# 15-213 "The course that gives CMU its Zip!"

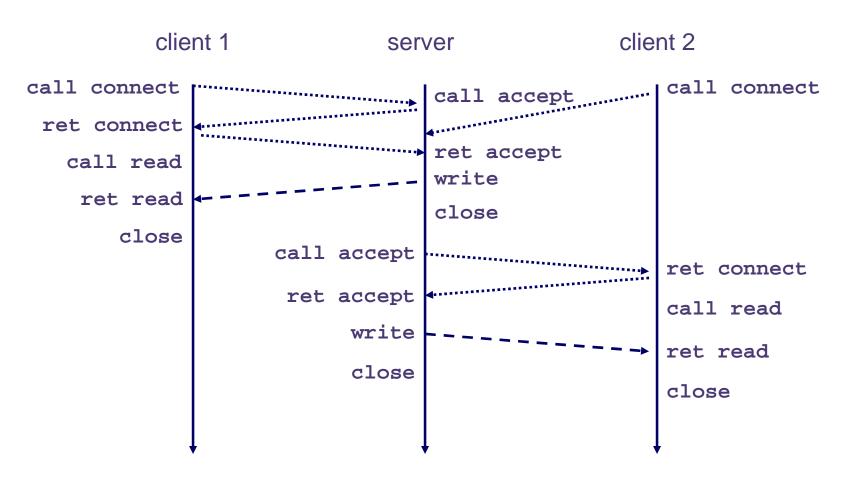
# Concurrent Servers Dec 3, 2002

#### **Topics**

- Limitations of iterative servers
- Process-based concurrent servers
- Event-based concurrent servers
- Threads-based concurrent servers

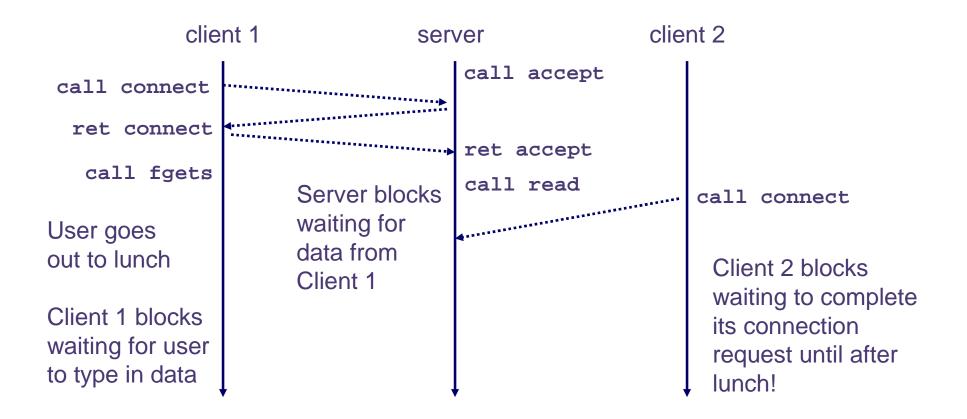
### **Iterative Servers**

#### Iterative servers process one request at a time.



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### Fundamental Flaw of Iterative Servers



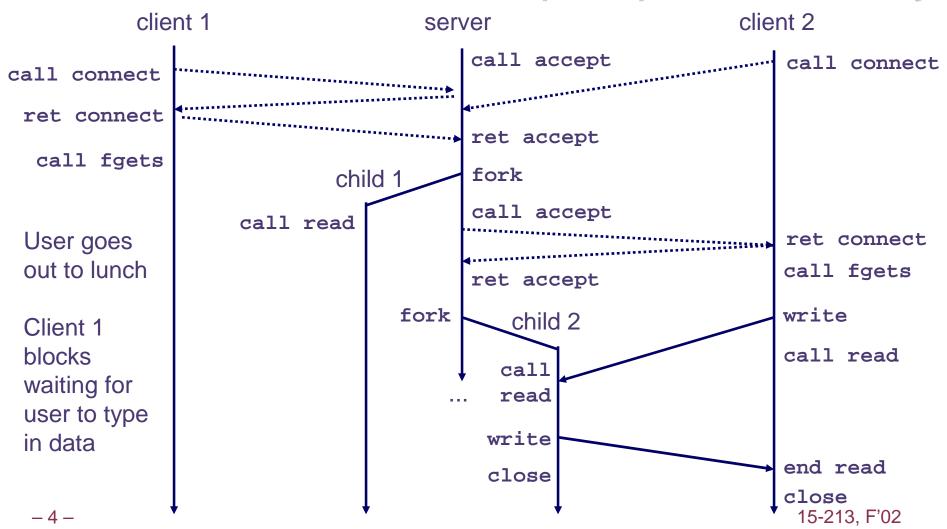
#### Solution: use concurrent servers instead.

■ Concurrent servers use multiple concurrent flows to serve multiple clients at the same time.

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### **Concurrent Servers**

#### Concurrent servers handle multiple requests concurrently.



# Three Basic Mechanisms for Creating Concurrent Flows

#### 1. Processes

- Kernel automatically interleaves multiple logical flows.
- Each flow has its own private address space.

#### 2. I/O multiplexing with select()

- User manually interleaves multiple logical flows.
- **■** Each flow shares the same address space.
- Popular for high-performance server designs.

#### 3. Threads

- Kernel automatically interleaves multiple logical flows.
- Each flow shares the same address space.
- Hybrid of processes and I/O multiplexing!

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### **Process-Based Concurrent Server**

```
* echoserverp.c - A concurrent echo server based on processes
 * Usage: echoserverp <port>
#include <ics.h>
#define BUFSIZE 1024
void echo(int connfd);
void handler(int sig);
int main(int argc, char **argv) {
  int listenfd, connfd;
  int portno;
  struct sockaddr in clientaddr;
  int clientlen = sizeof(struct sockaddr in);
  if (argc != 2) {
    fprintf(stderr, "usage: %s <port>\n", argv[0]);
    exit(0);
 portno = atoi(argv[1]);
  listenfd = open listenfd(portno);
```

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# Process-Based Concurrent Server (cont)

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# Process-Based Concurrent Server (cont)

```
/* handler - reaps children as they terminate */
void handler(int sig) {
  pid_t pid;
  int stat;

while ((pid = waitpid(-1, &stat, WNOHANG)) > 0)
  ;
  return;
}
```

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# Implementation Issues With Process-Based Designs

# Server should restart accept call if it is interrupted by a transfer of control to the SIGCHLD handler

- Not necessary for systems with POSIX signal handling.
  - Our Signal wrapper tells kernel to automatically restart accept
- Required for portability on some older Unix systems.

#### Server must reap zombie children

to avoid fatal memory leak.

#### Server must close its copy of connfd.

- Kernel keeps reference for each socket.
- After fork, refcnt(connfd) = 2.
- Connection will not be closed until refcnt(connfd)=0.

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# Pros and Cons of Process-Based Designs

- + Handles multiple connections concurrently
- + Clean sharing model
  - descriptors (no)
  - file tables (yes)
  - global variables (no)
- + Simple and straightforward.
- Additional overhead for process control.
- Nontrivial to share data between processes.
  - Requires IPC (interprocess communication) mechanisms FIFO's (named pipes), System V shared memory and semaphores

I/O multiplexing provides more control with less \_\_\_\_overhead...

# Event-Based Concurrent Servers Using I/O Multiplexing

Maintain a pool of connected descriptors.

#### Repeat the following forever:

- Use the Unix select function to block until:
  - (a) New connection request arrives on the listening descriptor.
  - (b) New data arrives on an existing connected descriptor.
- If (a), add the new connection to the pool of connections.
- If (b), read any available data from the connection
  - Close connection on EOF and remove it from the pool.

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### The select Function

select() sleeps until one or more file descriptors in the set readset are ready for reading.

```
#include <sys/select.h>
int select(int maxfdp1, fd_set *readset, NULL, NULL, NULL);
```

#### readset

- Opaque bit vector (max FD\_SETSIZE bits) that indicates membership in a descriptor set.
- If bit k is 1, then descriptor k is a member of the descriptor set.

#### maxfdp1

- Maximum descriptor in descriptor set plus 1.
- Tests descriptors 0, 1, 2, ..., maxfdp1 1 for set membership.

select() returns the number of ready descriptors and sets each bit of readset to indicate the ready status of its corresponding descriptor.

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# Macros for Manipulating Set Descriptors

```
void FD ZERO(fd set *fdset);
    ■ Turn off all bits in fdset.
void FD_SET(int fd, fd_set *fdset);
    ■ Turn on bit fd in fdset.
void FD CLR(int fd, fd set *fdset);
    ■ Turn off bit fd in fdset.
int FD ISSET(int fd, *fdset);
    Is bit fd in fdset turned on?
```

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### select Example

```
* main loop: wait for connection request or stdin command.
* If connection request, then echo input line
* and close connection. If stdin command, then process.
*/
printf("server> ");
fflush(stdout);
while (notdone) {
    * select: check if the user typed something to stdin or
    * if a connection request arrived.
    * /
  FD ZERO(&readfds); /* initialize the fd set */
  FD SET(listenfd, &readfds); /* add socket fd */
  FD_SET(0, &readfds); /* add stdin fd (0) */
   Select(listenfd+1, &readfds, NULL, NULL, NULL);
```

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## select Example (cont)

#### First we check for a pending event on stdin.

```
/* if the user has typed a command, process it */
if (FD_ISSET(0, &readfds)) {
   fgets(buf, BUFSIZE, stdin);
   switch (buf[0]) {
   case 'c': /* print the connection count */
      printf("Received %d conn. requests so far.\n", connectcnt);
     printf("server> ");
     fflush(stdout);
     break:
   case 'q': /* terminate the server */
     notdone = 0;
      break:
   default: /* bad input */
      printf("ERROR: unknown command\n");
      printf("server> ");
      fflush(stdout);
```

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## select Example (cont)

#### Next we check for a pending connection request.

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### **Event-based Concurrent Echo Server**

```
* echoservers.c - A concurrent echo server based on select
#include "csapp.h"
typedef struct { /* represents a pool of connected descriptors */
   int maxfd; /* largest descriptor in read set */
   fd set read set; /* set of all active descriptors */
   fd set ready set; /* subset of descriptors ready for reading */
   int nready; /* number of ready descriptors from select */
   int maxi; /* highwater index into client array */
   int clientfd[FD SETSIZE]; /* set of active descriptors */
   rio t clientrio[FD SETSIZE]; /* set of active read buffers */
} pool;
int byte_cnt = 0; /* counts total bytes received by server */
```

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```
int main(int argc, char **argv)
    int listenfd, connfd, clientlen = sizeof(struct sockaddr in);
    struct sockaddr in clientaddr;
    static pool pool;
    listenfd = Open listenfd(argv[1]);
    init pool(listenfd, &pool);
   while (1) {
        pool.ready set = pool.read set;
        pool.nready = Select(pool.maxfd+1, &pool.ready set,
                             NULL, NULL, NULL);
        if (FD ISSET(listenfd, &pool.ready set)) {
            connfd = Accept(listenfd, (SA *)&clientaddr,&clientlen);
            add client(connfd, &pool);
        check clients(&pool);
```

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```
/* initialize the descriptor pool */
void init_pool(int listenfd, pool *p)
{
    /* Initially, there are no connected descriptors */
    int i;
    p->maxi = -1;
    for (i=0; i< FD_SETSIZE; i++)
        p->clientfd[i] = -1;

    /* Initially, listenfd is only member of select read set */
    p->maxfd = listenfd;
    FD_ZERO(&p->read_set);
    FD_SET(listenfd, &p->read_set);
}
```

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```
void add client(int connfd, pool *p) /* add connfd to pool p */
    int i;
   p->nready--;
   for (i = 0; i < FD SETSIZE; i++) /* Find available slot */
        if (p->clientfd[i] < 0) {</pre>
            p->clientfd[i] = connfd;
            Rio readinitb(&p->clientrio[i], connfd);
            FD SET(connfd, &p->read set); /* Add desc to read set */
            if (connfd > p->maxfd) /* Update max descriptor num */
               p->maxfd = connfd;
            if (i > p->maxi) /* Update pool high water mark */
                p->maxi = i;
            break:
    if (i == FD SETSIZE) /* Couldn't find an empty slot */
        app_error("add_client error: Too many clients");
```

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```
void check_clients(pool *p) { /* echo line from ready descs in pool p */
    int i, connfd, n;
   char buf[MAXLINE];
   rio t rio;
    for (i = 0; (i \le p->maxi) && (p->nready > 0); i++) {
        connfd = p->clientfd[i];
        rio = p->clientrio[i];
        /* If the descriptor is ready, echo a text line from it */
        if ((connfd > 0) && (FD ISSET(connfd, &p->ready set))) {
            p->nready--;
            if ((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
                byte cnt += n;
                Rio writen(connfd, buf, n);
            else {/* EOF detected, remove descriptor from pool */
                Close(connfd);
                FD CLR(connfd, &p->read set);
                p->clientfd[i] = -1;
```

## Pro and Cons of Event-Based Designs

- + One logical control flow.
- + Can single-step with a debugger.
- + No process or thread control overhead.
  - Design of choice for high-performance Web servers and search engines.
- Significantly more complex to code than process- or thread-based designs.
- Can be vulnerable to denial of service attack
  - How?

Threads provide a middle ground between processes and I/O multiplexing...

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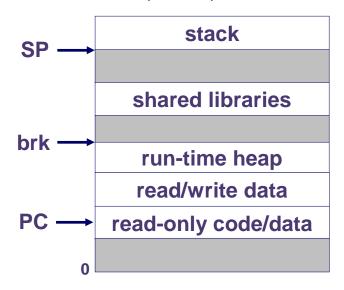
### **Traditional View of a Process**

#### Process = process context + code, data, and stack

#### **Process context**

Program context:
Data registers
Condition codes
Stack pointer (SP)
Program counter (PC)
Kernel context:
VM structures
Descriptor table
brk pointer

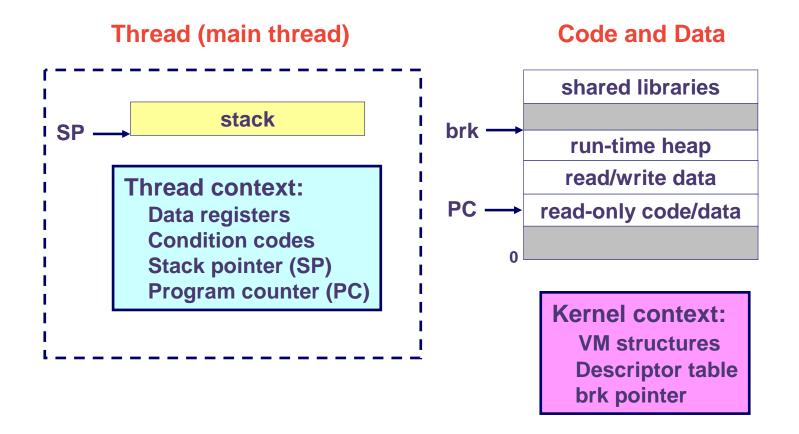
#### Code, data, and stack



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### **Alternate View of a Process**

**Process = thread + code, data, and kernel context** 



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## A Process With Multiple Threads

#### Multiple threads can be associated with a process

- Each thread has its own logical control flow (sequence of PC values)
- Each thread shares the same code, data, and kernel context
- Each thread has its own thread id (TID)

Thread 1 (main thread)

**Shared code and data** 

Thread 2 (peer thread)

stack 1

Thread 1 context:

Data registers

Condition codes

SP1

PC1

run-time heap
read/write data
read-only code/data

Kernel context:
VM structures
Descriptor table
brk pointer

stack 2

Thread 2 context:

Data registers

Condition codes

SP2

PC2

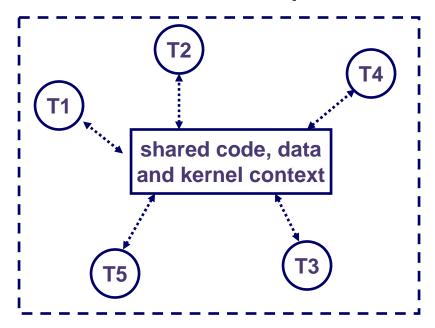
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# **Logical View of Threads**

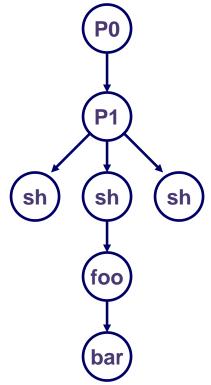
# Threads associated with a process form a pool of peers.

Unlike processes which form a tree hierarchy

Threads associated with process foo



**Process hierarchy** 



### **Concurrent Thread Execution**

Two threads run concurrently (are concurrent) if their logical flows overlap in time.

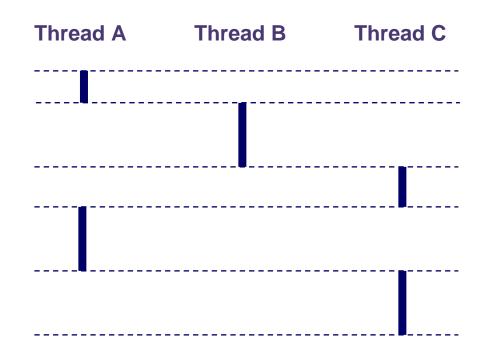
Otherwise, they are sequential.

#### **Examples:**

■ Concurrent: A & B, A&C

Sequential: B & C

Time



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#### Threads vs. Processes

#### How threads and processes are similar

- Each has its own logical control flow.
- Each can run concurrently.
- Each is context switched.

#### How threads and processes are different

- Threads share code and data, processes (typically) do not.
- Threads are somewhat less expensive than processes.
  - Process control (creating and reaping) is twice as expensive as thread control.
  - Linux/Pentium III numbers:
    - » ~20K cycles to create and reap a process.
    - » ~10K cycles to create and reap a thread.

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### Posix Threads (Pthreads) Interface

# Pthreads: Standard interface for ~60 functions that manipulate threads from C programs.

- Creating and reaping threads.
  - pthread\_create
  - pthread\_join
- Determining your thread ID
  - pthread\_self
- Terminating threads
  - pthread\_cancel
  - pthread\_exit
  - exit [terminates all threads], ret [terminates current thread]
- Synchronizing access to shared variables
  - pthread\_mutex\_init
  - pthread\_mutex\_[un]lock
  - pthread\_cond\_init
  - pthread\_cond\_[timed]wait

# The Pthreads "hello, world" Program

```
* hello.c - Pthreads "hello, world" program
                                                     Thread attributes
#include "csapp.h"
                                                      (usually NULL)
void *thread(void *vargp);
                                                     Thread arguments
int main() {
                                                         (void *p)
  pthread t tid;
  Pthread_create(&tid, NULL, thread, NULL);
  Pthread join(tid, NULL);
  exit(0);
                                                     return value
                                                      (void **p)
/* thread routine */
void *thread(void *vargp) {
  printf("Hello, world!\n");
  return NULL;
```

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### Execution of Threaded"hello, world"

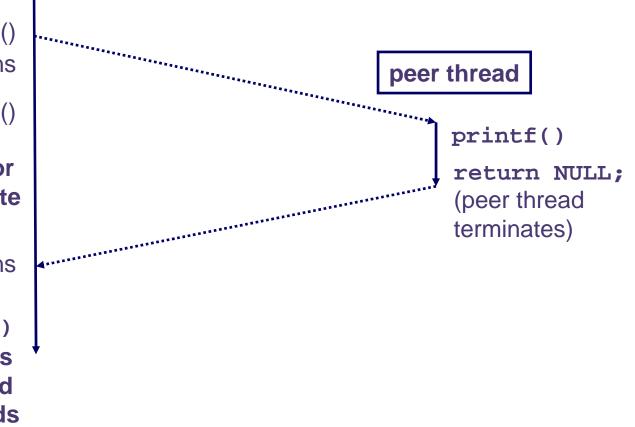
main thread

call Pthread\_create()
Pthread\_create() returns
call Pthread\_join()

main thread waits for peer thread to terminate

Pthread\_join() returns

exit()
terminates
main thread and
any peer threads



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# Thread-Based Concurrent Echo Server

```
int main(int argc, char **argv)
    int listenfd, *connfdp, port, clientlen;
   struct sockaddr in clientaddr;
   pthread t tid;
   if (argc != 2) {
        fprintf(stderr, "usage: %s <port>\n", argv[0]);
        exit(0);
   port = atoi(argv[1]);
   listenfd = open listenfd(port);
   while (1) {
        clientlen = sizeof(clientaddr);
        connfdp = Malloc(sizeof(int));
        *connfdp = Accept(listenfd, (SA *) &clientaddr, &clientlen);
        Pthread create(&tid, NULL, thread, connfdp);
```

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# Thread-Based Concurrent Server (cont)

```
* thread routine */
void *thread(void *vargp)
{
   int connfd = *((int *)vargp);

   Pthread_detach(pthread_self());
   Free(vargp);

   echo_r(connfd); /* reentrant version of echo() */
   Close(connfd);
   return NULL;
}
```

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### **Issues With Thread-Based Servers**

#### Must run "detached" to avoid memory leak.

- At any point in time, a thread is either *joinable* or *detached*.
- Joinable thread can be reaped and killed by other threads.
  - must be reaped (with pthread\_join) to free memory resources.
- Detached thread cannot be reaped or killed by other threads.
  - resources are automatically reaped on termination.
- Default state is joinable.
  - use pthread\_detach(pthread\_self()) to make detached.

#### Must be careful to avoid unintended sharing.

- For example, what happens if we pass the address of connfd to the thread routine?
  - Pthread\_create(&tid, NULL, thread, (void
    \*)&connfd);

#### All functions called by a thread must be thread-safe

(next lecture)

# Pros and Cons of Thread-Based Designs

- + Easy to share data structures between threads
  - e.g., logging information, file cache.
- + Threads are more efficient than processes.
- --- Unintentional sharing can introduce subtle and hardto-reproduce errors!
  - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads.
  - (next lecture)

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