Welcome to the Journal of Human-Robot Interaction

Michael Goodrich and I welcome you to the inaugural issue of the *Journal of Human-Robot Interaction* (JHRI). Our aim is for this journal to be the leading peer-reviewed interdisciplinary journal of human-robot interaction. To further the goal of creating high impact quickly, Michael and I, with the help of the associate editors and advisory board, have adopted a strategy to create special issues containing related HRI papers of high interest and quality. The inaugural issue grew out of a highly successful RSS workshop. Special editors, Leila Takayama and Brian Scassellati, invited members of the workshop and others to submit. All the papers were independently peer reviewed and those that passed initial muster were invited to revise for another round of review. The second special issue will emphasize the global nature of our field. The special editors, Michael Goodrich and Kerstin Severinson Eklundh, announced the issue broadly and invited papers from around the world. Following our process for maintaining quality, all submitted papers have been sent out for independent peer review, revision, and re-review if needed. (And the same process will apply to all issues of the journal.) The third special issue, which I am editing, will contain journal papers based on great papers from HRI-related conferences. The fourth special issue will emphasize systems, addressing a gap across HRI conferences. The special editor, Takayuki Kanda, has been soliciting articles and authors. Chosen articles will be given a special slot for presentations in the HRI 2013 conference.

Not all future issues of JHRI will be special issues. Indeed, we have already received unsolicited papers on a variety of HRI topics. If you have a wonderful paper, please do not wait for the announcement of a special issue. We consider the field broadly, to include how people interact with robots and robotic technologies, how to improve these interactions and make new kinds of interaction possible, and the effects of HRI designs on people and society. We also will consider different types of content including video, datasets, reviews of the literature, or teaching materials. We encourage submission of papers from all fields including robotics, computer science, engineering, design, the behavioral and social sciences, and human-computer interaction. Our strategy is to give top preference to readable high quality papers that contribute to the state of the art and general knowledge and that are written to be intelligible to a wide range of audiences.

Sara Kiesler
Editor

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