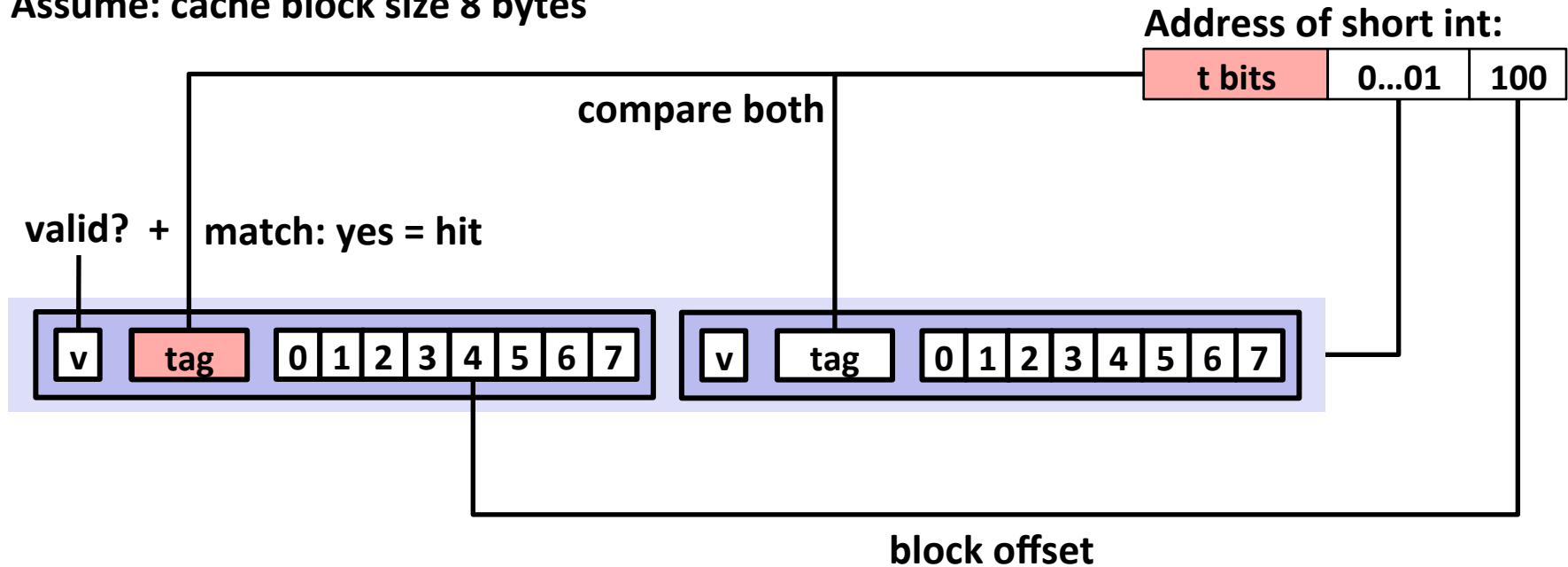


S sets

E-way Set Associative Cache (Here: E = 2)

E = 2: Two lines per set

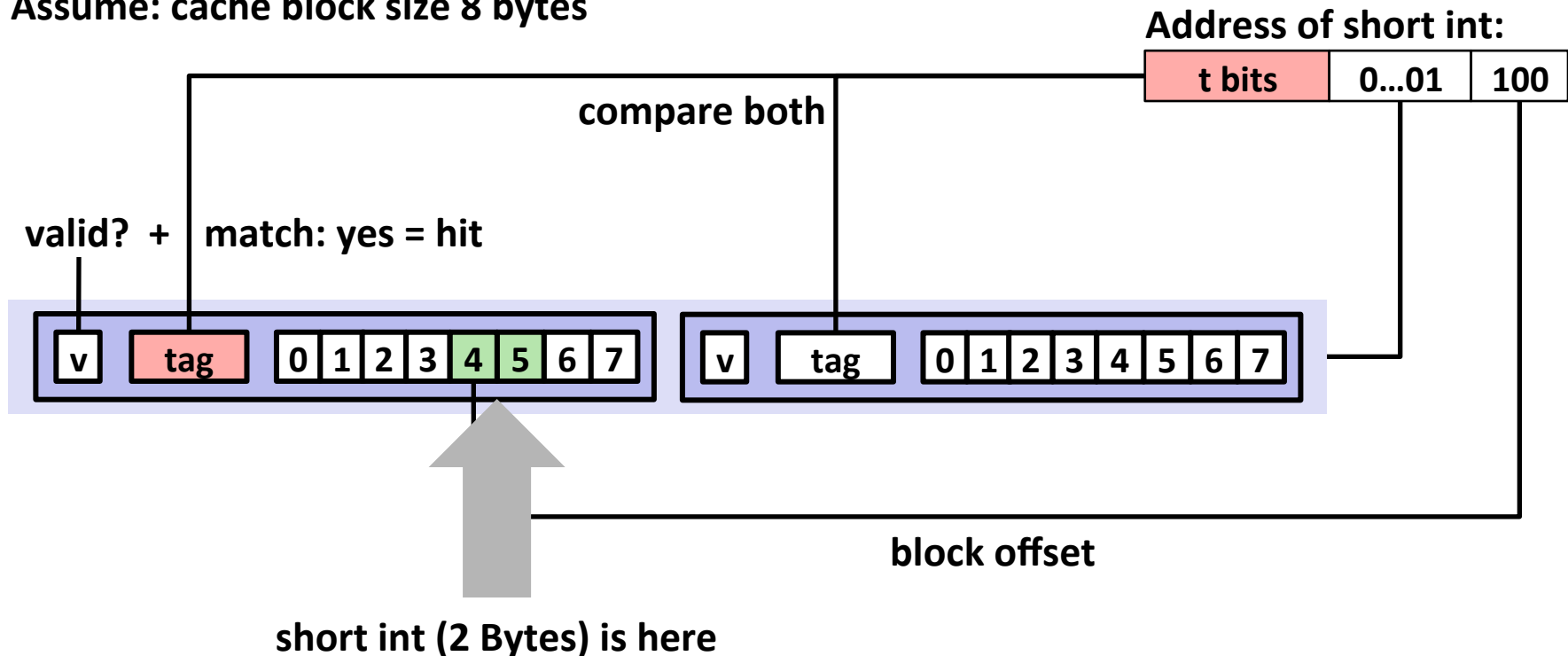
Assume: cache block size 8 bytes



E-way Set Associative Cache (Here: E = 2)

E = 2: Two lines per set

Assume: cache block size 8 bytes



No match:

- One line in set is selected for eviction and replacement
- Replacement policies: random, least recently used (LRU), ...

2-Way Set Associative Cache Simulation

t=2	s=1	b=1
xx	x	x

M=16 byte addresses, B=2 bytes/block,
S=2 sets, E=2 blocks/set

Address trace (reads, one byte per read):

0	[00 <u>0</u> 0] ₂ ,	miss
1	[00 <u>0</u> 1] ₂ ,	hit
7	[0 <u>1</u> 11] ₂ ,	miss
8	[10 <u>0</u> 0] ₂ ,	miss
0	[00 <u>0</u> 0] ₂	hit

	v	Tag	Block
Set 0	1	00	M[0-1]
	1	10	M[8-9]
Set 1	1	01	M[6-7]
	0		

What about writes?

■ Multiple copies of data exist:

- L1, L2, L3, Main Memory, Disk

■ What to do on a write-hit?

- **Write-through** (write immediately to memory)
- **Write-back** (defer write to memory until replacement of line)
 - Need a dirty bit (line different from memory or not)

■ What to do on a write-miss?

- **Write-allocate** (load into cache, update line in cache)
 - Good if more writes to the location follow
- **No-write-allocate** (writes straight to memory, does not load into cache)

■ Typical

- Write-through + No-write-allocate
- **Write-back + Write-allocate**

Why Index Using Middle Bits?

Direct mapped: One line per set
Assume: cache block size 8 bytes

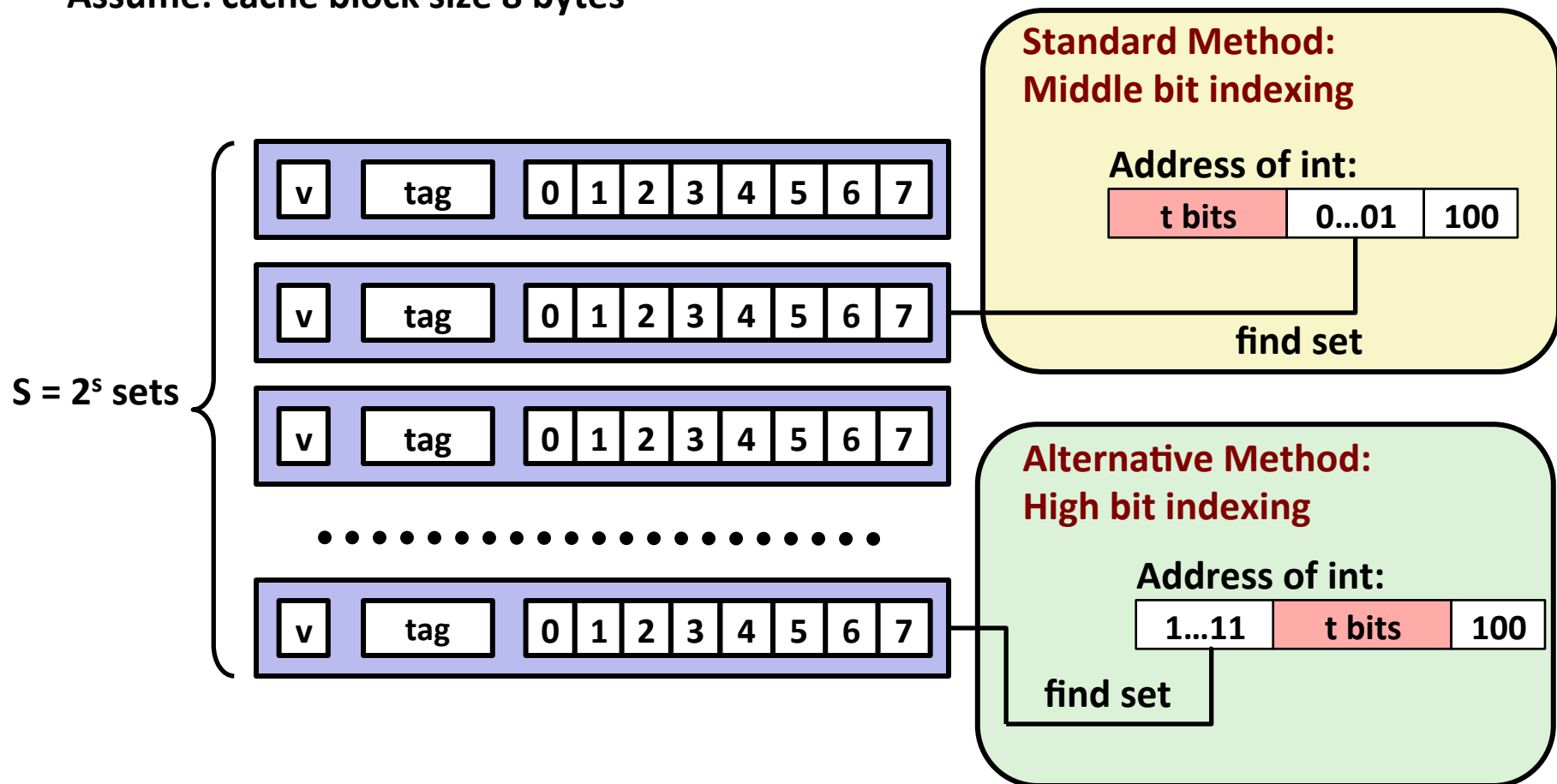
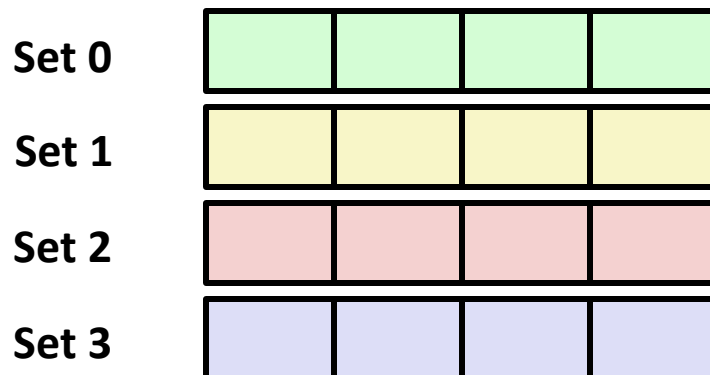


Illustration of Indexing Approaches

- 64-byte memory
 - 6-bit addresses
- 16 byte, direct-mapped cache
- Block size = 4 (4 sets)
- 2 bits tag, 2 bits index, 2 bits offset



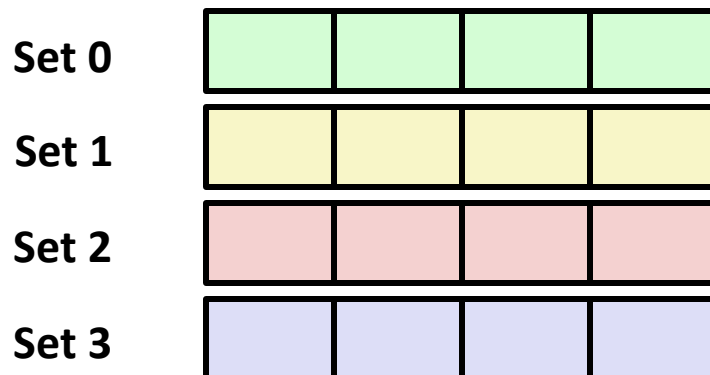
				0000xx
				0001xx
				0010xx
				0011xx
				0100xx
				0101xx
				0110xx
				0111xx
				1000xx
				1001xx
				1010xx
				1011xx
				1100xx
				1101xx
				1110xx
				1111xx

Middle Bit Indexing

■ Addresses of form **TTSSBB**

- **TT** Tag bits
- **SS** Set index bits
- **BB** Offset bits

■ Makes good use of spatial locality



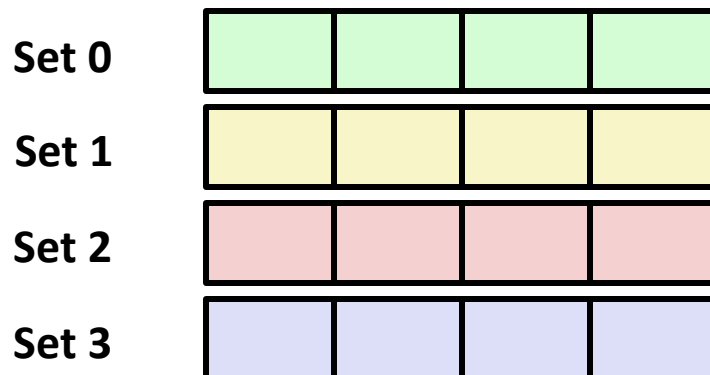
				0000xx
				0001xx
				0010xx
				0011xx
				0100xx
				0101xx
				0110xx
				0111xx
				1000xx
				1001xx
				1010xx
				1011xx
				1100xx
				1101xx
				1110xx
				1111xx





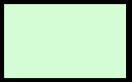
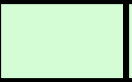
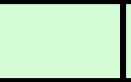
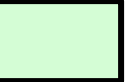
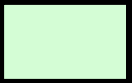
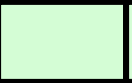
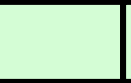
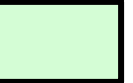
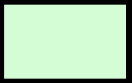
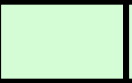
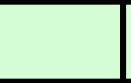
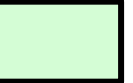
















































High Bit Indexing

■ Addresses of form **SS****TT****BB**

- **SS** Set index bits
- **TT** Tag bits
- **BB** Offset bits

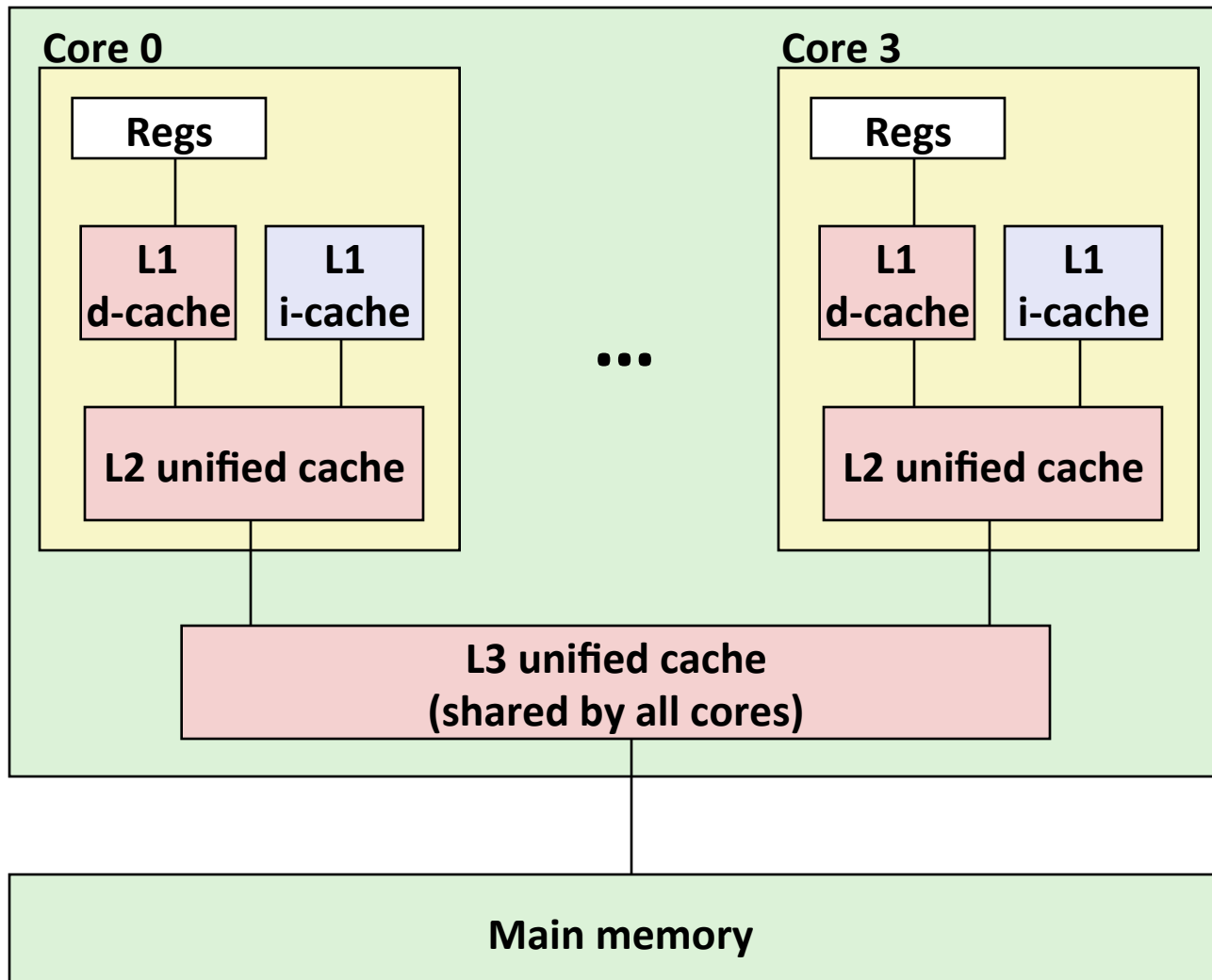
■ Program with high spatial locality would generate lots of conflicts



				0000xx
				0001xx
				0010xx
				0011xx
				0100xx
				0101xx
				0110xx
				0111xx
				1000xx
				1001xx
				1010xx
				1011xx
				1100xx
				1101xx
				1110xx
				1111xx

Intel Core i7 Cache Hierarchy

Processor package



L1 i-cache and d-cache:
32 KB, 8-way,
Access: 4 cycles

L2 unified cache:
256 KB, 8-way,
Access: 10 cycles

L3 unified cache:
8 MB, 16-way,
Access: 40-75 cycles

Block size: 64 bytes for
all caches.

Example: Core i7 L1 Data Cache

32 kB 8-way set associative

64 bytes/block

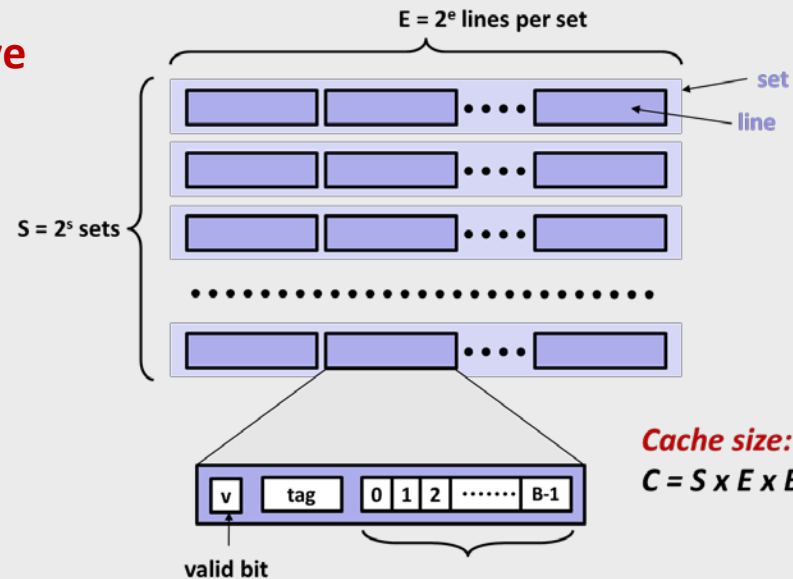
47 bit address range

B =

S = , s =

E = , e =

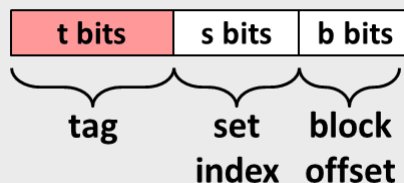
C =



Cache size:
 $C = S \times E \times B$ data bytes

Hex	Decimal	Binary
0	0	0000
1	1	0001
2	2	0010
3	3	0011
4	4	0100
5	5	0101
6	6	0110
7	7	0111
8	8	1000
9	9	1001
A	10	1010
B	11	1011
C	12	1100
D	13	1101
E	14	1110
F	15	1111

Address of word:



Block offset: . bits

Set index: . bits

Tag: . bits

Stack Address:

0x00007f7262a1e010

Block offset:

0x??

Set index:

0x??

Tag:

0x??

Example: Core i7 L1 Data Cache

32 kB 8-way set associative

64 bytes/block

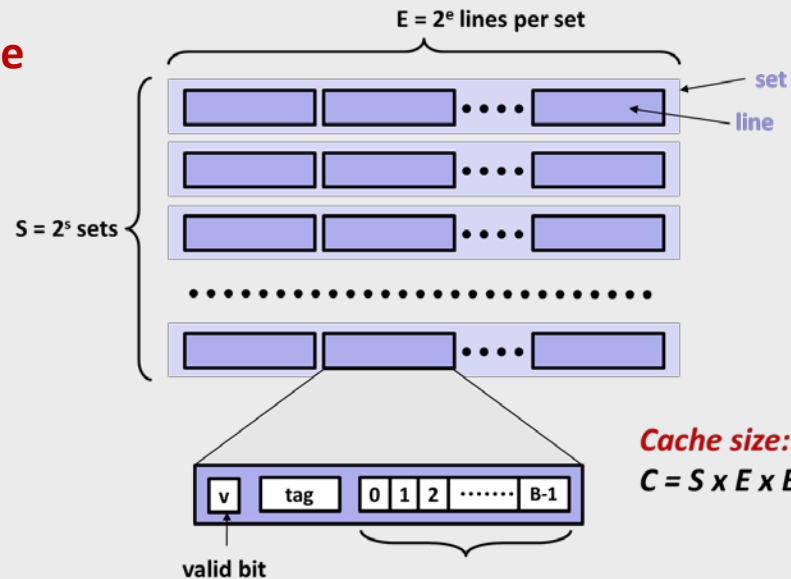
47 bit address range

$B = 64$

$S = 64, s = 6$

$E = 8, e = 3$

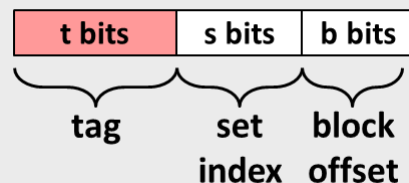
$C = 64 \times 64 \times 8 = 32,768$



Cache size:
 $C = S \times E \times B$ data bytes

Hex	Decimal	Binary
0	0	0000
1	1	0001
2	2	0010
3	3	0011
4	4	0100
5	5	0101
6	6	0110
7	7	0111
8	8	1000
9	9	1001
A	10	1010
B	11	1011
C	12	1100
D	13	1101
E	14	1110
F	15	1111

Address of word:



Block offset: 6 bits

Set index: 6 bits

Tag: 35 bits

Stack Address:

0x00007f7262a1e010

0000 0001 0000

Block offset: **0x10**

Set index: **0x0**

Tag: **0x7f7262a1e**

Cache Performance Metrics

■ Miss Rate

- Fraction of memory references not found in cache (misses / accesses)
= $1 - \text{hit rate}$
- Typical numbers (in percentages):
 - 3-10% for L1
 - can be quite small (e.g., $< 1\%$) for L2, depending on size, etc.

■ Hit Time

- Time to deliver a line in the cache to the processor
 - includes time to determine whether the line is in the cache
- Typical numbers:
 - 4 clock cycle for L1
 - 10 clock cycles for L2

■ Miss Penalty

- Additional time required because of a miss
 - typically 50-200 cycles for main memory (Trend: increasing!)

Let's think about those numbers

- **Huge difference between a hit and a miss**
 - Could be 100x, if just L1 and main memory

- **Would you believe 99% hits is twice as good as 97%?**
 - Consider:
 - cache hit time of 1 cycle
 - miss penalty of 100 cycles

 - Average access time:
 - 97% hits: $1 \text{ cycle} + 0.03 \times 100 \text{ cycles} = 4 \text{ cycles}$
 - 99% hits: $1 \text{ cycle} + 0.01 \times 100 \text{ cycles} = 2 \text{ cycles}$

- **This is why “miss rate” is used instead of “hit rate”**

Writing Cache Friendly Code

- **Make the common case go fast**
 - Focus on the inner loops of the core functions
- **Minimize the misses in the inner loops**
 - Repeated references to variables are good (**temporal locality**)
 - Stride-1 reference patterns are good (**spatial locality**)

Key idea: Our qualitative notion of locality is quantified through our understanding of cache memories

Today

- Cache organization and operation
- **Performance impact of caches**
 - The memory mountain
 - Rearranging loops to improve spatial locality

The Memory Mountain

- **Read throughput** (read bandwidth)
 - Number of bytes read from memory per second (MB/s)
- **Memory mountain:** Measured read throughput as a function of spatial and temporal locality.
 - Compact way to characterize memory system performance.

Memory Mountain Test Function

```

long data[MAXELEMS]; /* Global array to traverse */

/* test - Iterate over first "elems" elements of
 *         array "data" with stride of "stride", using
 *         using 4x4 loop unrolling.
 */
int test(int elems, int stride) {
    long i, sx2=stride*2, sx3=stride*3, sx4=stride*4;
    long acc0 = 0, acc1 = 0, acc2 = 0, acc3 = 0;
    long length = elems, limit = length - sx4;

    /* Combine 4 elements at a time */
    for (i = 0; i < limit; i += sx4) {
        acc0 = acc0 + data[i];
        acc1 = acc1 + data[i+stride];
        acc2 = acc2 + data[i+sx2];
        acc3 = acc3 + data[i+sx3];
    }

    /* Finish any remaining elements */
    for (; i < length; i++) {
        acc0 = acc0 + data[i];
    }
    return ((acc0 + acc1) + (acc2 + acc3));
}

```

mountain/mountain.c

Call test() with many combinations of elems and stride.

For each elems and stride:

1. Call test() once to warm up the caches.
2. Call test() again and measure the read throughput(MB/s)

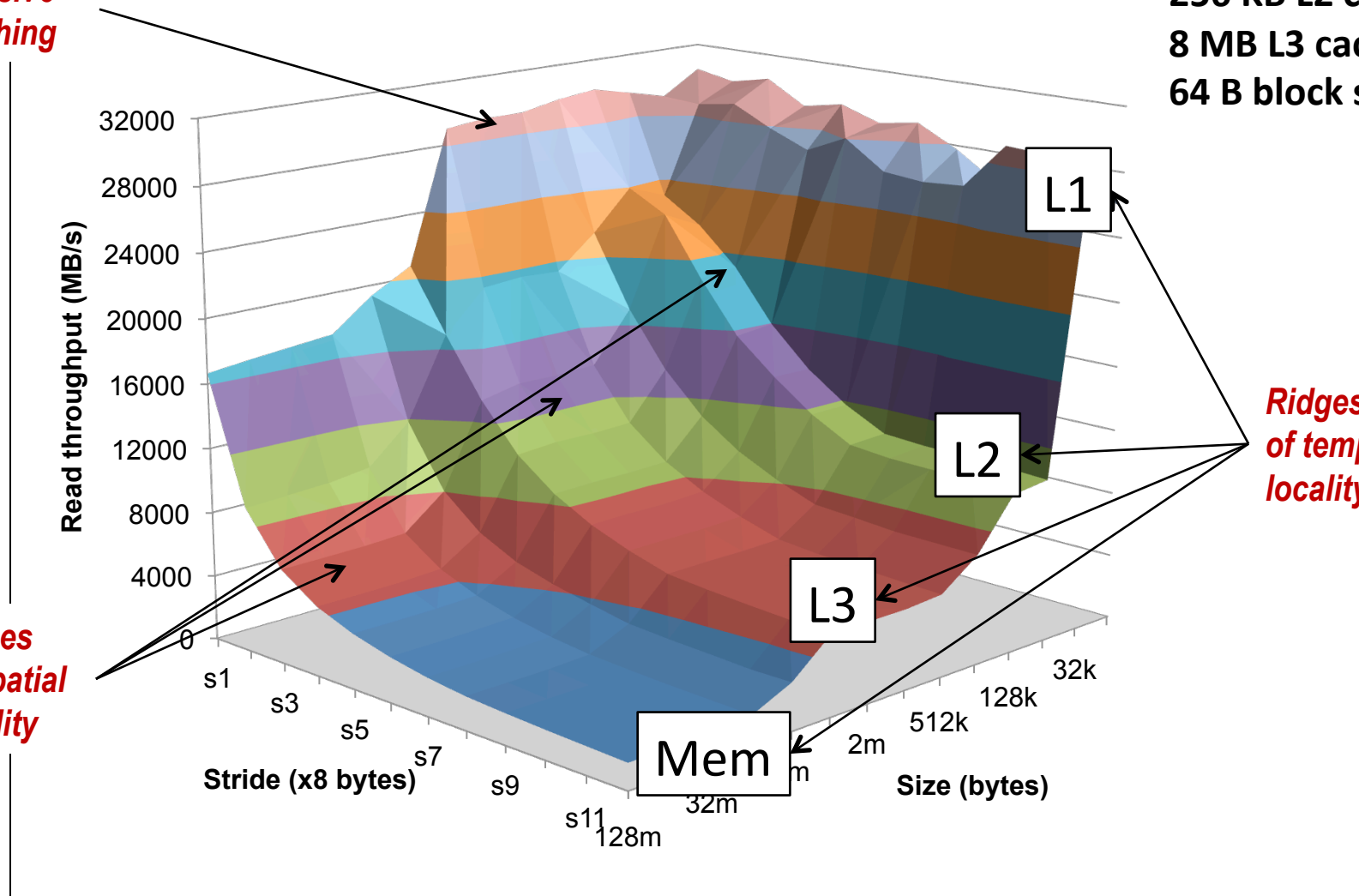
The Memory Mountain

Core i5 Haswell
 3.1 GHz
 32 KB L1 d-cache
 256 KB L2 cache
 8 MB L3 cache
 64 B block size

*Aggressive
prefetching*

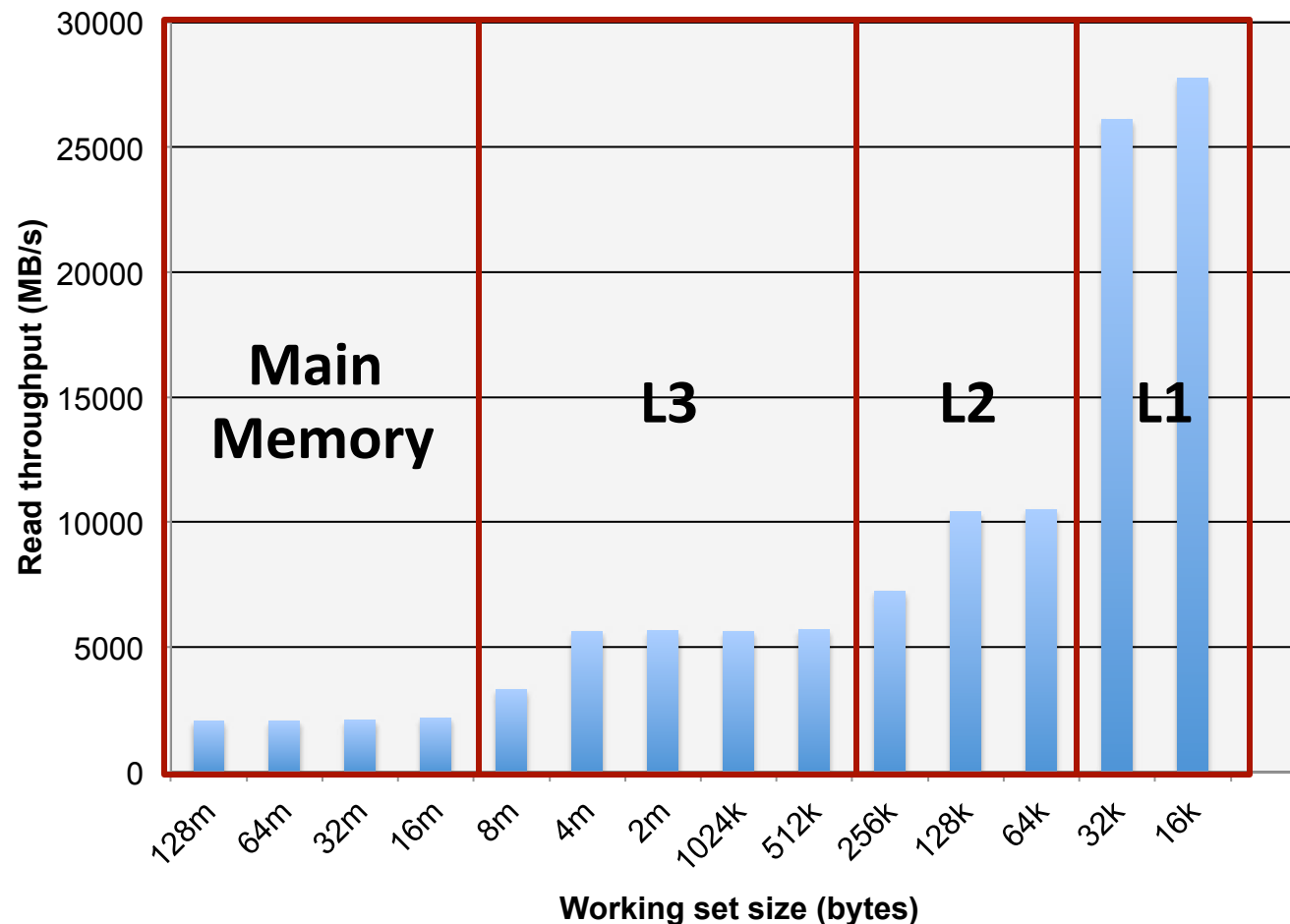
*Slopes
of spatial
locality*

*Ridges
of temporal
locality*



Cache Capacity Effects from Memory Mountain

Core i7 Haswell
3.1 GHz
32 KB L1 d-cache
256 KB L2 cache
8 MB L3 cache
64 B block size

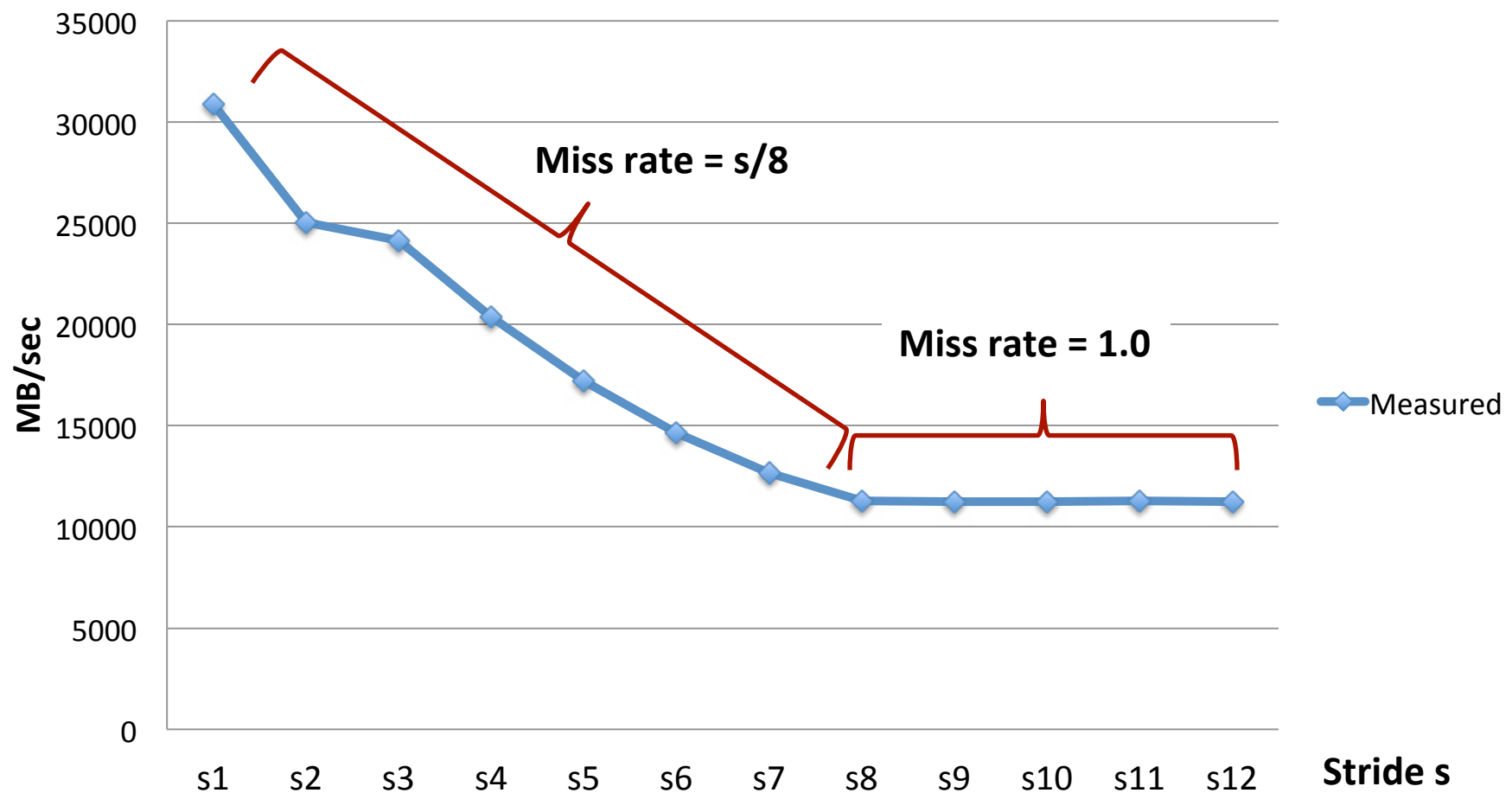


Slice through
memory
mountain with
stride=8

Cache Block Size Effects from Memory Mountain

Core i7 Haswell
2.26 GHz
32 KB L1 d-cache
256 KB L2 cache
8 MB L3 cache
64 B block size

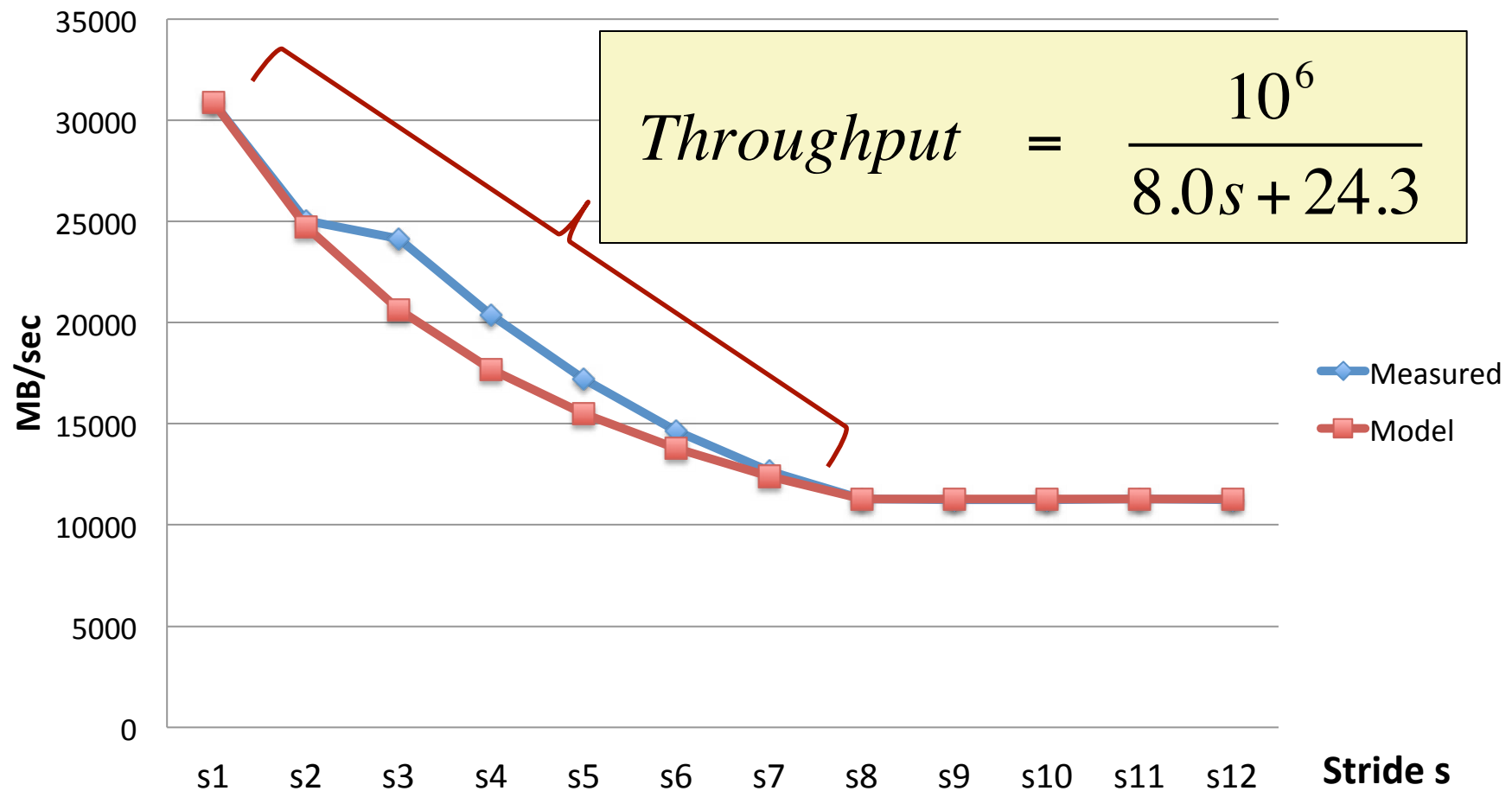
Throughput for size = 128K



Modeling Block Size Effects from Memory Mountain

Core i7 Haswell
2.26 GHz
32 KB L1 d-cache
256 KB L2 cache
8 MB L3 cache
64 B block size

Throughput for size = 128K



Today

- Cache organization and operation
- Performance impact of caches
 - The memory mountain
 - Rearranging loops to improve spatial locality

Matrix Multiplication Example

■ Description:

- Multiply $N \times N$ matrices
- Matrix elements are doubles (8 bytes)
- $2N^3$ total FP operations
- N reads per source element
- N values summed per destination
 - but may be able to hold in register

```
/* ijk */
for (i=0; i<n; i++) {
    for (j=0; j<n; j++) {
        sum = 0.0;
        for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
        c[i][j] = sum;
    }
}
```

*Variable **sum** held in register*

matmult/mm.c

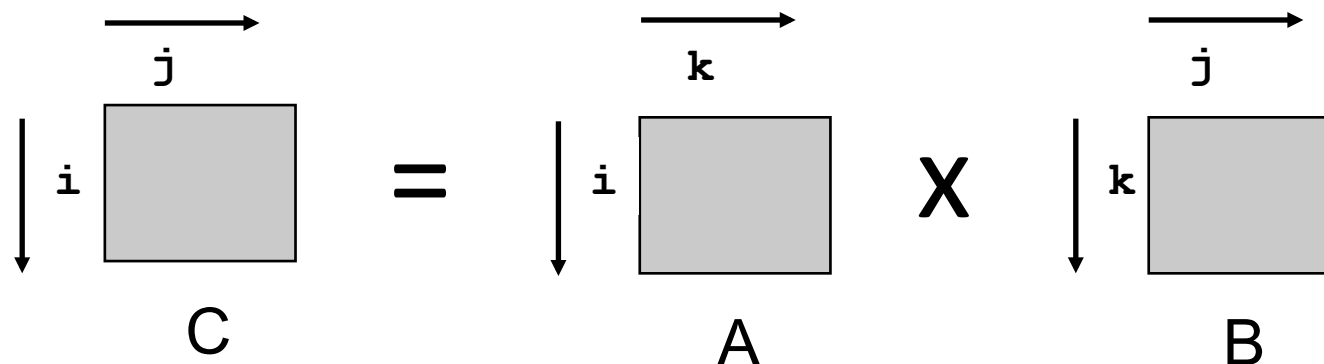
Miss Rate Analysis for Matrix Multiply

■ Assume:

- Block size = 64B (big enough for four doubles)
- Matrix dimension (N) is very large
 - Approximate $1/N$ as 0.0
- Cache is not even big enough to hold multiple rows

■ Analysis Method:

- Look at access pattern of inner loop



Layout of C Arrays in Memory (review)

- **C arrays allocated in row-major order**
 - each row in contiguous memory locations
- **Stepping through columns in one row:**
 - `for (i = 0; i < N; i++)`
 `sum += a[0][i];`
 - accesses successive elements
 - if block size (B) > sizeof(a_{ij}) bytes, exploit spatial locality
 - miss rate = sizeof(a_{ij}) / B
- **Stepping through rows in one column:**
 - `for (i = 0; i < n; i++)`
 `sum += a[i][0];`
 - accesses distant elements
 - no spatial locality!
 - miss rate = 1 (i.e. 100%)

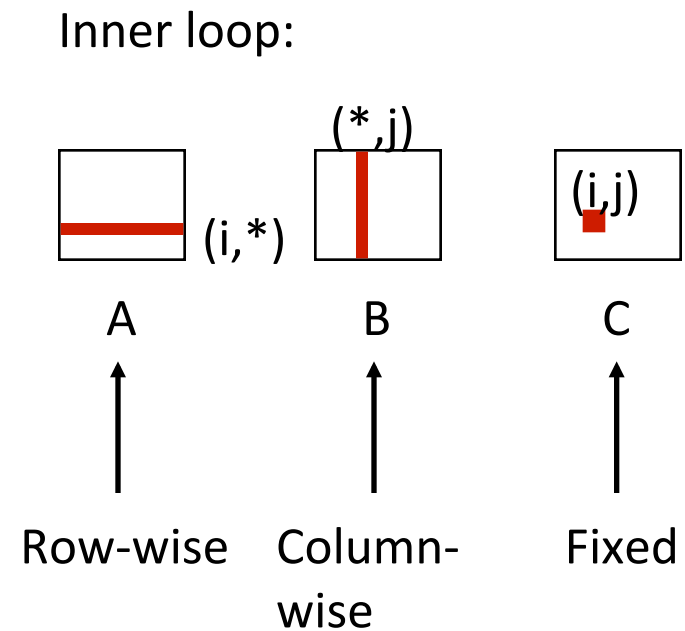
Matrix Multiplication (ijk)

```

/* ijk */
for (i=0; i<n; i++) {
    for (j=0; j<n; j++) {
        sum = 0.0;
        for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
        c[i][j] = sum;
    }
}

```

matmult/mm.c



Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.125	1.0	0.0

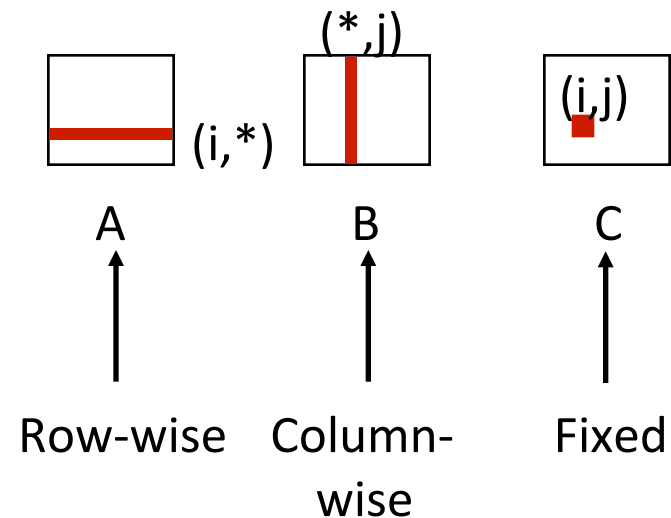
Matrix Multiplication (jik)

```

/* jik */
for (j=0; j<n; j++) {
    for (i=0; i<n; i++) {
        sum = 0.0;
        for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
        c[i][j] = sum
    }
}
                                     matmult/mm.c

```

Inner loop:



Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.125	1.0	0.0

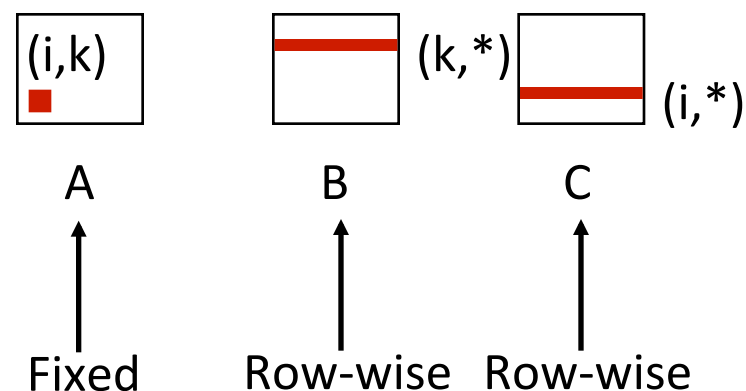
Matrix Multiplication (kij)

```

/* kij */
for (k=0; k<n; k++) {
    for (i=0; i<n; i++) {
        r = a[i][k];
        for (j=0; j<n; j++)
            c[i][j] += r * b[k][j];
    }
}
                                     matmult/mm.c

```

Inner loop:



Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.0	0.125	0.125

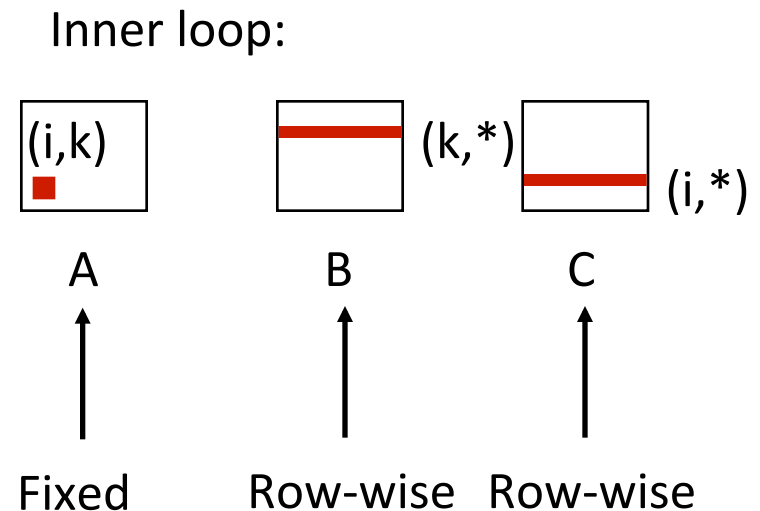
Matrix Multiplication (ikj)

```

/* ikj */
for (i=0; i<n; i++) {
    for (k=0; k<n; k++) {
        r = a[i][k];
        for (j=0; j<n; j++)
            c[i][j] += r * b[k][j];
    }
}

```

matmult/mm.c



Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.0	0.125	0.125

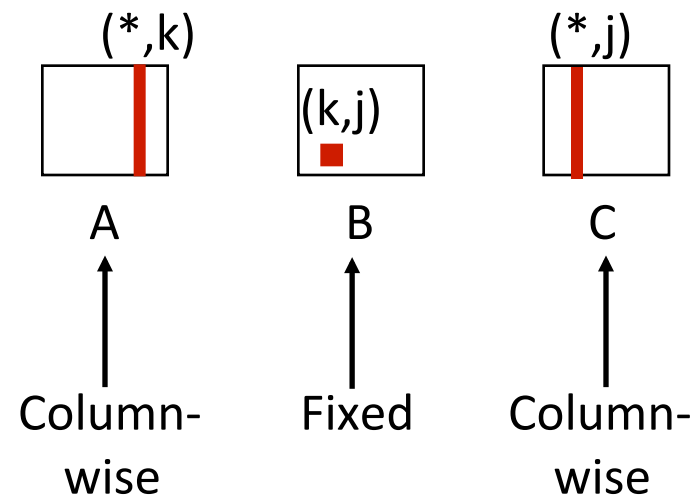
Matrix Multiplication (jki)

```

/* jki */
for (j=0; j<n; j++) {
    for (k=0; k<n; k++) {
        r = b[k][j];
        for (i=0; i<n; i++)
            c[i][j] += a[i][k] * r;
    }
}
matmult/mm.c

```

Inner loop:



Misses per inner loop iteration:

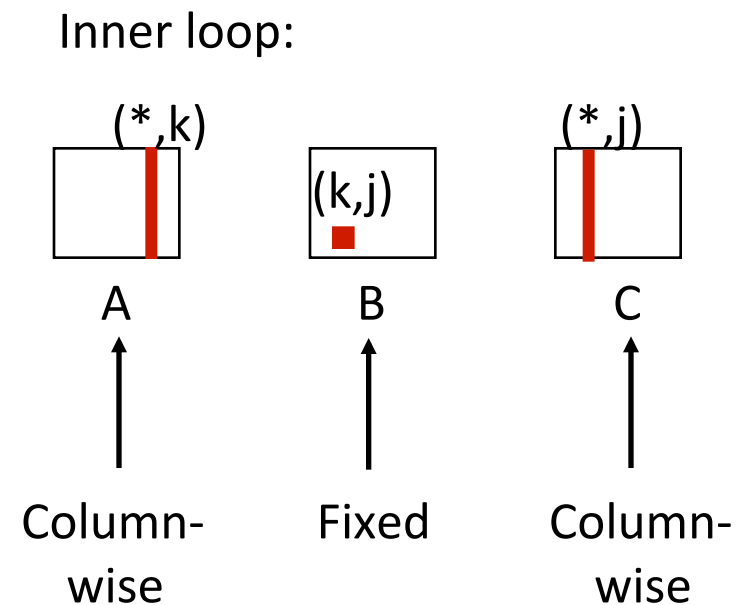
<u>A</u>	<u>B</u>	<u>C</u>
1.0	0.0	1.0

Matrix Multiplication (kji)

```

/* kji */
for (k=0; k<n; k++) {
    for (j=0; j<n; j++) {
        r = b[k][j];
        for (i=0; i<n; i++)
            c[i][j] += a[i][k] * r;
    }
}
                                     matmult/mm.c

```



Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
1.0	0.0	1.0

Summary of Matrix Multiplication

```
for (i=0; i<n; i++) {
    for (j=0; j<n; j++) {
        sum = 0.0;
        for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
        c[i][j] = sum;
    }
}
```

ijk (& jik):

- 2 loads, 0 stores
- misses/iter = **1.125**

```
for (k=0; k<n; k++) {
    for (i=0; i<n; i++) {
        r = a[i][k];
        for (j=0; j<n; j++)
            c[i][j] += r * b[k][j];
    }
}
```

kij (& ikj):

- 2 loads, 1 store
- misses/iter = **0.25**

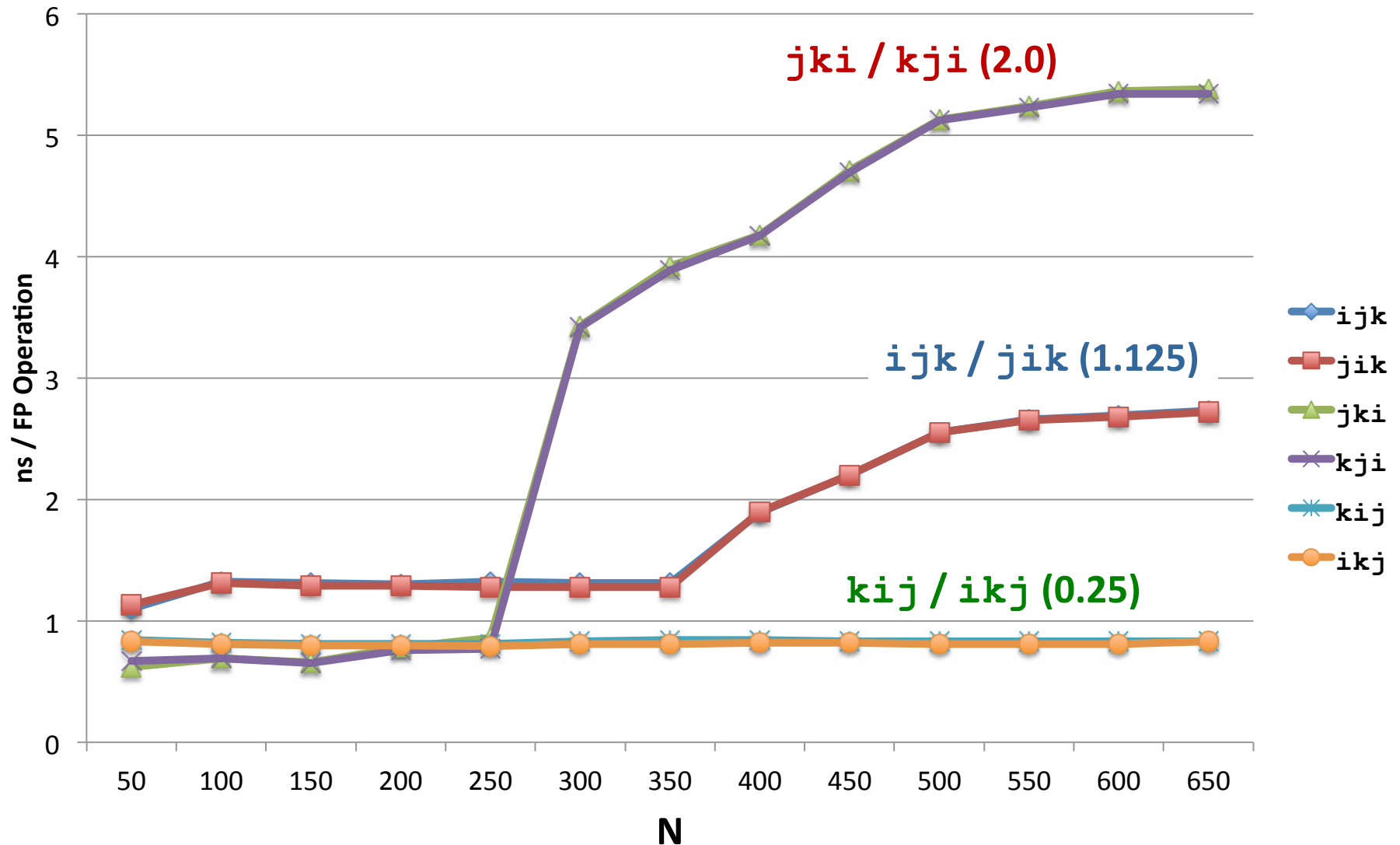
```
for (j=0; j<n; j++) {
    for (k=0; k<n; k++) {
        r = b[k][j];
        for (i=0; i<n; i++)
            c[i][j] += a[i][k] * r;
    }
}
```

jki (& kji):

- 2 loads, 1 store
- misses/iter = **2.0**

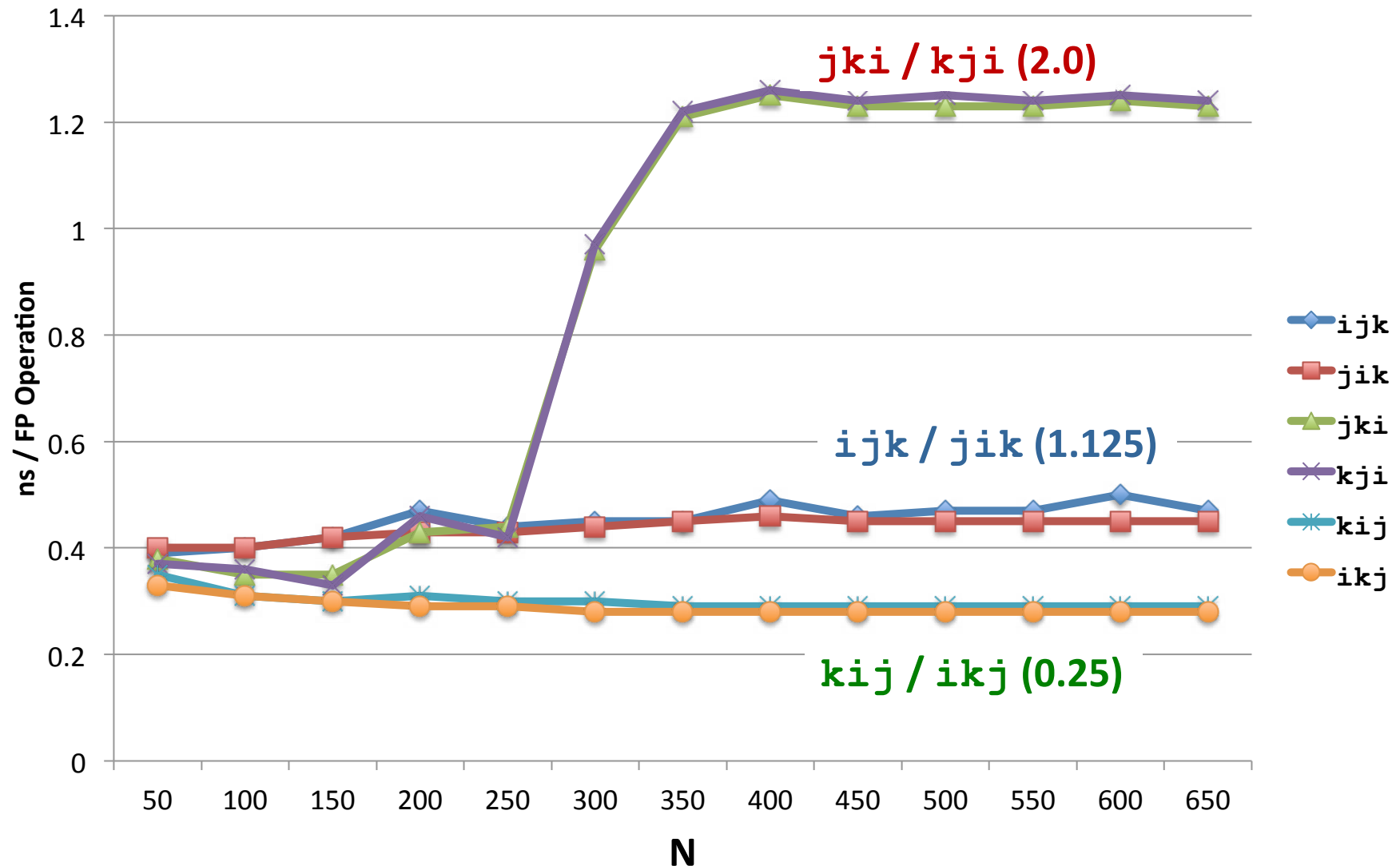
2008-era Matrix Multiply Performance

Nanoseconds per floating-point operation. Measured on 2.4GHz Core 2 Duo



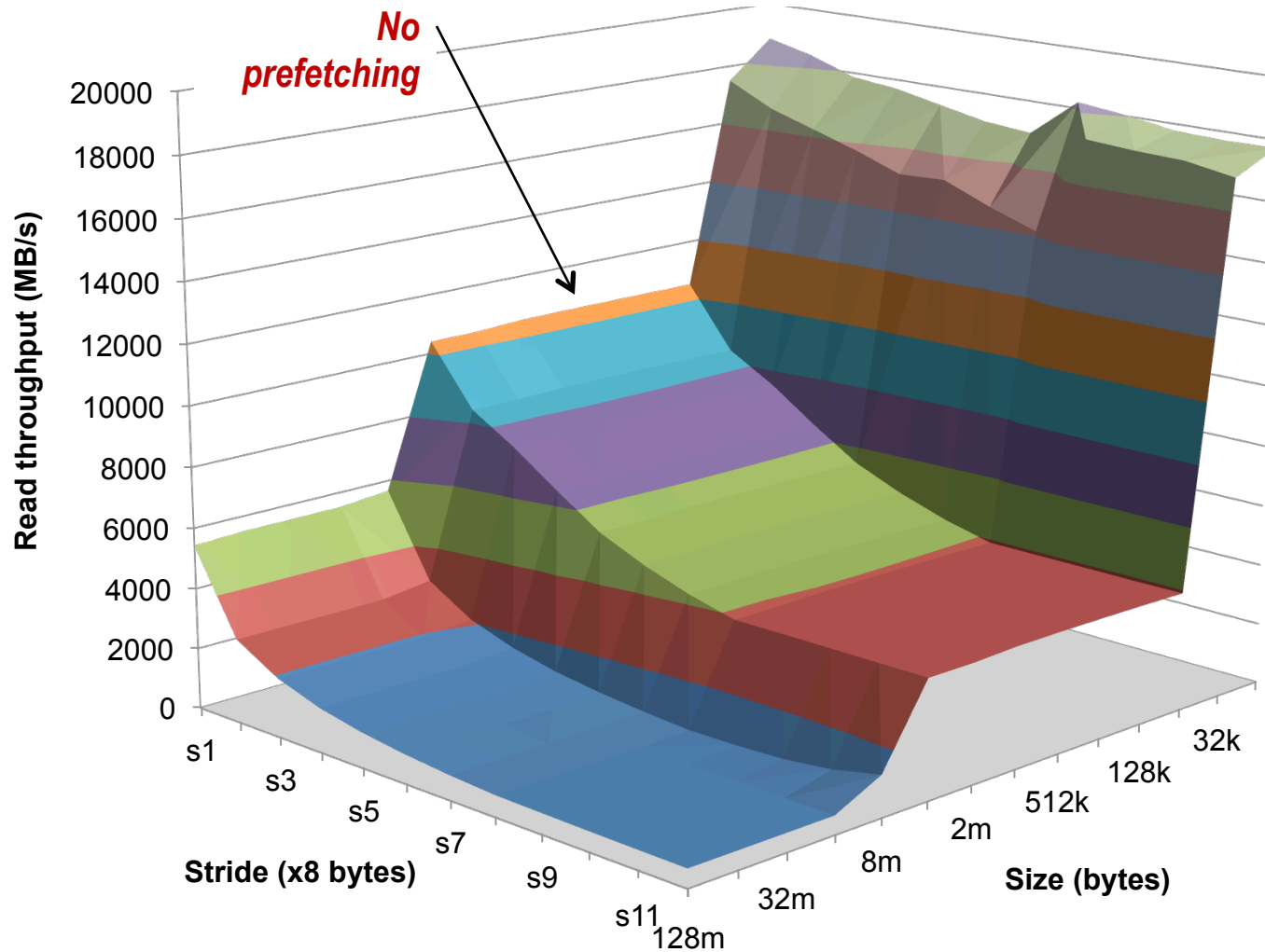
2014-era Matrix Multiply Performance

Nanoseconds per floating-point operation. Measured on 3.1 Ghz Haswell



2008 Memory Mountain

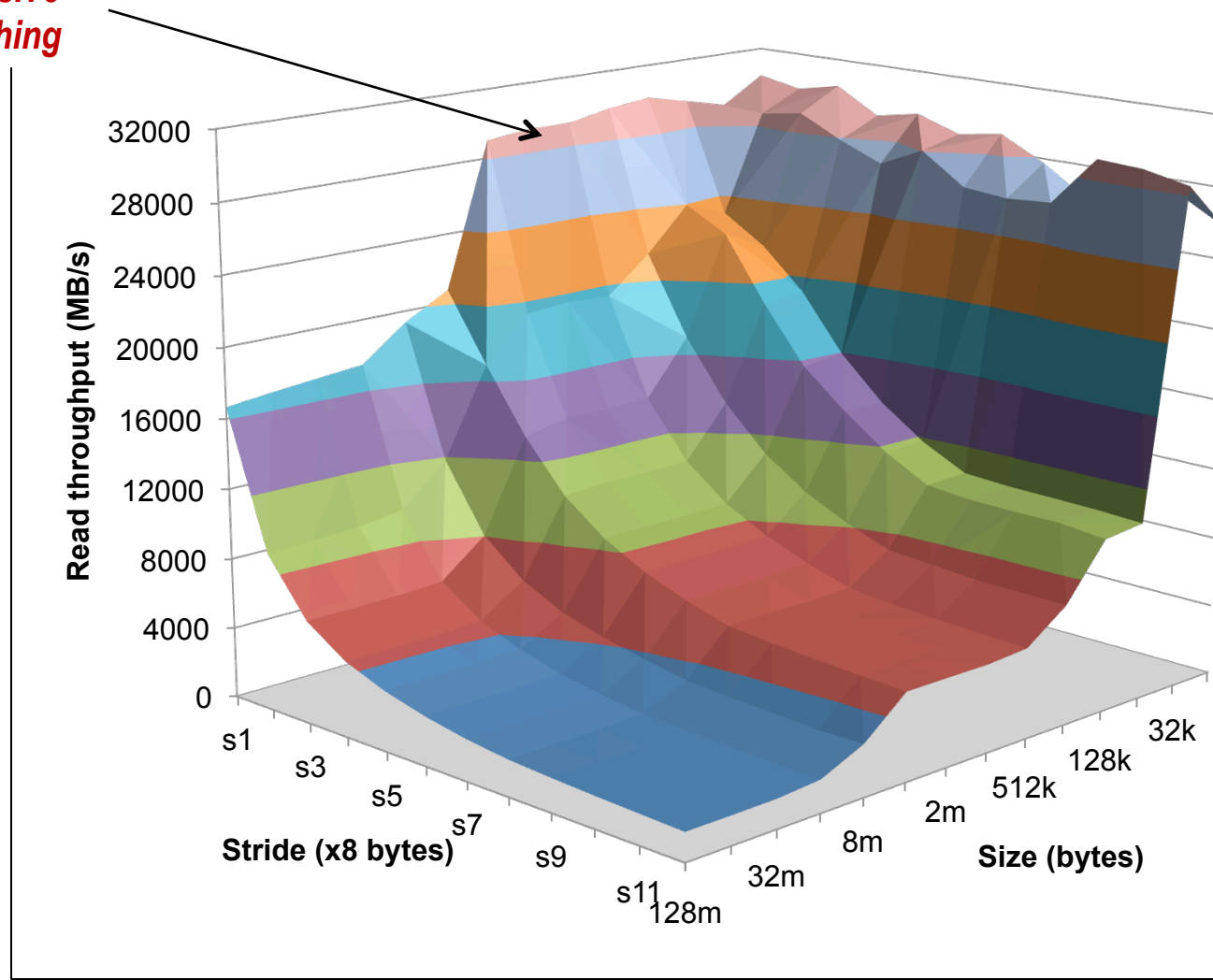
Core 2 Duo
2.4 GHz
32 KB L1 d-cache
6MB L2 cache
64 B block size



2014 Memory Mountain

Core i5 Haswell
 3.1 GHz
 32 KB L1 d-cache
 256 KB L2 cache
 8 MB L3 cache
 64 B block size

*Aggressive
prefetching*



EXTRA SLIDES

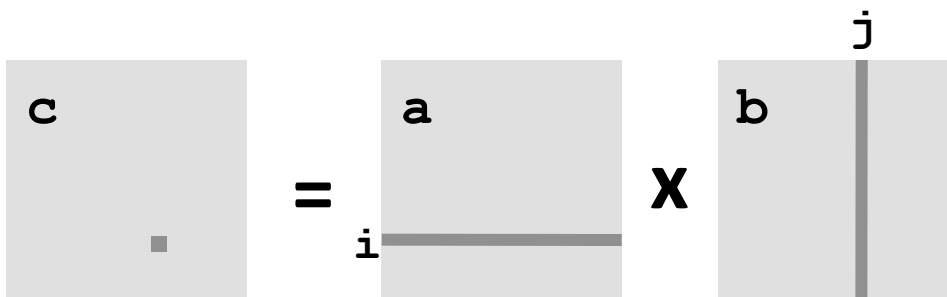
Today

- Cache organization and operation
- Performance impact of caches
 - The memory mountain
 - Rearranging loops to improve spatial locality
 - Using blocking to improve temporal locality

Example: Matrix Multiplication

```
c = (double *) calloc(sizeof(double), n*n);

/* Multiply n x n matrices a and b */
void mmm(double *a, double *b, double *c, int n) {
    int i, j, k;
    for (i = 0; i < n; i++)
        for (j = 0; j < n; j++)
            for (k = 0; k < n; k++)
                c[i*n + j] += a[i*n + k] * b[k*n + j];
}
```



Cache Miss Analysis

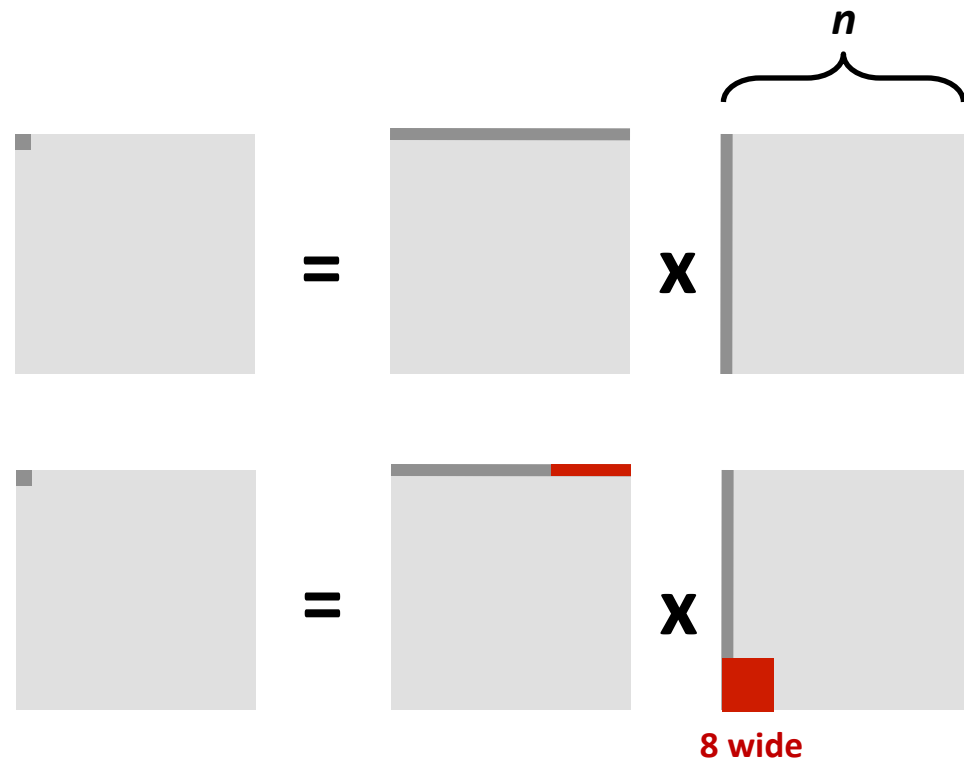
■ Assume:

- Matrix elements are doubles
- Cache block = 8 doubles
- Cache size $C \ll n$ (much smaller than n)

■ First iteration:

- $n/8 + n = 9n/8$ misses

- Afterwards **in cache:**
(schematic)



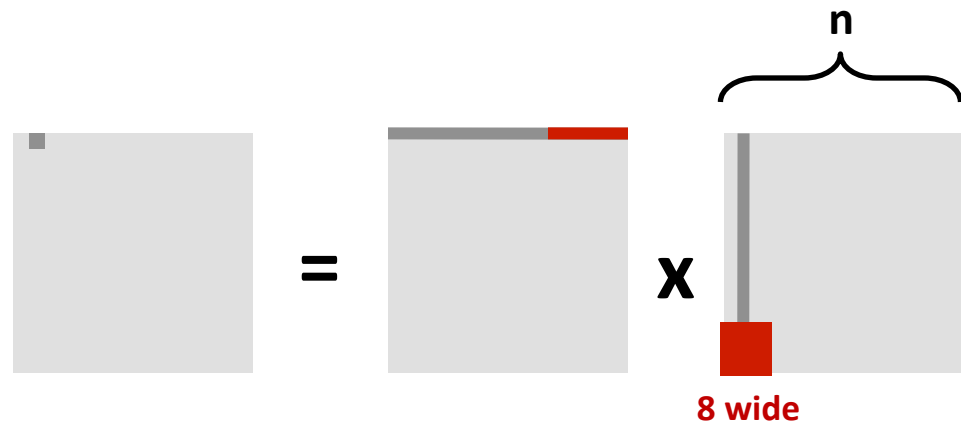
Cache Miss Analysis

■ Assume:

- Matrix elements are doubles
- Cache block = 8 doubles
- Cache size $C \ll n$ (much smaller than n)

■ Second iteration:

- Again:
 $n/8 + n = 9n/8$ misses



■ Total misses:

- $9n/8 n^2 = (9/8) n^3$

Blocked Matrix Multiplication

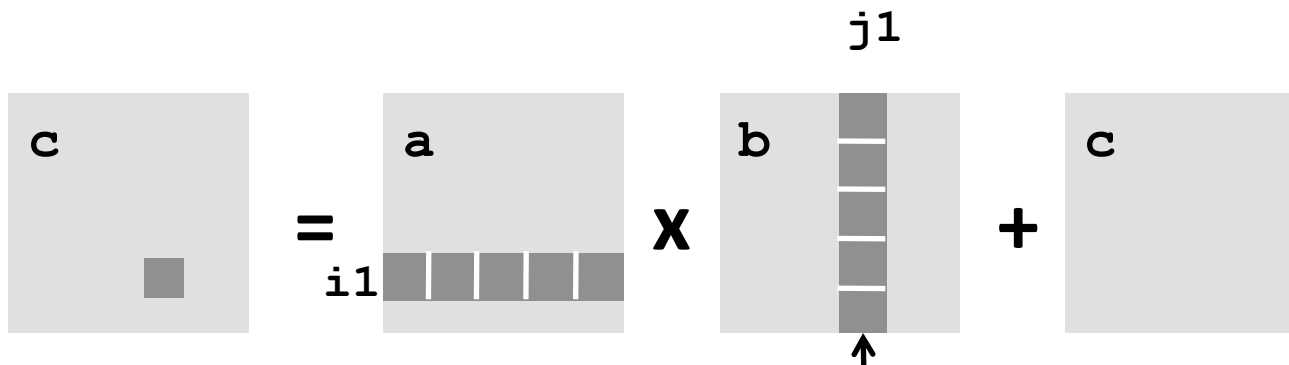
```

c = (double *) calloc(sizeof(double), n*n);

/* Multiply n x n matrices a and b */
void mmm(double *a, double *b, double *c, int n) {
    int i, j, k;
    for (i = 0; i < n; i+=B)
        for (j = 0; j < n; j+=B)
            for (k = 0; k < n; k+=B)
                /* B x B mini matrix multiplications */
                for (i1 = i; i1 < i+B; i1++)
                    for (j1 = j; j1 < j+B; j1++)
                        for (k1 = k; k1 < k+B; k1++)
                            c[i1*n+j1] += a[i1*n + k1]*b[k1*n + j1];
}

```


matmult/bmm.c



Block size B x B

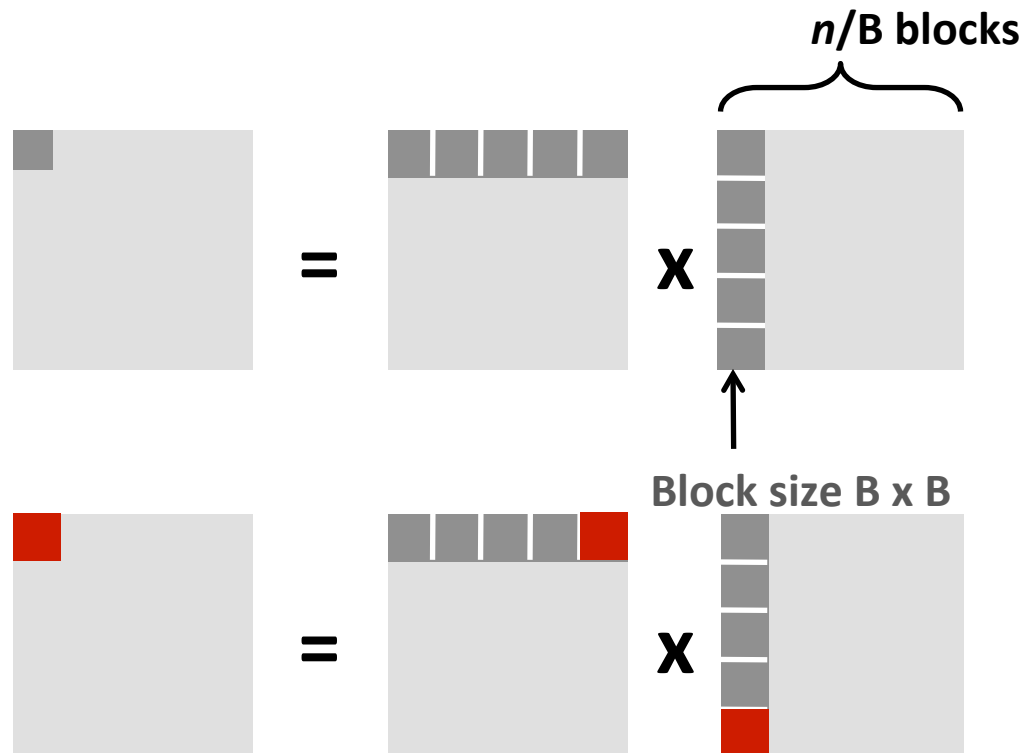
Cache Miss Analysis

■ Assume:

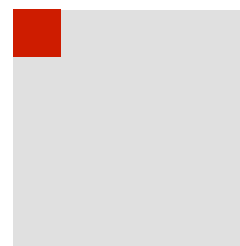
- Cache block = 8 doubles
- Cache size $C \ll n$ (much smaller than n)
- Three blocks  fit into cache: $3B^2 < C$

■ First (block) iteration:

- $B^2/8$ misses for each block
- $2n/B \times B^2/8 = nB/4$
(omitting matrix c)




- Afterwards in cache
(schematic)



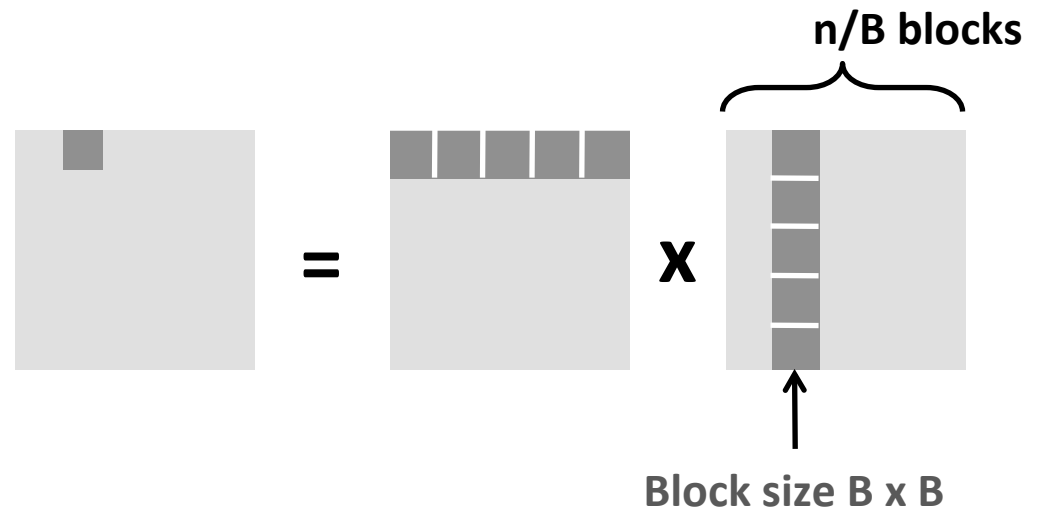
Cache Miss Analysis

■ Assume:

- Cache block = 8 doubles
- Cache size $C \ll n$ (much smaller than n)
- Three blocks  fit into cache: $3B^2 < C$

■ Second (block) iteration:

- Same as first iteration
- $2n/B \times B^2/8 = nB/4$



■ Total misses:

- $nB/4 * (n/B)^2 = n^3/(4B)$

Blocking Summary

- No blocking: $(9/8) n^3$
- Blocking: $1/(4B) n^3$

- Suggest largest possible block size B , but limit $3B^2 < C$!

- Reason for dramatic difference:
 - Matrix multiplication has inherent temporal locality:
 - Input data: $3n^2$, computation $2n^3$
 - Every array elements used $O(n)$ times!
 - But program has to be written properly

Cache Summary

- **Cache memories can have significant performance impact**
- **You can write your programs to exploit this!**
 - Focus on the inner loops, where bulk of computations and memory accesses occur.
 - Try to maximize spatial locality by reading data objects with sequentially with stride 1.
 - Try to maximize temporal locality by using a data object as often as possible once it's read from memory.