Concurrent Programming
December 2, 2004

Topics
- Limitations of iterative servers
- Process-based concurrent servers
- Event-based concurrent servers
- Threads-based concurrent servers
Concurrent Programming is Hard!

- The human mind tends to be sequential
- The notion of time is often misleading
- Thinking about all possible sequences of events in a computer system is at least error prone and frequently impossible
- Classical problem classes of concurrent programs:
  - Races: outcome depends on arbitrary scheduling decisions elsewhere in the system
    - Example: who gets the last seat on the airplane?
  - Deadlock: improper resource allocation prevents forward progress
    - Example: traffic gridlock
  - Lifelock / Starvation / Fairness: external events and/or system scheduling decisions can prevent sub-task progress
    - Example: people always jump in front of you in line
- Many aspects of concurrent programming are beyond the scope of 15-213
Iterative Servers

Iterative servers process one request at a time.

client 1

- call connect
- ret connect
- call read
- ret read
- close

server

- call accept
- ret accept
- write
- close

client 2

- call connect
- ret connect
- call read
- ret read
- close
Fundamental Flaw of Iterative Servers

Solution: use **concurrent servers** instead.

- Concurrent servers use multiple concurrent flows to serve multiple clients at the same time.
Concurrent Servers: Multiple Processes

Concurrent servers handle multiple requests concurrently.

Client 1
- call connect
- ret connect
- call fgets

User goes out to lunch

Client 1 blocks waiting for user to type in data

Server
- call accept
- ret accept
- forking

Child 1
- call read

Child 2
- call read
- write
- close

Client 2
- call connect
- ret connect
- call fgets

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Three Basic Mechanisms for Creating Concurrent Flows

1. Processes
   - Kernel automatically interleaves multiple logical flows.
   - Each flow has its own private address space.

2. Threads
   - Kernel automatically interleaves multiple logical flows.
   - Each flow shares the same address space.
   - Hybrid of processes and I/O multiplexing!

3. I/O multiplexing with `select()`
   - User manually interleaves multiple logical flows.
   - Each flow shares the same address space.
   - Popular for high-performance server designs.
int main(int argc, char **argv) {
    int listenfd, connfd;
    int port = atoi(argv[1]);
    struct sockaddr_in clientaddr;
    int clientlen = sizeof(clientaddr);
    listenfd = Open_listenfd(port);
    while (1) {
        connfd = Accept(listenfd, (SA *)&clientaddr, &clientlen);
        echo(connfd);
        Close(connfd);
    }
    exit(0);
}

- Accept a connection request
- Handle echo requests until client terminates
void echo(int connfd)
{
    size_t n;
    char buf[MAXLINE];
    rio_t rio;

    Rio_readinitb(&rio, connfd);
    while((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
        printf("server received \%d bytes\n", n);
        Rio_writen(connfd, buf, n);
    }
}

- Server reads lines of text
- Echos them right back
int main(int argc, char **argv)
{
    int listenfd, connfd;
    int port = atoi(argv[1]);
    struct sockaddr_in clientaddr;
    int clientlen=sizeof(clientaddr);

    Signal(SIGCHLD, sigchld_handler);
    listenfd = Open_listenfd(port);
    while (1) {
        connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
        if (Fork() == 0) {
            Close(listenfd); /* Child closes its listening socket */
            echo(connfd); /* Child services client */
            Close(connfd); /* Child closes connection with client */
            exit(0);      /* Child exits */
        }
        Close(connfd); /* Parent closes connected socket (important!) */
    }
}
Process-Based Concurrent Server (cont)

```c
void sigchld_handler(int sig)
{
    while (waitpid(-1, 0, WNOHANG) > 0)
    {
        return;
    }
}
```

- Reap all zombie children
Implementation Issues With Process-Based Designs

Server should restart `accept` call if it is interrupted by a transfer of control to the SIGCHLD handler

- Not necessary for systems with POSIX signal handling.
  - Our `Signal` wrapper tells kernel to automatically restart `accept`
- Required for portability on some older Unix systems.

Server must reap zombie children

- to avoid fatal memory leak.

Server must close its copy of `connfd`.

- Kernel keeps reference for each socket.
- After fork, `refcnt(connfd) = 2`.
- Connection will not be closed until `refcnt(connfd) = 0`.
Pros and Cons of Process-Based Designs

+ Handles multiple connections concurrently

+ Clean sharing model
  - descriptors (no)
  - file tables (yes)
  - global variables (no)

+ Simple and straightforward.

- Additional overhead for process control.

- Nontrivial to share data between processes.
  - Requires IPC (interprocess communication) mechanisms
    FIFO’s (named pipes), System V shared memory and semaphores
Traditional View of a Process

Process = process context + code, data, and stack

Program context:
- Data registers
- Condition codes
- Stack pointer (SP)
- Program counter (PC)

Kernel context:
- VM structures
- Descriptor table
- brk pointer

Code, data, and stack:
- Stack
- Shared libraries
- Run-time heap
- Read/write data
- Read-only code/data

SP → stack
brk → run-time heap
PC → read-only code/data
Alternate View of a Process

Process = thread + code, data, and kernel context

Thread (main thread):
- Stack
- Thread context:
  - Data registers
  - Condition codes
  - Stack pointer (SP)
  - Program counter (PC)

Code and Data:
- Shared libraries
- Run-time heap
- Read/write data
- Read-only code/data

Kernel context:
- VM structures
- Descriptor table
- Brk pointer
A Process With Multiple Threads

Multiple threads can be associated with a process

- Each thread has its own logical control flow
- Each thread shares the same code, data, and kernel context
  - Share common virtual address space
- Each thread has its own thread id (TID)

Thread 1 (main thread)  Shared code and data  Thread 2 (peer thread)

<table>
<thead>
<tr>
<th>Thread 1 context:</th>
<th>Shared code and data</th>
<th>Thread 2 context:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data registers</td>
<td>shared libraries</td>
<td>Data registers</td>
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<tr>
<td>Condition codes</td>
<td>run-time heap</td>
<td>Condition codes</td>
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<td>SP1</td>
<td>read/write data</td>
<td>SP2</td>
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<td>PC1</td>
<td>read-only code/data</td>
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<td>VM structures</td>
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<td>Descriptor table</td>
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<tr>
<td>brk pointer</td>
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</tbody>
</table>

stack 1

stack 2

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Logical View of Threads

Threads associated with process form a pool of peers.
- Unlike processes which form a tree hierarchy

Threads associated with process foo

Process hierarchy

shared code, data and kernel context
Concurrent Thread Execution

Two threads run concurrently (are concurrent) if their logical flows overlap in time.

Otherwise, they are sequential.

Examples:
- Concurrent: A & B, A&C
- Sequential: B & C
Threads vs. Processes

How threads and processes are similar
- Each has its own logical control flow.
- Each can run concurrently.
- Each is context switched.

How threads and processes are different
- Threads share code and data, processes (typically) do not.
- Threads are somewhat less expensive than processes.
  - Process control (creating and reaping) is twice as expensive as thread control.
  - Linux/Pentium III numbers:
    » ~20K cycles to create and reap a process.
    » ~10K cycles to create and reap a thread.
Posix Threads (Pthreads) Interface

*Pthreads*: Standard interface for ~60 functions that manipulate threads from C programs.

- Creating and reaping threads.
  - `pthread_create`
  - `pthread_join`

- Determining your thread ID
  - `pthread_self`

- Terminating threads
  - `pthread_cancel`
  - `pthread_exit`
  - `exit` [terminates all threads] , `ret` [terminates current thread]

- Synchronizing access to shared variables
  - `pthread_mutex_init`
  - `pthread_mutex_[un]lock`
  - `pthread_cond_init`
  - `pthread_cond_[timed]wait`
The Pthreads "hello, world" Program

/*
 * hello.c - Pthreads "hello, world" program
 */
#include "csapp.h"

void *thread(void *vargp);

int main() {
    pthread_t tid;

    Pthread_create(&tid, NULL, thread, NULL);
    Pthread_join(tid, NULL);
    exit(0);
}

/* thread routine */
void *thread(void *vargp) {
    printf("Hello, world!\n");
    return NULL;
}
Execution of Threaded “hello, world”

main thread

call Pthread_create()
Pthread_create() returns

call Pthread_join()

main thread waits for peer thread to terminate

Printf()
return NULL;
(peer thread terminates)

Pthread_join() returns

exit()
terminates

main thread and any peer threads

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Thread-Based Concurrent Echo Server

```c
int main(int argc, char **argv)
{
    int port = atoi(argv[1]);
    struct sockaddr_in clientaddr;
    int clientlen = sizeof(clientaddr);
    pthread_t tid;

    int listenfd = Open_listenfd(port);
    while (1) {
        int *connfdp = Malloc(sizeof(int));
        *connfdp = Accept(listenfd, (SA *) &clientaddr, &clientlen);
        Pthread_create(&tid, NULL, echo_thread, connfdp);
    }
}
```

- Spawn new thread for each client
- Pass it copy of connection file descriptor
- Note use of Malloc!
  - Without corresponding free
Thread-Based Concurrent Server (cont)

/* thread routine */
void *echo_thread(void *vargp)
{
    int connfd = *((int *)vargp);
    Pthread_detach(pthread_self());
    Free(vargp);
    echo(connfd);
    Close(connfd);
    return NULL;
}

- Run thread in “detached” mode
  - Runs independently of other threads
  - Reaped when it terminates

- Free storage allocated to hold clientfd
  - “Producer-Consumer” model
Potential Form of Unintended Sharing

```c
while (1) {
    int connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
    Pthread_create(&tid, NULL, echo_thread, (void *) &connfd);
}
```

### Diagram

```
main thread

connfd = connfd₁

connfd = connfd₂

Race!

Peer₁ stack

Peer₂ stack

Main thread stack

connfd

peer₁

connfd = *vargp

peer₂

connfd = *vargp

vargp

vargp
```

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Issues With Thread-Based Servers

Must run “detached” to avoid memory leak.

- At any point in time, a thread is either joinable or detached.
  - Joinable thread can be reaped and killed by other threads.
    - Must be reaped (with `pthread_join`) to free memory resources.
  - Detached thread cannot be reaped or killed by other threads.
    - Resources are automatically reaped on termination.
- Default state is joinable.
  - Use `pthread_detach(pthread_self())` to make detached.

Must be careful to avoid unintended sharing.

- For example, what happens if we pass the address of `connfd` to the thread routine?
  - `Pthread_create(&tid, NULL, thread, (void *) &connfd);`

All functions called by a thread must be thread-safe

- *(next lecture)*
Pros and Cons of Thread-Based Designs

+ Easy to share data structures between threads
  - e.g., logging information, file cache.

+ Threads are more efficient than processes.

--- Unintentional sharing can introduce subtle and hard-to-reproduce errors!
  - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads.
  - (next lecture)
Event-Based Concurrent Servers
Using I/O Multiplexing

Maintain a pool of connected descriptors.

Repeat the following forever:

- Use the Unix `select` function to block until:
  - (a) New connection request arrives on the listening descriptor.
  - (b) New data arrives on an existing connected descriptor.

- If (a), add the new connection to the pool of connections.
- If (b), read any available data from the connection
  - Close connection on EOF and remove it from the pool.
The select Function

select() sleeps until one or more file descriptors in the set readset ready for reading.

```c
#include <sys/select.h>

int select(int maxfdpl, fd_set *readset, NULL, NULL, NULL);
```

readset
- Opaque bit vector (max FD_SETSIZE bits) that indicates membership in a descriptor set.
- If bit k is 1, then descriptor k is a member of the descriptor set.

maxfdpl
- Maximum descriptor in descriptor set plus 1.
- Tests descriptors 0, 1, 2, ..., maxfdpl - 1 for set membership.

select() returns the number of ready descriptors and sets each bit of readset to indicate the ready status of its corresponding descriptor.
Macros for Manipulating Set Descriptors

void FD_ZERO(fd_set *fdset);
  ■ Turn off all bits in fdset.

void FD_SET(int fd, fd_set *fdset);
  ■ Turn on bit fd in fdset.

void FD_CLR(int fd, fd_set *fdset);
  ■ Turn off bit fd in fdset.

int FD_ISSET(int fd, *fdset);
  ■ Is bit fd in fdset turned on?
**Overall Structure**

### Manage Pool of Connections
- **listenfd**: Listen for requests from new clients
- **Active clients**: Ones with a valid connection

### Use select to detect activity
- New request on listenfd
- Request by active client

### Required Activities
- Adding new clients
- Removing terminated clients
- Echoing
/* 
 * echoservers.c - A concurrent echo server based on select 
 */
#include "csapp.h"

typedef struct { /* represents a pool of connected descriptors */
    int maxfd;       /* largest descriptor in read_set */
    fd_set read_set; /* set of all active descriptors */
    fd_set ready_set; /* subset of descriptors ready for reading */
    int nready;       /* number of ready descriptors from select */
    int maxi;         /* highwater index into client array */
    int clientfd[FD_SETSIZE]; /* set of active descriptors */
    rio_t clientrio[FD_SETSIZE]; /* set of active read buffers */
} pool;

int byte_cnt = 0; /* counts total bytes received by server */
Pool Example

- listenfd = 3
- maxfd = 12
- maxi = 6
- read_set = { 3, 4, 5, 7, 10, 12 }

Clientfd

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | ...
|---|---|---|---|---|---|---|---|---|---|---
| 10 | 7 | 4 | -1 | -1 | 12 | 5 | -1 | -1 | -1 |...

- Active
- Inactive
- Never Used
Main Loop

```c
int main(int argc, char **argv)
{
    int listenfd, connfd, clientlen = sizeof(struct sockaddr_in);
    struct sockaddr_in clientaddr;
    static pool pool;

    listenfd = Open_listenfd(argv[1]);
    init_pool(listenfd, &pool);

    while (1) {
        pool.ready_set = pool.read_set;
        pool.nready = Select(pool.maxfd+1, &pool.ready_set,
                              NULL, NULL, NULL);

        if (FD_ISSET(listenfd, &pool.ready_set)) {
            connfd = Accept(listenfd, (SA *)&clientaddr,&clientlen);
            add_client(connfd, &pool);
        }
        check_clients(&pool);
    }
}
```
/* initialize the descriptor pool */
void init_pool(int listenfd, pool *p)
{
    /* Initially, there are no connected descriptors */
    int i;
    p->maxi = -1;
    for (i=0; i< FD_SETSIZE; i++)
        p->clientfd[i] = -1;

    /* Initially, listenfd is only member of select read set */
    p->maxfd = listenfd;
    FD_ZERO(&p->read_set);
    FD_SET(listenfd, &p->read_set);
}
Initial Pool

- listenfd = 3
- maxfd = 3
- maxi = -1
- read_set = { 3 }

Clientfd Table:

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</table>

Never Used
void add_client(int connfd, pool *p) /* add connfd to pool p */
{
    int i;
    p->nready--;

    for (i = 0; i < FD_SETSIZE; i++) /* Find available slot */
        if (p->clientfd[i] < 0) {
            p->clientfd[i] = connfd;
            Rio_readinitb(&p->clientrio[i], connfd);

            FD_SET(connfd, &p->read_set); /* Add desc to read set */

            if (connfd > p->maxfd) /* Update max descriptor num */
                p->maxfd = connfd;
            if (i > p->maxi) /* Update pool high water mark */
                p->maxi = i;
            break;
        }
    if (i == FD_SETSIZE) /* Couldn't find an empty slot */
        app_error("add_client error: Too many clients");
}
Adding Client with fd 11

- maxfd = 12
- maxi = 6
- read_set = {3, 4, 5, 7, 10, 11, 12}

<table>
<thead>
<tr>
<th>clientfd</th>
<th>listenfd = 3</th>
</tr>
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<tbody>
<tr>
<td>0</td>
<td>10</td>
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</tbody>
</table>

- Active
- Inactive
- Active
- Never Used

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Checking Clients

```c
void check_clients(pool *p) {
    /* echo line from ready descs in pool p */
    int i, connfd, n;
    char buf[MAXLINE];
    rio_t rio;

    for (i = 0; (i <= p->maxi) && (p->nready > 0); i++) {
        connfd = p->clientfd[i];
        rio = p->clientrio[i];

        /* If the descriptor is ready, echo a text line from it */
        if ((connfd > 0) && (FD_ISSET(connfd, &p->ready_set))) {
            p->nready--;
            if ((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
                byte_cnt += n;
                Rio_writen(connfd, buf, n);
            } else /* EOF detected, remove descriptor from pool */
                Close(connfd);
            FD_CLR(connfd, &p->read_set);
            p->clientfd[i] = -1;
        }
    }
}
```
Pro and Cons of Event-Based Designs

+ One logical control flow.
+ Can single-step with a debugger.
+ No process or thread control overhead.
  - Design of choice for high-performance Web servers and search engines.
- Significantly more complex to code than process- or thread-based designs.
- Can be vulnerable to denial of service attack
  - How?
Approaches to Concurrency

Processes
- Hard to share resources: Easy to avoid unintended sharing
- High overhead in adding/removing clients

Threads
- Easy to share resources: Perhaps too easy
- Medium overhead
- Not much control over scheduling policies
- Difficult to debug
  - Event orderings not repeatable

I/O Multiplexing
- Tedious and low level
- Total control over scheduling
- Very low overhead
- Cannot create as fine grained a level of concurrency