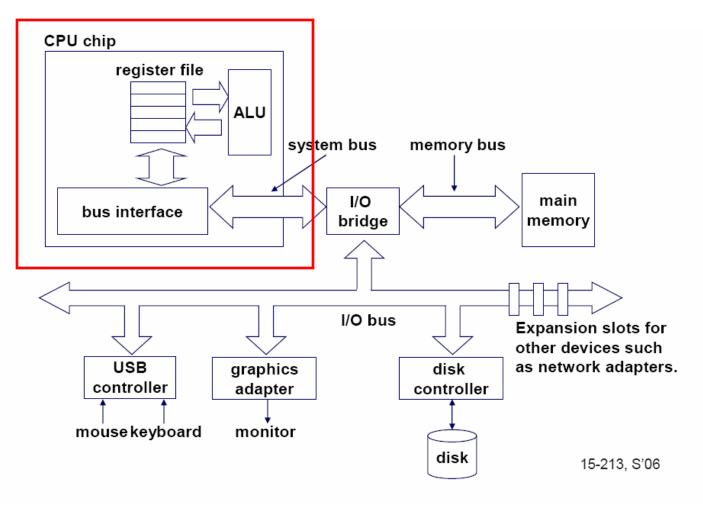
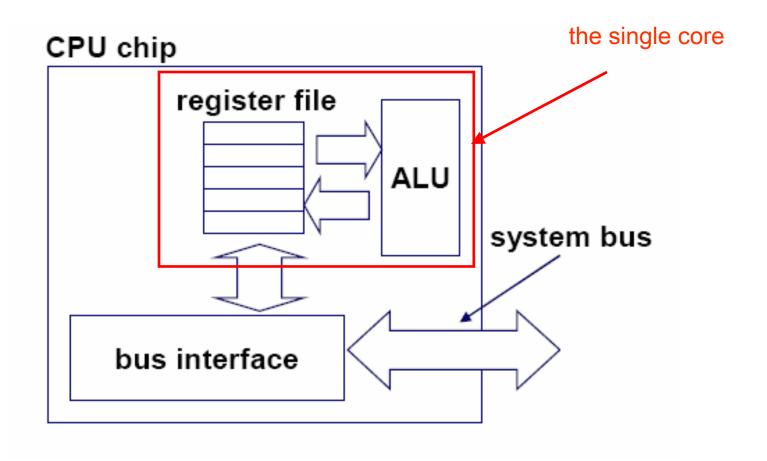
Multi-core architectures

Jernej Barbic 15-213, Spring 2007 May 3, 2007

Single-core computer

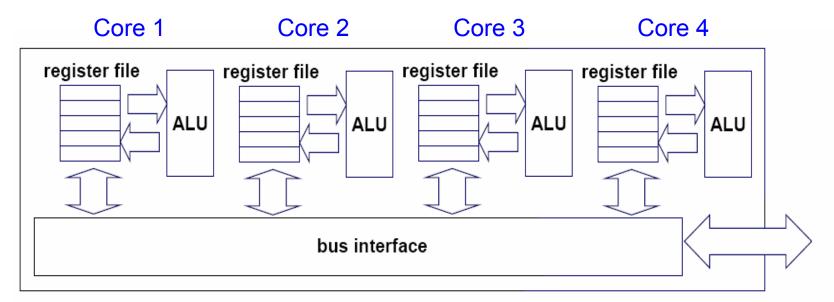


Single-core CPU chip



Multi-core architectures

 This lecture is about a new trend in computer architecture: Replicate multiple processor cores on a single die.

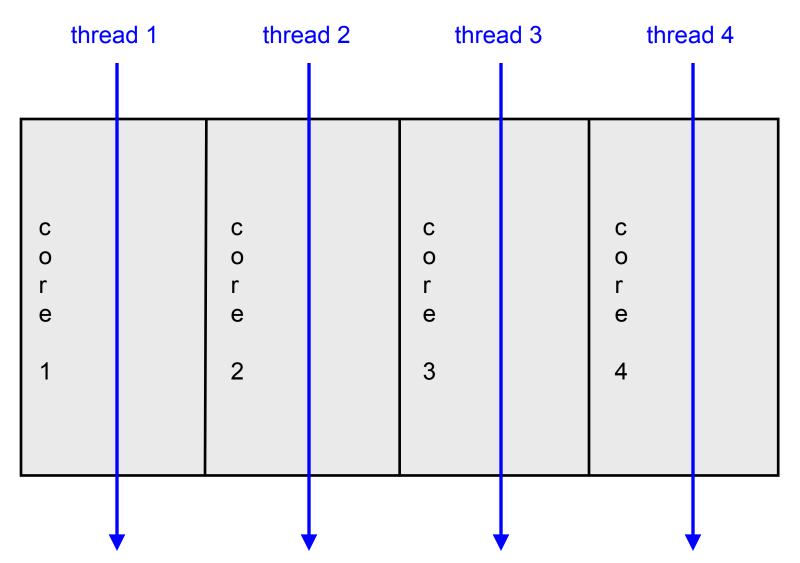


Multi-core CPU chip

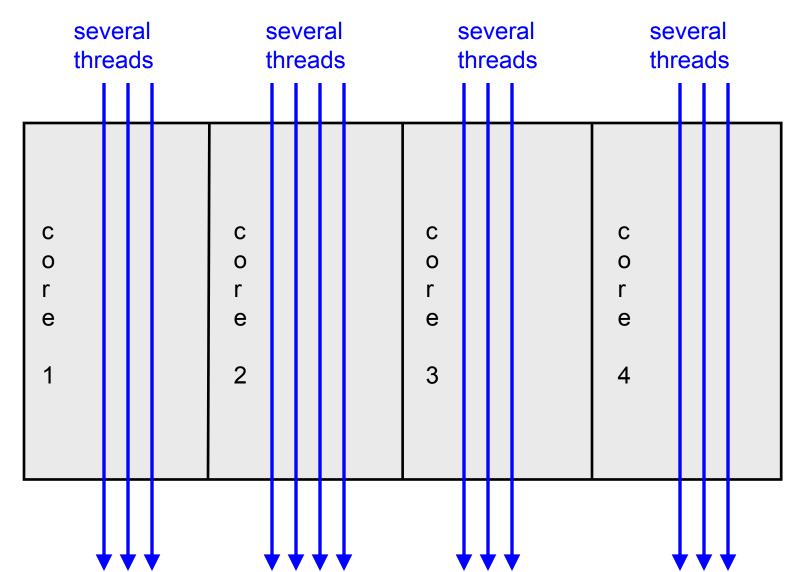
- The cores fit on a single processor socket
- Also called CMP (Chip Multi-Processor)

С	С	С	С
0	0	0	0
r	r	r	r
е	е	е	е
1	2	3	4

The cores run in parallel



Within each core, threads are time-sliced (just like on a uniprocessor)



Interaction with the Operating System

- OS perceives each core as a separate processor
- OS scheduler maps threads/processes to different cores
- Most major OS support multi-core today: Windows, Linux, Mac OS X, ...

Why multi-core?

- Difficult to make single-core clock frequencies even higher
- Deeply pipelined circuits:
 - heat problems
 - speed of light problems
 - difficult design and verification
 - large design teams necessary
 - server farms need expensive air-conditioning



- Many new applications are multithreaded
- General trend in computer architecture (shift towards more parallelism)

Instruction-level parallelism

- Parallelism at the machine-instruction level
- The processor can re-order, pipeline instructions, split them into microinstructions, do aggressive branch prediction, etc.
- Instruction-level parallelism enabled rapid increases in processor speeds over the last 15 years

Thread-level parallelism (TLP)

- This is parallelism on a more coarser scale
- Server can serve each client in a separate thread (Web server, database server)
- A computer game can do AI, graphics, and physics in three separate threads
- Single-core superscalar processors cannot fully exploit TLP
- Multi-core architectures are the next step in processor evolution: explicitly exploiting TLP

General context: Multiprocessors

 Multiprocessor is any computer with several processors



SIMD

- Single instruction, multiple data
- Modern graphics cards

MIMD

Multiple instructions, multiple data

Lemieux cluster, Pittsburgh supercomputing center

Multiprocessor memory types

 Shared memory:
 In this model, there is one (large) common shared memory for all processors

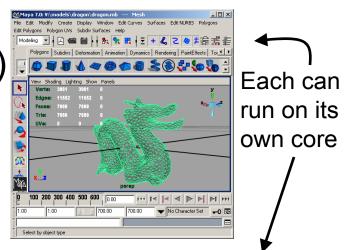
Distributed memory:
 In this model, each processor has its own (small) local memory, and its content is not replicated anywhere else

Multi-core processor is a special kind of a multiprocessor: All processors are on the same chip

- Multi-core processors are MIMD:
 Different cores execute different threads
 (Multiple Instructions), operating on different parts of memory (Multiple Data).
- Multi-core is a shared memory multiprocessor:
 All cores share the same memory

What applications benefit from multi-core?

- Database servers
- Web servers (Web commerce)
- Compilers
- Multimedia applications
- Scientific applications, CAD/CAM
- In general, applications with *Thread-level parallelism* (as opposed to instruction-level parallelism)





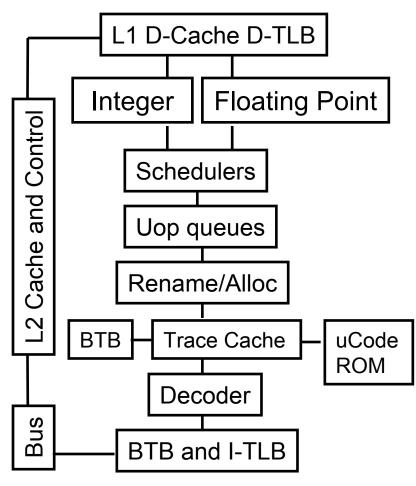
More examples

- Editing a photo while recording a TV show through a digital video recorder
- Downloading software while running an anti-virus program
- "Anything that can be threaded today will map efficiently to multi-core"
- BUT: some applications difficult to parallelize

A technique complementary to multi-core: Simultaneous multithreading

- Problem addressed: The processor pipeline can get stalled:
 - Waiting for the result of a long floating point (or integer) operation
 - Waiting for data to arrive from memory

Other execution units wait unused



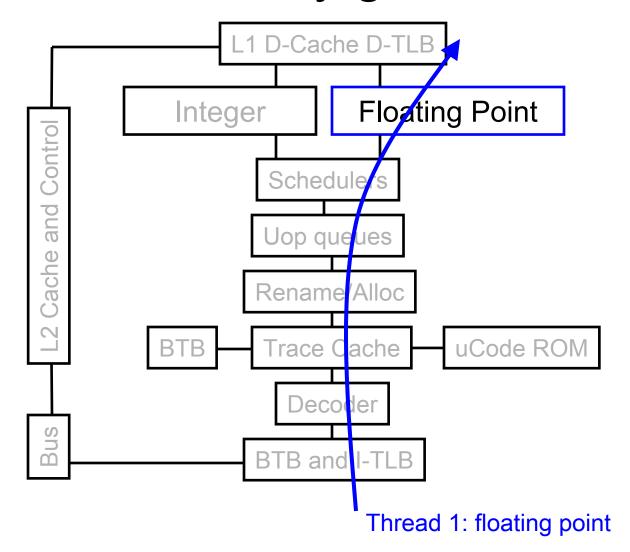
Source: Intel

Simultaneous multithreading (SMT)

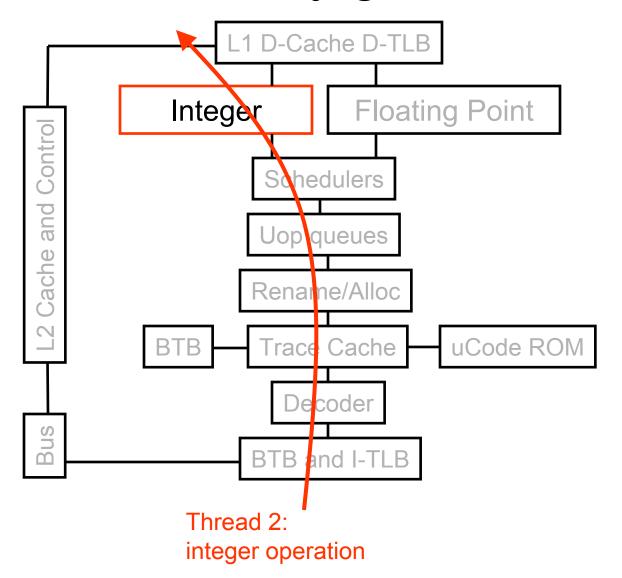
- Permits multiple independent threads to execute SIMULTANEOUSLY on the SAME core
- Weaving together multiple "threads" on the same core

 Example: if one thread is waiting for a floating point operation to complete, another thread can use the integer units

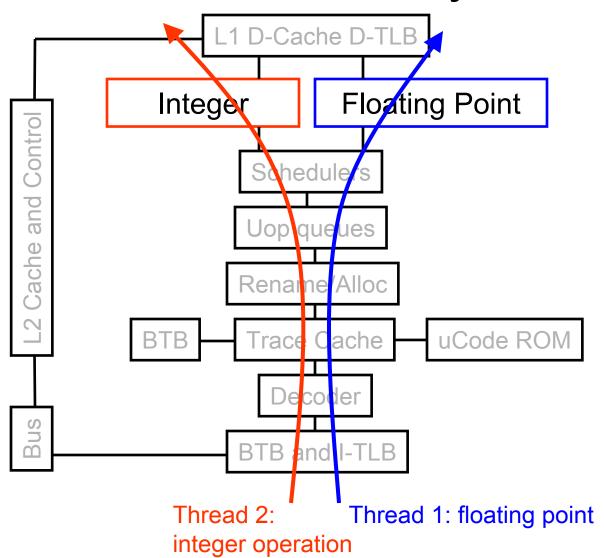
Without SMT, only a single thread can run at any given time



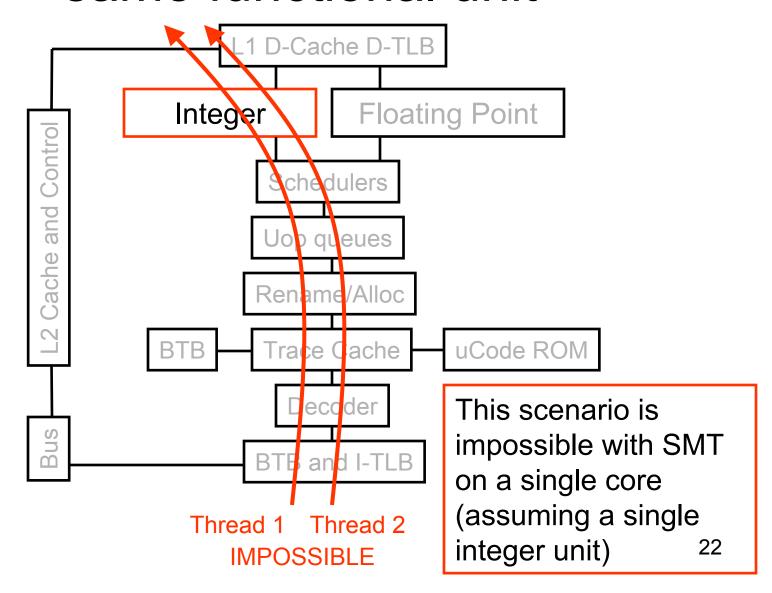
Without SMT, only a single thread can run at any given time



SMT processor: both threads can run concurrently



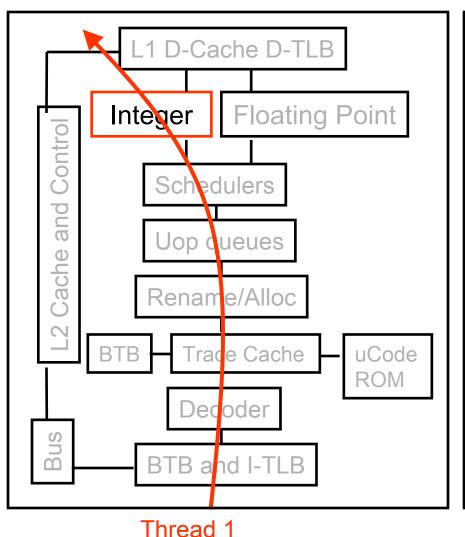
But: Can't simultaneously use the same functional unit

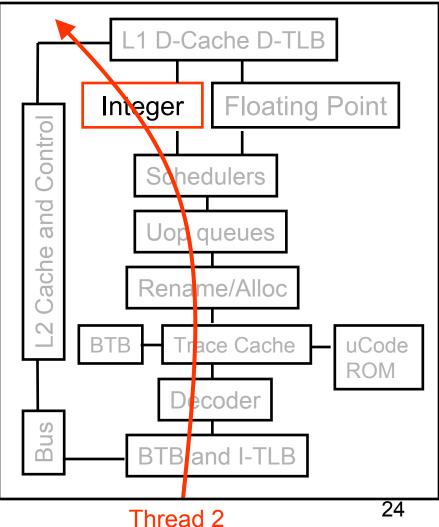


SMT not a "true" parallel processor

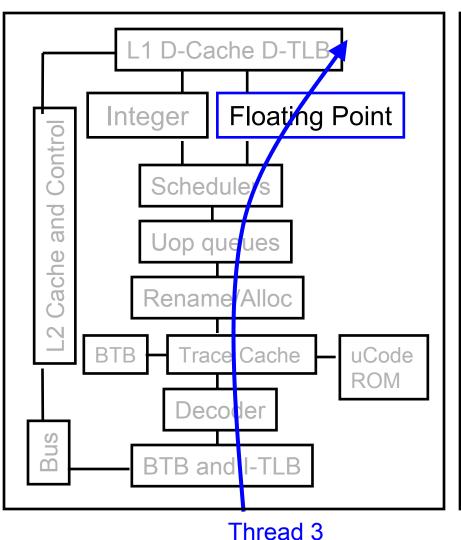
- Enables better threading (e.g. up to 30%)
- OS and applications perceive each simultaneous thread as a separate "virtual processor"
- The chip has only a single copy of each resource
- Compare to multi-core:
 each core has its own copy of resources

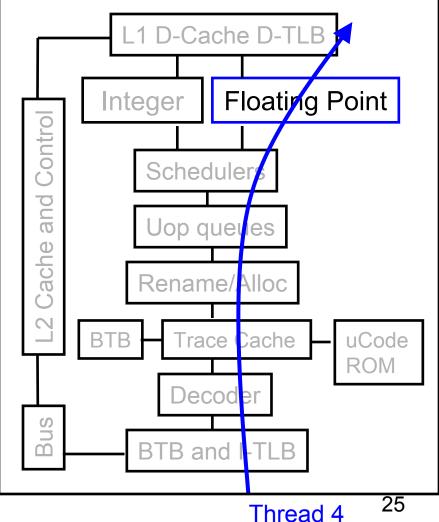
Multi-core: threads can run on separate cores





Multi-core: threads can run on separate cores

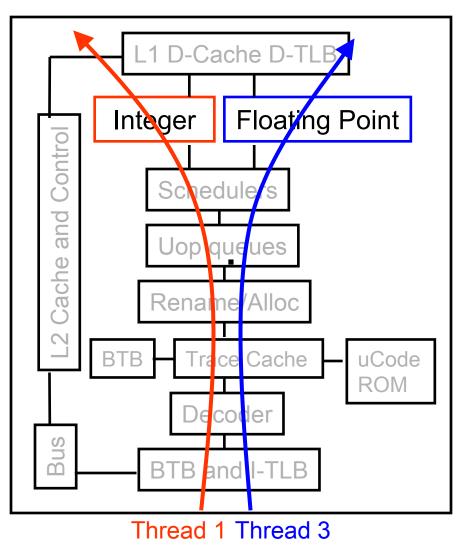


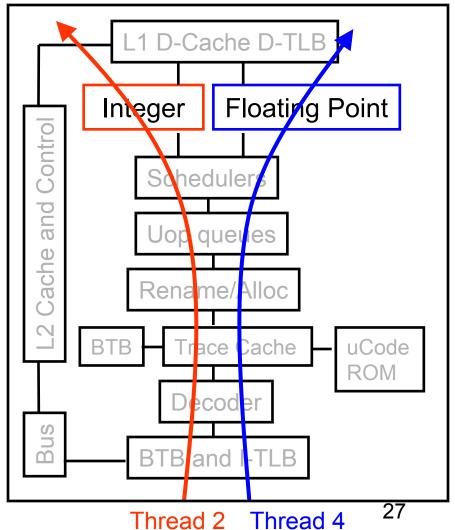


Combining Multi-core and SMT

- Cores can be SMT-enabled (or not)
- The different combinations:
 - Single-core, non-SMT: standard uniprocessor
 - Single-core, with SMT
 - Multi-core, non-SMT
 - Multi-core, with SMT: our fish machines
- The number of SMT threads:
 - 2, 4, or sometimes 8 simultaneous threads
- Intel calls them "hyper-threads"

SMT Dual-core: all four threads can run concurrently





Comparison: multi-core vs SMT

Advantages/disadvantages?

Comparison: multi-core vs SMT

Multi-core:

- Since there are several cores,
 each is smaller and not as powerful
 (but also easier to design and manufacture)
- However, great with thread-level parallelism

SMT

- Can have one large and fast superscalar core
- Great performance on a single thread
- Mostly still only exploits instruction-level parallelism

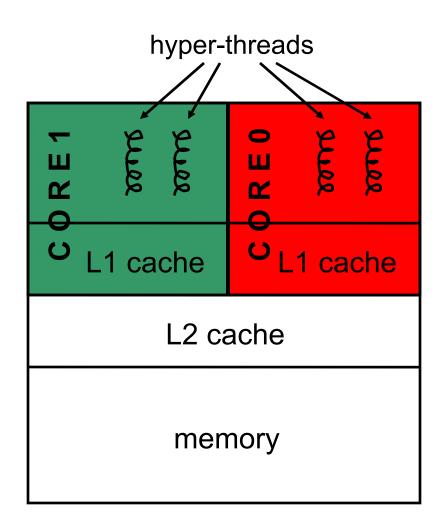
The memory hierarchy

- If simultaneous multithreading only:
 - all caches shared
- Multi-core chips:
 - L1 caches private
 - L2 caches private in some architectures and shared in others
- Memory is always shared

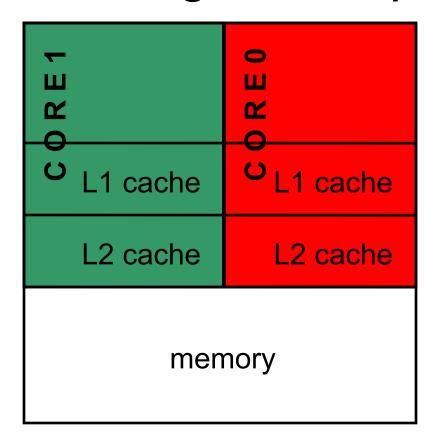
"Fish" machines

Dual-core
 Intel Xeon processors

- Each core is hyper-threaded
- Private L1 caches
- Shared L2 caches

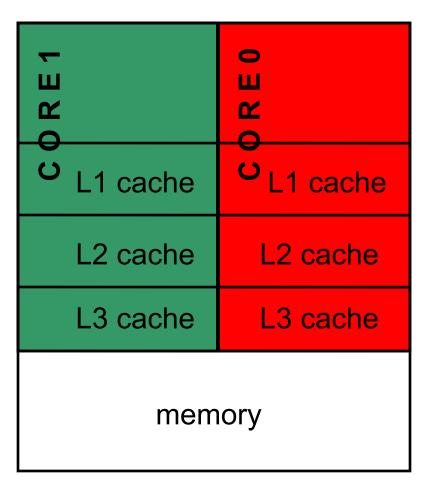


Designs with private L2 caches



Both L1 and L2 are private

Examples: AMD Opteron, AMD Athlon, Intel Pentium D



A design with L3 caches

Example: Intel Itanium 2

Private vs shared caches?

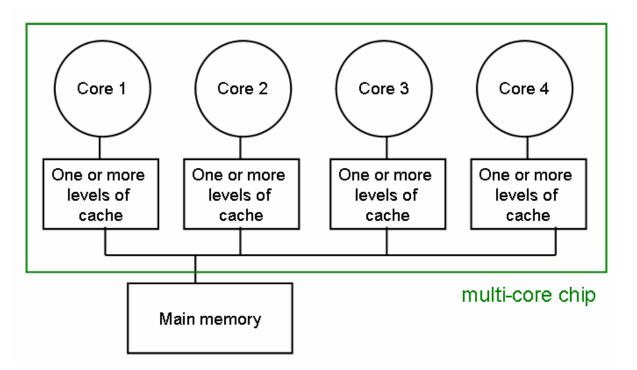
Advantages/disadvantages?

Private vs shared caches

- Advantages of private:
 - They are closer to core, so faster access
 - Reduces contention
- Advantages of shared:
 - Threads on different cores can share the same cache data
 - More cache space available if a single (or a few) high-performance thread runs on the system

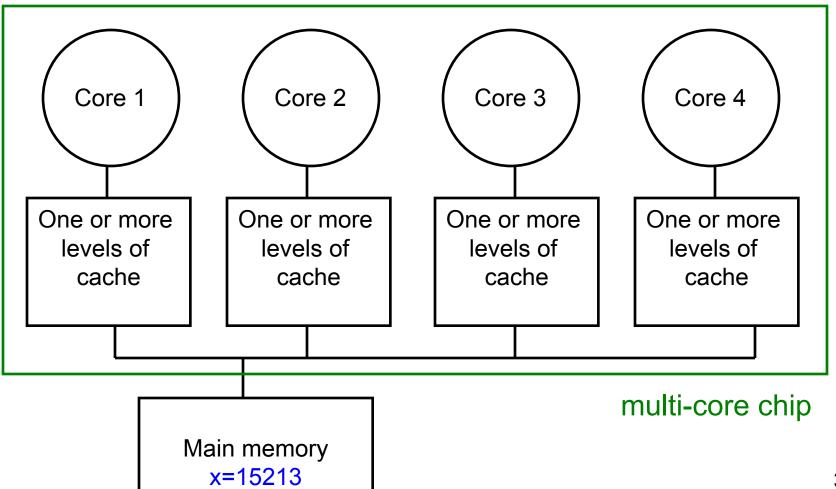
The cache coherence problem

- Since we have private caches:
 How to keep the data consistent across caches?
- Each core should perceive the memory as a monolithic array, shared by all the cores

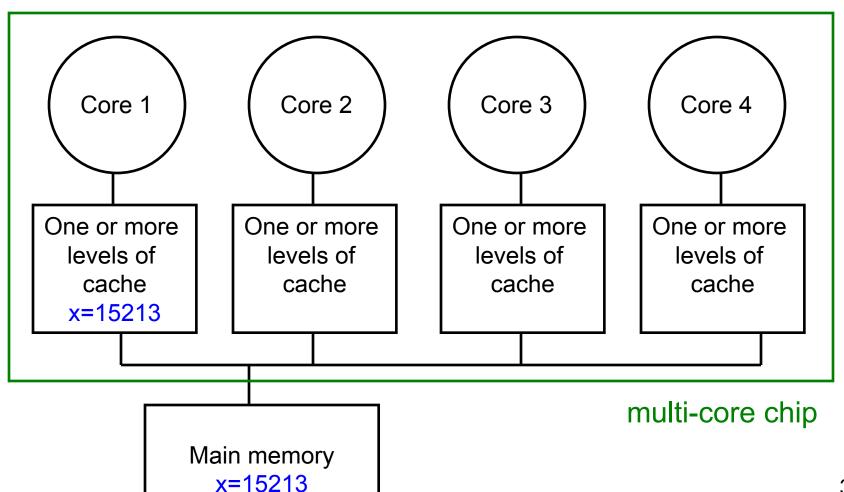


The cache coherence problem

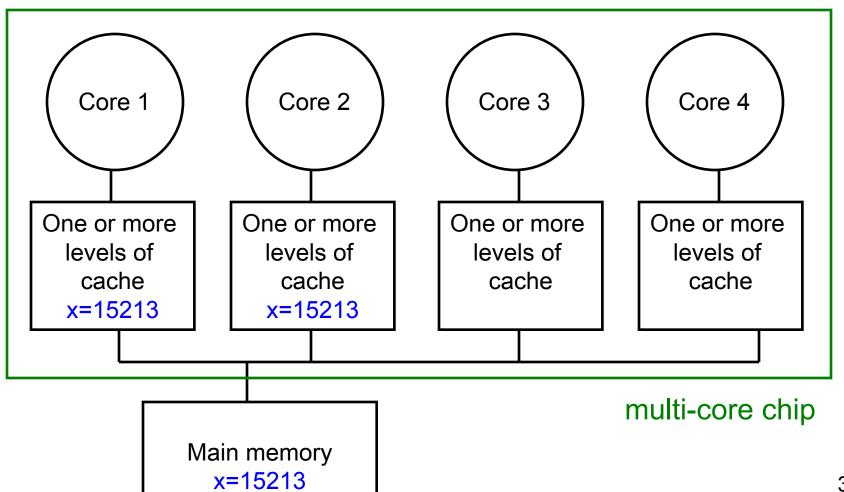
Suppose variable x initially contains 15213



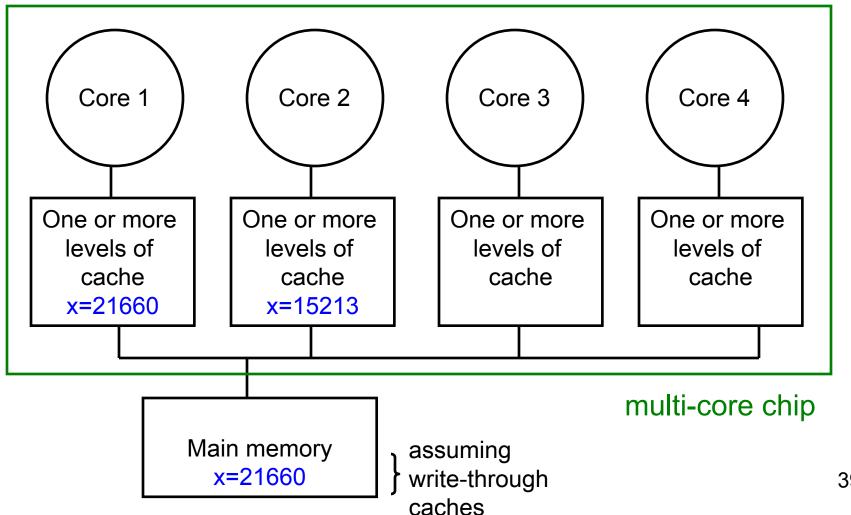
Core 1 reads x



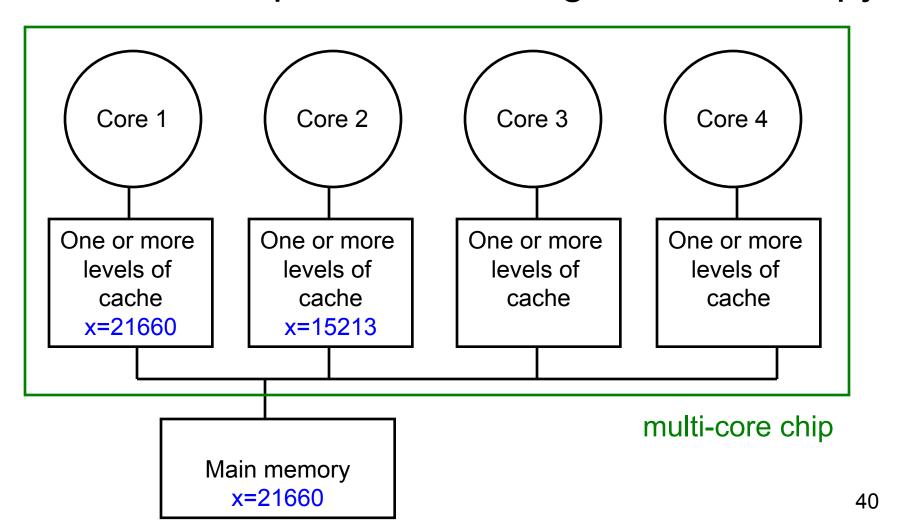
Core 2 reads x



Core 1 writes to x, setting it to 21660



Core 2 attempts to read x... gets a stale copy

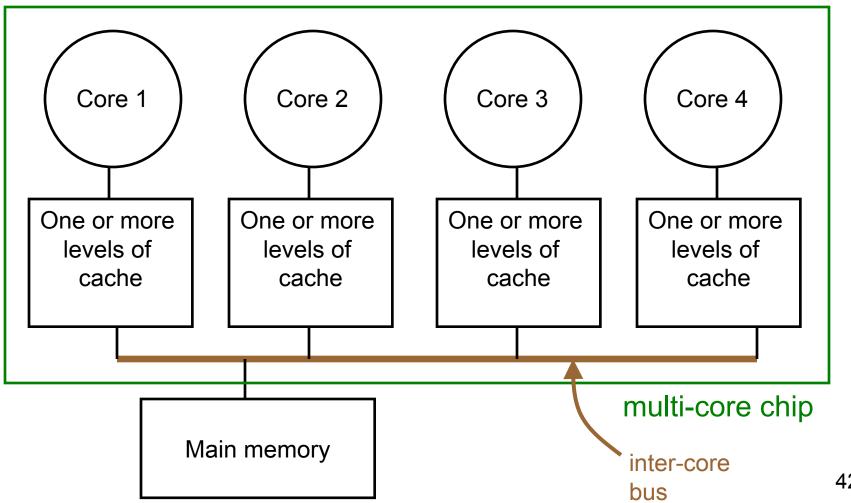


Solutions for cache coherence

- This is a general problem with multiprocessors, not limited just to multi-core
- There exist many solution algorithms, coherence protocols, etc.

 A simple solution: invalidation-based protocol with snooping

Inter-core bus

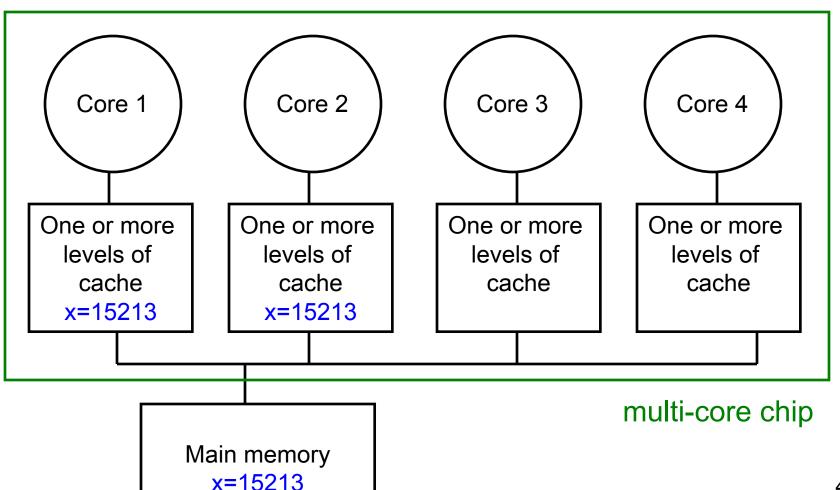


Invalidation protocol with snooping

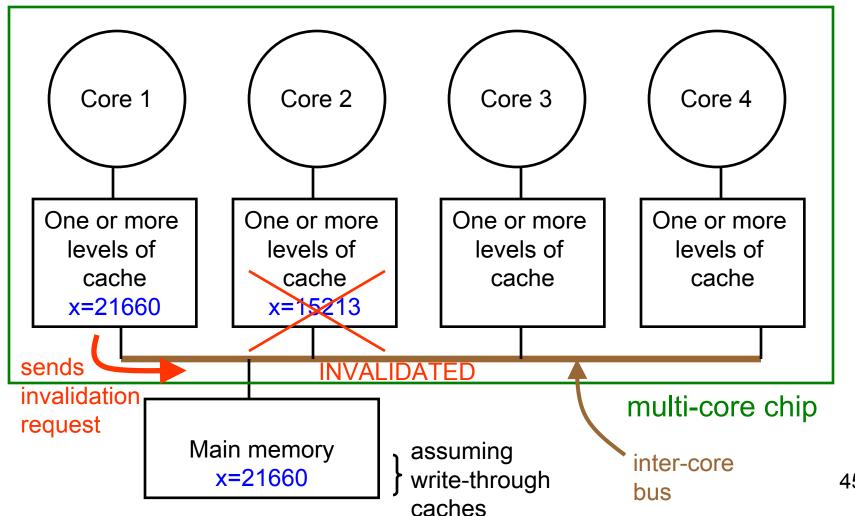
- Invalidation:
 - If a core writes to a data item, all other copies of this data item in other caches are *invalidated*
- Snooping:

All cores continuously "snoop" (monitor) the bus connecting the cores.

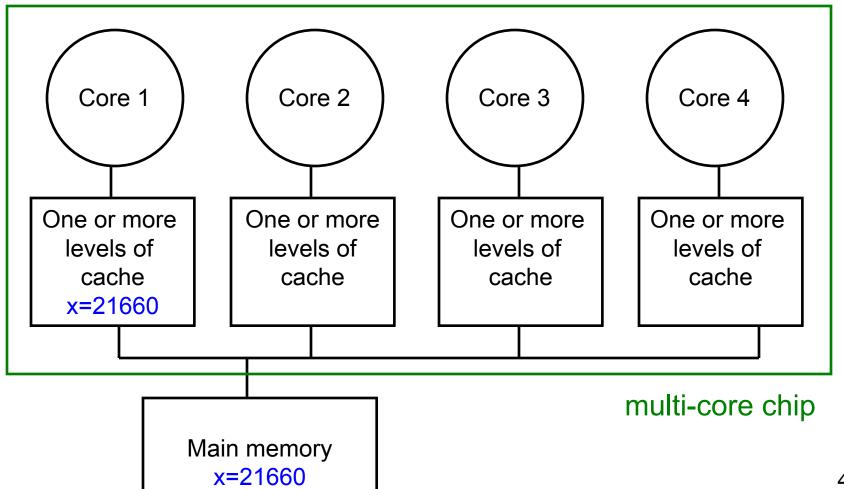
Revisited: Cores 1 and 2 have both read x



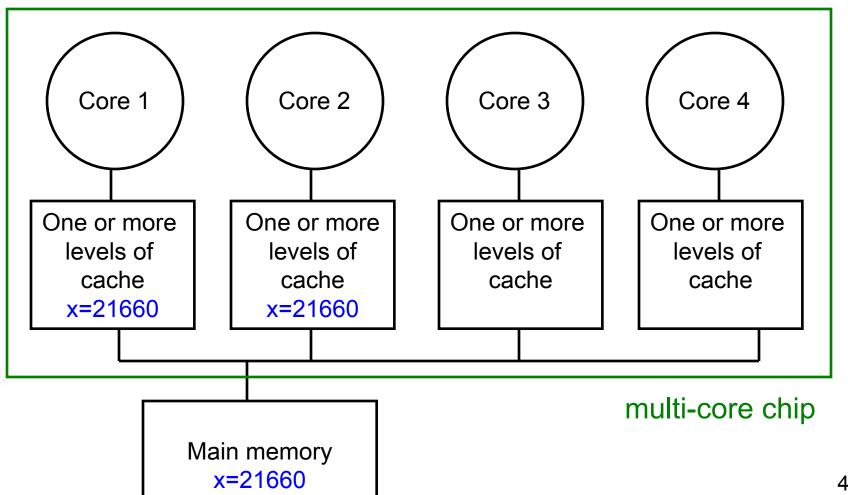
Core 1 writes to x, setting it to 21660



After invalidation:

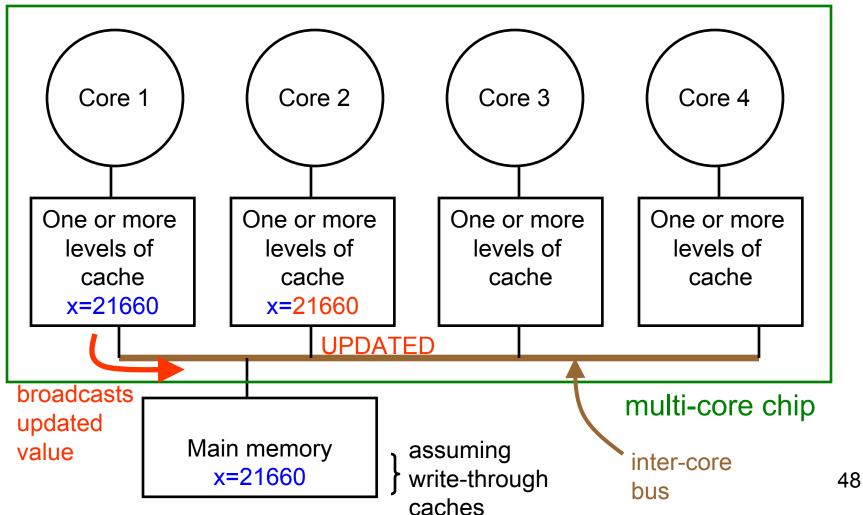


Core 2 reads x. Cache misses, and loads the new copy.



Alternative to invalidate protocol: update protocol

Core 1 writes x=21660:



Which do you think is better? Invalidation or update?

Invalidation vs update

- Multiple writes to the same location
 - invalidation: only the first time
 - update: must broadcast each write
 (which includes new variable value)

 Invalidation generally performs better: it generates less bus traffic

Invalidation protocols

- This was just the basic invalidation protocol
- More sophisticated protocols use extra cache state bits
- MSI, MESI (Modified, Exclusive, Shared, Invalid)

Programming for multi-core

Programmers must use threads or processes

Spread the workload across multiple cores

Write parallel algorithms

OS will map threads/processes to cores

Thread safety very important

 Pre-emptive context switching: context switch can happen AT ANY TIME

 True concurrency, not just uniprocessor time-slicing

 Concurrency bugs exposed much faster with multi-core

However: Need to use synchronization even if only time-slicing on a uniprocessor

```
int counter=0;
void thread1() {
 int temp1=counter;
 counter = temp1 + 1;
void thread2() {
 int temp2=counter;
 counter = temp2 + 1;
```

Need to use synchronization even if only time-slicing on a uniprocessor

```
temp1=counter;
counter = temp1 + 1;
                            gives counter=2
temp2=counter;
counter = temp2 + 1
temp1=counter;
temp2=counter;
                            gives counter=1
counter = temp1 + 1;
counter = temp2 + 1
```

Assigning threads to the cores

Each thread/process has an affinity mask

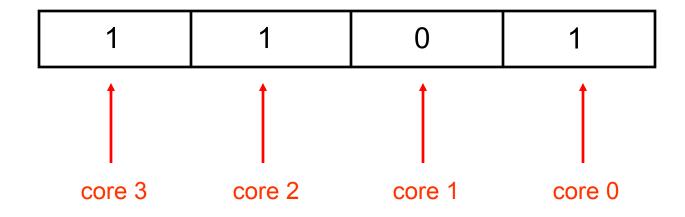
 Affinity mask specifies what cores the thread is allowed to run on

Different threads can have different masks

Affinities are inherited across fork()

Affinity masks are bit vectors

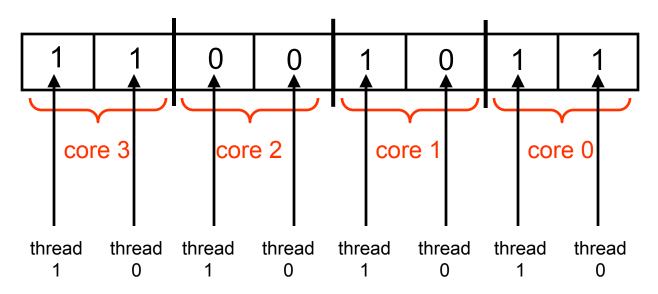
Example: 4-way multi-core, without SMT



 Process/thread is allowed to run on cores 0,2,3, but not on core 1

Affinity masks when multi-core and SMT combined

- Separate bits for each simultaneous thread
- Example: 4-way multi-core, 2 threads per core



- Core 2 can't run the process
- Core 1 can only use one simultaneous thread

Default Affinities

 Default affinity mask is all 1s: all threads can run on all processors

 Then, the OS scheduler decides what threads run on what core

 OS scheduler detects skewed workloads, migrating threads to less busy processors

Process migration is costly

- Need to restart the execution pipeline
- Cached data is invalidated
- OS scheduler tries to avoid migration as much as possible: it tends to keeps a thread on the same core
- This is called soft affinity

Hard affinities

 The programmer can prescribe her own affinities (hard affinities)

 Rule of thumb: use the default scheduler unless a good reason not to

When to set your own affinities

- Two (or more) threads share data-structures in memory
 - map to same core so that can share cache
- Real-time threads: Example: a thread running a robot controller:
 - must not be context switched, or else robot can go unstable



Source: Sensable.com

- dedicate an entire core just to this thread

Kernel scheduler API

```
#include <sched.h>
int sched_getaffinity(pid_t pid,
  unsigned int len, unsigned long * mask);
```

Retrieves the current affinity mask of process 'pid' and stores it into space pointed to by 'mask'.

'len' is the system word size: sizeof(unsigned int long)

Kernel scheduler API

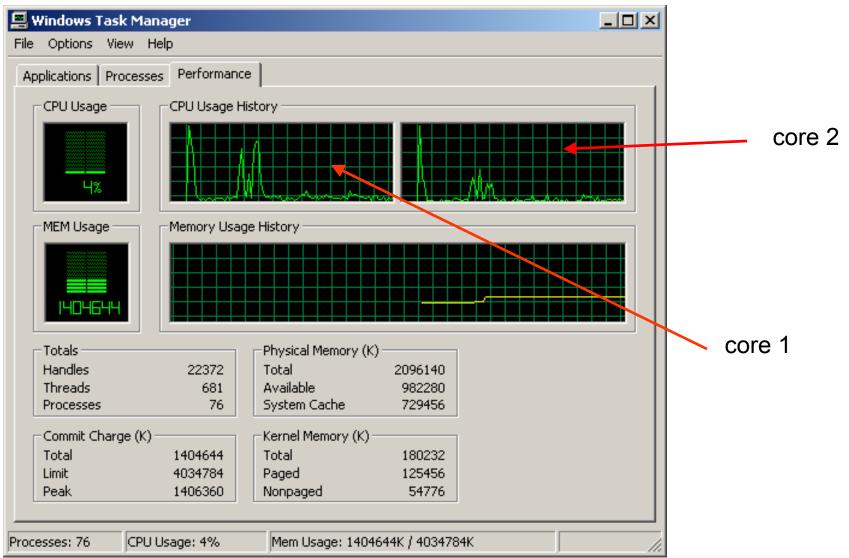
```
#include <sched.h>
int sched_setaffinity(pid_t pid,
    unsigned int len, unsigned long * mask);
```

Sets the current affinity mask of process 'pid' to *mask 'len' is the system word size: sizeof(unsigned int long)

To query affinity of a running process:

```
[barbic@bonito ~]$ taskset -p 3935 pid 3935's current affinity mask: f
```

Windows Task Manager



Legal licensing issues

 Will software vendors charge a separate license per each core or only a single license per chip?

 Microsoft, Red Hat Linux, Suse Linux will license their OS per chip, not per core

Conclusion

 Multi-core chips an important new trend in computer architecture



 Several new multi-core chips in design phases



 Parallel programming techniques likely to gain importance