

Machine Learning 10-701

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Today:

- Naïve Bayes – Big Picture
- Logistic regression
- Gradient ascent
- Generative – discriminative classifiers

Readings:

Required:

- Mitchell: "Naïve Bayes and Logistic Regression"
(see class website)

Optional

- Ng and Jordan paper (class website)

Gaussian Naïve Bayes – Big Picture

Logistic Regression

Idea:

- Naïve Bayes allows computing $P(Y|X)$ by learning $P(Y)$ and $P(X|Y)$
- Why not learn $P(Y|X)$ directly?

- Consider learning $f: X \rightarrow Y$, where
 - X is a vector of real-valued features, $\langle X_1 \dots X_n \rangle$
 - Y is boolean
 - assume all X_i are conditionally independent given Y
 - model $P(X_i | Y = y_k)$ as Gaussian $N(\mu_{ik}, \sigma_i)$
 - model $P(Y)$ as Bernoulli (π)
- What does that imply about the form of $P(Y|X)$?

$$P(Y = 1 | X = \langle X_1, \dots, X_n \rangle) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Derive form for $P(Y|X)$ for continuous X_i

$$\begin{aligned}
 P(Y = 1|X) &= \frac{P(Y = 1)P(X|Y = 1)}{P(Y = 1)P(X|Y = 1) + P(Y = 0)P(X|Y = 0)} \\
 &= \frac{1}{1 + \frac{P(Y=0)P(X|Y=0)}{P(Y=1)P(X|Y=1)}} \\
 &= \frac{1}{1 + \exp(\ln \frac{P(Y=0)P(X|Y=0)}{P(Y=1)P(X|Y=1)})} \\
 &= \frac{1}{1 + \exp((\ln \frac{1-\pi}{\pi}) + \sum_i \ln \frac{P(X_i|Y=0)}{P(X_i|Y=1)})} \\
 P(x | y_k) &= \frac{1}{\sigma_{ik}\sqrt{2\pi}} e^{-\frac{(x-\mu_{ik})^2}{2\sigma_{ik}^2}} \\
 &\quad \sum_i \left(\frac{\mu_{i0} - \mu_{i1}}{\sigma_i^2} X_i + \frac{\mu_{i1}^2 - \mu_{i0}^2}{2\sigma_i^2} \right) \\
 P(Y = 1|X) &= \frac{1}{1 + \exp(w_0 + \sum_{i=1}^n w_i X_i)}
 \end{aligned}$$

Very convenient!

$$P(Y = 1|X = \langle X_1, \dots, X_n \rangle) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

implies

$$P(Y = 0|X = \langle X_1, \dots, X_n \rangle) =$$

implies

$$\frac{P(Y = 0|X)}{P(Y = 1|X)} =$$

implies

$$\ln \frac{P(Y = 0|X)}{P(Y = 1|X)} =$$

Very convenient!

$$P(Y = 1|X = \langle X_1, \dots, X_n \rangle) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

implies

$$P(Y = 0|X = \langle X_1, \dots, X_n \rangle) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

implies

$$\frac{P(Y = 0|X)}{P(Y = 1|X)} = \exp(w_0 + \sum_i w_i X_i)$$

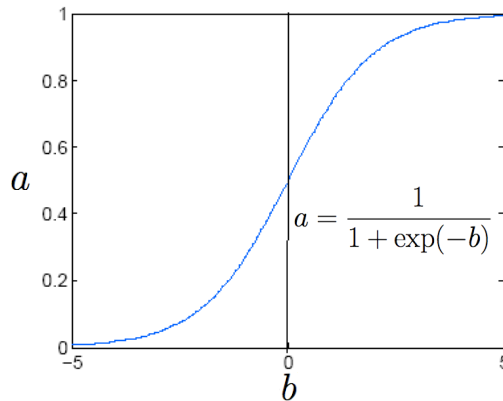
linear
classification
rule!

implies

$$\ln \frac{P(Y = 0|X)}{P(Y = 1|X)} = w_0 + \sum_i w_i X_i$$

$$\ln \frac{P(Y = 0|X)}{P(Y = 1|X)} = w_0 + \sum_i w_i X_i$$

Logistic function



$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_{i=1}^n w_i X_i)}$$

Logistic regression more generally

- Logistic regression when Y not boolean (but still discrete-valued).
- Now $y \in \{y_1 \dots y_R\}$: learn $R-1$ sets of weights

$$\text{for } k < R \quad P(Y = y_k|X) = \frac{\exp(w_{k0} + \sum_{i=1}^n w_{ki} X_i)}{1 + \sum_{j=1}^{R-1} \exp(w_{j0} + \sum_{i=1}^n w_{ji} X_i)}$$

$$\text{for } k=R \quad P(Y = y_R|X) = \frac{1}{1 + \sum_{j=1}^{R-1} \exp(w_{j0} + \sum_{i=1}^n w_{ji} X_i)}$$

Training Logistic Regression: MCLE

- we have L training examples: $\{\langle X^1, Y^1 \rangle, \dots, \langle X^L, Y^L \rangle\}$
- maximum likelihood estimate for parameters W

$$W_{MLE} = \arg \max_W P(\langle X^1, Y^1 \rangle \dots \langle X^L, Y^L \rangle | W)$$

$$= \arg \max_W \prod_l P(\langle X^l, Y^l \rangle | W)$$
- maximum conditional likelihood estimate

Training Logistic Regression: MCLE

- Choose parameters $W = \langle w_0, \dots, w_n \rangle$ to maximize conditional likelihood of training data

where
$$P(Y = 0 | X, W) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$P(Y = 1 | X, W) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

- Training data $D = \{\langle X^1, Y^1 \rangle, \dots, \langle X^L, Y^L \rangle\}$
- Data likelihood = $\prod_l P(X^l, Y^l | W)$
- Data conditional likelihood = $\prod_l P(Y^l | X^l, W)$

$$W_{MCLE} = \arg \max_W \prod_l P(Y^l | W, X^l)$$

Expressing Conditional Log Likelihood

$$l(W) \equiv \ln \prod_l P(Y^l | X^l, W) = \sum_l \ln P(Y^l | X^l, W)$$

$$P(Y = 0 | X, W) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$P(Y = 1 | X, W) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\begin{aligned} l(W) &= \sum_l Y^l \ln P(Y^l = 1 | X^l, W) + (1 - Y^l) \ln P(Y^l = 0 | X^l, W) \\ &= \sum_l Y^l \ln \frac{P(Y^l = 1 | X^l, W)}{P(Y^l = 0 | X^l, W)} + \ln P(Y^l = 0 | X^l, W) \\ &= \sum_l Y^l (w_0 + \sum_i^n w_i X_i^l) - \ln(1 + \exp(w_0 + \sum_i^n w_i X_i^l)) \end{aligned}$$

Maximizing Conditional Log Likelihood

$$P(Y = 0 | X, W) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

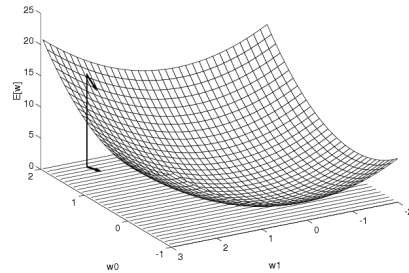
$$P(Y = 1 | X, W) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$\begin{aligned} l(W) &\equiv \ln \prod_l P(Y^l | X^l, W) \\ &= \sum_l Y^l (w_0 + \sum_i^n w_i X_i^l) - \ln(1 + \exp(w_0 + \sum_i^n w_i X_i^l)) \end{aligned}$$

Good news: $l(W)$ is concave function of W

Bad news: no closed-form solution to maximize $l(W)$

Gradient Descent



Gradient

$$\nabla E[\vec{w}] \equiv \left[\frac{\partial E}{\partial w_0}, \frac{\partial E}{\partial w_1}, \dots, \frac{\partial E}{\partial w_n} \right]$$

Training rule:

$$\Delta \vec{w} = -\eta \nabla E[\vec{w}]$$

i.e.,

$$\Delta w_i = -\eta \frac{\partial E}{\partial w_i}$$

Maximize Conditional Log Likelihood: Gradient Ascent

$$\begin{aligned} l(W) &\equiv \ln \prod_l P(Y^l | X^l, W) \\ &= \sum_l Y^l (w_0 + \sum_i w_i X_i^l) - \ln(1 + \exp(w_0 + \sum_i w_i X_i^l)) \end{aligned}$$

$$\frac{\partial l(W)}{\partial w_i} = \sum_l X_i^l (Y^l - \hat{P}(Y^l = 1 | X^l, W))$$

Maximize Conditional Log Likelihood: Gradient Ascent

$$\begin{aligned}l(W) &\equiv \ln \prod_l P(Y^l | X^l, W) \\&= \sum_l Y^l (w_0 + \sum_i^n w_i X_i^l) - \ln(1 + \exp(w_0 + \sum_i^n w_i X_i^l))\end{aligned}$$

$$\frac{\partial l(W)}{\partial w_i} = \sum_l X_i^l (Y^l - \hat{P}(Y^l = 1 | X^l, W))$$

Gradient ascent algorithm: iterate until change $< \epsilon$

For all i , repeat

$$w_i \leftarrow w_i + \eta \sum_l X_i^l (Y^l - \hat{P}(Y^l = 1 | X^l, W))$$

That's all for M(C)LE. How about MAP?

- One common approach is to define priors on W
 - Normal distribution, zero mean, identity covariance
- Helps avoid very large weights and overfitting
- MAP estimate

$$W \leftarrow \arg \max_W \ln P(W) \prod_l P(Y^l | X^l, W)$$

- let's assume Gaussian prior: $W \sim N(0, \sigma)$

MLE vs MAP

- Maximum conditional likelihood estimate

$$W \leftarrow \arg \max_W \ln \prod_l P(Y^l | X^l, W)$$

$$w_i \leftarrow w_i + \eta \sum_l X_i^l (Y^l - \hat{P}(Y^l = 1 | X^l, W))$$

- Maximum a posteriori estimate with prior $W \sim N(0, \sigma^2 I)$

$$W \leftarrow \arg \max_W \ln [P(W) \prod_l P(Y^l | X^l, W)]$$

$$w_i \leftarrow w_i - \eta \lambda w_i + \eta \sum_l X_i^l (Y^l - \hat{P}(Y^l = 1 | X^l, W))$$

MAP estimates and Regularization

- Maximum a posteriori estimate with prior $W \sim N(0, \sigma^2 I)$

$$W \leftarrow \arg \max_W \ln [P(W) \prod_l P(Y^l | X^l, W)]$$

$$w_i \leftarrow w_i - \eta \lambda w_i + \eta \sum_l X_i^l (Y^l - \hat{P}(Y^l = 1 | X^l, W))$$

called a “regularization” term

- helps reduce overfitting, especially when training data is sparse
- keep weights nearer to zero (if $P(W)$ is zero mean Gaussian prior), or whatever the prior suggests
- used very frequently in Logistic Regression

The Bottom Line

- Consider learning $f: X \rightarrow Y$, where
 - X is a vector of real-valued features, $\langle X_1 \dots X_n \rangle$
 - Y is boolean
 - assume all X_i are conditionally independent given Y
 - model $P(X_i | Y = y_k)$ as Gaussian $N(\mu_{ik}, \sigma_i)$
 - model $P(Y)$ as Bernoulli (π)
- Then $P(Y|X)$ is of this form, and we can directly estimate W
$$P(Y = 1 | X = \langle X_1, \dots, X_n \rangle) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$
- Furthermore, same holds if the X_i are boolean
 - trying proving that to yourself

Generative vs. Discriminative Classifiers

Training classifiers involves estimating $f: X \rightarrow Y$, or $P(Y|X)$

Generative classifiers (e.g., Naïve Bayes)

- Assume some functional form for $P(X|Y)$, $P(X)$
- Estimate parameters of $P(X|Y)$, $P(X)$ directly from training data
- Use Bayes rule to calculate $P(Y|X = x_i)$

Discriminative classifiers (e.g., Logistic regression)

- Assume some functional form for $P(Y|X)$
- Estimate parameters of $P(Y|X)$ directly from training data

Use Naïve Bayes or Logistic Regression?

Consider

- Restrictiveness of modeling assumptions
- Rate of convergence (in amount of training data) toward asymptotic hypothesis
 - i.e., the learning curve

Naïve Bayes vs Logistic Regression

Consider Y boolean, X_i continuous, $X = \langle X_1 \dots X_n \rangle$

Number of parameters to estimate:

- NB:

- LR:

$$P(Y = 0|X, W) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$P(Y = 1|X, W) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Naïve Bayes vs Logistic Regression

Consider Y boolean, X_i continuous, $X = \langle X_1 \dots X_n \rangle$

Number of parameters:

- NB: $4n + 1$
- LR: $n + 1$

Estimation method:

- NB parameter estimates are uncoupled
- LR parameter estimates are coupled

G.Naïve Bayes vs. Logistic Regression

[Ng & Jordan, 2002]

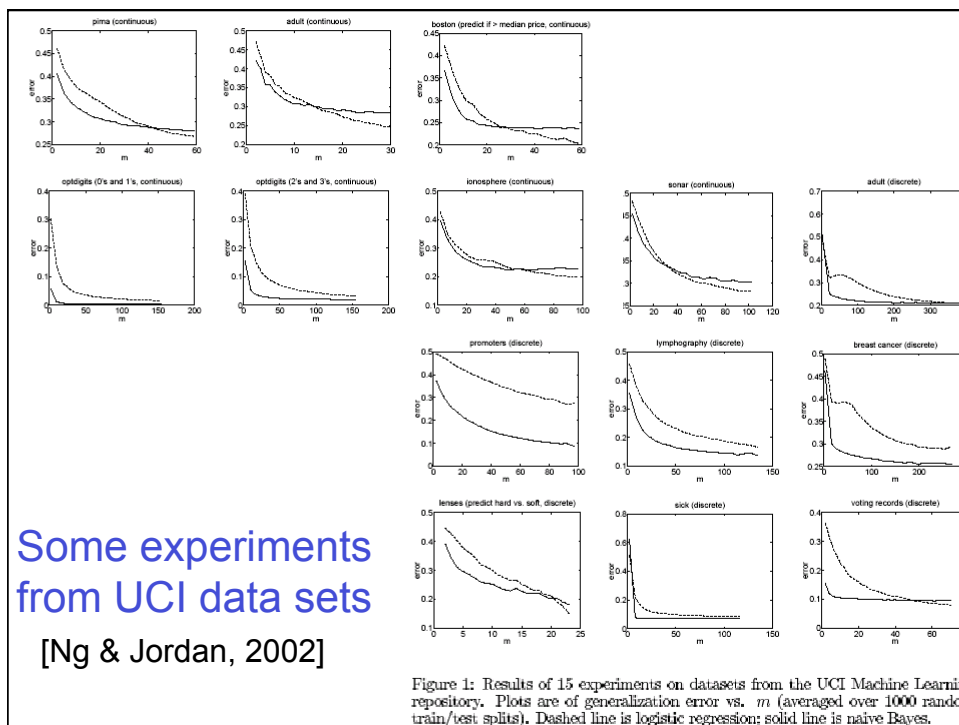
- Generative and Discriminative classifiers
- *Asymptotic comparison* (# training examples \rightarrow infinity)
 - when conditional independence assumptions correct
 - GNB, LR produce identical classifiers
 - when conditional independence assumptions incorrect
 - LR is less biased – does not assume cond indep.
 - therefore expected to outperform GNB when both given infinite training data

Naïve Bayes vs. Logistic Regression

- Generative and Discriminative classifiers
- *Non-asymptotic analysis* (see [Ng & Jordan, 2002])
 - convergence rate of parameter estimates – how many training examples needed to assure good estimates?
 - GNB order $\log n$ (where $n = \#$ of attributes in X)
 - LR order n

GNB converges more quickly to its (perhaps less accurate) asymptotic estimates

Informally: because LR's parameter estimates are coupled, but GNB's are not



Summary: Naïve Bayes and Logistic Regression

- Modeling assumptions
 - Naïve Bayes more biased (cond. indep)
 - Both learn linear decision surfaces
- Convergence rate (n =number training examples)
 - Naïve Bayes $\sim O(\log n)$
 - Logistic regression $\sim O(n)$
- Bottom line
 - Naïve Bayes converges faster to its (potentially too restricted) final hypothesis

What you should know:

- Logistic regression
 - Functional form follows from Naïve Bayes assumptions
 - For Gaussian Naïve Bayes assuming variance $\sigma_{i,k} = \sigma_i$
 - For discrete-valued Naïve Bayes too
 - But training procedure picks parameters without the conditional independence assumption
 - MLE training: pick W to maximize $P(Y | X, W)$
 - MAP training: pick W to maximize $P(W | X, Y)$
 - regularization: e.g., $P(W) \sim N(0, \sigma)$
 - helps reduce overfitting
- Gradient ascent/descent
 - General approach when closed-form solutions for MLE, MAP are unavailable
- Generative vs. Discriminative classifiers
 - Bias vs. variance tradeoff