## Advanced Optimization

 (10-801: CMU)
## Lecture 22

Fixed-point theory; nonlinear conic optimization
07 Apr 2014

Suvrit Sra

Many optimization problems

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\begin{aligned}
h(x) & =0 \\
x-h(x) & =0 \\
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## Three types of results

1 Geometric: Banach contraction and relatives
2 Order-theoretic: Knaster-Tarski
3 Topological: Brouwer, Schauder-Leray, etc.

## Fixed-point theory - main concerns

- existence of a solution
- uniqueness of a solution
- stability under small perturbations of parameters
- structure of solution set (failing uniqueness)
- algorithms / approximation methods to obtain solutions
- rate of convergence analyses

Fixed-point theory - Banach contraction
Some conditions under which the nonlinear equation

$$
x=T x, \quad x \in M \subset X,
$$

can be solved by iterating

$$
x_{k+1}=T x_{k}, \quad x_{0} \in M, \quad k=0,1, \ldots
$$

## Fixed-point theory - Banach contraction

Theorem (Banach 1922.) Suppose (i) $T: M \subseteq X \rightarrow M$; (ii) $M$ is closed, nonempty set in a complete metric space $(X, d)$; (iii) $T$ is $q$-contractive, i.e.,

$$
d(T x, T y) \leq q d(x, y), \quad \forall x, y \in M, \text { constant } 0 \leq q<1
$$

Then, we have the following:
(i) $T x=x$ has exactly one solution ( $T$ has a unique FP in $M$ )
(ii) The sequence $\left\{x_{k}\right\}$ converges to the solution for any $x_{0} \in M$
(iii) A priori error estimate

$$
d\left(x_{k}, x^{*}\right) \leq q^{k}(1-q)^{-1} d\left(x_{0}, x_{1}\right)
$$

(iv) A posterior error estimate

$$
d\left(x_{k+1}, x^{*}\right) \leq q(1-q)^{-1} d\left(x_{k}, x_{k+1}\right)
$$

(v) (Global) linear rate of convergence: $d\left(x_{k+1}, x^{*}\right) \leq q d\left(x_{k}, x^{*}\right)$

Fixed-point theory - Banach contraction

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- Several other variations of maps have been studied for Banach spaces (see e.g., book by Bauschke, Combettes (2012))

Banach contraction - proof
Blackboard

## Banach contraction - proof

## Blackboard

## Summary:

- $d$ must be positive-definite, i.e, $d(x, y)=0$ iff $x=y$
- ( $X, d$ ) must be complete (contain all its Cauchy sequences)
- $T: M \rightarrow M, M$ must be closed
- But $M$ need not be compact!
- Contraction is often a rare luxury; nonexpansive maps are more common (we've already seen several)


## More general fixed-point theorems

Theorem (Brouwer FP.) Every continuous function from a convex compact subset $M \subset \mathbb{R}^{d}$ to $M$ itself has a fixed-point.

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- Any algorithm for computing a Brouwer FP based on function evaluations only must in the worst case perform a number of function evaluations exponential in both the number of digits of accuracy and the dimension.
- Contrast with $n=1$, where bisection yields $\left|f(\hat{x})-f^{*}\right| \leq 2^{-\delta}$ in $O(\delta)$

FP theorem for set-valued mappings (recall $x \in(I-\partial f)(x)$ )

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## Set-valued map

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F: M \rightarrow 2^{M}, \quad x \in M \mapsto F(x) \in 2^{M} \text {, i.e. } F(x) \subseteq M
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## Closed-graph

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& \quad\{(x, y) \mid y \in F(x)\} \text { is a closed subset of } X \times X \\
& \text { (i.e., } \left.x_{k} \rightarrow x, y_{k} \rightarrow y \text { and } y_{k} \in F\left(x_{k}\right) \Longrightarrow y \in F(x)\right)
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## Kakutani fixed-point theorem

FP theorem for set-valued mappings (recall $x \in(I-\partial f)(x)$ )

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Theorem (S. Kakutani 1941.) Let $M \subset \mathbb{R}^{n}$ be nonempty, convex, compact. Let $F: M \rightarrow 2^{M}$ be a set-valued map with a closed graph; also for all $x \in M$, let $F(x)$ be non-empty and convex. Then, $F$ has a fixed point.

Application: See proof of Nash equilibrium on Wikipedia

## Brouwer FP - example

- Consider a Markov transition matrix $A \in \mathbb{R}_{+}^{n \times n}$
- Column stochastic: $a_{i j} \geq 0$ and $\sum_{i} a_{i j}=1$ for $1 \leq j \leq n$


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$$
\text { How to compute such an } x \text { ? }
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## Conic optimization

Some definitions

- Let $K$ be a cone in a real vector space $V$
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- Let $y \in K$ and $x \in V$. We say $y$ dominates $x$ if

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\alpha y \preceq_{K} x \preceq_{K} \beta y, \quad \text { for some } \alpha, \beta \in \mathbb{R} \text {. }
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## Max-min gauges

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M_{K}(x / y) & :=\inf \{\beta \in \mathbb{R} \mid x \leq \beta y\} \\
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\end{aligned}
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Shorthand: $\leq \equiv \preceq_{K}$

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## Hilbert projective metric

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Proposition. Let $K$ be a cone in $V ;\left(K, d_{H}\right)$ satisfies:

- $d_{H}(x, y) \geq 0$, and $d_{H}(x, y)=d_{H}(y, x)$ for all $x, y \in K$
- $d_{H}(x, z) \leq d_{H}(x, y)+d_{H}(y, z)$ for all $x \sim_{K} y \sim_{K} z$, and

■ $d_{H}(\alpha x, \beta y)=d_{H}(x, y)$ for all $\alpha, \beta>0$ and $x, y \in K$.
If $K$ is closed, then $d_{H}(x, y)=0$ iff $x=\lambda y$ for some $\lambda>0$. In this case, if $X \subset K$ satisfies that for each $x \in K \backslash\{0\}$ there is a unique $\lambda>0$ such that $\lambda x \in X$ and $P$ is a part of $K$, then $\left(P \cap X, d_{H}\right)$ is a genuine metric space.

Proof: on blackboard


Def. (OPSH maps.) Let $K \subseteq V$ and $K^{\prime} \subseteq V^{\prime}$ be closed cones. The $f: K \rightarrow K^{\prime}$ is called order preserving if for $x \leq_{K} y, f(x) \leq_{K^{\prime}} f(y)$. It is homogeneous of degree $r$ if $f(\lambda x)=\lambda^{r} f(x)$ for all $x \in K$ and $\lambda>0$. It is subhomogeneous if $\lambda f(x) \leq f(\lambda x)$ for all $x \in K$ and $0<\lambda<1$.

Exercise: Prove that if $f: K \rightarrow K^{\prime}$ is OPH of degree $r>0$ then

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- In particular, if $r=1$, then $f$ is nonexpansive (in $d_{H}$ )


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Contraction ratio
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Theorem (Birkhoff.) Let $\Delta(L):=\sup \left\{d_{H}(L x, L y) \mid L x \sim_{K} L y\right\}$ be the projective diameter of $L$. Then

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- If $\Delta(L)<\infty$, then we have a strict contraction!


## Application to Pagerank eigenvector

- Markov transition matrix $A \in \mathbb{R}_{+}^{n \times n}$
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- Suppose $\Delta(A)<\infty$ - (next slide)


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- Linear rate of convergence


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d_{H}(x, y)=\log \left(\max _{i, j \in I_{x}} \frac{x_{i} y_{j}}{x_{j} y_{i}}\right)
$$

Lemma If $A \in \mathbb{R}_{+}^{m \times n}$. If there exists $J \subset[n]$ s.t. $A e_{i} \sim_{K^{\prime}} A e_{j}$ for all $i, j \in J$, and $A e_{i}=0$ for all $i \notin J$ then the projective diameter

$$
\Delta(A)=\max _{i, j \in J} d_{H}\left(A e_{i}, A e_{j}\right)<\infty
$$

## More applications

- Geometric optimization on the psd cone

Sra, Hosseini (2013). "Conic geometric optimisation on the manifold of positive definite matrices." arXiv:1312.1039.

- MDPs, Stochastic games, Nonlinear eigenvalue problems, etc.
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^ Nonlinear Perron-Frobenius theory. Lemmens, Nussbaum (2013).

