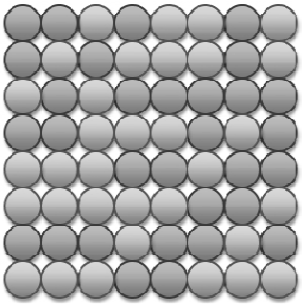
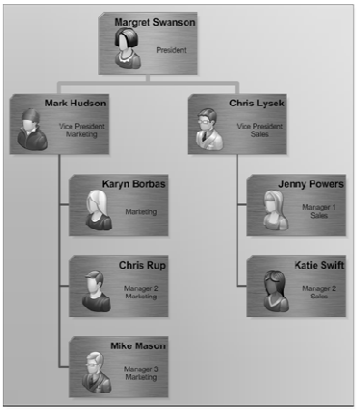


UNIT 6C
Organizing Data: Trees and Graphs

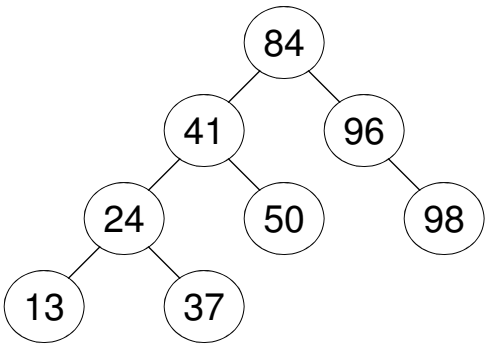
Trees



Trees

- A **tree** is a hierarchical data structure.
  - Every tree has a **node** called the **root**.
  - Each node can have 1 or more nodes as **children**.
  - A node that has no children is called a **leaf**.
- A common tree in computing is a **binary tree**.
  - A binary tree consists of nodes that have at most 2 children.
  - A **complete binary tree** has the maximum number of nodes on each of its levels.
- Applications: data compression, file storage, game trees

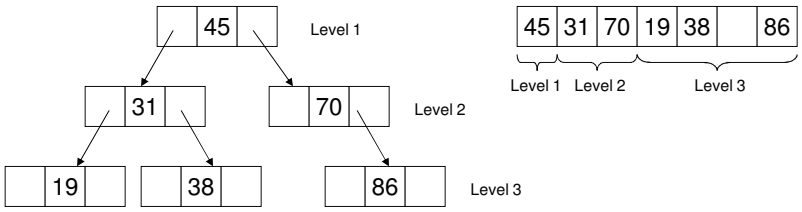
Binary Tree



The root has the data value 84.
There are 4 leaves in this binary tree: 13, 37, 50, 98.
This binary tree is not complete.

Binary Trees: Implementation

- One common implementation of binary trees uses nodes like a linked list does.
  - Instead of having a "next" pointer, each node has a "left" pointer and a "right" pointer.
- We could also use an array.



Binary Search Tree (BST)

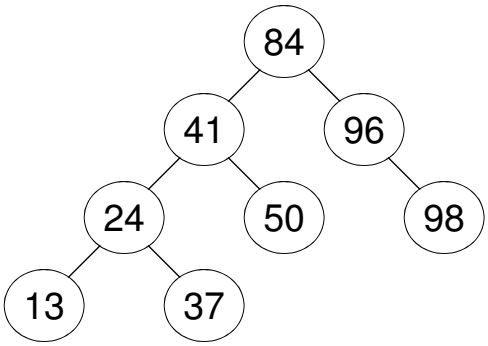
- A binary search tree (BST) is a binary tree such that
  - All nodes to the left of any node have data values less than that node
  - All nodes to the right of any node have data values greater than that node

Inserting into a BST

- For each data value that you wish to insert into the binary search tree:
  - Start at the root and compare the new data value with the root.
  - If it is less, move down left. If it is greater, move down right.
  - Repeat on the child of the root until you end up in a position that has no node.
  - Insert a new node at this empty position.

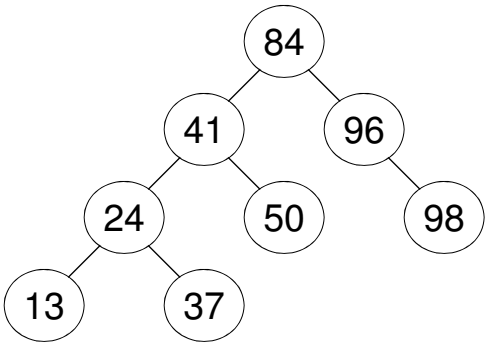
Example

- Insert: 84, 41, 96, 24, 37, 50, 13, 98



Using a BST

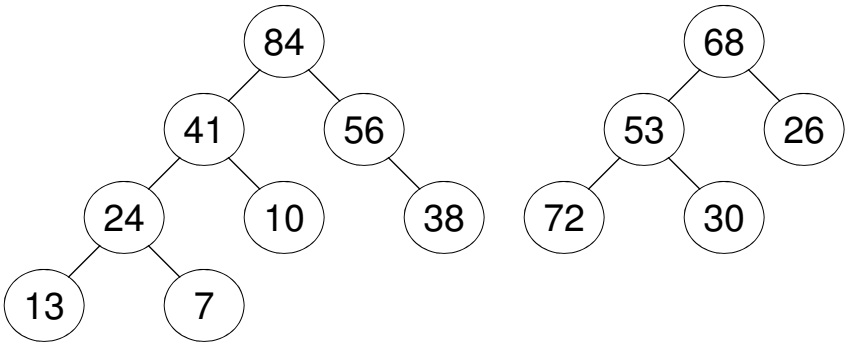
- How would you search for an element in a BST?



Max-Heaps

- A max-heap is a binary tree such that
  - The largest data value is in the root
  - For every node in the max-heap, its children contain smaller data.
  - The max-heap is an almost-complete binary tree.
    - An almost-complete binary tree is a binary tree such that every level of the tree has the maximum number of nodes possible except possibly the last level, where its nodes are attached as far left as possible.

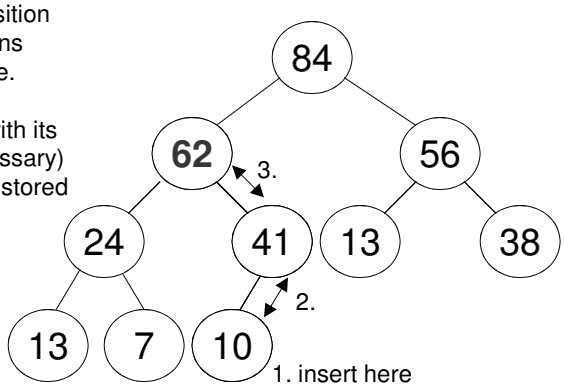
These are not heaps! Why?



Adding data to a Max-Heap

Insert new data into next available tree position so the tree remains (almost) complete.

Exchange data with its parent(s) (if necessary) until the tree is restored to a heap.



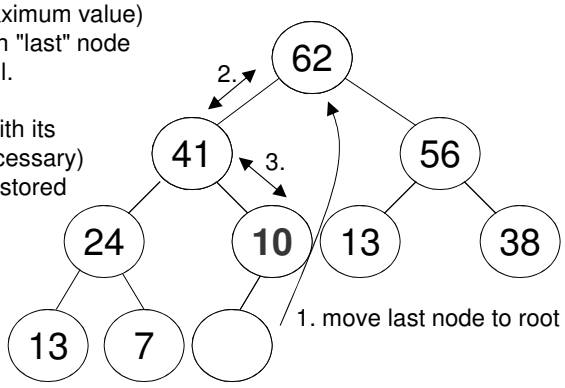
Building a Max-Heap

- To build a max-heap, just insert each element one at a time into the heap using the previous algorithm.

Removing Data from a Max-Heap

Remove root (maximum value) and replace it with "last" node of the lowest level.

Exchange data with its larger child (if necessary) until the tree is restored to a heap.



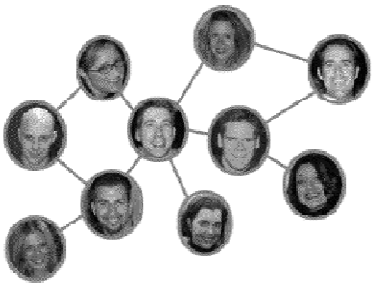
BSTs vs. Max-Heaps

- Which tree is designed for easier searching?
- Which tree is designed for retrieving the maximum value quickly?
- A heap is guaranteed to be "balanced" (complete or almost-complete).
  What about a BST?

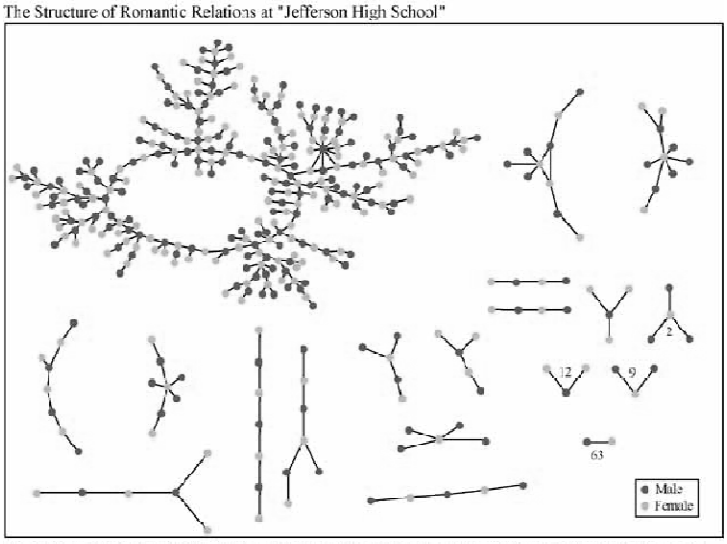
BSTs vs Max-Heaps

- BST with n elements
  - Insert and Search:
    - worst case O(log n) if tree is "balanced"
    - worst case O(n) in general since tree could have one node per level
- Max-Heap with n elements
  - Insert and Remove-Max
    - worst case O(log n) since tree is always "balanced"
  - Find-Max
    - worst case O(1) since max is always at the root

Graphs



The Structure of Romantic Relations at "Jefferson High School"

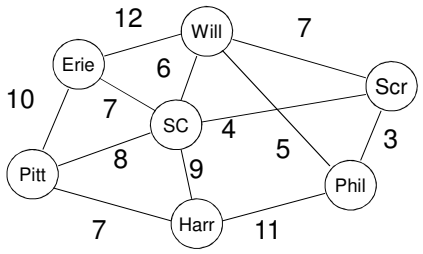


Each circle represents a student and lines connecting students represent romantic relations occuring within the 6 months preceding the interview. Numbers under the figure count the number of times that pattern was observed (i.e. we found 63 pairs unconnected to anyone else).

Graphs

- A **graph** is a data structure that consists of a set of vertices and a set of edges connecting pairs of the vertices.
  - A graph doesn't have a root, per se.
  - A vertex can be connected to any number of other vertices using edges.
  - An edge may be bidirectional or directed (one-way).
  - An edge may have a weight on it that indicates a cost for traveling over that edge in the graph.
- Applications: computer networks, transportation systems, social relationships

A Weighted Graph



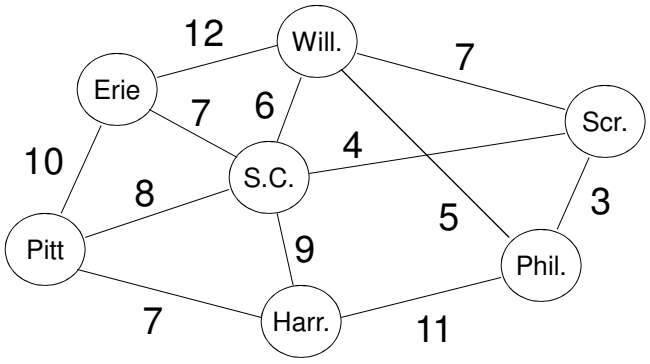
0	1	2	3	4	5	6
Pitt.	Erie	Will.	S.C.	Harr.	Scr.	Phil.

vertices

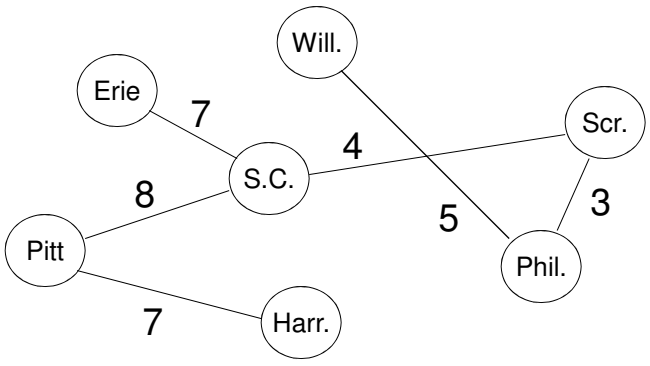
	0	1	2	3	4	5	6
0	0	10	0	8	7	0	0
1	10	0	12	7	0	0	0
2	0	12	0	6	0	7	5
3	8	7	6	0	9	4	0
4	7	0	0	9	0	0	11
5	0	0	7	4	0	0	3
6	0	0	5	0	11	3	0

edges

Original Graph

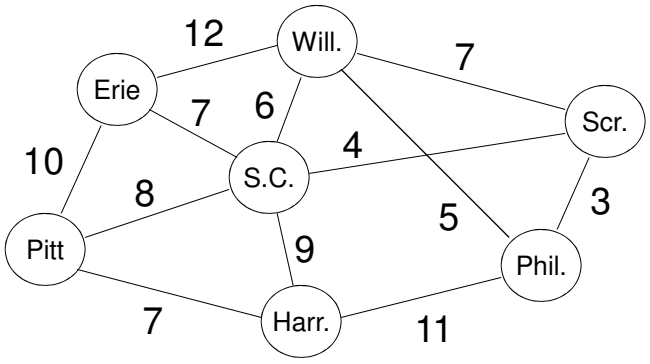


Minimal Spanning Tree

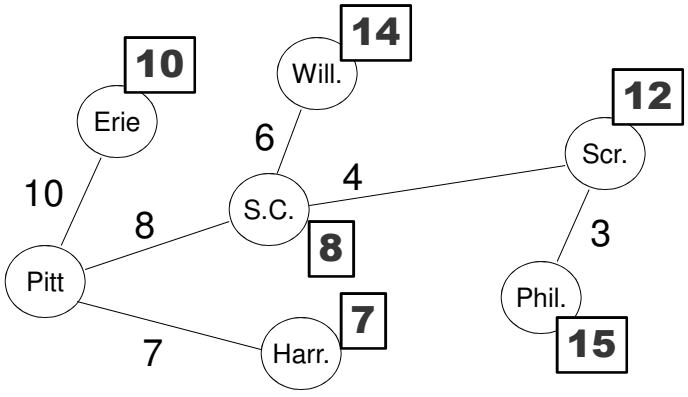


The minimum total cost to connect all vertices using edges from the original graph without using cycles. (minimum total cost = 34)

Original Graph



Shortest Paths from Pittsburgh



The total costs of the shortest path from Pittsburgh to every other location using only edges from the original graph.